



Qutrit Circuits and Algebraic Relations: A Pathway to Efficient Spin-1 Hamiltonian Simulation

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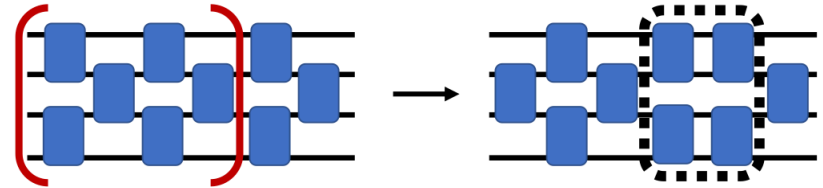
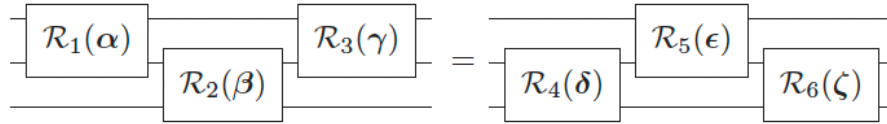
PhysRevA.109.012426

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Yang-Baxter-type equations and Qubit Circuit Compression

- Circuit compression by applying the Yang-Baxter type equation on a two-qubit time propagator

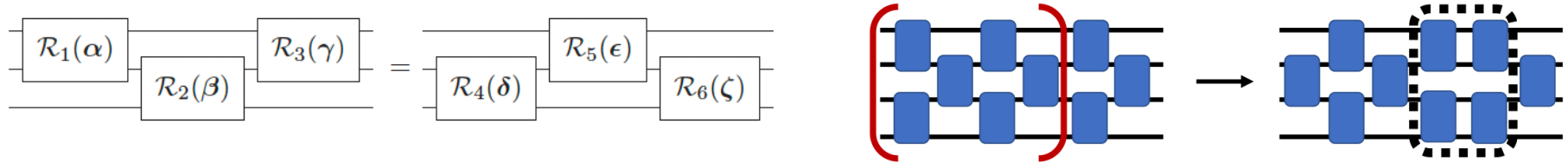
$R_\theta = e^{-i\theta(A \otimes B)}$, where $A, B \in SU(2)$. - [Phys. Rev. A 106, 012412 \(2022\), B. Peng, S. Gulania, Y. Alexeev, and N. Govind.](#)



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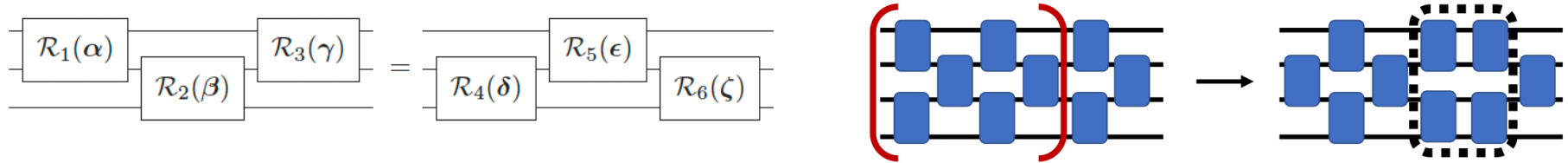


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- Remarkably, turn-over relation compresses time evolution circuit to a depth that scales linearly with respect to the number of qubits.
- Question:** Can we generalize idea to quantum circuits with higher dimensions?
Exploratory effort in this direction, - quantum time dynamics of the one-dimensional spin-1 Heisenberg model.
- Map Spin-1 system states onto qutrit states for efficient algebraic relations.

Notation and Spin-Algebra

Treat qudits as spins quantum states via $s = (d - 1)/2$

$d = 3 \Rightarrow s = 1$, with z-basis representation

$$S^x = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} = \frac{1}{\sqrt{2}} [(X \oplus 0) + (0 \oplus X)],$$

$$S^y = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 & -i & 0 \\ i & 0 & -i \\ 0 & i & 0 \end{pmatrix} = \frac{1}{\sqrt{2}} [(Y \oplus 0) + (0 \oplus Y)]$$

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where X, Y, Z are the Pauli gates.

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Rewrite in a simpler way for numerical ease via Permutation matrices

$$\tilde{S}^x = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & -i \\ 0 & -i & 0 \end{pmatrix}, \quad \tilde{S}^y = \begin{pmatrix} 0 & 0 & i \\ 0 & 0 & 0 \\ -i & 0 & 0 \end{pmatrix} = P_y \tilde{S}^x P_y^\dagger, \quad \tilde{S}^z = \begin{pmatrix} 0 & i & 0 \\ -i & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = P_z \tilde{S}^x P_z^\dagger$$

$$P_y = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Similar to the $SU(2)$ cases, $\{\tilde{S}^x, \tilde{S}^y, \tilde{S}^z\}$ satisfy commutation algebra

$$P_z = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix}$$

$$[\tilde{S}^x, \tilde{S}^y] = i\tilde{S}^z, \quad [\tilde{S}^y, \tilde{S}^z] = i\tilde{S}^x, \quad [\tilde{S}^z, \tilde{S}^x] = i\tilde{S}^y$$

Note: Basis change $\{S^x, S^y, S^z\} \leftrightarrow \{\tilde{S}^x, \tilde{S}^y, \tilde{S}^z\}$ does not affect algebraic/circuit relations

Algebraic and Numerical turn-overs

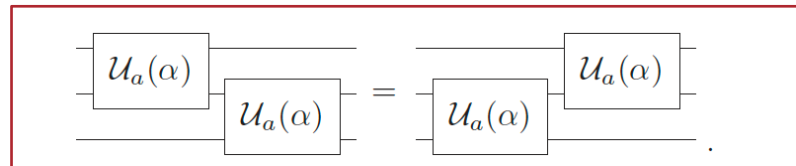
Two Qutrit time propagators:

$$\mathcal{U}_x(\alpha) = \exp(-i\alpha \tilde{S}^x \otimes \tilde{S}^x), \quad \mathcal{U}_y(\alpha) = \exp(-i\alpha \tilde{S}^y \otimes \tilde{S}^y), \quad \mathcal{U}_z(\alpha) = \exp(-i\alpha \tilde{S}^z \otimes \tilde{S}^z)$$

From the Permutation matrices,



A simple feature is that $\mathcal{U}_a(\alpha)$, $a \in \{x, y, z\}$ satisfies



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From the Permutation matrices,

$$\begin{array}{c} \text{---} \\ \text{---} \end{array} \boxed{\mathcal{U}_y(\alpha)} \begin{array}{c} \text{---} \\ \text{---} \end{array} = \begin{array}{c} \boxed{P_y} \\ \boxed{P_y} \end{array} \boxed{\mathcal{U}_x(\alpha)} \begin{array}{c} \boxed{P_y^\dagger} \\ \boxed{P_y^\dagger} \end{array} \begin{array}{c} \text{---} \\ \text{---} \end{array} \quad \begin{array}{c} \text{---} \\ \text{---} \end{array} \boxed{\mathcal{U}_z(\alpha)} \begin{array}{c} \text{---} \\ \text{---} \end{array} = \begin{array}{c} \boxed{P_z} \\ \boxed{P_z} \end{array} \boxed{\mathcal{U}_x(\alpha)} \begin{array}{c} \boxed{P_z^\dagger} \\ \boxed{P_z^\dagger} \end{array} \begin{array}{c} \text{---} \\ \text{---} \end{array}.$$

An interesting feature is that $\mathcal{U}_a(\alpha)$, $a \in \{x, y, z\}$ satisfies

$$\begin{array}{c} \text{---} \\ \text{---} \end{array} \boxed{\mathcal{U}_a(\alpha)} \boxed{\mathcal{U}_a(\alpha)} \begin{array}{c} \text{---} \\ \text{---} \end{array} = \begin{array}{c} \text{---} \\ \text{---} \end{array} \boxed{\mathcal{U}_a(\alpha)} \boxed{\mathcal{U}_a(\alpha)} \begin{array}{c} \text{---} \\ \text{---} \end{array}.$$

Case 1: Same rotation (algebraic proof)

(1) LHS:

$$\begin{array}{c} \text{---} \\ \text{---} \end{array} \boxed{\mathcal{U}_a(\alpha)} \boxed{\mathcal{U}_a(\alpha)} \begin{array}{c} \text{---} \\ \text{---} \end{array} = \begin{array}{c} \boxed{\mathcal{U}_a(2\alpha)} \\ \boxed{\mathcal{U}_a(\alpha)} \end{array} \begin{array}{c} \text{---} \\ \text{---} \end{array} = \begin{array}{c} \text{---} \\ \text{---} \end{array} \boxed{\mathcal{U}_a(\alpha)} \boxed{\mathcal{U}_a(2\alpha)} \begin{array}{c} \text{---} \\ \text{---} \end{array}$$

(2) RHS:

$$\begin{array}{c} \text{---} \\ \text{---} \end{array} \boxed{\mathcal{U}_a(\alpha)} \boxed{\mathcal{U}_a(\alpha)} \begin{array}{c} \text{---} \\ \text{---} \end{array} = \begin{array}{c} \boxed{\mathcal{U}_a(\alpha)} \\ \boxed{\mathcal{U}_a(2\alpha)} \end{array} \begin{array}{c} \text{---} \\ \text{---} \end{array} = \begin{array}{c} \text{---} \\ \text{---} \end{array} \boxed{\mathcal{U}_a(2\alpha)} \boxed{\mathcal{U}_a(\alpha)} \begin{array}{c} \text{---} \\ \text{---} \end{array}$$

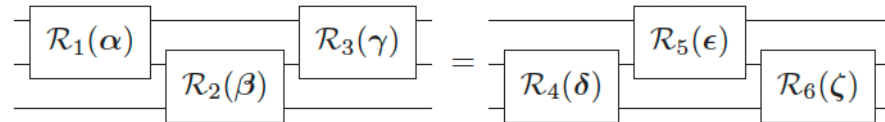
(3) LHS = RHS:

$$\begin{array}{c} \text{---} \\ \text{---} \end{array} \boxed{\mathcal{U}_a(\alpha)} \boxed{\mathcal{U}_a(2\alpha)} \begin{array}{c} \text{---} \\ \text{---} \end{array} = \begin{array}{c} \text{---} \\ \text{---} \end{array} \boxed{\mathcal{U}_a(\alpha)} \boxed{\mathcal{U}_a(2\alpha)} \boxed{\mathcal{U}_a(\alpha)} \begin{array}{c} \text{---} \\ \text{---} \end{array}$$

Numerically approximate turn-over identities

Case 2: Different rotations (*algebraic proof still searching?*).

Establish $(3^3 \times 3^3)$ matrix relation:

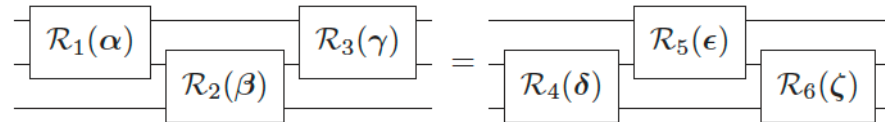


$$[\mathcal{R}_1(\alpha) \otimes I_3][I_3 \otimes \mathcal{R}_2(\beta)][\mathcal{R}_3(\gamma) \otimes I_3] = [I_3 \otimes \mathcal{R}_4(\delta)][\mathcal{R}_5(\epsilon) \otimes I_3][I_3 \otimes \mathcal{R}_6(\zeta)]$$

i.e. Denoting LHS as $W_L(\vec{\theta}_L)$ and RHS as $W_R(\vec{\theta}_R)$, fix $\vec{\theta}_L$ while optimizing for $\vec{\theta}_R$.

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i.e. Denoting LHS as $W_L(\vec{\theta}_L)$ and RHS as $W_R(\vec{\theta}_R)$, fix $\vec{\theta}_L$ while optimizing for $\vec{\theta}_R$.

- Explore Spin-1 XY Hamiltonian on 3 qutrits:

$$H_{XY} = -J \sum_{i=0}^2 \tilde{S}_i^x \tilde{S}_{i+1}^x + \tilde{S}_i^y \tilde{S}_{i+1}^y,$$

$$e^{-itH_{XY}} = e^{itJ \sum_{i=0}^2 \tilde{S}_i^x \tilde{S}_{i+1}^x + \tilde{S}_i^y \tilde{S}_{i+1}^y}$$

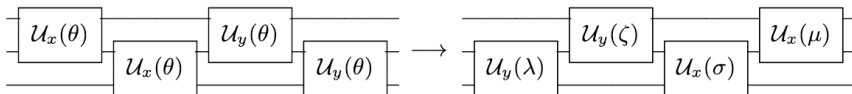
- Consider possible trotterizations, and explore approximate identities by minimizing gate infidelity :

$$C(\vec{\theta}_L, \vec{\theta}_R) = 1 - \frac{1}{(3^3)^2} \left\| \text{tr} (W_L(\vec{\theta}_L) W_R^\dagger(\vec{\theta}_R)) \right\|^2$$

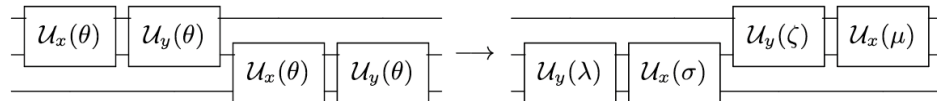
Numerically approximate turn-over identities

Possible Trotterizations of the 3-qutrits isotropic XY Hamiltonian

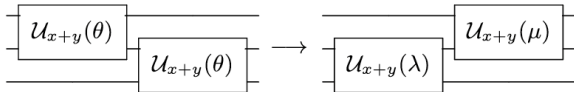
T_1 :



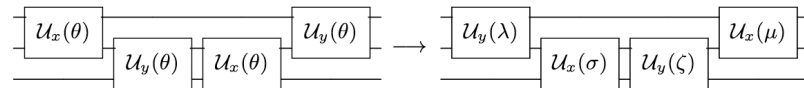
T_2 :



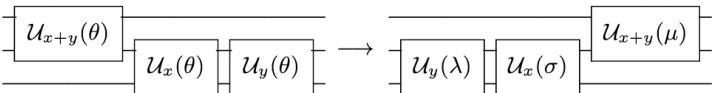
T_3 :



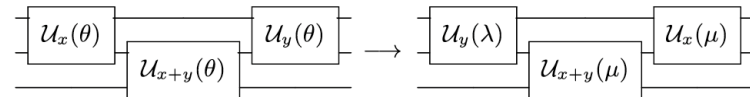
T_4 :



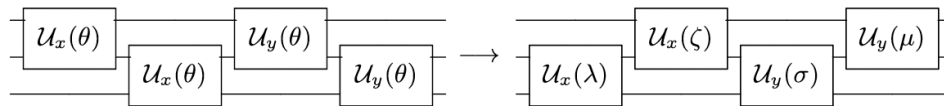
T_5 :



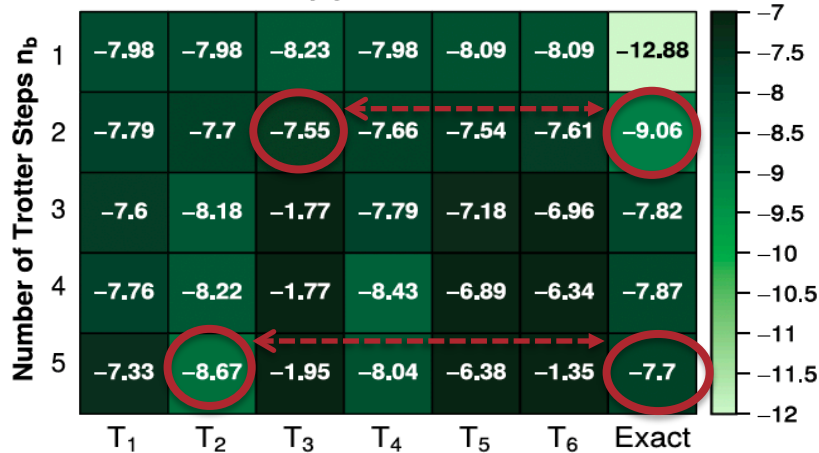
T_6 :



$$\begin{aligned}\mathcal{U}_x^{i,j}(\theta) &= \exp(-i\theta \tilde{S}_i^x \otimes \tilde{S}_j^x), \\ \mathcal{U}_y^{i,j}(\theta) &= \exp(-i\theta \tilde{S}_i^y \otimes \tilde{S}_j^y), \\ \mathcal{U}_{x+y}^{i,j}(\theta) &= \exp(-i\theta (\tilde{S}_i^x \otimes \tilde{S}_j^x + \tilde{S}_i^y \otimes \tilde{S}_j^y)).\end{aligned}$$

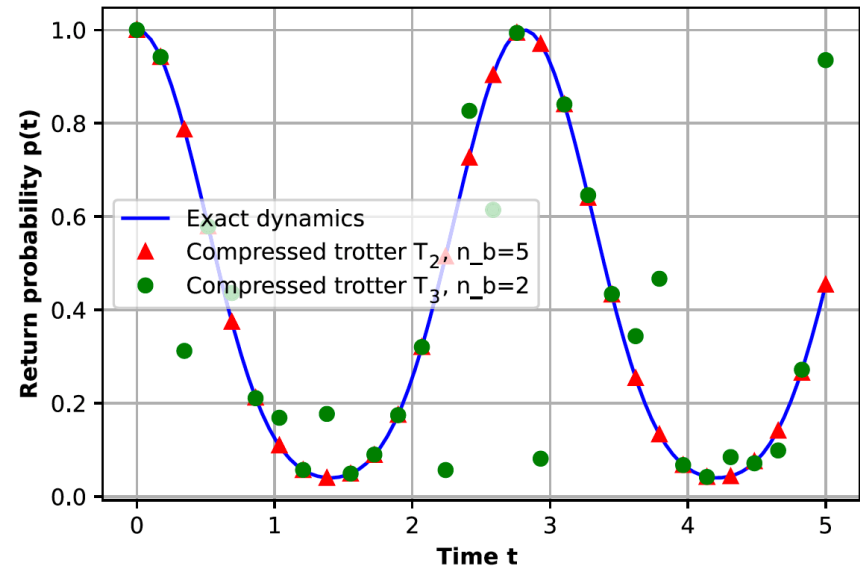


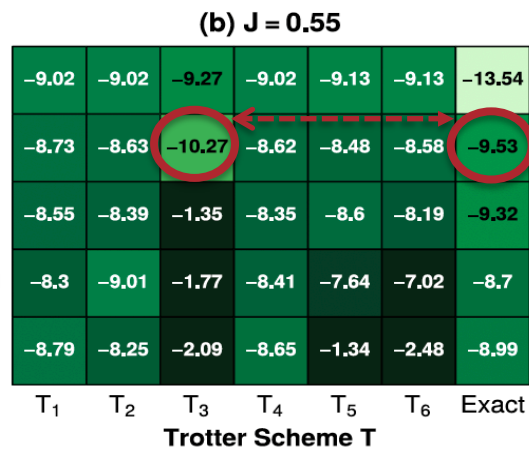
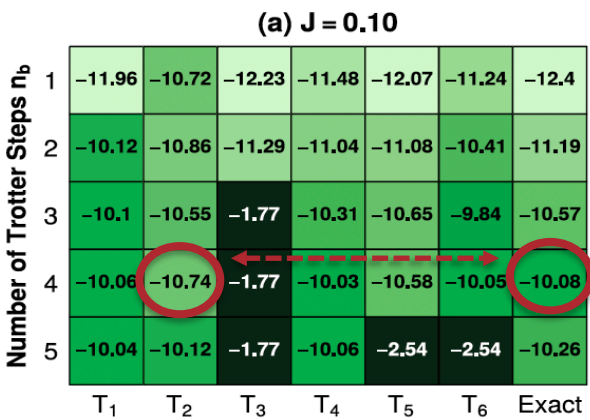
An exact-in-principle identity used for setting up the lower bounds in the numerical tests.

(c) $J = 1.00$ 

Infidelity, $\log_{10}[\min_{\vec{\theta}_R} C(\vec{\theta}_L, \vec{\theta}_R)]$, for Trotter forms 1,...,6. Infidelity to be relatively low as compared to numerical values of the exact identity.

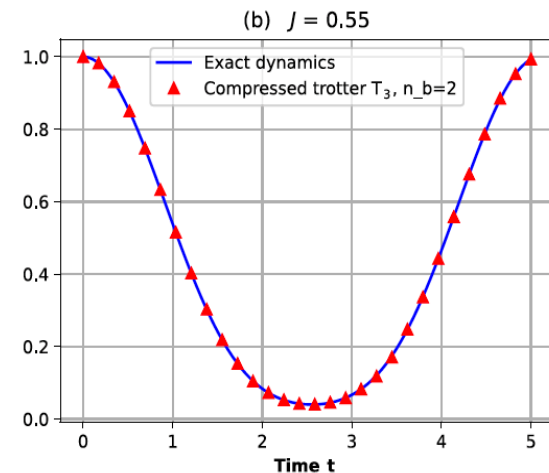
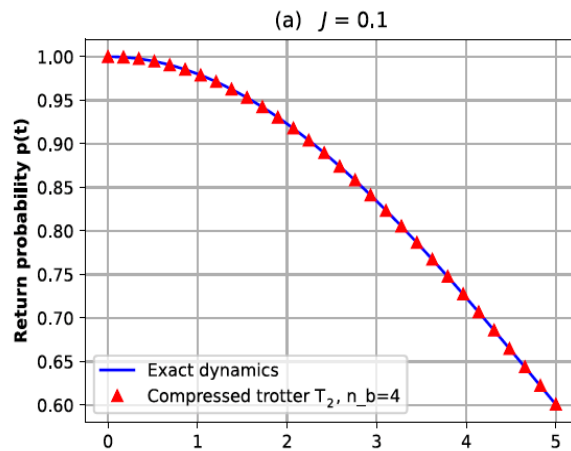
$$p(t) = \|\langle 202 | e^{itH_{XY}} | 202 \rangle\|^2 \text{ as a function of time.}$$





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$p(t) = \|\langle 202 | e^{itH_{XY}} | 202 \rangle\|^2$ as a function of time. For $T_3, n_b = 2$, approximately $\frac{2n}{3}$ gates are removed, while $T_2, n_b = 4$, approximately $\left\lfloor \frac{2n}{5} \right\rfloor - 1$ gates are removed.



THANK YOU

Additional SQMS Presentations

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