

PYG4OMETRY : A TOOL TO CREATE GEOMETRIES FOR GEANT4, BDSIM, G4BEAMLINE AND FLUKA FOR PARTICLE LOSS AND ENERGY DEPOSIT STUDIES

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Abstract

Studying the energy deposits in accelerator components, mechanical supports, services, ancillary equipment and shielding requires a detailed computer readable description of the component geometry. The creation of geometries is a significant bottleneck in producing complete simulation models and reducing the effort required will provide the ability of non-experts to simulate the effects of beam losses on realistic accelerators. The paper describes a flexible and easy to use Python package to create geometries usable by either Geant4 (and so BDSIM or G4Beamline) or FLUKA either from scratch or by conversion from common engineering formats, such as STEP or IGES created by industry standard CAD/CAM packages. The conversion requires an intermediate conversion to STL or similar triangular or tetrahedral tessellation description. A key capability of pyg4ometry is to mix GDML/STEP/STL geometries and visualisation of the resulting geometry and determine if there are any geometric overlaps. An example conversion of a complex geometry used in Geant4/BDSIM is presented.

INTRODUCTION

Simulating radiation transport in an accelerator beamline requires a description of the 3D layout, structure, dimensions and material properties of the physical objects that the beam particles can interact with. This description is commonly referred to as a “geometry model” or “geometry”. In general, the elements (volumes) in such a model must not overlap, ensuring that particles can be located in only one volume at a time. There is also a trade-off between the geometry detail and the simulation execution time. Because of those constraints, radiation transport geometries have traditionally been prepared by hand.

Pyg4ometry started as a python scripting tool to generate beam line geometries for BDSIM. BDSIM is a Geant4 application which allows a user to rapidly create a full three dimensional model of an accelerator from an optical description. A guiding principle of BDSIM is rapid simulation of accelerator models, the MADX input format for example can be converted for use in BDSIM in minutes. Rarely described in accelerator optical descriptions is the geometry of the physical material that comprises the accelerator, beam-pipe, magnets, supports, tunnel, beam instrumentation etc. The aim of pyg4ometry is to create a tool in which complex geometry can be created as quickly as a generic

BDSIM model. A key requirement is to be able to integrate and composite geometry sources to a single file.

Particle Transport Codes

There are multiple different Monte Carlo (MC) codes to simulate the transportation and physics processes of particles though accelerators and detectors, these include Geant4 [1], MCOMPX [2] and FLUKA [3]. Generally accelerator codes, like MAD8 [4], MADX [5], Transport [6] etc, are interfaced to a MC code to produce a complete simulation of beam losses. Two beam line simulation tools have been developed on the basis of Geant4; BDSIM [7–9] and G4Beamline [10].

Geometry Generation and GDML

The specification of the geometry of the material surrounding an accelerator can be an exceedingly time consuming and error prone task. Typically either the detector or accelerator infrastructure is constructed over many years and the simulation geometry can be created over similar time scales. This does not allow for rapid simulation of a system as the burden of creating the geometry is too great. An XML-based markup language, Geometry Description Markup Language (GDML) is used as the file format for geometry export in pyg4ometry.

SOFTWARE IMPLEMENTATION

Pyg4ometry is a collection of python classes that mimic closely the C++ interface of Geant4. The aim to have all of the “detector” description classes implemented in python, these include geometry, materials and optical surfaces. The pyg4ometry defined geometry can then quickly be written as a GDML file for loading into BDSIM or G4Beamline. This is a much quicker interface to a full C++ Geant4 application and any programmed geometry can be viewed quickly using VTK. Geometry defined using Pyg4ometry can be converted to a surface triangulation using primitive mesh generation of each solid in python and a constructive solid geometry (CSG) library based on Binary Space Partitioning (BSP) trees. GDML has a simple mathematical expression language so geometries can be parametrised, this is also implemented in pyg4ometry using ANTLR [11]. A Python interface to the geometry primitives of Geant4 allows conversion applications to be developed from FLUKA/STEP/STL descriptions to pyg4ometry. Finally and most importantly pyg4ometry provides an interface to GDML, as the python interpreter performs important syntax checking of large and complex geometries.

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EXAMPLES

Python

A complete code example for creation of a simple geometry consisting of three Iron solids is shown below. The python interfaces are so similar to the Geant4 C++ interface and the user can refer to the Geant4 documentation.

```
import pyg4ometry.gdml as gd
import pyg4ometry.geant4 as g4
import pyg4ometry.visualisation as vi
import numpy as _np

# create empty data storage structure
reg = g4.Registry()

# 1) expressions
wx = gd.Constant("wx", "100", reg)
wy = gd.Constant("wy", "100", reg)
wz = gd.Constant("wz", "100", reg)
bx = gd.Constant("bx", "10", reg)
by = gd.Constant("by", "10", reg)
bz = gd.Constant("bz", "10", reg)

# 2) materials
wm = g4.MaterialPredefined("G4_Galactic", reg)
m = g4.MaterialPredefined("G4_Fe", reg)

# 3) solids
wb = g4.solid.Box("wb", wx, wy, wz, reg)
b = g4.solid.Box("b", bx, by, bz, reg)
s = g4.solid.Orb("o", bx/2, reg)
t = g4.solid.Tubs("t", 0, bx/2, bz, 0, 2*_np.pi, reg)

# 4) structure
wl = g4.LogicalVolume(wb, wm, "wl", reg)
bl = g4.LogicalVolume(b, m, "b", reg)
sl = g4.LogicalVolume(s, m, "s", reg)
tl = g4.LogicalVolume(t, m, "t", reg)
bp = g4.PhysicalVolume([0,0,0,0], [0,0,0],
                        bl, "b_pv", wl, reg)
sp = g4.PhysicalVolume([0,0,0], [-2*bx,0,0],
                        sl, "s_pv", wl, reg)
tp = g4.PhysicalVolume([0,0.5,0], [2*bx,0,0],
                        tl, "t_pv", wl, reg)

# set world volume
reg.setWorld("wl")

# 5) gdml output
w = gd.Writer()
w.addDetector(reg)
w.write("simple.gdml")

# 6) visualisation
v = vi.VtkViewer()
v.addLogicalVolume(wl)
v.addAxes(40)
v.view()
```

The code is divided in 6 blocks of definitions, reusable parameters, materials, solids, structure and placement, GDML IO and finally visualisation. A key difference between

pyg4ometry and Geant4 is a dedicated object known as the Registry to store all geometry definitions to be stored in the output file. The VTK output from this example is shown in Figure 1, where three solids, a cube, sphere and cylinder, are placed with translations and rotations within a cubical world volume.

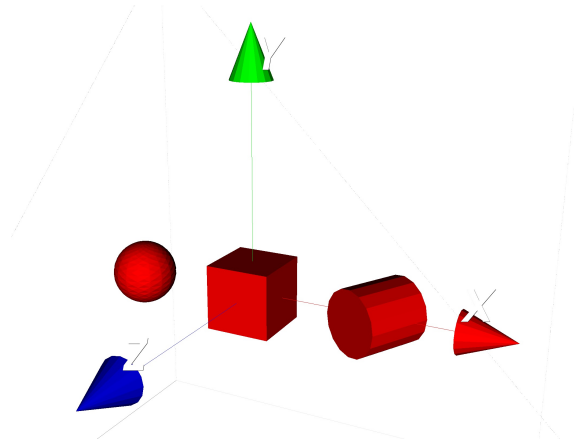


Figure 1: Example of three primitive Geant4 solids rendered in VTK.

Figure 2 shows a more complex geometry example of a cavity beam position monitor and short sections of beam pipe.

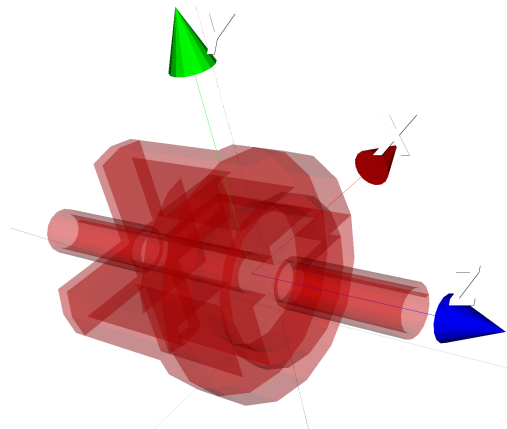


Figure 2: Example of a more complex geometry example, a cavity beam position monitor.

Standard Tessellation Language (STL)

STL file format describes a raw unstructured triangulated surface, where the surface normal is defined by the ordering of the vertices. Pyg4ometry supports the loading STL files and conversion to G4TessellatedSolid. A classic STL example loaded in pg4ometry and displayed in VTK is shown in Figure 3

```
import pyg4ometry
r = pyg4ometry.stl.Reader("example.stl")
reg = r.getRegistry()
```


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