



Gravitational-wave tests of general relativity with ground-based detectors and pulsar-timing arrays

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Abstract

This review is focused on tests of Einstein's theory of general relativity with gravitational waves that are detectable by ground-based interferometers and pulsar-timing experiments. Einstein's theory has been greatly constrained in the quasi-linear, quasi-stationary regime, where gravity is weak and velocities are small. Gravitational waves are allowing us to probe a complimentary, yet previously unexplored regime: the non-linear and dynamical *extreme gravity regime*. Such a regime is, for example, applicable to compact binaries coalescing, where characteristic velocities can reach fifty percent the speed of light and gravitational fields are large and dynamical. This review begins with the theoretical basis and the predicted gravitational-wave observables of modified gravity theories. The review continues with a brief description of the detectors, including both gravitational-wave interferometers and pulsar-timing arrays, leading to a discussion of the data analysis formalism that is applicable for such tests. The review then discusses gravitational-wave tests using compact binary systems, and ends with a description of the first gravitational wave observations by advanced LIGO, the stochastic

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Change summary Major revision, updated and expanded.

Change details We have implemented a great deal of changes to generate this new updated version. These have led to a document that is about twice the size of the original one with about 3 times the number of references (increased from 475 to 1220). In particular, we have added a new author, Prof. Kent Yagi from U. of Virginia, who was instrumental in the update process. We have also added content related to the plethora of tests of GR that have been performed with the Advanced LIGO and Virgo observations. We have also created a completely new Sect. 5 on tests of GR with PTAs, since the latter have now detected a stochastic background. In the process of updating the document, we also corrected several typos in equations that we found since the time we created the original document.

Extended author information available on the last page of the article

gravitational wave background observations by pulsar timing arrays, and the tests that can be performed with them.

Keywords General relativity · Gravitational waves · Pulsar timing · Experimental tests · Observational tests · Alternative theories · Compact binaries

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1 Introduction

1.1 The importance of testing

The era of precision gravitational-wave astrophysics commenced with the first direct gravitational-wave observations by the advanced Laser Interferometer Gravitational Observatory (aLIGO) (Abbott et al. 2016a) and all the other events that were discovered by aLIGO, Virgo and KAGRA (Abbott et al. 2019a, 2021a, 2023). With it, a plethora of previously unavailable information has flooded in, allowing for unprecedented astrophysical measurements and tests of fundamental theories (Abbott et al. 2016d, 2019b, c, 2021b, c; Yunes et al. 2016; Berti et al. 2018a, b). Nobody would question the importance of more precise astrophysical measurements, but one may wonder whether fundamental tests are truly necessary, considering the many successes of Einstein’s theory of General Relativity (GR). GR has passed many tests through Solar System, binary pulsar and cosmological observations (see e.g. Freire and Wex 2024; Will 2014; Psaltis 2008b), but what many of these have in common is that they sample the quasi-stationary, quasi-linear *weak field*. That is, they sample the regime of spacetime where the gravitational field is weak relative to the mass-energy of the system, the characteristic velocities of gravitating bodies are typically small relative to the speed of light, and the gravitational field is stationary or quasi-stationary relative to the characteristic size of the system. Direct electromagnetic imaging of supermassive black holes by the Event Horizon Telescope (EHT) (Akiyama et al. 2019, 2022a) has the potential to probe gravity in the strong gravitational potential

regime (Akiyama et al. 2022b), provided astrophysical mismodeling and statistical uncertainties can be controlled (Gralla 2021; Gralla et al. 2020; Völkel et al. 2021; Lara et al. 2021). The systems EHT observes, however, are quasi-stationary and the curvature of spacetime around supermassive black holes is not as high as that for stellar-mass black holes and neutron stars. On the other hand, the *extreme gravity* regime,¹ where spacetime is highly dynamical, gravity is strong and self-gravitating bodies have non-negligible velocities, is precisely the area gravitational waves open for exploration.

To make this more concrete, let us define the gravitational compactness via $\mathcal{C} = \mathcal{M}/\mathcal{R}$, where \mathcal{M} and \mathcal{R} are the characteristic mass and length scale of the system (henceforth, we set $G = c = 1$). Let us also define the characteristic velocities \mathcal{V} of the system as a measure of the rate of change of the gravitational field in the center of mass frame. The characteristic velocity can be related to the timescale on which the gravitational energy changes significantly, $\mathcal{T} = E/\dot{E}$, with E the characteristic gravitational energy and \dot{E} its rate of change, through $\mathcal{V} = \mathcal{R}/\mathcal{T}$. While the compactness \mathcal{C} is a measure of how strong gravity is in the system, the velocity \mathcal{V} is a measure of how dynamical the spacetime is. With these definitions at hand, we define the weak field, the strong field and the extreme gravity regimes as follows:

$$\textbf{Weak Field Regime : } \mathcal{C} \ll 1 \rightarrow \mathcal{M} \ll \mathcal{R} \quad \text{and} \quad \mathcal{V} \ll 1 \rightarrow \mathcal{M} \ll \mathcal{T}, \quad (1)$$

$$\textbf{Strong Field Regime : } \mathcal{C} \lesssim \mathcal{O}(1) \rightarrow \mathcal{M} \lesssim \mathcal{R} \quad \text{and} \quad \mathcal{V} \ll 1 \rightarrow \mathcal{M} \ll \mathcal{T}, \quad (2)$$

$$\textbf{Extreme Gravity Regime : } \mathcal{C} \lesssim \mathcal{O}(1) \rightarrow \mathcal{M} \lesssim \mathcal{R} \quad \text{and} \quad \mathcal{V} \lesssim \mathcal{O}(1) \rightarrow \mathcal{M} \lesssim \mathcal{T}. \quad (3)$$

In spite of the naming convention, there is much information that can be gained from weak-field and strong-field tests. In fact, entire classes of modified gravity theories have been effectively ruled out (or at the very least stringently constrained) by Solar System observations alone (Will 2014), as we discuss below.

Let us provide some examples of these regimes. The prototypical example for weak-field tests are observations in the Solar System. For the Earth-Sun system, \mathcal{M} is essentially the mass of the Sun, while \mathcal{R} is the Earth-Sun orbital separation, which leads to $\mathcal{C} = \mathcal{O}(10^{-8})$, $\mathcal{V} = \mathcal{O}(10^{-4})$ and $\mathcal{T} = \mathcal{O}(10^6)$ seconds. The characteristic compactness and velocity are clearly very small, and this is true for any planet or satellite in the Solar System. Even if an object were in a circular orbit at the surface of the Sun, its gravitational compactness would be $\mathcal{O}(10^{-6})$, its characteristic velocity $\mathcal{O}(10^{-3})$ and the characteristic timescale $\mathcal{O}(10^3)$ seconds. A particularly important Solar System test that has been used to stringently constrain many modified theories of gravity is the observation of the Shapiro time delay, i.e. the

¹ Notice that “extreme gravity” is not synonymous with Planck scale physics in this context. In fact, a stationary black hole would not serve as a probe of extreme gravity, even if one were to somehow acquire information about the gravitational potential close to the singularity. This is because any such observation would necessarily be lacking information about the dynamical sector of the gravitational interaction. Planck scale physics is perhaps more closely related to strong-curvature physics.

delay of photons as they traverse a regime of curved spacetime. In 2003, the Cassini Probe (Bertotti et al. 2003) sent radio signals to Earth while on its way to Saturn while Earth was being eclipsed by the Sun, thus sensitively probing the Shapiro time delay effect. The characteristic radius in this experiment is the radius of the Sun, which gives $\mathcal{C} = \mathcal{O}(10^{-6})$ and $\mathcal{V} = 0$, since this observation does not sample the dynamical nature of spacetime.

The classic example for strong-field tests are observations of binary pulsars. Neutron stars are strong-field sources of gravity because the ratio of their mass to their radius (their matter compactness) is of $\mathcal{O}(10^{-1})$. However, many observables are not sensitive to the gravitational field at the surface of the pulsar. For example, observations of the orbital decay rate with the double binary pulsar J0737-3039 (Lyne et al. 2004; Kramer et al. 2006) have a characteristic compactness of $\mathcal{C} = \mathcal{O}(10^{-5})$, velocities of $\mathcal{V} = \mathcal{O}(10^{-3})$ and timescales of $\mathcal{T} = \mathcal{O}(10^3)$ seconds, where \mathcal{R} is the orbital separation $\mathcal{R} = \mathcal{O}(10^6 \text{ km})$ and $M \approx 3M_\odot$ is the total mass. Observations of the Shapiro time delay with the same system, where photons from one neutron star pass close to its binary companion,² have a characteristic compactness of $\mathcal{C} = \mathcal{O}(10^{-4})$, where $\mathcal{R} = \mathcal{O}(10^4 \text{ km})$ is the photon's distance of closest approach and $\mathcal{M} = \mathcal{O}(1.34M_\odot)$ is the mass of one of the pulsars. Shapiro time delay observations, however, are not probes of the dynamics of the spacetime, so $\mathcal{V} = 0$ and $\mathcal{T} = \infty$.

A typical example of an extreme gravity scenario is the merger of compact objects, like black holes or neutron stars. In such scenarios, the characteristic compactness and velocity can reach $\mathcal{C} = \mathcal{O}(1) = \mathcal{V}$ during merger. Moreover, the late inspiral proceeds so fast that the characteristic timescale can reach $\mathcal{T} = \mathcal{O}(10^{-4})$ seconds. We see then that direct gravitational-wave observations sample gravitational compactnesses and velocities much larger than those weak-field and strong-field observations can probe. Of course, this had to be the case, since the inspiral that aLIGO observed is completely driven by gravitational-wave emission, where the latter cannot be treated as a small perturbation to linear order. However, given the aLIGO observations to date, which have small to moderate signal-to-noise ratios, the constraints on modified gravity effects derived from these cannot always compete with those obtained with weak-field and strong-field observations yet.

Even though Solar System and binary pulsar observations do not give us access to the extreme gravity regime, they have indeed served (and will continue to serve) as invaluable tools to learn about gravity. Solar System tests effectively cured an outbreak of modified gravity theories in the 1970s and 1980s, as summarized for example in Will (2014). Binary pulsars were crucial as the first indirect detectors of gravitational waves, and later to kill certain theories, like Rosen's bimetric gravity (Rosen 1974), and heavily constrain others that predict dipolar energy loss, as we will see in Sects. 2 and 4. Similarly, electromagnetic observations of black hole accretion disks probe GR in another strong-field sector: the non-linear but fully

² Contrary to popular belief, this Shapiro time delay observation does not probe distances comparable to the surface of neutron stars. Photons from pulsar A do graze pulsar B, but the photon's distance of closest approach depends sensitively on the inclination angle, which is not exactly 90 degrees for J0737-3039 (Lyne et al. 2004; Kramer et al. 2006).

stationary regime, verifying that black holes are described by the Kerr metric (Akiyama et al. 2022b).

Given these successes of Einstein's theory, one may wonder why one should bother with testing GR in the extreme gravity regime. Needless to say, the role of science is to *predict and verify* and not to assume without proof. Moreover, the incompleteness of GR in the quantum regime, together with the somewhat unsatisfactory requirement of the dark sector of cosmology (including dark energy and dark matter) have prompted many studies of modifications to GR. Gravitational waves have now begun to verify Einstein's theory in a regime previously inaccessible to us, and as such, these tests are invaluable. In many areas of physics, however, GR is so ingrained that questioning its validity is synonymous with heresy. Dimensional arguments are usually employed to argue that any quantum gravitational correction will necessarily and unavoidably be unobservable, as the former are expected at a (Planck) scale that is inaccessible to detectors. This rationalization is dangerous, as it introduces a theoretical bias in the analysis of new observations of the Universe, thus quenching the potential for new discoveries. For example, if astrophysicists had followed such a rationalization when studying supernova data, they would not have discovered that the Universe is expanding. Dimensional arguments suggest that the cosmological constant is over 100 orders of magnitude larger than the value required to agree with observations. When observing the Universe for the first time in a completely new way, it seems more conservative to remain *agnostic* about what is expected and what is not, thus allowing the data itself to guide our efforts toward theoretically understanding the gravitational interaction.

1.2 Testing general relativity versus testing alternative theories

When *testing GR*, one considers Einstein's theory as a *null hypothesis* and searches for generic deviations. On the other hand, when *testing modified gravity* one starts from a particular modified gravity model, develops its equations and solutions and then predicts certain observables that then might or might not agree with experiment. Similarly, one may define a *bottom-up* approach versus a *top-down* approach. In the former, one starts from some observables in an attempt to discover fundamental symmetries that may lead to a more complete theory, as was done when constructing the standard model of elementary particles. On the other hand, a top-down approach starts from some fundamental theory and then derives its consequence.

Both approaches possess strengths and weaknesses. In the top-down approach one has complete control over the theory under study, being able to write down the full equations of motion, answer questions about well-posedness and stability of solutions, and predict observables. But, as we see in Sect. 2, carrying out such an approach can be quixotic within any one model. What is worse, the lack of a complete and compelling alternative to GR makes choosing a particular modified theory difficult.

Given this, one might wish to attempt a bottom-up approach, where one considers a set of principles one wishes to test without explicit mention of any particular

theory. One usually starts by assuming GR as a null-hypothesis and then considers deformations away from GR. The hope is that experiments will be sensitive to such deformations, thus either constraining the size of the deformations or pointing toward a possible inconsistency. But if experiments do confirm a GR deviation, a bottom-up approach fails at providing a given particular action from which to derive such a deformation. In fact, there can be several actions that lead to similar deformations, all of which can be consistent with the data within its experimental uncertainties.

Nonetheless, both approaches are complementary. The bottom-up approach draws inspiration from particular examples carried out in the top-down approach, therefore allowing for a *map* between deformations of GR and theoretical physics. Given a verification of GR through a bottom-up approach, one can then use this map to place specific constraints on physical interactions that cannot present in the observations carried out. This mapping, of course, is critically important, since without it one would not know what physics one is constraining with the given observations. This is indeed the route most commonly taken in observations of the extreme gravity regime, as we will see in this review.

1.3 Gravitational-wave tests versus other tests of general relativity

Gravitational-wave tests differ from other tests of GR in many ways. Perhaps one of the most important differences is the spacetime regime gravitational waves sample. Indeed, as already mentioned, gravitational waves have access to the most extreme gravitational environments in Nature. Moreover, gravitational waves travel essentially unimpeded from their source to Earth, and thus, they do not suffer from issues associated with obscuration. Gravitational waves also exist in the absence of luminous matter, thus allowing us to observe electromagnetically dark objects, such as black hole inspirals.

This last point is particularly important as gravitational waves from inspiraling black-hole binaries are one of the cleanest astrophysical systems in Nature. In the last stages of inspiral, when such gravitational waves are detectable by ground-based interferometers, the evolution of binary black holes is essentially unaffected by any other matter or electromagnetic fields present in the system. As such, one does not need to deal with uncertainties associated with astrophysical matter. Unlike tests of Einstein's theory with accretion disk observations, binary black hole gravitational-wave tests may well be the cleanest probes of GR.

Of course, what is an advantage here, can be also a huge disadvantage in another context. Gravitational waves from compact binaries are intrinsically transient, i.e. they turn on for a certain amount of time and then shut off. This is unlike binary pulsar systems, for which astrophysicists have already collected tens of years of data. Moreover, gravitational-wave tests rely on specific detections that cannot be anticipated beforehand. This is in contrast to Earth-based laboratory experiments, where one has complete control over the experimental setup. Finally, the intrinsic weakness of gravitational waves makes detection a very difficult task that requires complex data-analysis algorithms to extract signals from the noise. As such, gravitational-wave tests are limited by the signal-to-noise ratio and affected by

systematics associated with the modeling of the waves, issues that are not as important in other loud astrophysical systems. The signal-to-noise-ratio limitation will be remedied with next-generation detectors, which will be able to detect many more events, some of which will be extremely loud.

1.4 Ground-based versus space-based detectors and interferometers versus pulsar timing

This review article focuses only on ground-based detectors, by which we mean both gravitational-wave interferometers, such as aLIGO (Abramovici et al. 1992; Abbott et al. 2009; Harry 2010), Advanced Virgo (Acernese et al. 2005, 2007), KAGRA (Yuzurihara 2023; Itoh 2023), the Einstein Telescope (ET) (Punturo et al. 2010; Sathyaprakash 2012), and the Cosmic Explorer (CE) (Evans et al. 2021), as well as pulsar timing arrays (for a review of gravitational-wave tests of GR with space-based detectors, see Gair et al. 2013; Yagi 2013; Arun et al. 2022). Ground-based detectors have the limitation of being contaminated by man-made and Nature-made noise, such as ground and air traffic, logging, earthquakes, ocean tides and waves, which are clearly absent in space-based detectors. Ground-based detectors, however, have the clear benefit that they can be continuously upgraded and repaired in case of malfunction, which is obviously not possible with space-based detectors.

As far as tests of GR are concerned, there is a drastic difference in space-based and ground-based detectors: the gravitational-wave frequencies these detectors are sensitive to. For various reasons that we will not go into, space-based interferometers are likely to have a million kilometer long arms, and thus, be sensitive in the milli-Hz band. On the other hand, ground-based interferometers are bound to the surface and curvature of the Earth, and thus, they have kilometer-long arms and are sensitive in the deca- and hecta-Hz band. Different types of interferometers are then sensitive to different types of gravitational-wave sources. For example, when considering binary coalescences, ground-based interferometers are sensitive to late inspirals and mergers of neutron stars and stellar-mass black holes, while space-based detectors will be sensitive to supermassive black hole binaries with masses around $10^5 M_\odot$.

The impact of a different population of sources in tests of GR depends on the particular modified gravity theory considered. When studying quadratic gravity theories, as we see in Sect. 2, the Einstein–Hilbert action is modified by introducing higher order curvature operators, which are naturally suppressed by powers of the inverse of the radius of curvature of the system. Thus, space-based detectors will not be ideal at constraining these theories with supermassive black holes, as their radius of curvature is much larger than that of the stellar-mass black holes at merger that ground-based detectors observe. However, although space-based detectors will not be sensitive to neutron-star-binary coalescences, they are expected to detect the inspiral of a supermassive black hole with a neutron star or a stellar-mass black hole. In these extreme mass-ratio inspirals, quadratic gravity modifications sourced by the smaller object will be dominant (since recall these modifications scale

inversely with the radius of curvature), and thus, may be constrained with space-based detectors.

Space-based detectors are also unique in their potential to probe the spacetime geometry of supermassive black holes through gravitational waves emitted during extreme-mass-ratio inspirals. In these inspirals, the stellar-mass compact object is on a generic decaying orbit around the supermassive black hole, generating millions of cycles of gravitational waves in the sensitivity band of space-based detectors (in fact, they can easily out-live the detector itself!). Therefore, even small changes to the radiation-reaction force, or to the background geometry, can lead to noticeable effects in the waveform observable and thus to stringent tests of GR (Amaro-Seoane et al. 2007; Ryan 1995, 1997a; Kesden et al. 2005; Glampedakis and Babak 2006; Barack and Cutler 2007; Li and Lovelace 2008; Gair et al. 2008; Sopuerta and Yunes 2009; Yunes and Sopuerta 2010; Apostolatos et al. 2009; Lukes-Gerakopoulos et al. 2010; Gair and Yunes 2011; Contopoulos et al. 2011; Canizares et al. 2012b; Gair et al. 2013; Perkins et al. 2021b; Maselli et al. 2020a, 2022; Barausse et al. 2020; Arun et al. 2022).

Space-based detectors also have the advantage of range, which is particularly important when considering modified gravity effects that accumulate with the distance traveled by the gravitational wave, e.g. theories in which gravitons do not travel at light speed (Mirshekari et al. 2012). Space-based detectors have a horizon distance much larger than second-generation ground-based detectors; the former can see black-hole mergers to redshifts of order 10 if there are any at such early times in the universe, while the latter are confined to events within redshift 1³. Gravitational waves emitted from distant regions in spacetime need a longer time to propagate from the source to the detectors. Thus, theories that modify the propagation of gravitational waves will be better constrained by space-based detectors than second-generation ground-based detectors (Will 1998; Berti et al. 2005a, 2011; Stavridis and Will 2009; Yagi and Tanaka 2010a; Arun and Will 2009; Keppel and Ajith 2010; Mirshekari et al. 2012; Perkins et al. 2021b).

Another important difference between detectors is their response to an impinging gravitational wave. Ground-based detectors, as we see in Sect. 3, cannot separate between the two possible scalar modes (the longitudinal and the breathing modes) of metric theories of gravity, due to an intrinsic degeneracy in the response functions. Space-based detectors in principle also possess this degeneracy, but they may be able to break it through Doppler modulation if the interferometer orbits the Sun. Pulsar timing arrays, on the other hand, lack this degeneracy altogether, and thus, they can in principle constrain the existence of these different polarizations independently.

One way in which pulsar-timing arrays differ from interferometers in their potential to test GR is the frequency space they are most sensitive to. Interferometers can observe the late inspiral and merger of compact binaries, while pulsar timing arrays are restricted to gravitational waves emitted in the very early inspiral. This is why the latter do not need very accurate waveform templates that account for the highly-dynamical and non-linear nature of gravity; leading-order quadrupole

³ Next-generation ground-based detectors are expected to have a horizon distance of $z \sim 20$.

waveforms are sufficient (Corbin and Cornish 2010). In turn, this implies that pulsar timing arrays cannot constrain theories that only deviate significantly from GR in the late inspiral or merger, while they are exceptionally well-suited for constraining low-frequency deviations.

We therefore see a complementarity emerging: different detectors can test GR in different complementary regimes:

- Ground-based detectors are best at constraining non-GR effect that are largest in the late inspiral and merger of stellar-mass compact binaries, including both conservative and dissipative modifications.
- Space-based detectors are best at constraining modifications to the propagation of gravitational waves, the geometry of supermassive black holes and corrections to the radiation-reaction force in extreme mass-ratio inspirals.
- Pulsar-timing arrays are best at constraining the polarization content of gravitational radiation and any deviation from GR that dominates at low orbital frequencies.

Through the simultaneous implementation of all these tests, GR can be put on a much firmer footing in all parts of the extreme gravity regime.

1.5 Notation and conventions

We follow mainly the notation of Misner et al. (1973), where Greek indices stand for spacetime coordinates and spatial indices in the middle of the alphabet (i, j, k, \dots) for spatial indices. Parenthesis and square brackets in index lists stand for symmetrization and anti-symmetrization respectively, e.g. $A_{(\mu\nu)} = (A_{\mu\nu} + A_{\nu\mu})/2$ and $A_{[\mu\nu]} = (A_{\mu\nu} - A_{\nu\mu})/2$. Partial derivatives with respect to spacetime and spatial coordinates are denoted $\partial_\mu A = A_{,\mu}$ and $\partial_i A = A_{,i}$ respectively. Covariant differentiation is denoted $\nabla_\mu A = A_{;\mu}$, multiple covariant derivatives $\nabla^{\mu\nu\dots} = \nabla^\mu \nabla^\nu \dots$, and the curved spacetime D'Alembertian $\square A = \nabla_\mu \nabla^\mu A$. The determinant of the metric $g_{\mu\nu}$ is g , $R_{\mu\nu\delta\sigma}$ is the Riemann tensor, $R_{\mu\nu}$ is the Ricci tensor, R is the Ricci scalar and $G_{\mu\nu}$ is the Einstein tensor. The Levi-Civita tensor and symbol are $\epsilon^{\mu\nu\delta\sigma}$ and $\bar{\epsilon}^{\mu\nu\delta\sigma}$ respectively, with $\bar{\epsilon}^{0123} = +1$ in an orthonormal, positively oriented frame. We use geometric units ($G = c = 1$) and the Einstein summation convention is implied.

We will be mostly concerned with *metric theories*, where gravitational radiation is only defined much farther than a gravitational-wave wavelength from the source. In this far- or radiation-zone, the metric tensor can be decomposed as

$$g_{\mu\nu} = \eta_{\mu\nu} + h_{\mu\nu}, \quad (4)$$

with $\eta_{\mu\nu}$ the Minkowski metric and $h_{\mu\nu}$ the metric perturbation. If the theory considered has additional fields ϕ , these can also be decomposed in the far-zone as

$$\phi = \phi_0 + \psi, \quad (5)$$

with ϕ_0 the background value of the field and ψ a perturbation. With such a

decomposition, the field equations for the metric will usually be wave equations for the metric perturbation and for the field perturbation, in a suitable gauge.

2 Modified gravity theories

In this section, we discuss some of the many possible modified gravity theories that have been studied in the context of gravitational-wave tests. We begin with a description of the theoretically desirable properties that such theories must have. We then proceed with a review of the theories so far explored as far as gravitational waves are concerned. We will leave out the description of many theories in this chapter, especially those which currently lack a gravitational-wave analysis; we refer the interested reader to Berti et al. (2015), Barack et al. (2019). We will conclude with a brief description of unexplored theories as possible avenues for future research.

2.1 Desirable theoretical properties

The space of possible theories is infinite, and thus, one is tempted to reduce it by considering a subspace that satisfies a certain number of properties. Although the number and details of such properties depend on the theorist's taste, there is at least one *fundamental property* that all scientists would agree on:

1. **Precision Tests.** The theory must produce predictions that pass all solar system, binary pulsar, cosmological, gravitational-wave and experimental tests that have been carried out.

This requirement can be further divided into the following:

- 1.a **General Relativity Limit.** There must exist some limit, continuous or discontinuous, such as the weak-field one, in which the predictions of the theory are consistent with those of GR within experimental precision.
- 1.b **Existence of Known Solutions** (Wald 2009). The theory must admit solutions that correspond to observed phenomena, including but not limited to (nearly) flat spacetime, (nearly) Newtonian stars, and cosmological solutions.
- 1.c **Stability of Solutions** (Wald 2009). The special solutions described in Property (1.b) must be stable to small perturbations on timescales smaller than the age of the Universe. For example, perturbations to (nearly) Newtonian stars, such as impact by asteroids, should not render such solutions unstable.

Of course, these properties are not all necessarily independent, as the existence of a weak-field limit usually also implies the existence of known solutions. On the other hand, the mere existence of solutions does not necessarily imply that these are stable.

In addition to these fundamental requirements, one might also wish to require that any new modified gravity theory possesses certain *theoretical properties*. These

properties will vary depending on the theorist, but the two most common ones are listed below:

2. **Well-motivated from Fundamental Physics.** There must be some fundamental theory or principle from which the modified theory (effective or not) derives. This fundamental theory would solve some fundamental problem in physics, such as late time acceleration or the incompatibility between Quantum Mechanics and GR.
3. **Well-posed Initial-Value Formulation** (Wald 2009). A wide class of freely specifiable initial data must exist, such that there is a uniquely determined solution to the modified field equations that depends continuously on this data.

The second property goes without saying at some level, as one expects modified-gravity-theory constructions to be motivated from some (perhaps yet incomplete) quantum- gravitational description of nature. As for the third property, the continuity requirement is necessary because otherwise the theory would lose predictive power, given that initial conditions can only be measured to a finite accuracy. Moreover, small changes in the initial data should not lead to solutions outside the causal future of the data; that is, causality must be preserved. Section 2.2 expands on this well-posedness property further.

One might be concerned that Property (2) automatically implies that any predicted deviation from astrophysical observables will be too small to be detectable. This argument usually goes as follows. Any quantum gravitational correction to the action will “naturally” introduce at least one new scale, and this, by dimensional analysis, must be the Planck scale. Since this scale is usually assumed to be larger than 1 TeV in natural units (or 10^{-35} m in geometric units), gravitational-wave observations will never be able to observe quantum-gravitational modifications (see, e.g., Dubovsky et al. 2007 for a similar argument). In our view, such arguments can be extremely dangerous, since they induce a certain theoretical bias in the search for new phenomena. For example, let us consider the supernova observations of the late time expansion of the universe that led to the discovery of the cosmological constant. The above argument certainly fails for the cosmological constant, which on dimensional arguments is over 100 orders of magnitude too small. If the supernova teams had respected this argument, they would not have searched for a cosmological constant in their data. Today, we try to explain our way out of the failure of such dimensional arguments by claiming that there must be some exquisite cancellation that renders the cosmological constant small; but this, of course, came only *after* the constant had been measured. One is not trying to argue here that cancellations of this type are common and that quantum gravitational modifications are necessarily expected in gravitational-wave observations. Rather, we are arguing that one should remain *agnostic* about what is expected and what is not, and allow oneself to be surprised without quenching the potential for new discoveries that accompanies the era of gravitational-wave astrophysics.

One last property that we wish to consider for the purposes of this review is the following:

4. **Extreme Gravity Inconsistency.** The theory must lead to observable deviations from GR in extreme gravity.

Many modified gravity models have been proposed that pose *infrared* or cosmological modifications to GR, aimed at explaining certain astrophysical or cosmological observables, like the late expansion of the Universe. Such modified models usually reduce to GR in the strong-field, and particularly, in the extreme-gravity regime, for example via a Vainshtein like mechanism (Vainshtein 1972; Deffayet et al. 2002; Babichev and Deffayet 2013) in a static spherically-symmetric context. Extending this mechanism to highly-dynamical extreme gravity scenarios has not been fully worked out yet (de Rham et al. 2013a, b, 2024; Gerhardinger et al. 2024). Gravitational-wave tests of GR, however, are concerned with modified theories that predict deviations in extreme gravity, precisely where cosmological modified models do not. Clearly, Property (4) is not necessary for a theory to be a valid description of nature. This is because a theory might be identical to GR in the weak, strong and extreme gravity regimes, yet different at the Planck scale, where it would be unified with quantum mechanics. However, Property (4) is a desirable feature if one is to test this theory with gravitational-wave observations.

2.2 Well-posedness and effective theories

Property (3) not only requires the existence of an initial-value formulation, but also that it be well-posed, which is not necessarily guaranteed. For example, the Cauchy–Kowalewski theorem states that a system of n partial differential equations for n unknown functions ϕ_i of the form $\phi_{i,tt} = F_i(x^\mu; \phi_{j,\mu}; \phi_{j,ti}; \phi_{j,ik})$, with F_i analytic functions has an initial-value formulation (see, e.g., Wald 1984). This theorem, however, does not guarantee continuity or the causal conditions described above. For this, one has to rely on more general energy arguments, for example constructing a suitable energy measure that obeys the dominant energy condition and using it to show well-posedness (see, e.g., Hawking and Ellis 1973; Wald 1984). One can show that second-order, hyperbolic partial differential equations, i.e., equations of the form

$$\nabla^\mu \nabla_\mu \phi + A^\mu \nabla_\mu \phi + B\phi + C = 0, \quad (6)$$

where A^μ is an arbitrary vector field and (B, C) are smooth functions, have a well-posed initial-value formulation. Moreover, the Leray theorem proves that any quasilinear, diagonal, second-order hyperbolic system also has a well-posed initial-value formulation (Wald 1984).

Proving the well-posedness of an initial-value formulation for systems of higher-than-second-order, partial differential equations is much more difficult. In fact, to our knowledge, no general theorems exist of the type described above that apply to third, fourth or higher-order, partial, non-linear and coupled differential equations. Usually, one resorts to the Ostrogradski theorem (Ostrogradsky 1850) to rule out (or at the very least cast serious doubt on) theories that lead to such higher-order field equations. Ostrogradski's theorem states that Lagrangians that contain terms with

higher than first time-derivatives possess a linear instability in the Hamiltonian (see, e.g., Woodard 2007 for a nice review).⁴ As an example, consider the Lagrangian density

$$\mathcal{L} = \frac{m}{2} \dot{q}^2 - \frac{m\omega^2}{2} q^2 - \frac{gm}{2\omega^2} \ddot{q}^2, \quad (7)$$

whose equations of motion,

$$\ddot{q} + \omega^2 q = -\frac{g}{\omega^2} \dddot{q}, \quad (8)$$

obviously contain higher derivatives. The exact solution to this differential equation is

$$q = A_1 \cos k_1 t + B_1 \sin k_1 t + A_2 \cos k_2 t + B_2 \sin k_2 t, \quad (9)$$

where (A_i, B_i) are constants and $k_{1,2}^2/\omega^2 = (1 \mp \sqrt{1-4g})/(2g)$. The on-shell Hamiltonian is then

$$H = \frac{m}{2} \sqrt{1-4g} k_1^2 (A_1^2 + B_1^2) - \frac{m}{2} \sqrt{1-4g} k_2^2 (A_2^2 + B_2^2), \quad (10)$$

from which it is clear that mode 1 carries positive energy, while mode 2 carries negative energy and forces the Hamiltonian to be unbounded from below. The latter implies that dynamical degrees of freedom can reach arbitrarily negative energy states. If interactions are present, then an “empty” state would instantaneously decay into a collection of positive and negative energy particles, which cannot describe the Universe we live in (Woodard 2007).

The Ostrogradski theorem (Ostrogradsky 1850), however, can be evaded if the Lagrangian in Eq. (7) describes an *effective theory*, i.e., a theory that is a truncation of a more general or complete theory. Let us reconsider the particular example above, assuming now that the coupling constant g is an effective theory parameter and Eq. (7) is only valid to linear order in g . One approach is to search for perturbative solutions of the form $q_{\text{pert}} = x_0 + gx_1 + \dots$, which leads to the system of differential equations

$$\ddot{x}_n + \omega^2 x_n = -\frac{1}{\omega^2} \dddot{x}_{n-1}, \quad (11)$$

with $x_{-1} = 0$. Solving this set of n differential equations and resumming, one finds

$$q_{\text{pert}} = A_1 \cos k_1 t + B_1 \sin k_1 t. \quad (12)$$

Notice that q_{pert} contains only the positive (well-behaved) energy solution of Eq. (9), i.e., perturbation theory acts to retain only the well-behaved, stable solution of the full theory in the $g \rightarrow 0$ limit. One can also think of the perturbative theory as the full theory with additional constraints, i.e., the removal of unstable modes, which is why such an analysis is sometimes called *perturbative constraints* (Cooney et al. 2009, 2010; Yunes and Pretorius 2009a).

⁴ Stability and well-posedness are not the same concepts and they do not necessarily imply each other. For example, a well-posed theory might have stable and unstable solutions. For ill-posed theories, it does not make sense to talk about stability of solutions.

Another way to approach effective field theories that lead to equations of motion with higher-order derivatives is to apply the method of *order-reduction*. In this method, one substitutes the low-order derivatives of the field equations into the high-order derivative part, thus rendering the resulting new theory usually well-posed. One can think of this as a series resummation, where one changes the non-linear behavior of a function by adding uncontrolled, higher-order terms. Let us provide an explicit example by reconsidering the theory in Eq. (7). To lowest order in g , the equation of motion is that of a simple harmonic oscillator,

$$\ddot{q} + \omega^2 q = \mathcal{O}(g), \quad (13)$$

which is obviously well posed. One can then order-reduce the full equation of motion, Eq. (8), by substituting Eq. (13) into the right-hand side of Eq. (8). Doing so, one obtains the order-reduced equation of motion

$$\ddot{q} + \omega^2 q = g\ddot{q} + \mathcal{O}(g^2), \quad (14)$$

which clearly now has no high-order derivatives and is well posed provided $g \ll 1$. The solution to this order-reduced differential equation is q_{pert} once more, but with k_1 linearized in $g \ll 1$. Therefore, the solutions obtained with a perturbative decomposition and with the order-reduced equation of motion are the same to linear order in g . Of course, since an effective field theory is only defined to a certain order in its perturbative parameter, both treatments are equally valid, with the unstable mode effectively removed in both cases.

Such a perturbative analysis, however, can say nothing about the well-posedness of the full theory from which the effective theory derives, or of the effective theory if treated as an exact one (i.e., not as a perturbative expansion). In fact, a well-posed full theory may have both stable and unstable solutions. The arguments presented above only discuss the stability of solutions in an effective theory, and thus, they are self-consistent only within their perturbative scheme. A full theory may have non-perturbative instabilities, but these can only be studied once one has a full (non-truncated in g) theory, from which Eq. (7) derives as a truncated expansion. Lacking a full quantum theory of nature, quantum gravitational models are usually studied in a truncated low-energy expansion, where the leading-order piece is GR and higher order pieces are multiplied by a small coupling constant. One can perturbatively explore the well-behaved sector of the truncated theory about solutions to the leading-order theory. Such an analysis, however, is incapable of answering questions about well-posedness or non-linear stability of the full theory.

2.3 Explored theories

In this subsection we briefly describe the theories that have so far been studied in some depth as far as gravitational waves are concerned. In particular, we focus only on those theories that have been sufficiently studied so that predictions of the expected gravitational waveforms (the observables of gravitational-wave detectors) have been obtained for at least a typical source, such as the quasi-circular inspiral of a compact binary.

2.3.1 Scalar-tensor theories

2.3.2 Classic type

The classic type of scalar-tensor theory (Brans and Dicke 1961; Damour and Esposito-Farèse 1992; Faraoni et al. 1999; Faraoni and Gunzig 1999; Fujii and Maeda 2003; Goenner 2012) is defined by the Einstein-frame action (where we will restore Newton's gravitational constant G in this section)

$$S_{\text{ST}}^{(\text{E})} = \frac{1}{16\pi G} \int d^4x \sqrt{-g} [R - 2g^{\mu\nu}(\partial_\mu\varphi)(\partial_\nu\varphi) - V(\varphi)] + S_{\text{mat}}[\psi_{\text{mat}}, A^2(\varphi)g_{\mu\nu}], \quad (15)$$

where φ is a scalar field, $A(\varphi)$ is a coupling function, $V(\varphi)$ is a potential function, ψ_{mat} represents matter degrees of freedom and G is Newton's constant in the Einstein frame. For more details on this theory, we refer the interested reader to the reviews by Will (2014, 2018b).

The Einstein frame is not the frame where the metric governs clocks and rods, and thus, it is convenient to recast the theory in the Jordan frame through the conformal transformation $\tilde{g}_{\mu\nu} = A^2(\varphi)g_{\mu\nu}$:

$$S_{\text{ST}}^{(\text{J})} = \frac{1}{16\pi G} \int d^4x \sqrt{-\tilde{g}} \left[\phi \tilde{R} - \frac{\omega(\phi)}{\phi} \tilde{g}^{\mu\nu}(\partial_\mu\phi)(\partial_\nu\phi) - \phi^2 V \right] + S_{\text{mat}}[\psi_{\text{mat}}, \tilde{g}_{\mu\nu}], \quad (16)$$

where $\tilde{g}_{\mu\nu}$ is the physical metric, the new scalar field ϕ is defined via $\phi \equiv A^{-2}$, the coupling field is $\omega(\phi) \equiv (\alpha^{-2} - 3)/2$ and $\alpha \equiv A_{,\varphi}/A$. When cast in the Jordan frame, it is clear that scalar-tensor theories are metric theories (see Will 2014 for a definition), since the matter sector depends only on matter degrees of freedom and the physical metric (without a direct coupling of the scalar field). When the coupling $\omega(\phi) = \omega_{\text{BD}}$ is constant, then Eq. (16) reduces to the massless version of Jordan–Fierz–Brans–Dicke theory (Brans and Dicke 1961).

The modified field equations in this classical scalar-tensor theory in the Einstein frame are

$$\begin{aligned} \square\varphi &= \frac{1}{4} \frac{dV}{d\varphi} - 4\pi G \frac{\delta S_{\text{mat}}}{\delta\varphi}, \\ G_{\mu\nu} &= 8\pi G \left(T_{\mu\nu}^{\text{mat}} + T_{\mu\nu}^{(\varphi)} \right), \end{aligned} \quad (17)$$

where

$$T_{\mu\nu}^{(\varphi)} = \frac{1}{4\pi} \left[\varphi_{,\mu}\varphi_{,\nu} - \frac{1}{2}g_{\mu\nu}\varphi_{,\delta}\varphi^{\delta} - \frac{1}{4}g_{\mu\nu}V(\varphi) \right] \quad (18)$$

is a stress-energy tensor for the scalar field. The matter stress–energy tensor is not constructed from the Einstein-frame metric alone, but by the combination $A(\varphi)^2 g_{\mu\nu}$.

In the Jordan frame and neglecting the potential, the modified field equations are (Will 2018b)

$$\begin{aligned}\tilde{\square}\phi &= \frac{1}{3+2\omega(\phi)} \left(8\pi T^{\text{mat}} - \frac{d\omega}{d\phi} \tilde{g}^{\mu\nu} \phi_{,\mu} \phi_{,\nu} \right), \\ \tilde{G}_{\mu\nu} &= \frac{8\pi G}{\phi} T^{\text{mat}}_{\mu\nu} + \frac{\omega}{\phi^2} \left(\phi_{,\mu} \phi_{,\nu} - \frac{1}{2} \tilde{g}_{\mu\nu} \tilde{g}^{\sigma\rho} \phi_{,\sigma} \phi_{,\rho} \right) + \frac{1}{\phi} (\phi_{,\mu\nu} - \tilde{g}_{\mu\nu} \tilde{\square}\phi),\end{aligned}\quad (19)$$

where T^{mat} is the trace of the matter stress-energy tensor $T^{\text{mat}}_{\mu\nu}$ constructed from the physical metric $\tilde{g}_{\mu\nu}$. The form of the modified field equations in the Jordan frame suggest that in the weak-field limit one may consider scalar-tensor theories as modifying Newton's gravitational constant via $G \rightarrow G(\phi) = G/\phi$.

Using the decompositions of Eqs. (4)–(5), the field equations of massless Jordan–Fierz–Brans–Dicke theory can be linearized in the Jordan frame to find (see, e.g., Will and Zaglauer 1989)

$$\square_\eta \theta^{\mu\nu} = -16\pi \tau^{\mu\nu}, \quad \square_\eta \psi = -16\pi S, \quad (20)$$

where \square_η is the D'Alembertian operator of flat spacetime, we have defined a new metric perturbation

$$\theta^{\mu\nu} = h^{\mu\nu} - \frac{1}{2} \eta^{\mu\nu} h - \frac{\psi}{\phi_0} \eta^{\mu\nu}, \quad (21)$$

with h the trace of the metric perturbation and

$$\tau^{\mu\nu} = \phi_0^{-1} T^{\mu\nu}_{\text{mat}} + t^{\mu\nu}, \quad (22)$$

$$\begin{aligned}S &= -\frac{1}{6+4\omega_{BD}} \left(T^{\text{mat}} - 3\phi \frac{\partial T^{\text{mat}}}{\partial \phi} \right) \left(1 - \frac{\theta}{2} - \frac{\psi}{\phi_0} \right) \\ &\quad - \frac{1}{16\pi} \left(\psi_{,\mu\nu} \theta^{\mu\nu} + \frac{1}{\phi_0} \phi_{,\mu} \psi^{\mu,\nu} \right),\end{aligned}\quad (23)$$

with cubic remainders in either the metric perturbation or the scalar perturbation. The quantity $\partial T^{\text{mat}}/\partial\phi$ arises in an effective point-particle theory, where the matter action is a functional of both the Jordan-frame metric and the scalar field. The quantity $t^{\mu\nu}$ is a function of quadratic or higher order in $\theta^{\mu\nu}$ or ψ . These equations can now be solved given a particular physical system, as done for quasi-circular binaries in Will and Zaglauer (1989), Saijo et al. (1997), Ohashi et al. (1996). Given the above evolution equations, Jordan–Fierz–Brans–Dicke theory possesses a scalar (spin-0) mode, in addition to the two transverse-traceless (spin-2) modes of GR, i.e., Jordan–Fierz–Brans–Dicke theory is of Type N_3 in the $E(2)$ classification (Eardley et al. 1973; Will 2014).

Let us now discuss whether these scalar-tensor theories satisfy the properties discussed in Sect. 2.1, starting with Property 1. Massless Jordan–Fierz–Brans–Dicke theory agrees with all known experimental tests provided $\omega_{BD} > 4 \times 10^4$, a bound imposed by the tracking of the Cassini spacecraft through observations of the

Shapiro time delay (Bertotti et al. 2003). Massive Jordan–Fierz–Brans–Dicke theory has been constrained to $\omega_{\text{BD}} > 4 \times 10^4$ and $m_s < 2.5 \times 10^{-20}$ eV, with m_s the mass of the scalar field (Perivolaropoulos 2010; Alsing et al. 2012). Of course, these bounds are not independent, as when $m_s \rightarrow 0$ one recovers the standard massless constraint, while when $m_s \rightarrow \infty$, ω_{BD} cannot be bounded as the scalar becomes non-dynamical. Observations of the Nordtvedt effect with Lunar Laser Ranging observations, as well as observations of the orbital period derivative of white-dwarf/ neutron-star binaries, yield similar or slightly stronger constraints (Damour and Esposito-Farèse 1996, 1998; Alsing et al. 2012; Freire et al. 2012b; Voisin et al. 2020; Kramer et al. 2021). For example, the Cassini bound was recently updated by the observation of the Nordtvedt effect in a pulsar triple system J0337+1715 (Ransom et al. 2014; Archibald et al. 2018) to $\omega_{\text{BD}} > 1.4 \times 10^5$ (Voisin et al. 2020). Neglecting any homogeneous, cosmological solutions to the scalar-field evolution equation, it is clear that in the limit $\omega_{\text{BD}} \rightarrow \infty$ one recovers GR, i.e., scalar-tensor theories have a continuous limit to Einstein’s theory, but see Faraoni (1999) for caveats for certain spacetimes. Moreover, Salgado et al. (2008), Lanahan-Tremblay and Faraoni (2007), Wald (1984) have verified that scalar-tensor theories with minimal or non-minimal coupling in the Jordan frame can be cast in a strongly-hyperbolic form, and thus, they possess a well-posed initial-value formulation. Therefore, scalar-tensor theories possess both Properties (1) and (3).

These classical scalar-tensor theories also possess Property (2), since they can be derived from the low-energy limit of certain string theories. The integration of string quantum fluctuations leads to a higher-dimensional string theoretical action that reduces locally to a field theory similar to a scalar-tensor one (Garay and García-Bellido 1993; Fradkin and Tseytlin 1985), the mapping being $\phi = e^{-2\psi}$, with ψ one of the string moduli fields (Damour and Polyakov 1994a, b). Moreover, scalar-tensor theories can be mapped to $f(R)$ theories, where one replaces the Ricci scalar by some functional of R . In particular, one can show that $f(R)$ theories are equivalent to Jordan–Fierz–Brans–Dicke theory with $\omega_{\text{BD}} = 0$, via the mapping $\phi = df(R)/dR$ and $V(\phi) = R df(R)/dR - f(R)$ (Chiba 2003; Sotiriou 2006). For a review on this topic, see De Felice and Tsujikawa (2010).

As for Property (4), these classical scalar-tensor theories are not typically built with the aim to introduce extreme gravity corrections to GR.⁵ Instead, they typically lead to modifications of Einstein’s theory in the weak-field, i.e., modifications that dominate in scenarios with sufficiently weak gravitational interactions. Although this might seem strange, it is natural if one considers, for example, one of the key modifications introduced by scalar-tensor theories: the emission of dipolar gravitational radiation. Such dipolar emission dominates over the General Relativistic quadrupolar emission for systems at large separation, where the gravitational compactness is small, such as in binary pulsars or in the very early inspiral of compact binaries. Therefore, one would expect scalar-tensor theories to

⁵ The process of spontaneous scalarization in a particular type of scalar-tensor theory (Damour and Esposito-Farèse 1992, 1993) does introduce strong-field modifications because it induces non-perturbative corrections that can affect the structure of neutron stars. These subclass of scalar-tensor theories would satisfy Property (4).

be best constrained by experiments or observations of compact binaries with large separations, as it has been explicitly shown in Yunes et al. (2012).

Black holes and stars continue to exist in these scalar-tensor theories. Stellar configurations are modified from their GR profile (Will and Zaglauer 1989; Damour and Esposito-Farèse 1996, 1998; Harada 1997, 1998; Tsuchida et al. 1998; Sotani and Kokkotas 2004; DeDeo and Psaltis 2003; Sotani 2012; Horbatsch and Burgess 2011), while black holes are not. Indeed, Hawking (Hawking 1972b; Dykla 1972; Hawking 1971; Carter 1971; Israel 1968; Robinson 1975) has proved that Jordan–Fierz–Brans–Dicke black holes that are stationary and the endpoint of gravitational collapse are identical to those of GR. This proof has been extended to a general class of scalar-tensor models (Sotiriou and Faraoni 2012). That is, stationary black holes radiate any excess “hair”, i.e., any additional degrees of freedom, after gravitational collapse, a result sometimes referred to as the *no-hair* theorem for black holes in scalar-tensor theories. This result has been extended even further to allow for quasi-stationary scenarios in generic scalar-tensor theories through the study of extreme-mass ratio inspirals (Yunes et al. 2012) (small black hole in orbit around a much larger one), post-Newtonian comparable-mass inspirals (Mirshekari and Will 2013; Lang 2014, 2015) and numerical simulations of comparable-mass black hole mergers with a non-trivial initial scalar field profile (Healy et al. 2012; Berti et al. 2013). The only way for black holes to grow hair in scalar tensor theories is if one allows for non-trivial boundary conditions for the scalar field (Healy et al. 2012; Horbatsch and Burgess 2012) or if one allows for the presence of matter around black holes (Cardoso et al. 2013a, b).

Let us now discuss going beyond these classical scalar-tensor theories. Damour and Esposito-Farèse (1992), Damour and Esposito-Farèse (1993) proposed a theory defined by the action in Eq. (16) but with the conformal factor $A(\phi) = e^{\alpha\phi + \beta\phi^2/2}$ or the coupling function $\omega(\phi) = -3/2 - 2\pi G/(\beta \log \phi)$, where α and β are constants. When $\beta = 0$, one recovers standard Jordan–Fierz–Brans–Dicke theory. When $\beta \lesssim -4$ (the precise value of β depending on the equation of state), non-perturbative effects that develop if the gravitational energy is large enough can force neutron stars to spontaneously acquire a non-trivial scalar field profile, to *spontaneously scalarize* (Damour and Esposito-Farèse 1992, 1993). Scalar charges of such neutron stars have been tabulated in Anderson and Yunes (2019), while analytic expressions were found in Yagi and Stepnitzka (2021) through resummation or in Zhao et al. (2019), Guo et al. (2021) through surrogate modeling. Moreover, binary neutron stars that initially had no scalar hair in their early inspiral can also acquire it before they merge, either when their binding energy exceeds some threshold (*dynamical scalarization*) or due to the presence of an external scalar field (*induced scalarization*) (Barausse et al. 2013; Palenzuela et al. 2014). In this way, this new class of scalar-tensor theories, as well as the screened scalar tensor theories discussed in Zhang et al. (2017a), were thought to be consistent with Solar System experiments, yet predict modifications in strong gravity scenarios. Binary pulsar observations have constrained this theory in the (α, β) space; very roughly speaking, $\beta > -4$ and $\alpha < 10^{-3}$ (Damour and Esposito-Farèse 1996, 1998; Freire et al. 2012b; Shao et al. 2017; Anderson et al. 2019; Voisin et al. 2020; Kramer et al. 2021; Zhao et al. 2022a).

Scalarization in the standard Damour–Esposito–Farèse scalar-tensor theory, however, has been shown to be inconsistent with solar system constraints upon accounting for the cosmological evolution of the scalar field (Damour and Nordtvedt 1993a, b; Sampson et al. 2014b; Anderson et al. 2016). Back in the early 1990s, Damour and Nordtvedt (1993a, b) showed that for $\beta > 0$, GR is an attractor in cosmological phase space. This means that the scalar field damps out upon cosmological evolution, becoming very small at small cosmological redshifts, and thus, passing solar system tests today. When $\beta < 0$, however, Sampson et al. (2014b) showed that the cosmological evolution of the field leads to a runaway solution that maximally violates solar system tests today. One is then forced to consider variations of the standard theory (e.g., changing the conformal coupling function $A(\phi)$ (Anderson et al. 2016; Mendes and Ortiz 2016), giving the scalar a mass (Ramazanoğlu and Pretorius 2016), etc.) or the standard theory with $\beta > 0$ (Palenzuela and Liebling 2016) if one wishes both solar system tests to be passed and scalarization to occur in neutron stars. For example, de Pirey Saint Alby and Yunes (2017) showed that endowing the scalar field with a mass introduces oscillatory behavior in the scalar field upon cosmological evolution, suppressing the runaway solution and allowing the theory to pass solar system constraints, while still allowing for spontaneous scalarization (Ramazanoğlu and Pretorius 2016).

2.3.3 Horndeski theory

Another type of scalar-tensor theory is Horndeski gravity (Horndeski 1974) (see, e.g., Kobayashi 2019 for a recent review). This theory is the most general model with a single scalar field that leads to field equations with at most second-order derivatives (Horndeski 1974). This theory has become popular because it was shown to be equivalent to a curved-spacetime, generalized scalar-tensor theory with Galilean shift symmetry (Deffayet et al. 2009), which is related to theories that aim at explaining the late-time acceleration of the Universe with a modified theory of gravity (Ratra and Peebles 1988; Caldwell et al. 1998; Armendariz-Picon et al. 2001; Dvali et al. 2000; Nicolis et al. 2009; Sotiriou and Faraoni 2010; Tsujikawa 2010; Clifton et al. 2012; Nojiri and Odintsov 2011). Horndeski gravity, however, is not a single theory, but rather a class of models, where the action depends on free functional degrees of freedom of the scalar field and its kinetic energy. Its action is given by

$$\begin{aligned} S_{\text{Horndeski}} = & \frac{1}{16\pi G} \int d^4x \sqrt{-g} \{ G_2(\phi, X) - G_3(\phi, X) \square \phi + G_4(\phi, X) R \\ & + G_{4X} \left[(\square \phi)^2 - \phi^{\mu\nu} \phi_{\mu\nu} \right] \\ & + G_5(\phi, X) G^{\mu\nu} \phi_{\mu\nu} - \frac{G_{5X}}{6} \left[(\square \phi)^3 - 3 \square \phi \phi^{\mu\nu} \phi_{\mu\nu} + 2 \phi_{\mu\nu} \phi^{\nu\lambda} \phi_{\lambda}^{\mu} \right] \} \\ & + S_{\text{mat}}[\psi_{\text{mat}}, g_{\mu\nu}], \end{aligned} \quad (24)$$

where the $G_i(\cdot, \cdot)$ are arbitrary functionals of the scalar field ϕ and $X = -\phi_{,\mu} \phi^{\mu\nu} / 2$, with $G_{iX} \equiv \partial G_i / \partial X$. In an attempt to reduce this class to a smaller subset, one can

restrict attention to models that allow for a stable Minkowski background and non-trivial cosmological evolution in the presence of matter with a homogeneous and isotropic spacetime, which defines the Fab Four class of theories (Charmousis et al. 2012a, b). The action of this class of theories is

$$S_{\text{Fab-Four}} = \frac{1}{16\pi G} \int d^4x \sqrt{-g} [V_1(\phi)R + V_2(\phi)R_{\text{GB}} + V_3(\phi)G^{\mu\nu}(\partial_\mu\phi)(\partial_\nu\phi) + V_4(\phi)P^{\mu\nu\rho\sigma}(\partial_\mu\phi)(\partial_\nu\phi)(\partial_\rho\phi)(\partial_\sigma\phi)] + S_{\text{mat}}[\psi_{\text{mat}}, g_{\mu\nu}], \quad (25)$$

where R_{GB} is the Gauss–Bonnet invariant, $P^{\mu\nu\rho\sigma}$ is the double-dual Riemann tensor (Maselli et al. 2016c) and the $V_i(\phi)$ are free functions of the scalar field. Different choices of the latter define different scalar-tensor theories. For example, when $V_1(\phi) = 1$, $V_2(\phi) = \phi$ and all other $V_i(\phi)$, the theory reduces to Einstein–dilaton–Gauss–Bonnet gravity in the decoupling limit (Yunes and Stein 2011; Yagi et al. 2012b), which we will discuss in more detail in Sec. 2.3.4. Horndeski theories admit a modified harmonic formulation (Kovács and Reall 2020a, b) that makes the theories well-posed, as long as the coupling parameter in the theories is smaller than all the other length scales in the problem. The well-posedness of scalar-tensor theories was also studied in Bezares et al. (2021), Lara et al. (2022) by applying a formulation inspired by that of Müller, Israel and Stewart for relativistic viscous hydrodynamics (Cayuso et al. 2017; Allwright and Lehner 2019; Cayuso and Lehner 2020; Cayuso et al. 2023; Corman et al. 2024).

Compact black holes and stars have been studied in Horndeski gravity and in the Fab Four subclass. Hui and Nicolis (2013) have proved that black holes in shift-symmetric Horndeski gravity have no-hair, i.e., the scalar field does not activate, provided the spacetime is asymptotically flat, static and spherically symmetric, with the scalar field inheriting these symmetries. One can of course break some of the assumptions that Hui and Nicolis used, and thus, construct hairy black hole solutions (see, e.g., Rinaldi 2012; Sotiriou and Zhou 2014a; Anabalón et al. 2014; Babichev and Charmousis 2014; Minamitsuji 2014b; Sotiriou and Zhou 2014b; Minamitsuji 2014a; Cisterna et al. 2015; or the review by Herdeiro and Radu 2015). Many of these results were extended in the slow-rotation limit in Maselli et al. (2015b). Slowly-rotating neutron star solutions in the Fab Four subclass of Horndeski theories were studied in Maselli et al. (2016c). This analysis showed that a particular theory (the so-called “Paul” member of the Fab Four class) is ruled out due to its inability to allow for neutron star solutions. Sakstein et al. (2017) found very massive neutron star solutions embedded in an asymptotically de Sitter spacetime within a particular type of extended theory. See, for example, Chagoya and Tasinato (2018), Kobayashi and Hiramatsu (2018), Ogawa et al. (2020), Barranco et al. (2021), Boumaza and Langlois (2022) for other recent works on relativistic stars in Horndeski and beyond.

2.3.4 Massive graviton theories

Massive graviton theories are those in which the gravitational interaction is propagated by a massive gauge boson, i.e., a graviton with mass $m_g \neq 0$ or Compton

wavelength $\lambda_g \equiv h/(m_g c) < \infty$. Einstein's theory predicts massless gravitons and thus gravitational propagation at light speed, but if this were not the case, then a certain delay would develop between electromagnetic and gravitational signals emitted simultaneously at the source. Fierz and Pauli (1939) were the first to write down an action for a free massive graviton, and ever since then, much work has gone into the construction of such models. For a detailed review, see, e.g., Hinterbichler (2012), de Rham (2014).

Gravitational theories with massive gravitons are somewhat well-motivated from a fundamental physics perspective, and thus, one can say they possess Property (2). Indeed, in loop quantum cosmology (Ashtekar et al. 2003; Bojowald 2005), the cosmological extension to loop quantum gravity, the graviton dispersion relation acquires holonomy corrections during loop quantization that endow the graviton with a mass (Bojowald and Hossain 2008) $m_g = \Delta^{-1/2} \gamma^{-1} (\rho / \rho_c)$, with γ the Barbero–Immirzi parameter, Δ the area operator, and ρ and ρ_c the total and critical cosmological energy densities respectively. In string-theory–inspired effective theories, such as Dvali's compact, extra-dimensional theory (Dvali et al. 2000) such massive modes also arise.

Massive graviton modes also occur in many other modified gravity models. In Rosen's bimetric theory (Rosen 1974), for example, photons and gravitons follow null geodesics of different metrics (Will 2014, 2018b). In Visser's massive graviton theory (Visser 1998), the graviton is given a mass at the level of the action through an effective perturbative description of gravity, at the cost of introducing a non-dynamical background metric, i.e., a prior geometry. A recent re-incarnation of this model goes by the name of new massive gravity, or its generalization bigravity, where again two metric tensors are introduced (Pilo 2011; Paulos and Tolley 2012; Hassan and Rosen 2012a, b; De Felice et al. 2014; Narikawa et al. 2015). In Bekenstein's Tensor-Vector-Scalar (TeVeS) theory (Bekenstein 2004), the existence of a scalar and a vector field lead to subluminal GW propagation.

Old massive graviton theories have a theoretical issue, the van Dam–Veltman–Zakharov (vDVZ) discontinuity (van Dam and Veltman 1970; Zakharov 1970), which is associated with Property 1.a, i.e., a GR limit. The problem is that certain predictions of massive graviton theories do not reduce to those of GR in the $m_g \rightarrow 0$ limit. This can be understood qualitatively by studying how the 5 spin states of the graviton behave in this limit. Two of them become the two GR helicity states of the massless graviton. Another two become helicity states of a massless vector that decouples from the tensor perturbations in the $m_g \rightarrow 0$ limit. The last state, the scalar mode, however, retains a finite coupling to the trace of the stress-energy tensor in this limit. Therefore, massive graviton theories in the $m_g \rightarrow 0$ limit do not reduce to GR, since the scalar mode does not decouple.

Given these difficulties, and lacking a specific action that was not vDVZ discontinuous, the community began to consider certain *phenomenological* effects that one would expect to be present in massive gravity. If the graviton is truly massive, whatever the action may be, two class of modifications to Einstein's theory are expected to be present:

- (i) Modification to Newton's laws;

(ii) Modification to gravitational wave propagation.

Typically, modifications of class (i) correspond to the replacement of the Newtonian potential by a Yukawa type potential (in the non-radiative, near-zone of any body of mass M): $V = (M/r) \rightarrow (M/r) \exp(-r/\lambda_g)$, where r is the distance to the body (Will 1998). Tests of such a Yukawa interaction have been proposed through observations of bound clusters, tidal interactions between galaxies (Goldhaber and Nieto 1974) and weak gravitational lensing (Choudhury et al. 2004), but such tests are model dependent. On the other hand, solar system bounds are more robust, as we will discuss later.

Modifications of class (ii) are in the form of a modified gravitational-wave dispersion relation. Such a modification was originally parameterized via (Will 1998)

$$\frac{v_g^2}{c^2} = 1 - \frac{m_g^2 c^4}{E^2}, \quad (26)$$

where v_g and m_g are the speed and mass of the graviton, while E is its energy, usually associated to its frequency via the quantum mechanical relation $E = hf$. This modified dispersion relation is inspired by special relativity, a more general version of which, inspired by quantum gravitational theories, is (Mirshekari et al. 2012)

$$\frac{v_g^2}{c^2} = 1 - \lambda^\alpha, \quad (27)$$

where α is now a parameter that depends on the theory and λ is a dimensionless quantity that represents deviations from light speed propagation. For example, in Rosen's bimetric theory (Rosen 1974), the graviton does not travel at the speed of light, but at some other speed partially determined by the prior geometry. In many metric theories of gravity, $\lambda = A m_g^2 c^4 / E^2$, where A is some amplitude that depends on the metric theory (see discussion in Mirshekari et al. 2012). Either modification to the dispersion relation has the net effect of slowing gravitons down, such that there is a difference in the time of arrival of photons and gravitons. Moreover, such an energy-dependent dispersion relation would affect the accumulated gravitational wave phase observed at gravitational-wave detectors, as we will discuss in Sect. 4. Given these modifications to the dispersion relation, one would expect the generation of gravitational waves to also be greatly affected in such theories. We will present general arguments in Sect. 4, however, that point at these generation effects being subdominant relative to modifications that arise in the propagation of gravitational waves, since the latter accumulate as they travel and sources of gravitational waves are at cosmological distances (Yunes et al. 2016).

From the structure of the above phenomenological modifications, it is clear that GR can be recovered in the $m_g \rightarrow 0$ limit, avoiding the vDVZ issue altogether by construction. Such phenomenological modifications have been constrained by several types of experiments and observations (de Rham et al. 2017). Using the modification to Newton's third law and precise observations of the motion of the

inner planets of the solar system together with Kepler's third law, Will (1998) found a bound of $\lambda_g > 2.8 \times 10^{12}$ km, which was recently updated to $\lambda_g > 3.9 \times 10^{13}$ km (Will 2018a; Bernus et al. 2020) and 1.22×10^{15} km (Mariani et al. 2023). Recent observations of the S2 star orbit around Sgr A* have placed a new bound of $\lambda_g > 4.3 \times 10^{11}$ km (Zakharov et al. 2016). Such constraints are purely static, as they do not probe the radiative sector of the theory. Dynamical constraints, however, do exist: through observations of the decay of the orbital period of binary pulsars, Finn and Sutton (2002) found a bound⁶ of $\lambda_g > 1.6 \times 10^{10}$ km; working within cubic Galileon theory, which is effectively a massive gravity theory, Shao et al. (2020) found $\lambda_g > 7 \times 10^{18}$ km due to the absence of Galileon radiation (de Rham et al. 2013b) in binary pulsars, taking into account the Vainshtein suppression in radiation; by investigating the stability of Schwarzschild and Kerr black holes, Brito et al. (2013b) placed the constraint $\lambda_g > 2.4 \times 10^{13}$ km in Fierz–Pauli theory (Fierz and Pauli 1939). New constraints that use gravitational waves have been proposed, including measuring a difference in time of arrival of electromagnetic and gravitational waves (Cutler et al. 2003; Kocsis et al. 2008), as well as direct observation of gravitational waves emitted by binary pulsars. As we shall see in Sect. 4.3.1, aLIGO has placed stringent constraints on massive graviton effects in the propagation of gravitational waves (Abbott et al. 2016d; Yunes et al. 2016; Abbott et al. 2019b, c, 2021b, c).

Somewhat recently, however, it has been found that the vDVZ discontinuity can in fact be evaded by carefully including non-linearities in the action. Vainshtein (Vainshtein 1972; Kogan et al. 2001; Deffayet et al. 2002; Babichev and Deffayet 2013) showed that around any spherically-symmetric source of mass M , there exists a certain radius $r < r_V \equiv (r_S \lambda_g^4)^{1/5}$, with r_S the Schwarzschild radius, where linear theory cannot be trusted. Since $r_V \rightarrow \infty$ as $m_g \rightarrow 0$, this implies that there is no radius at all in which the linear approximation can be trusted in the massless limit. Of course, to determine then whether massive graviton theories have a continuous limit to GR, one must include non-linear corrections to the action (see also an argument by Arkani-Hamed et al. 2003), which are much more difficult to construct and work with. These considerations gave birth to new, non-linear massive gravity theories (Bergshoeff et al. 2009; de Rham et al. 2011, 2013a, b; Gümrükçüoğlu et al. 2012; Bergshoeff et al. 2013), or new massive gravity for short. In this theory, non-linear interactions are added to the action through the inclusion of an auxiliary fixed metric. A generalization of new massive gravity that allows the auxiliary metric to be dynamical goes by the name of bigravity.

There has been much activity in the study of gravitational waves in the ghost-free bigravity extension of new massive gravity theories (De Felice et al. 2014; Narikawa et al. 2015; Max et al. 2017, 2018), so let us here present more details of this model. The ghost-free bigravity action is given by

⁶ The model considered by Finn and Sutton (2002) is not phenomenological, but it contains a ghost mode.

$$S_{\text{bg}} = \frac{M_g^2}{2} \int d^4x \sqrt{-g} R + \frac{\kappa_b M_g^2}{2} \int d^4x \sqrt{-\tilde{g}} \tilde{R} - m^2 M_g^2 \int d^4x \sqrt{-g} \sum_{n=0}^4 c_n V_n(Y_v^\mu) + S_m[\psi_{\text{mat}}, g_{\mu\nu}], \quad (28)$$

where $g_{\mu\nu}$ is the metric tensor of our universe, i.e., that which couples to the matter degrees of freedom ψ_{mat} with coupling $M_g = (8\pi G)^{-1/2}$, with R its associated Ricci scalar and g its determinant. The metric tensor $\tilde{g}_{\mu\nu}$, with its associated Ricci scalar \tilde{R} , determinant \tilde{g} and coupling constant κ_b , couples non-minimally to $g_{\mu\nu}$ through the third term in the action. The latter depends on the graviton mass m , coupling constants c_n and complicated functionals $V_n[\cdot]$ of $Y_v^\mu := \sqrt{g^{\mu x} \tilde{g}_{xv}}$.

The generation of gravitational waves has not been worked out in this theory yet, but their propagation has. In bigravity, the $g_{\mu\nu}$ and $\tilde{g}_{\mu\nu}$ metric tensors are massless and massive spin-2 degrees of freedom respectively, which implies they carry 2 + 5 modes (2 transverse-traceless ones in $g_{\mu\nu}$, 2 transverse-traceless ones in $\tilde{g}_{\mu\nu}$, 2 transverse vector ones in $\tilde{g}_{\mu\nu}$, and a breathing mode in $\tilde{g}_{\mu\nu}$). The evolution equations for the dominant transverse-traceless modes (assuming propagation on the same background) are (Narikawa et al. 2015)

$$\square_c h_{+,x} + m^2 \Gamma_c (h_{+,x} - \tilde{h}_{+,x}) = 0, \quad (29)$$

$$\square_c \tilde{h}_{+,x} + \frac{m^2 \Gamma_c}{\kappa_b \xi_c} (\tilde{h}_{+,x} - h_{+,x}) = 0, \quad (30)$$

where (Γ_c, ξ_c) are constants that depend on the coupling parameters of the theory, while the operator $\square_c = \partial_t^2 - v^2 \nabla^2$, with v the propagation speed of the mode. One then sees that the perturbation to the physical metric couples to the perturbation of the auxiliary metric, leading to oscillations between the two modes. This behavior is analogous to neutrino oscillations in the standard model, where the “mass matrix” is non-diagonal.

Given how relatively new massive gravity and bigravity are, many of the properties listed in Sect. 2.1 have not yet been fully explored. Clearly, these theories are constructed to satisfy Property 1.a, the GR limit. Black holes, neutron stars and white dwarfs in ghost-free massive gravity and bigravity have been studied in Volkov (2012), Volkov (2013), Babichev and Fabbri (2014a), Enander and Mortsell (2015), Katsuragawa et al. (2016), Li et al. (2016), Aoki et al. (2016), Sullivan and Yunes (2018), Hendi et al. (2017), Yamazaki et al. (2019), Eslam Panah and Liu (2019), Gervalle and Volkov (2020), and their stability has also been analyzed (Babichev et al. 2016) (see Babichev and Brito 2015 for a review on black hole solutions in massive gravity). Spherically symmetric black holes were constructed in Comelli et al. (2012), Volkov (2012), Gervalle and Volkov (2020), Brito et al. (2013a), which appear to be linearly stable in a region of parameter space (Babichev and Fabbri 2013, 2014b; Brito et al. 2013b, c; Kobayashi et al. 2016; Gervalle and Volkov 2020). Rotating black hole solutions were also found with asymptotically

flat boundary conditions in Babichev and Fabbri (2013) and with anti-de Sitter boundary conditions in Ayón-Beato et al. (2016), although it is not clear whether these solutions are stable. A weak field analysis was carried out in De Felice et al. (2014), where the authors found that Solar System tests can be avoided if the mass of the graviton is large enough due to the activation of a form of Vainshtein screening in bigravity. Similarly, the construction of stars in massive bigravity began around 2012. The first neutron stars in massive bigravity were constructed by Volkov (2012), assuming spherical symmetry and an incompressible fluid equation of state. This analysis was then extended in Enander and Mortsell (2015), who also considered whether black holes and neutron stars can arise naturally from gravitational collapse in these theories. Sullivan et al. (2021) constructed the first rotating neutron star solutions in massive bigravity, using the Hartle–Thorne slow-rotation approximation and a wide class of realistic equations of state. The stability of these solutions has not yet been studied, and thus, much more work remains to be done to understand their non-linearly stability. Lacking knowledge of what a bigravity spacetime for binary systems looks like, the study of the generation of gravitational waves in dynamical spacetimes has not yet been tackled.

Whether all of these theories are well-posed as an initial-value problem (Property 3) remains unclear. For ghost-free massive gravity with flat reference metric, however, the theory has indeed been shown to be well-posed by introducing higher order gradient terms (de Rham et al. 2023). The well-posedness of bigravity has not yet been proven. Torsello et al. (2020) studied a covariant formulation in this theory that allows one to prove strong hyperbolicity in GR. The authors found that strong hyperbolicity in bigravity cannot be claimed with the same assumptions as in GR. Massive gravity theories are well-motivated extensions of GR from a fundamental physics standpoint, given that many particles in the standard model that are known to have a mass. Finally, it is currently unclear whether these theories lead to modifications in the extreme gravity regime, except perhaps for the graviton oscillations discussed above. One might be concerned that the mass of the graviton and subsequent modifications to the graviton dispersion relation should be suppressed by the Planck scale. However, Collins et al. (2004), Collins et al. (2009) have suggested that Lorentz violations in perturbative quantum field theories could be dramatically enhanced when one regularizes and renormalizes them. This is because terms that vanish upon renormalization due to Lorentz invariance do not vanish in Lorentz-violating theories, thus leading to an enhancement (Gambini et al. 2011). Whether such an enhancement is truly present in massive gravity depends on the particular model considered and has not yet been studied in detail.

Let us close this section with a note of caution about Lorentz violations and massive gravity: although massive gravity theories unavoidably lead to a modification to the graviton dispersion relation, and the latter are also common in Lorentz-violating theories, the converse is not necessarily true, i.e. a modification to the dispersion relation, for example due to Lorentz-violating effects, does not necessarily imply a massive graviton. In fact, modifications to the dispersion relation are usually accompanied by modifications to either the Lorentz group or its action in real or momentum space. Such Lorentz-violating effects are commonly found in quantum gravitational theories, including loop quantum gravity (Bojowald

and Hossain 2008) and string theory (Chouha and Brandenberger 2005; Szabo 2010), as well as other effective models (Berezhiani et al. 2007, 2008). In Doubly Special Relativity (Amelino-Camelia 2001; Magueijo and Smolin 2002; Amelino-Camelia 2002, 2010), the graviton dispersion relation is modified at high energies by modifying the law of transformation of inertial observers. Modified graviton dispersion relations have also been shown to arise in generic extra-dimensional models (Sefiedgar et al. 2011a), in Hořava–Lifshitz theory (Hořava 2009a, b; Vacaru 2012; Blas and Sanctuary 2011) and in theories with non-commutative geometries (Garattini 2011; Garattini and Mandanici 2011, 2012). Even though the dispersion relation is modified in these theories, they do not require a massive graviton.

2.3.5 Einstein-æther theory and khronometric gravity

Violations of Lorentz symmetry are inherent in quantum gravitational models. Particle physics experiments have already placed very stringent constraints on Lorentz violation in the matter sector (Kostelecky 2004; Kostelecky and Russell 2011; Mattingly 2005; Jacobson et al. 2006; Kostelecky and Tasson 2011). A generic way to represent such constraints is to bound the coefficients of the standard model extension (SME) (Colladay and Kostelecký 1998; Kostelecký 1998, 1999), a framework in which one adds all possible Lorentz-violating interactions to the action of the Standard Model. These experiments, however, cannot place stringent constraints on Lorentz violation that enters primarily in the gravitational sector, inducing violations in the matter sector only as a second-order process (Pospelov and Shang 2012; Liberati 2013).

The most common way to represent violations of Lorentz symmetry in the gravity sector is through a preferred time direction at every spacetime point. This preferred frame is typically described by an æther vector field U^μ that is timelike and unit-norm, thus breaking boost symmetry, and consequently Lorentz invariance. The most generic covariant action that (i) depends only on the metric tensor and the æther vector field, and their first derivatives, and (ii) is quadratic in the latter, is given by (Jacobson and Mattingly 2001; Eling et al. 2004; Jacobson 2008a)

$$S_{\text{EA}} = \frac{1}{16\pi G_{\text{EA}}} \int d^4x \sqrt{-g} (R - M^{\alpha\beta}_{\mu\nu} \nabla_\alpha U^\mu \nabla_\beta U^\nu) + S_m(\psi_{\text{mat}}, g_{\mu\nu}), \quad (31)$$

up to total divergences, where g is the determinant of the metric $g_{\mu\nu}$, R is its associated Ricci scalar,

$$M^{\alpha\beta}_{\mu\nu} \equiv c_1 g^{\alpha\beta} g_{\mu\nu} + c_2 \delta_\mu^\alpha \delta_\nu^\beta + c_3 \delta_\nu^\alpha \delta_\mu^\beta + c_4 U^\alpha U^\beta g_{\mu\nu}, \quad (32)$$

(c_1, c_2, c_3, c_4) are (dimensionless) coupling constants, and $G_N = G_{\text{EA}}[1 - (c_1 + c_4)/2]^{-1}$, with G_{EA} the “bare” gravitational constant and G_N the “Newtonian” gravitational constant measured with Cavendish-type experiments (Carroll and Lim 2004). This action defines Einstein-æther theory (Jacobson and Mattingly 2001), which ought to be thought of as an effective field theory, i.e., the

low-energy description of some as-of-yet-unknown high-energy theory (Armenariz-Picon et al. 2010).

A simpler way to violate Lorentz symmetry gravitationally is to require that the preferred time direction be present *globally*, rather than locally in spacetime. This amounts to restricting Einstein-æther theory by requiring the æther field to be orthogonal to hypersurfaces of constant preferred time. Defining these hypersurfaces through level surfaces of the *khronon*⁷ scalar field T , then this implies requiring that

$$U_\mu = \frac{\partial_\mu T}{\sqrt{g^{\mu\nu}\partial_\mu T \partial_\nu T}}, \quad (33)$$

and thus, the æther vector field is no longer generic. Choosing the time coordinate to coincide with the khronon field, and reducing the Einstein-æther action through the above constraint, one finds (Jacobson 2010; Blas et al. 2010a, 2011)

$$S_{\text{KG}} = \frac{1-\beta}{16\pi G_{\text{EA}}} \int dT d^3x N \sqrt{h} \left(K_{ij} K^{ij} - \frac{1+\lambda}{1-\beta} K^2 + \frac{1}{1-\beta} {}^{(3)}R + \frac{\alpha}{1-\beta} a_i a^i \right) + S_{\text{mat}}(\psi_{\text{mat}}, g_{\mu\nu}), \quad (34)$$

where $N = (g^{TT})^{-1/2}$ is the lapse function, K^{ij} , ${}^{(3)}R$ and h^{ij} are the extrinsic curvature, the 3-Ricci curvature and the 3-metric associated with the constant T hypersurfaces respectively, the acceleration of the khronon field is $a_i \equiv \partial_i \ln N$, and (α, β, λ) are coupling constants related to the Einstein-æther couplings via $(\alpha, \beta, \lambda) = (c_1 + c_4, c_1 + c_3, c_2)$. This action defines khronometric gravity (Blas et al. 2010a, 2011), and it also ought to be thought of as an effective theory. In fact, khronometric gravity is the low-energy limit of Hořava gravity (Hořava 2009b), a power-counting renormalizable theory of gravity (Hořava 2009b; Blas et al. 2010b).

Variation of the action with respect to all fields yields the field equations of the theory. The field equations of Einstein-æther theory are

$$G_{\alpha\beta} - T_{\alpha\beta}^{\text{EA}} = 8\pi G_{\text{EA}} T_{\alpha\beta}^{\text{mat}}, \quad (35)$$

$$\mathbb{A}_\mu \equiv \left(\nabla_\alpha J^{\alpha\nu} - c_4 \dot{U}_\alpha \nabla^\nu U^\alpha \right) (g_{\mu\nu} - U_\mu U_\nu) = 0, \quad (36)$$

where $G_{\alpha\beta}$ is the Einstein tensor, and the æther stress-energy tensor is

⁷ This word comes from the Greek word $\chi\rho\circ\circ\circ\varsigma$ (khronos), meaning time. The letter “k” was chosen to avoid confusion with other theories that use the prefix “chrono” (Lévi 1927; Segal 1972).

$$\begin{aligned}
T_{\alpha\beta}^{\text{EA}} = & \nabla_\mu \left(J_{(\alpha}^\mu U_{\beta)} - J_{(\alpha}^\mu U_{\beta)} - J_{(\alpha\beta)} U^\mu \right) \\
& + c_1 \left[(\nabla_\mu U_\alpha) (\nabla^\mu U_\beta) - (\nabla_\alpha U_\mu) (\nabla_\beta U^\mu) \right] \\
& + \left[U_\nu (\nabla_\mu J^{\mu\nu}) - c_4 \dot{U}^2 \right] U_\alpha U_\beta + c_4 \dot{U}_\alpha \dot{U}_\beta + \frac{1}{2} M^{\sigma\rho}_{\mu\nu} \nabla_\rho U^\nu g_{\alpha\beta},
\end{aligned} \tag{37}$$

with the shorthands $J_\mu^\alpha \equiv M^{\alpha\beta}_{\mu\nu} \nabla_\beta U^\nu$ and $\dot{U}_\nu \equiv U^\mu \nabla_\mu U_\nu$. The field equations of khronometric gravity are

$$G_{\alpha\beta} - T_{\alpha\beta}^{\text{EA}} - 2\mathbb{E}_{(\alpha} U_{\beta)} = 8\pi G_{\text{EA}} T_{\alpha\beta}^{\text{mat}}, \tag{38}$$

$$\nabla_\mu \left(\frac{\mathbb{E}^\mu}{\sqrt{\nabla^\alpha T \nabla_\alpha T}} \right) = 0, \tag{39}$$

where \mathbb{E}_α was defined in Eq. (36).

The field equations in these two Lorentz-violating gravity theories have been solved in a variety of scenarios. For example, spherically symmetric, static, and flat vacuum solutions (non-rotating black holes) have been found, and in fact discovered to be the same in the two theories (Jacobson 2010; Blas and Sibiryakov 2011; Blas et al. 2011; Barausse and Sotiriou 2012). In fact, hypersurface-orthogonal solutions to Einstein- \mathcal{A} ether theory will also be solutions in khronometric gravity. Slowly-rotating black hole solutions have also been found, but they are not the same (Wang 2013; Barausse and Sotiriou 2012, 2013b, a). Recently, rotating black hole solutions without the slow-rotation approximation were constructed numerically (Adam et al. 2022). Slowly-moving black hole solutions were studied in Ramos and Barausse (2019), Kovachik and Sibiryakov (2023) with which one can extract sensitivities that are responsible for scalar and vector radiation in a binary (Foster 2007; Yagi et al. 2014a, b). Quasi-normal modes of black holes were studied in Konoplya and Zhidenko (2007a, b), Ding (2017, 2019), Churilova (2020), Franchini et al. (2021). These black holes have been shown numerically to be the end state of gravitational collapse for values of the coupling constants that are consistent with observational constraints (Eling and Jacobson 2006; Garfinkle et al. 2007; Barausse et al. 2011; Akhoury et al. 2018). Regarding neutron stars, non-rotating configurations were studied in Eling et al. (2007), while slowly-moving solutions were constructed in Yagi et al. (2014a, b), Barausse (2019), Gupta et al. (2021). Recently, Ajith et al. (2022) studied slowly-rotating or tidally-deformed neutron stars and found that there exist new types of Love numbers. Moreover, the motion of test-particles has been found to be geodesic in both theories, which implies the absence of a “fifth force” and violations of the WEP. This comes about because both theories are diffeomorphism invariant, which then implies that the matter stress-energy tensor associated with S_m is covariantly conserved, $\nabla^\mu T_{\mu\nu}^{\text{mat}} = 0$. This is not, however, the case for strongly self-gravitating bodies (like neutron stars and black holes), which follow non-geodesic paths that depend on the bodies’ internal structure, a violation of the strong equivalence principle that is sometimes referred to as the Nördvedt effect (Nordtvedt Jr 1968a; Roll et al. 1964).

Lorentz-violating gravity has been constrained with solar system observations that check for the existence of preferred-frame effects. Constraints derived with such observations are parameterized in terms of the $(\alpha_1^{\text{ppN}}, \alpha_2^{\text{ppN}})$ preferred-frame parameters of the ppN framework. In particular, lunar laser observations and observations of the solar alignment with the ecliptic plane have placed the constraints $|\alpha_1^{\text{ppN}}| \lesssim 10^{-4}$ and $|\alpha_2^{\text{ppN}}| \lesssim 10^{-7}$ (Will 2014) – binary pulsar observations have also placed stringent constraints on the strongly self-gravitating counterparts to $\alpha_{1,2}$ (Shao et al. 2013; Shao and Wex 2012). In Einstein-æther theory, the ppN parameters (α_1, α_2) are functions of the coupling constants c_i , namely

$$\begin{aligned}\alpha_1^{\text{ppN,EA}} &= -\frac{8(c_3^2 + c_1 c_4)}{2c_1 - c_+ c_-}, \\ \alpha_2^{\text{ppN,EA}} &= \frac{\alpha_1^{\text{ppN}}}{2} - \frac{(c_1 + 2c_3 - c_4)(2c_1 + 3c_2 + c_3 + c_4)}{(2 - c_{14})(c_1 + c_2 + c_3)},\end{aligned}\quad (40)$$

while in khronometric gravity, the ppN parameters are functions of the (α, β, λ) , namely

$$\begin{aligned}\alpha_1^{\text{ppN,KG}} &= 4 \frac{\alpha - 2\beta}{\beta - 1}, \\ \alpha_2^{\text{ppN,KG}} &= \frac{(\alpha - 2\beta)}{(\beta - 1)(\lambda + \beta)(\alpha - 2)} [-\beta^2 + \beta(\alpha - 3) + \alpha + \lambda(-1 - 3\beta + 2\alpha)].\end{aligned}\quad (41)$$

Notice that $\alpha_2^{\text{ppN,KG}}$ can be written in terms of $\alpha_1^{\text{ppN,KG}}$, so requiring that the latter be small automatically ensures the former is also small.

Because of the many coupling constants in these theories, solar system constraints on only two combinations $(\alpha_1^{\text{ppN}} \text{ and } \alpha_2^{\text{ppN}})$ are not enough to break all degeneracies and constrain the individual coupling parameters; for this, one requires new constraints, such as those obtained from binary pulsar observations. The latter are typically studied by assuming $\alpha_1^{\text{ppN}} = 0 = \alpha_2^{\text{ppN}}$ to reduce the 4- and 3-dimensional coupling parameter spaces to a 2-dimensional one. In Einstein-æther theory, this implies (Foster and Jacobson 2006; Jacobson 2008a)

$$c_2 = \frac{-2c_1^2 - c_1 c_3 + c_3^2}{3c_1}, \quad c_4 = -\frac{c_3^2}{c_1}, \quad (42)$$

leaving $c_{\pm} \equiv c_1 \pm c_3$ as the only two free coupling parameters, while in khronometric gravity the condition implies $\alpha = 2\beta$, leaving (β, λ) as the only two free coupling parameters. The strongest constraints on c_{\pm} and (β, λ) come from observations of the orbital decay rate of PSR J1141-6545 (Bhat et al. 2008), PSR J0348+0432 (Antoniadis et al. 2013), PSR J0737-3039 (Kramer et al. 2006) and PSR J1738+0333 (Freire et al. 2012a), which require $(c_+, c_-) \lesssim (0.03, 0.003)$ and $(\beta, \lambda) \lesssim (0.005, 0.1)$ (Yagi et al. 2014a, b). The khronometric constraint also makes use of Big-Bang Nucleosynthesis constraints (Audren et al. 2013; Carroll and Lim 2004; Zuntz et al. 2008; Jacobson 2008a), derived from the agreement between

observed and predicted metal abundances in the early universe, which require that the ratio of Newton's gravitational constant in that cosmological era to that measured today be close to unity. Weaker constraints on c_{\pm} have also been obtained by requiring the stability of perturbations about a Minkowski background (Jacobson and Mattingly 2004) and the absence of gravitational Cherenkov radiation (Elliott et al. 2005). Combining all of these constraints together, one arrives at $c_i \lesssim 10^{-2}$, while $(\alpha, \beta, \lambda) \lesssim (0.01, 0.005, 0.1)$.

As we will discuss later, the binary neutron star merger event GW170817 (Abbott et al. 2017c), together with its electromagnetic counterparts GRB 170817A (Abbott et al. 2017d), has constrained deviations in the propagation speed of gravitational waves to less than one part in 10^{15} relative to the speed of light (Abbott et al. 2017a). In Einstein-æther and khronometric gravity, the propagation speed of the tensor mode depends only on $c_1 + c_3$ or β . This means that this combination of parameters is constrained to be smaller than 10^{-15} . Imposing this new bound and all the other bounds mentioned earlier, two viable regions remain in the Einstein-Æther parameter space (Sarbach et al. 2019; Oost et al. 2018). The first region can be found by saturating the solar system bound on α_1 (namely, assuming $|\alpha_1| \lesssim 10^{-4}$ but not $|\alpha_1| \ll 10^{-4}$). Doing so implies that $c_1 \approx -c_3 + \mathcal{O}(10^{-15})$, $c_4 \approx c_3 + \mathcal{O}(10^{-4})$, and $c_2 \approx (c_4 - c_3)[1 + \mathcal{O}(10^{-3})]$, which then means that $c_1 + c_3 \approx 0$, $c_4 - c_3 \approx c_2 \approx 0$, while $c_1 - c_3$ remains unconstrained. The second region can be found when one does *not* saturate the bound on α_1 , but instead requires that its magnitude be much smaller than 10^{-14} . In doing so, the α_2 bound is automatically satisfied when $c_1 + c_3 \approx 0$ and one is left with a two-dimensional parameter space $(c_2, c_1 - c_3)$ with the only constraint $|c_2| \lesssim 0.1$ coming from Big Bang Nucleosynthesis bounds. Gupta et al. (2021) reanalyzed the binary pulsar bounds on Einstein-æther theory within these viable parameter spaces and derived a new bound on α_1 , namely $|\alpha_1| \lesssim 10^{-5}$, which is 10 times stronger than the bound from solar system experiments. Regarding khronometric gravity, the new bounds on the coupling constants after GW170817 are given by $|\alpha| \lesssim 10^{-7}$, $|\beta| \lesssim 10^{-15}$ and $|\lambda| \lesssim 10^{-1}$ (Emir Gümrükçüoğlu et al. 2018).

Let us conclude this overview with a discussion of whether Einstein-æther theory and khronometric gravity satisfy the criteria laid out in Sect. 2.1. As discussed above, both theories satisfy Property 1, since they pass all constraints for sufficiently small coupling constants and solutions that could present astrophysical systems have been found and shown to be stable. Both theories also possess Property 2, since they are very well-motivated from fundamental physics. In fact, it is difficult to find a quantum gravitational model that does not violate Lorentz symmetry. Einstein-æther theory also satisfies Property 3, at least in part, since it has been shown to have an initial-value formulation that is also well-posed (Coley et al. 2015; Sarbach et al. 2019). Khronometric gravity, on the other hand, has not been studied in sufficient detail to determine whether the theory is well-posed, although given the results from Einstein-æther theory, one would expect it to be (at least in some limit). Finally, property 4 is also satisfied, since extreme gravity will be altered in Lorentz-violating theories. These modifications, however, are not just confined to the

extreme gravity regime, thus allowing for rather stringent bounds from solar system observations and from strong- field binary pulsar tests.

2.3.6 Modified quadratic gravity

Modified quadratic gravity is a family of models first discussed in the context of black holes and gravitational waves in Yunes and Stein (2011), Yagi et al. (2012b). The 4-dimensional action is given by

$$S \equiv \int d^4x \sqrt{-g} \left\{ \kappa R + \alpha_1 f_1(\vartheta) R^2 + \alpha_2 f_2(\vartheta) R_{\mu\nu} R^{\mu\nu} + \alpha_3 f_3(\vartheta) R_{\mu\nu\delta\sigma} R^{\mu\nu\delta\sigma} \right. \\ \left. + \alpha_4 f_4(\vartheta) R_{\mu\nu\delta\sigma}^* R^{\mu\nu\delta\sigma} - \frac{\beta}{2} [(\nabla_\mu \vartheta)(\nabla^\mu \vartheta) + 2V(\vartheta)] + \mathcal{L}_{\text{mat}} \right\}. \quad (43)$$

The quantity ${}^*R^\mu_{\nu\delta\sigma} = (1/2)\epsilon_{\delta\sigma}^{\alpha\beta}R^\mu_{\nu\alpha\beta}$ is the dual to the Riemann tensor. The quantity \mathcal{L}_{mat} is the external matter Lagrangian, while $f_i(\cdot)$ are functionals of the field ϑ , with (α_i, β) coupling constants and $\kappa = (16\pi G)^{-1}$. Clearly, the two terms second to last in Eq. (43) represent a canonical kinetic energy term and a potential. At this stage, one might be tempted to set $\beta = 1$ or the $\alpha_i = 1$ via a rescaling of the scalar field functional, but we shall not do so here.

The action in Eq. (43) is well-motivated from fundamental theories, as it contains all possible quadratic, algebraic curvature scalars with running (i.e., non-constant) couplings. The only restriction here is that all quadratic terms are assumed to couple to the *same* field, which need not be the case. For example, in string theory some terms might couple to the dilaton (a scalar field), while others couple to the axion (a pseudo scalar field) (Kanti and Tamvakis 1995; Cano and Ruipérez 2022). Nevertheless, one can recover well-known and motivated modified gravity theories in simple cases. For example, dynamical Chern–Simons modified gravity (Alexander and Yunes 2009) is recovered when $\alpha_4 = -\alpha_{\text{CS}}/4$ and all other $\alpha_i = 0$. Einstein–dilaton–Gauss–Bonnet gravity (Pani and Cardoso 2009) is obtained when $\alpha_4 = 0$ and $(\alpha_1, \alpha_2, \alpha_3) = (1, -4, 1)\alpha_{\text{EDGB}}$.⁸ Both theories unavoidably arise as low-energy expansions of heterotic string theory (Green et al. 1987a, b; Kanti and Tamvakis 1995; Alexander and Gates Jr 2006; Burgess 2004; Cano and Ruipérez 2022). As such, modified quadratic gravity theories should be treated as a class of effective field theories. Moreover, dynamical Chern–Simons Gravity also arises in loop quantum gravity (Ashtekar and Lewandowski 2004; Rovelli 2004) when the Barbero–Immirzi parameter is promoted to a field in the presence of fermions (Ashtekar et al. 1989; Alexander and Yunes 2008; Taveras and Yunes 2008; Mercuri and Taveras 2009; Gates Jr et al. 2009).

One should make a clean and clear distinction between the theory defined by the action of Eq. (43) and that of $f(R)$ theories. The latter are defined as functionals of the Ricci scalar only, while Eq. (43) contains terms proportional to the Ricci tensor and Riemann tensor squared. One could think of the subclass of $f(R)$ theories with

⁸ Technically, Einstein–Dilaton–Gauss–Bonnet gravity has a very particular set of coupling functions $f_1(\vartheta) = f_2(\vartheta) = f_3(\vartheta) \propto e^{\vartheta\gamma}$, where γ is a constant. In most cases, however, one can expand about $\gamma\vartheta \ll 1$, so that the functions become linear in the scalar field.

$f(R) = R^2$ as the limit of modified quadratic gravity with only $\alpha_1 \neq 0$ and $f_1(\vartheta) = 1$. In that very special case, one can map quadratic gravity theories and $f(R)$ gravity to a scalar-tensor theory. Another important distinction is that $f(R)$ theories are usually treated as exact, while the action presented above is to be interpreted as an *effective theory* (Burgess 2004) truncated to quadratic order in the curvature in a low-energy expansion of a more fundamental theory. This implies that there are cubic, quartic, etc. terms in the Riemann tensor that are not included in Eq. (43) and that presumably depend on higher powers of α_i . Thus, when studying such an effective theory one should also order-reduce the field equations and treat all quantities that depend on α_i perturbatively, the so-called *small-coupling approximation*. One can show that such an order reduction removes any additional polarization modes in propagating metric perturbations (Sopuerta and Yunes 2009; Stein and Yunes 2011) that naturally arise in $f(R)$ theories. In analogy to the treatment of the Ostrogradski instability in Sect. 2.1, order-reduction also lead to a theory with a well-posed initial value formulation (Delsate et al. 2015).

This family of theories is usually simplified by making the assumption that the coupling functions $f_i(\cdot)$ admit a Taylor expansion: $f_i(\vartheta) = f_i(0) + f'_i(0)\vartheta + \mathcal{O}(\vartheta^2)$ for small ϑ , where $f_i(0)$ and $f'_i(0)$ are constants and ϑ is assumed to vanish at asymptotic spatial infinity. Reabsorbing $f_i(0)$ into the coupling constants $\alpha_i^{(0)} \equiv \alpha_i f_i(0)$ and $f'_i(0)$ into the constants $\alpha_i^{(1)} \equiv \alpha_i f'_i(0)$, Eq. (43) becomes $S = S_{\text{GR}} + S_0 + S_1$ with

$$S_{\text{GR}} \equiv \int d^4x \sqrt{-g} \{ \kappa R + \mathcal{L}_{\text{mat}} \}, \quad (44a)$$

$$S_0 \equiv \int d^4x \sqrt{-g} \left\{ \alpha_1^{(0)} R^2 + \alpha_2^{(0)} R_{\mu\nu} R^{\mu\nu} + \alpha_3^{(0)} R_{\mu\nu\delta\sigma} R^{\mu\nu\delta\sigma} \right\}, \quad (44b)$$

$$S_1 \equiv \int d^4x \sqrt{-g} \left\{ \alpha_1^{(1)} \vartheta R^2 + \alpha_2^{(1)} \vartheta R_{\mu\nu} R^{\mu\nu} + \alpha_3^{(1)} \vartheta R_{\mu\nu\delta\sigma} R^{\mu\nu\delta\sigma} \right. \\ \left. + \alpha_4^{(1)} \vartheta R_{\mu\nu\delta\sigma} {}^* R^{\mu\nu\delta\sigma} - \frac{\beta}{2} [(\nabla_\mu \vartheta)(\nabla^\mu \vartheta) + 2V(\vartheta)] \right\}. \quad (44c)$$

Here, S_{GR} is the Einstein–Hilbert plus matter action, while S_0 and S_1 are corrections. The former is decoupled from ϑ , where the omitted term proportional to $\alpha_4^{(0)}$ does not affect the classical field equations since it is topological, i.e., it can be rewritten as the total 4-divergence of some 4-current. Similarly, if $\alpha_i^{(0)}$ were chosen to reconstruct the Gauss–Bonnet invariant, $(\alpha_1^{(0)}, \alpha_2^{(0)}, \alpha_3^{(0)}) = (1, -4, 1)\alpha_{\text{GB}}$, then this combination would also be topological and not affect the classical field equations. On the other hand, S_1 is a modification to GR with a direct (non-minimal) coupling to ϑ , such that as the field goes to zero, the modified theory reduces to GR.

Another restriction one usually makes to simplify quadratic gravity theories is to neglect the $\alpha_i^{(0)}$ terms and only consider the S_1 modification, which defines *restricted* quadratic gravity. The $\alpha_i^{(0)}$ terms represent corrections that are non-

dynamical. The term proportional to $\alpha_1^{(0)}$ resembles a certain class of $f(R)$ theories. As such, it can be mapped to a scalar tensor theory with a complicated potential, which has been heavily constrained by torsion-balance Eöt-Wash experiments to $\alpha_1^{(0)} < 2 \times 10^{-8} \text{ m}^2$ (Hoyle et al. 2004; Kapner et al. 2007; Berry and Gair 2011). Moreover, these theories have a fixed coupling constant that does not run with energy or scale. In restricted quadratic gravity, the scalar field effectively forces the running of the coupling. Nevertheless, gravitational waves in quadratic gravity with $\alpha_i^{(1)} = 0$ have been studied in Naf and Jetzer (2011), Kim et al. (2021), Tachinami et al. (2021), Alves et al. (2023).

Let us then concentrate on restricted quadratic gravity and drop the superscript in $\alpha_i^{(1)}$. The modified field equations are

$$G_{\mu\nu} + \frac{\alpha_1 \vartheta}{\kappa} \mathcal{H}_{\mu\nu}^{(0)} + \frac{\alpha_2 \vartheta}{\kappa} \mathcal{I}_{\mu\nu}^{(0)} + \frac{\alpha_3 \vartheta}{\kappa} \mathcal{J}_{\mu\nu}^{(0)} + \frac{\alpha_1}{\kappa} \mathcal{H}_{\mu\nu}^{(1)} + \frac{\alpha_2}{\kappa} \mathcal{I}_{\mu\nu}^{(1)} + \frac{\alpha_3}{\kappa} \mathcal{J}_{\mu\nu}^{(1)} + \frac{\alpha_4}{\kappa} \mathcal{K}_{\mu\nu}^{(1)} = \frac{1}{2\kappa} \left(T_{\mu\nu}^{\text{mat}} + T_{\mu\nu}^{(\vartheta)} \right), \quad (45)$$

where we have defined

$$\mathcal{H}_{\mu\nu}^{(0)} \equiv 2RR_{\mu\nu} - \frac{1}{2}g_{\mu\nu}R^2 - 2\nabla_{\mu\nu}R + 2g_{\mu\nu}\square R, \quad (46a)$$

$$\mathcal{I}_{\mu\nu}^{(0)} \equiv \square R_{\mu\nu} + 2R_{\mu\delta\nu\sigma}R^{\delta\sigma} - \frac{1}{2}g_{\mu\nu}R^{\delta\sigma}R_{\delta\sigma} + \frac{1}{2}g_{\mu\nu}\square R - \nabla_{\mu\nu}R, \quad (46b)$$

$$\mathcal{J}_{\mu\nu}^{(0)} \equiv 8R^{\delta\sigma}R_{\mu\delta\nu\sigma} - 2g_{\mu\nu}R^{\delta\sigma}R_{\delta\sigma} + 4\square R_{\mu\nu} - 2RR_{\mu\nu} + \frac{1}{2}g_{\mu\nu}R^2 - 2\nabla_{\mu\nu}R, \quad (46c)$$

$$\mathcal{H}_{\mu\nu}^{(1)} \equiv -4(\nabla_{(\mu}\vartheta)\nabla_{\nu)}R - 2R\nabla_{\mu\nu}\vartheta + g_{\mu\nu}[2R\square\vartheta + 4(\nabla^\delta\vartheta)\nabla_\delta R], \quad (46d)$$

$$\begin{aligned} \mathcal{I}_{\mu\nu}^{(1)} \equiv & -(\nabla_{(\mu}\vartheta)\nabla_{\nu)}R - 2\nabla^\delta\vartheta\nabla_{(\mu}R_{\nu)\delta} + 2\nabla^\delta\vartheta\nabla_\delta R_{\mu\nu} + R_{\mu\nu}\square\vartheta \\ & - 2R_{\delta(\mu}\nabla^\delta\nabla_{\nu)}\vartheta + g_{\mu\nu}(\nabla^\delta\vartheta\nabla_\delta R + R^{\delta\sigma}\nabla_\delta\vartheta), \end{aligned} \quad (46e)$$

$$\mathcal{J}_{\mu\nu}^{(1)} \equiv -8(\nabla^\delta\vartheta)(\nabla_{(\mu}R_{\nu)\delta} - \nabla_\delta R_{\mu\nu}) + 4R_{\mu\delta\nu\sigma}\nabla^{\delta\sigma}\vartheta, \quad (46f)$$

$$\mathcal{K}_{\mu\nu}^{(1)} \equiv -4(\nabla^\delta\vartheta)\epsilon_{\delta\sigma\chi}(\nabla^\chi R_{\nu)}^\sigma) + 4(\nabla_{\delta\sigma}\vartheta)^* R_{(\mu}^{\delta\sigma} R_{\nu)}^\sigma. \quad (46g)$$

The ϑ stress-energy tensor is

$$T_{\mu\nu}^{(\vartheta)} = \beta \left\{ (\nabla_\mu\vartheta)(\nabla_\nu\vartheta) - \frac{1}{2}g_{\mu\nu}[(\nabla_\delta\vartheta)(\nabla^\delta\vartheta) - 2V(\vartheta)] \right\}. \quad (47)$$

The field equations for the scalar field are

$$\beta\square\vartheta - \beta \frac{dV}{d\vartheta} = -\alpha_1 R^2 - \alpha_2 R_{\mu\nu}R^{\mu\nu} - \alpha_3 R_{\mu\nu\delta\sigma}R^{\mu\nu\delta\sigma} - \alpha_4 R_{\mu\nu\delta\sigma}^* R^{\mu\nu\delta\sigma}. \quad (48)$$

Notice that unlike traditional scalar-tensor theories, the scalar field is here sourced

by the geometry and not by the matter distribution directly. This implies that black holes in such theories are hairy, when some of the coupling constants are non-vanishing, and thus, their inertial mass does not coincide with their gravitational mass (Yunes and Stein 2011; Benkel et al. 2017, 2016; Berti et al. 2018b; Prabhu and Stein 2018; Julié and Berti 2019; Julié et al. 2022; Hegade et al. 2022), violating the strong equivalence principle (a violation typically quantified through certain sensitivity parameters—see also Sect. 4). Other compact stars, such as neutron stars, however, can be shown to not be hairy,⁹ and thus have vanishing sensitivities, in the above restricted quadratic gravity theory with couplings to the Gauss–Bonnet invariant or the Pontryagin density (Yagi et al. 2012b, 2016), as well as in more generic shift-symmetric Horndeski theories (Barausse and Yagi 2015). This fact is particularly important since dipole radiation, which has been stringently constrained with binary pulsars, is proportional to the square of the difference in the sensitivities of the stars. Thus, a suppression in the sensitivities implies that these theories automatically pass binary pulsar constraints, while still allowing for extreme gravity modifications in systems with black holes (Yagi et al. 2016; Barausse and Yagi 2015).

Let us review compact objects in quadratic gravity in more detail. In non-dynamical theories (when $\beta = 0$ and the scalar-fields are constant, refer to Eq. (43)), Yunes and Stein (2011) have shown that all metrics that are Ricci tensor flat are also solutions of the modified field equations (see also Psaltis et al. 2008). This is not so for dynamical theories, since then the ϑ field is sourced by curvature, leading to corrections to the field equations proportional to the Riemann tensor and its dual.

In dynamical Chern–Simons gravity, stationary and spherically-symmetric spacetimes are still described by GR solutions, but stationary and axisymmetric spacetimes are not. Instead, they are represented by (Yunes and Pretorius 2009a; Konno et al. 2009)

$$ds_{\text{CS}}^2 = ds_{\text{Kerr}}^2 + \frac{5\alpha_{\text{CS}}^2}{4\beta\kappa} \frac{a}{r^4} \left(1 + \frac{12M}{7r} + \frac{27M^2}{10r^2} \right) \sin^2 \theta d\theta dt + \mathcal{O}(a^2/M^2), \quad (49)$$

with the scalar field

$$\vartheta_{\text{CS}} = \frac{5\alpha_{\text{CS}}}{8} \frac{a}{M} \frac{\cos \theta}{r^2} \left(1 + \frac{2M}{r} + \frac{18M^2}{5r^2} \right) + \mathcal{O}(a^3/M^3), \quad (50)$$

where ds_{Kerr}^2 is the line element of the Kerr metric, and we recall that $\alpha_{\text{CS}} = -4\alpha_4$ in the notation of Sect. 2.3.4. These expressions are obtained in Boyer–Lindquist coordinates and in the small-rotation/small-coupling limit to $\mathcal{O}(a/M)$ in Yunes and Pretorius (2009a), Konno et al. (2009), to $\mathcal{O}(a^2/M^2)$ in Yagi et al. (2012d), and solutions to higher order in spin in Maselli et al. (2015a). The linear-in-spin corrections modify the frame-dragging effect, and they are of 3.5 post-Newtonian order. The quadratic-in-spin corrections modify the quadrupole moment, which

⁹ To be more specific, “hair” here refers to the monopole scalar charge. Neutron stars can have higher order hair, like dipole scalar hair in dynamical Chern–Simons gravity (Yagi et al. 2013).

induces 2 post-Newtonian-order corrections to the binding energy. However, the stability of these black holes has only been studied linearly (Garfinkle et al. 2010).

In Einstein–Dilaton–Gauss–Bonnet gravity, stationary and spherically-symmetric spacetimes are described, in the small-coupling approximation, by the line element (Yunes and Stein 2011)

$$ds_{\text{EDGB}}^2 = -f_{\text{Schw}}(1+h)dt^2 + f_{\text{Schw}}^{-1}(1+k)dr^2 + r^2d\Omega^2, \quad (51)$$

in Schwarzschild coordinates, where $d\Omega^2$ is the line element on the two-sphere, $f_{\text{Schw}} = 1 - 2M/r$ is the Schwarzschild factor, and we have defined

$$h = \frac{\alpha_3^2}{\beta\kappa M^4} \frac{1}{3f_{\text{Schw}}} \frac{M^3}{r^3} \left(1 + 26\frac{M}{r} + \frac{66}{5}\frac{M^2}{r^2} + \frac{96}{5}\frac{M^3}{r^3} - 80\frac{M^4}{r^4} \right), \quad (52)$$

$$k = -\frac{\alpha_3^2}{\beta\kappa M^4 f_{\text{Schw}}} \frac{1}{r^2} \frac{M^2}{r^2} \left[1 + \frac{M}{r} + \frac{52}{3}\frac{M^2}{r^2} + 2\frac{M^3}{r^3} + \frac{16}{5}\frac{M^4}{r^4} - \frac{368}{3}\frac{M^5}{r^5} \right], \quad (53)$$

while the corresponding scalar field is

$$\vartheta_{\text{EDGB}} = \frac{\alpha_3}{\beta} \frac{2}{Mr} \left(1 + \frac{M}{r} + \frac{4}{3}\frac{M^2}{r^2} \right). \quad (54)$$

This solution is not restricted just to Einstein–Dilaton–Gauss–Bonnet gravity, but it is also the most general, stationary and spherically-symmetric solution in quadratic gravity. This is because all terms proportional to $\alpha_{1,2}$ are proportional to the Ricci tensor, which vanishes in vacuum GR, while the α_4 term does not contribute in spherical symmetry (see Yunes and Stein 2011 for more details). Linear slow-rotation corrections to this solution have been found in Pani et al. (2011c), and analytic solutions to higher order in spin were found in Maselli et al. (2015a). Although the stability of these black holes has only been studied linearly as well (Ayzenberg et al. 2014), other dilatonic black hole solutions obtained numerically (equivalent to those in Einstein–Dilaton–Gauss–Bonnet theory in the limit of small fields) (Kanti et al. 1996) have been found to be mode stable under axial and polar perturbations (Kanti et al. 1998; Torii and Maeda 1998; Pani and Cardoso 2009; Blázquez-Salcedo et al. 2016).

Neutron stars also exist in quadratic modified gravity. In dynamical Chern–Simons gravity, the mass-radius relation remains unmodified to first order in the slow-rotation expansion, but the moment of inertia changes to this order (Yunes et al. 2010d; Ali-Haïmoud and Chen 2011), while the quadrupole moment and the mass measured at spatial infinity change to quadratic order in spin (Yagi et al. 2013). This is because the mass-radius relation, to first order in slow-rotation, depends on the spherically-symmetric part of the metric, which is unmodified in dynamical Chern–Simons gravity. In Einstein–Dilaton–Gauss–Bonnet gravity, the mass-radius relation is modified (Pani et al. 2011a). As in GR, these functions must be solved for numerically, and they depend on the equation of state.

The above restricted quadratic gravity model is not a good representative member of the wider class of quadratic gravity theories when $f_i(\vartheta)$ cannot be

approximated as a linear function. Examples include $f_i(\vartheta) = \vartheta^2$ and $f_i(\vartheta) = [1 - \exp(-6\vartheta^2)]/12$. For these cases and with a Gauss–Bonnet combination of $(\alpha_1, \alpha_2, \alpha_3, \alpha_4) = (1, -4, 1, 0)\alpha$, recent analyses have shown that black holes can spontaneously scalarize (Doneva and Yazadjiev 2018; Silva et al. 2018; Macedo et al. 2019; Cunha et al. 2019; East and Ripley 2021a; Doneva et al. 2022a), similar to spontaneous scalarization for neutron stars in scalar-tensor theories. The scalar charges can also be induced by spins (Collodel et al. 2020; Herdeiro et al. 2021; Berti et al. 2021; Dima et al. 2020; Elley et al. 2022). In a binary, dynamical scalarization can occur in analogy to scalar-tensor theories (Silva et al. 2021b; Doneva et al. 2022b; Julié 2023; Kuan et al. 2023a; Annunzi and Herdeiro 2023; Lara et al. 2024), but a crucial difference is that in scalar-Gauss–Bonnet gravity, black holes in a binary can also *de-scalarize* (Silva et al. 2021b; Doneva et al. 2022b).

From the structure of the above equations, it should be clear that the dynamics of ϑ guarantee that the modified field equations are covariantly conserved exactly. That is, one can easily verify that the covariant divergence of Eq. (45) identically vanishes upon imposition of Eq. (48). Such a result had to be so, as the action is diffeomorphism invariant. If one neglected the kinetic and potential energies of ϑ in the action, as was originally done in Jackiw and Pi (2003), the theory would possess preferred-frame effects and would not be covariantly conserved. A manifestation of the latter is the fact that such a theory requires an additional constraint, i.e., the right-hand side of Eq. (48) would have to vanish, which is an unphysical consequence of treating ϑ as prior structure (Yunes and Sopuerta 2008; Grumiller and Yunes 2008).

One last simplification that is usually made when studying modified quadratic gravity theories is to ignore the potential $V(\vartheta)$, i.e., set $V(\vartheta) = 0$. This potential can in principle be non-zero, for example if one wishes to endow ϑ with a mass or if one wishes to introduce a cosine driving term, like that for axions in field and string theory (see, e.g., Nashed and Nojiri 2023 for slowly-rotating black holes in dynamical Chern–Simons gravity with non-vanishing potentials). However, reasons exist to restrict the functional form of such a potential. First, a mass for ϑ will modify the evolution of any gravitational degree of freedom only if this mass is comparable to the inverse length scale of the problem under consideration (such as a binary system). This could be possible if there is an incredibly large number of fields with different masses in the theory, such as perhaps in the string axiverse picture (Arvanitaki and Dubovsky 2011; Kodama and Yoshino 2012; Marsh et al. 2012). In that picture, however, the moduli fields are endowed with a mass due to shift-symmetry breaking by non-perturbative effects; such masses are not expected to be comparable to the inverse length scale of binary systems. Second, no mass term may appear in a theory with a shift symmetry, i.e., invariance under the transformation $\vartheta \rightarrow \vartheta + \text{const}$. Such symmetries are common in four-dimensional, low-energy, effective string theories (Boulware and Deser 1985; Green et al. 1987a, b, Campbell et al. 1992; Burgess 2004), such as dynamical Chern–Simons and Einstein–Dilaton–Gauss–Bonnet theory. Similar considerations apply to other, more complicated potentials, such as a cosine term.

Given these field equations, one can linearize them about Minkowski space to find evolution equations for the perturbation in the small-coupling approximation. Doing so, one finds (Yagi et al. 2012b)

$$\begin{aligned} \square_\eta \vartheta = & -\frac{\alpha_1}{\beta} \left(\frac{1}{2\kappa} \right)^2 T_{\text{mat}}^2 - \frac{\alpha_2}{\beta} \left(\frac{1}{2\kappa} \right)^2 T_{\text{mat}}^{\mu\nu} T_{\mu\nu}^{\text{mat}} \\ & - \frac{2\alpha_3}{\beta} (h_{\alpha\beta,\mu\nu} h^{\alpha[\beta,\mu]\nu} + h_{\alpha\beta,\mu\nu} h^{\mu[\nu,\alpha]\beta}) \\ & - \frac{2\alpha_4}{\beta} \epsilon^{\alpha\beta\mu\nu} h_{\alpha\delta;\beta\gamma} h_\nu^{\gamma\delta}, \end{aligned} \quad (55)$$

where we have order-reduced the theory where possible and used the harmonic gauge condition (which is preserved in this class of theories; Sopuerta and Yunes 2009; Stein and Yunes 2011). The corresponding equation for the metric perturbation is rather lengthy and can be found in Eqs. (17)–(24) in Yagi et al. (2012b). Since these theories are to be considered effective, working always to leading order in α_i , one can show that they are perturbatively of type N_2 in the $E(2)$ classification (Eardley et al. 1973), i.e., in the far zone, the only propagating modes that survive are the two transverse-traceless (spin-2) metric perturbations (Sopuerta and Yunes 2009; Wagle et al. 2019). In the strong-field region, however, it is possible that additional modes are excited, although they decay rapidly as they propagate to future null infinity.

Lastly, let us discuss what is known about whether modified quadratic gravity satisfies the requirements discussed in Sect. 2.1. As it should be clear from the action itself, this modified gravity theory satisfies the fundamental requirement, i.e., passing all precision tests, provided the couplings α_i are sufficiently small. This is because such theories have a continuous limit to GR as $\alpha_i \rightarrow 0$.¹⁰ Dynamical Chern–Simons gravity is constrained only weakly from solar system experiments, $\xi_4^{1/4} < 10^8$ km, where $\xi_4 \equiv \alpha_4^2/(\beta\kappa)$, through observations of Lense–Thirring precession (Ali-Haïmoud and Chen 2011; Nakamura et al. 2019). However, much stronger bounds have been obtained through gravitational wave observations. Ringdown observations place a new bound of $\xi_4^{1/4} < 103$ km (Silva et al. 2023) by assuming a small-spin expansion (which may not be valid for rapidly-spinning black hole remnants), while a multi-messenger observations of gravitational wave and X-ray observations place a bound of $\xi_4^{1/4} < 22.6$ km (Silva et al. 2021a) as a null test of GR. The coupling constant of Einstein–Dilaton–Gauss–Bonnet gravity, $\xi_3 \equiv \alpha_3^2/(\beta\kappa)$, on the other hand, has been constrained by several experiments: solar system observations of the Shapiro time delay with the Cassini spacecraft placed the bound $\xi_3^{1/4} < 1.3 \times 10^7$ km (Bertotti et al. 2003; Amendola et al. 2007); the requirement that neutron stars still exist in this theory placed the constraint $\xi_3^{1/4} \lesssim 26$ km (Pani et al. 2011a), with the details depending somewhat on the central

¹⁰ Formally, as $\alpha_i \rightarrow 0$, one recovers GR with a dynamical scalar field. The latter, however, only couples minimally with the metric and does not couple to the matter sector, so it does not lead to any observable effects that distinguish it from GR.

density of the neutron star; the requirement that the neutron star maximum mass exceeds $2M_{\odot}$ also places the bound $\xi_3^{1/4} \lesssim 3.43$ km (Saffer and Yagi 2021), though this bound depends on the choice of the equation of state of nuclear matter; observations of the rate of change of the orbital period in the low-mass X-ray binary A0620-00 (Psaltis 2008a; Johannsen et al. 2009) has led to the 1σ constraint $\xi_3^{1/4} < 4.3$ km (Yagi 2012b); finally, recent gravitational wave observations place a 90%-credible constraint $\xi_3^{1/4} < 3.1$ km (Nair et al. 2019; Perkins et al. 2021a; Wang et al. 2021a; Lyu et al. 2022), which provides the strongest bound (see also Shao et al. 2023; Wang et al. 2023a; Gao et al. 2024 for more recent works).

Not all sub-properties of the fundamental requirement, however, are known to be satisfied. One can show that certain members of modified quadratic gravity possess known solutions and these are stable, at least linearly and in the small-coupling approximation. For example, in dynamical Chern–Simons gravity, spherically symmetric vacuum solutions are given by the Schwarzschild metric with constant ϑ to all orders in α_i (Jackiw and Pi 2003; Yunes and Sopuerta 2008; Rogatko 2013). Moreover, one can show that such a solution, as well as non-spinning black holes and branes in anti-de Sitter space (Delsate et al. 2011), are linearly stable to small perturbations (Molina et al. 2010; Garfinkle et al. 2010). Spinning solutions, on the other hand, continue to be elusive, with linearly-stable (Ayzenberg et al. 2014; Wagle et al. 2022), approximate solutions in the slow-rotation/small-coupling limit known both for black holes (Yunes and Pretorius 2009a; Konno et al. 2009; Pani et al. 2011c; Yagi et al. 2012d; Maselli et al. 2017; Alexander et al. 2021) and stars (Yunes et al. 2010d; Ali-Haïmoud and Chen 2011; Pani et al. 2011a; Yagi et al. 2013) and solutions in the fast-rotation/small-coupling limit known for black holes only (Konno and Takahashi 2014; Stein 2014; McNees et al. 2016; Delsate et al. 2018). In Einstein–Dilaton–Gauss–Bonnet theory, both non-spinning (Yunes and Stein 2011) and spinning (Pani et al. 2011c; Ayzenberg and Yunes 2014; Maselli et al. 2015a; Kleihaus et al. 2011, 2016a) black hole solutions are known, and they have been found to be linearly stable (Pani and Cardoso 2009; Blázquez-Salcedo et al. 2016; Okounkova 2019; Pierini and Gualtieri 2021, 2022). Neutron stars solutions have been constructed for non-spinning (Pani et al. 2011a; Saffer et al. 2019), spinning (Kleihaus et al. 2014, 2016b) and tidally-deformed (Saffer and Yagi 2021) configurations. Ripley and Pretorius (2020) found evidence that scalarized black holes are non-linearly stable when the coupling constant is sufficiently small.

The study of modified quadratic gravity theories as effective theories is valid provided one is sufficiently far from its cut-off scale, i.e., the scale beyond which higher-order curvature terms cannot be neglected any longer. One can estimate the magnitude of this scale by studying the size of loop corrections to the quadratic curvature terms in the action due to n -point interactions (Yagi et al. 2012d). Simple counting requires that the number of scalar and graviton propagators, P_s and P_g , satisfy the following relation in terms of the number of vertices V :

$$P_s = \frac{V}{2}, \quad P_g = (n-1) \frac{V}{2}. \quad (56)$$

Loop corrections are thus suppressed by factors of $\alpha_i^V M_{\text{pl}}^{(2-n)V} \Lambda^{nV}$, with M_{pl} the Planck mass and Λ an energy scale introduced by dimensional arguments. The cut-off scale above which the theory cannot be treated as an effective one can be approximated as the value of Λ at which the suppression factor becomes equal to unity:

$$\Lambda_c \equiv M_{\text{pl}}^{1-2/n} \alpha_i^{1/n}, \quad (57)$$

This cut-off scale automatically places a constraint on the magnitude of α_i above which higher-curvature corrections must be included. Setting the largest value of Λ_c to be equal to $\mathcal{O}(10\mu\text{m})$, thus saturating bounds from table-top experiments (Kapner et al. 2007), and solving for α_i , we find

$$\alpha_i^{1/2} < \mathcal{O}(10^8 \text{ km}). \quad (58)$$

Current bounds on α_i require the coupling constant to be much smaller than 10^8 km (Ali-Haïmoud and Chen 2011; Yagi 2012b; Nakamura et al. 2019; Nair et al. 2019; Silva et al. 2021a; Perkins et al. 2021a; Wang et al. 2021a; Lyu et al. 2022; Silva et al. 2023), thus justifying the treatment of these theories as effective models.

As for the other requirements discussed in Sect. 2.1, it is clear that modified quadratic gravity is well-motivated from fundamental theory, but it is not clear whether it has a well-posed initial-value formulation. From an effective point of view, a perturbative treatment in α_i naturally leads to stable solutions and a well-posed initial value problem, but this is probably not the case when the theory is treated as exact (Delsate et al. 2015). In fact, if one were to treat such a theory as exact (to all orders in α_i), then the evolution system is not hyperbolic in general, as higher than second time derivatives now drive the evolution (Delsate et al. 2015). Notice, however, that this says nothing about the fundamental theories that modified quadratic gravity derives from. This is because even if the truncated theory were ill-posed, higher order corrections that are neglected in the truncated version could restore well-posedness. For the Einstein–dilaton–Gauss–Bonnet case, the field equations remain second order in derivatives. Ripley and Pretorius (2019, 2020), East and Ripley (2021b) showed that, under spherical symmetry, the field equations remain hyperbolic and are well-posed when the coupling constant is small. On the other hand, when the coupling constant is large, there arises elliptic regions in spacetime where hyperbolicity of the equations is broken (see also Hegade et al. 2023).

As for the last requirement (that the theory modifies extreme gravity), modified quadratic theories are ideal in this respect. This is because they introduce corrections to the action that depend on higher powers of the curvature. In the extreme gravity regime, such higher powers could potentially become non-negligible relative to the Einstein–Hilbert action. Moreover, since the curvature scales inversely with the mass of the black holes under consideration, one expects

the largest deviations in systems with small mass, such as stellar-mass black hole mergers or extreme-mass-ratio inspirals (Sopuerta and Yunes 2009; Maselli et al. 2020a, 2022; Barsanti et al. 2022; Tan et al. 2024).

2.3.7 Variable G theories and large extra dimensions

Variable G theories are defined as those where Newton's gravitational constant is promoted to a spacetime function. Such a modification breaks the principle of equivalence (see Will 2014) because the laws of physics now become local position dependent. In turn, this implies that experimental results now depend on the spacetime position of the laboratory frame at the time of the experiment.

Many known modified gravity theories that violate the principle of equivalence, and in particular, the strong equivalence principle, predict a varying gravitational constant. A classic example is scalar-tensor theory (Will 2018b), which, as explained in Sect. 2.3.1, modifies the gravitational sector of the action by multiplying the Ricci scalar by a scalar field (in the Jordan frame). In such theories, one can effectively think of the scalar as promoting the coupling between gravity and matter to a field-dependent quantity $G \rightarrow G(\phi)$, thus violating local position invariance when ϕ varies. Another example are bimetric theories, such as that of Lightman–Lee (Lightman and Lee 1973), where the gravitational constant becomes time-dependent even in the absence of matter, due to possibly time-dependent cosmological evolution of the prior geometry. A final example is higher-dimensional, brane-world scenarios, where enhanced Hawking radiation (Emparan et al. 2002; Tanaka 2003) may lead to a time-varying effective 4D gravitational constant (Deffayet and Menou 2007), whose rate of change depends on the curvature radius of extra dimensions (Johannsen et al. 2009; McWilliams 2010; Yagi et al. 2011).

One can also construct $f(R)$ -type actions that introduce variability to Newton's constant. For example, consider the $f(R)$ model (Frolov and Guo 2011)

$$S = \int d^4x \sqrt{-g} \kappa R \left[1 + \alpha_0 \ln \left(\frac{R}{R_0} \right) \right] + S_{\text{mat}}, \quad (59)$$

where $\kappa = (16\pi G)^{-1}$, α_0 is a coupling constant and R_0 is a curvature scale. This action is motivated by certain renormalization group flow arguments (Frolov and Guo 2011). The field equations are

$$G_{\mu\nu} = \frac{1}{2\bar{\kappa}} T_{\mu\nu}^{\text{mat}} - \frac{\alpha_0}{\bar{\kappa}} R_{\mu\nu} - 2\frac{\kappa}{\bar{\kappa}} \frac{\alpha_0}{R^2} \nabla_{(\mu} R \nabla_{\nu)} R - \frac{1}{2} \frac{\alpha_0 \kappa}{\bar{\kappa}} g_{\mu\nu} \square R, \quad (60)$$

where we have defined the new constant

$$\bar{\kappa} := \kappa \left[1 + \frac{\alpha_0}{\kappa} \ln \left(\frac{R}{R_0} \right) \right]. \quad (61)$$

Clearly, the new coupling constant $\bar{\kappa}$ depends on the curvature scale involved in the problem, and thus, on the geometry, forcing G to run to zero in the ultraviolet limit.

Another example is a scalar-tensor theory with a non-minimal coupling to a topological invariant. For example, consider the model

$$S = \int d^4x \sqrt{-g} \left[\kappa \vartheta R + \vartheta \mathcal{T} - \frac{1}{2} (\nabla_\mu \vartheta)(\nabla^\mu \vartheta) \right] + S_{\text{mat}}, \quad (62)$$

where $\kappa = (16\pi G)^{-1}$ and \mathcal{T} is a topological invariant constructed from the curvature tensor, like the Gauss–Bonnet invariant or the Pontryagin density. Such a model, for example, arises in the axiverse scenario (Arvanitaki and Dubovsky 2011; Kodama and Yoshino 2012), where here we have redefined the field so that its kinetic energy is standard, and we have neglected any potential. The field equations are

$$G_{\mu\nu} = \frac{1}{2\bar{\kappa}} T_{\mu\nu}^{\text{mat}} + \frac{1}{2\bar{\kappa}} T_{\mu\nu}^{(\vartheta)} - \frac{1}{\kappa\sqrt{-g}} \frac{\delta}{\delta g^{\mu\nu}} (\sqrt{-g} \mathcal{T}), \quad (63)$$

$$\square \vartheta = -\kappa R - \mathcal{T} \quad (64)$$

where $T_{\mu\nu}^{(\vartheta)}$ is the stress-energy tensor of the ϑ scalar field [see Eq. (47)], and we have defined the new constant $\bar{\kappa} := \kappa \vartheta$. We see then that $G \rightarrow G(\vartheta) = G/\vartheta$, where ϑ is sourced by a topological invariant constructed from the curvature tensor and its trace.

An important point to address is whether variable G theories can lead to modifications to a *vacuum* spacetime, such as a black hole binary inspiral. In Einstein’s theory, G appears as the coupling constant between geometry, encoded by the Einstein tensor $G_{\mu\nu}$, and matter, encoded by the stress energy tensor $T_{\mu\nu}^{\text{mat}}$. When considering vacuum spacetimes, $T_{\mu\nu}^{\text{mat}} = 0$ and one might naively conclude that a variable G would not introduce any modification to such spacetimes. In fact, this is the case in scalar-tensor theories (without homogeneous, cosmological solutions to the scalar field equation), where the no-hair theorem establishes that black hole solutions are not modified (Hawking 1972b). On the other hand, scalar-tensor theories with a non-trivial boundary conditions for the scalar field (Healy et al. 2012; Jacobson 1999; Horbatsch and Burgess 2012) or in non-vacuum spacetimes (Cardoso et al. 2013a, b) can evade the no-hair theorem, endowing black holes with time-dependent hair, which in turn would introduce variability into G even in vacuum spacetimes (Berti et al. 2013).

In general, Newton’s constant plays a much more fundamental role than merely a coupling constant: it defines the relationship between energy and length. For example, for the *vacuum* Schwarzschild solution, G establishes the relationship between the radius R of the black hole and the rest-mass energy E of the spacetime via $R = 2GE/c^4$. Similarly, in a black-hole-binary spacetime, each black hole introduces an energy scale into the problem that is quantified by a specification of Newton’s constant. Therefore, one can think of variable G modifications as induced by some effective theory that modifies the mapping between the curvature scale and the energy scale of the problem, as is done for example in scalar-tensor theories with

a non-minimal coupling to a topological invariant (as shown above) or as done in theories with extra dimensions.

An explicit example of the latter is realized in braneworld models. Superstring theory suggests that physics should be described by 4 large dimensions, plus another 6 that are compactified and very small (Polchinski 1998a, b). The size of these extra dimensions is greatly constrained by particle theory experiments. Braneworld models, where a certain higher-dimensional membrane is embedded in a higher dimensional bulk spacetime, can however evade this constraint as only gravitons can interact with the bulk. The ADD model (Arkani-Hamed et al. 1998, 1999) is a particular example of such a braneworld, where the bulk is flat and compact and the brane is tensionless with ordinary fields localized on it. The size of these extra dimensions is constrained to micrometer scales by table-top experiments (Kapner et al. 2007; Adelberger et al. 2007).

What is relevant to gravitational-wave experiments is that in many of these braneworld models, black holes may not remain static (Emparan et al. 2002; Tanaka 2003). The argument goes roughly as follows: a five-dimensional black hole is dual to a four-dimensional one with conformal fields on it by the ADS/CFT conjecture (Maldacena 1998; Aharony et al. 2000), but since the latter must evolve via Hawking radiation, the black hole may lose mass. The Hawking mass loss rate is here enhanced by the large number of degrees of freedom in the conformal field theory, leading to an effective modification to Newton's laws and to the emission of gravitational radiation. Effectively, one can think of the black hole mass loss as due to the black hole being stretched away from the brane into the bulk, reducing the size of the brane-localized black hole. For black-hole binaries, one can then draw an analogy between this induced time-dependence in the black hole mass and a variable G theory, where Newton's constant becomes time-dependent (Yunes et al. 2010c). However, Figueras et al. (2011), Figueras and Wiseman (2011), Figueras and Tunyasuvunakool (2013) numerically found stable static solutions that do not require a radiation component and this was recently extended for rotating black holes (Biggs and Santos 2022). If such solutions were the ones realized in nature as a result of gravitational collapse on the brane, then the black hole mass would be time-independent, up to quantum correction due to Hawking evaporation, a negligible effect for realistic astrophysical systems. This is likely to be the case based on numerical simulations of the dynamics of gravitational collapse in such scenarios (Wang and Choptuik 2016) that are consistent with the static black hole solutions found in Figueras and Wiseman (2011).

Many experiments have been carried out to measure possible deviations from a constant G value, and they can broadly be classified into two groups: (a) those that search for the present or nearly present rate of variation (at redshifts close to zero); (b) those that search for *secular* variations over long time periods (at very large redshifts). Examples of experiments or observations of the first class include planetary radar-ranging (Pitjeva 2005; Genova et al. 2018), surface temperature observations of low-redshift millisecond pulsars (Jofré et al. 2006; Reisenegger et al. 2009), lunar ranging observations (Williams et al. 2004) and pulsar timing observations (Kaspi et al. 1994; Deller et al. 2008; Zhu et al. 2015, 2019), the latter two being the most stringent. Examples of experiments of the second class include

the evolution of the Sun (Guenther et al. 1998) and Big-Bang Nucleosynthesis (BBN) calculations (Copi et al. 2004; Bambi et al. 2005; Alvey et al. 2020), again with the latter being more stringent. For either class, the strongest constraints are about $\dot{G}/G \lesssim 10^{-13} \text{ yr}^{-1}$, varying somewhat from experiment to experiment.

Lacking a particularly compelling action to describe variable G theories, one is usually left with a phenomenological model of how such a modification to Einstein's theory would impact gravitational waves. Given that the part of the waveform that detectors are most sensitive to is the gravitational wave phase, one can model the effect of variable G theories by studying how the rate of change of its frequency would be modified. Assuming a Taylor expansion for Newton's constant, one can derive the modification to the evolution equation for the gravitational wave frequency, given whichever physical scenario one is considering. Solving such an evolution equation then leads to a modification in the accumulated gravitational wave phase observed at detectors on Earth. In Sect. 4 we will provide an explicit example of this for a compact binary system.

Let us now discuss whether such theories satisfy the criteria defined in Sect. 2.1. The fundamental property can be satisfied if the rate of change of Newton's constant is small enough, as variable G theories usually have a continuous limit to GR (as all derivatives of G go to zero). Whether variable G theories are well-motivated from fundamental physics (Property 2) depends somewhat on the particular effective model or action that one considers. But in general, Property 2 is usually satisfied, considering that such variability naturally arises in theories with extra dimensions, and the latter are also natural in all string theories. Variable G theories, however, usually fail at introducing modifications in the extreme gravity regime. Usually, such variability is parameterized as a Taylor expansion about some initial point with constant coefficients. That is, the variability of G is not usually constructed to become stronger closer to merger. The well-posed property and the sub-properties of the fundamental property depend somewhat on the particular effective theory used to describe varying G modifications. In the $f(R)$ case, one can impose restrictions on the functional form $f(\cdot)$ such that no ghosts ($f' > 0$) or instabilities ($f'' > 0$) arise (Frolov and Guo 2011). This, of course, does not guarantee that this (or any other such) theory is well-posed. A much more detailed analysis would be required to prove well-posedness of the class of theories that lead to a variable Newton's constant, but such is currently lacking.

2.3.8 Non-commutative geometry

Non-commutative geometry is a gravitational theory that generalizes the continuum Riemannian manifold of Einstein's theory with the product of it with a tiny, discrete, finite non-commutative space, composed of only two points. Although the non-commutative space has zero spacetime dimension, as the product manifold remains four dimensional, its internal dimensions are 6 to account for Weyl and chiral fermions. This space is discrete to avoid the infinite tower of massive particles that would otherwise be generated, as in string theory. Through this construction, one can recover the Standard Model of elementary particles, while accounting for

all (elementary particle) experimental data to date. Of course, the simple non-commutative space described above is expected to be replaced by a more complex model at Planckian energies. Thus, one is expected to treat such non-commutative geometry models as effective theories. Essentially nothing is currently known about the full non-commutative theory, of which the theories described in this section are an effective low-energy limit.

Before proceeding with an action-principle description of non-commutative geometry theories, we must distinguish between the spectral geometry approach championed by Connes (1996), and Moyal-type non-commutative geometries (Snyder 1947; Groenewold 1946; Moyal and Bartlett 1949). In the former, the manifold is promoted to a non-commutative object through the product of a Riemann manifold with a non-commutative space. In the latter, instead, a non-trivial set of commutation relations is imposed between operators corresponding to position. These two theories are in principle unrelated. In this review, we mostly concentrate on the former, though we will comment on the latter too.

The effective action for spectral non-commutative geometry theories (henceforth, non-commutative geometries for short) is

$$S = \int d^4x \sqrt{-g} \left(\kappa R + \alpha_0 C_{\mu\nu\delta\sigma} C^{\mu\nu\delta\sigma} + \tau_0 R^* R^* - \xi_0 R |H|^2 \right) + S_{\text{mat}}, \quad (65)$$

where H is related to the Higgs field, $C_{\mu\nu\delta\sigma}$ is the Weyl tensor, $(\alpha_0, \tau_0, \xi_0)$ are coupling constants and we have defined the quantity

$$R^* R^* := \frac{1}{4} \epsilon^{\mu\nu\rho\sigma} \epsilon_{\alpha\beta\gamma\delta} R_{\mu\nu}^{\alpha\beta} R_{\rho\sigma}^{\gamma\delta}. \quad (66)$$

Notice that this term integrates to the Euler characteristic, and since τ_0 is a constant, it is topological and does not affect the classical field equations. The last term of Eq. (65) is usually ignored, as H is assumed to be relevant only in the early universe. Finally, the second term can be rewritten in terms of the Riemann and Ricci tensors as

$$C_{\mu\nu\delta\sigma} C^{\mu\nu\delta\sigma} = \frac{1}{3} R^2 - 2R_{\mu\nu} R^{\mu\nu} + R_{\mu\nu\delta\sigma} R^{\mu\nu\delta\sigma}. \quad (67)$$

Notice that this corresponds to the modified quadratic gravity action of Eq. (44) with all $\alpha_i^{(1)} = 0$ and $(\alpha_1^{(0)}, \alpha_2^{(0)}, \alpha_3^{(0)}) = (1/3, -2, 1)$, which is not the Gauss–Bonnet invariant. Notice also that this model is not usually studied in modified quadratic gravity theory, as one usually concentrates on the terms that have an explicit scalar field coupling.

The field equations of this theory can be read directly from Eq. (45), but we repeat them here for completeness:

$$G_{\mu\nu} - \frac{2\alpha_0}{\kappa} [2\nabla^{\kappa\lambda} + R^{\lambda\kappa}] C_{\mu\lambda\nu\kappa} = \frac{1}{2\kappa} T_{\mu\nu}^{\text{mat}}. \quad (68)$$

One could in principle rewrite this in terms of the Riemann and Ricci tensors, but the expressions become quite complicated, as calculated explicitly in Eqs. (2) and

(3) of Yunes and Stein (2011). Due to the absence of a dynamical degree of freedom coupling to the modifications to the Einstein–Hilbert action, this theory is not covariantly conserved in vacuum. By this, we mean that the covariant divergence of Eq. (68) does not vanish in vacuum, thus violating the weak-equivalence principle and leading to additional equations that might over-constrain the system. In the presence of matter, the equations of motion will not be given by the vanishing of the covariant divergence of the matter stress-energy alone, but now there will be additional geometric terms.

Given these field equations, one can linearize them about a flat background to find the evolution equations for the metric perturbation (Nelson et al. 2010a, b)

$$(1 - \beta^{-2} \square_\eta) \square_\eta h_{\mu\nu} = -16\pi T_{\mu\nu}^{\text{mat}}, \quad (69)$$

where the term proportional to $\beta^2 = (-32\pi\alpha_0)^{-1}$ acts like a mass term. Here, one has imposed the transverse-traceless gauge (a refinement of Lorenz gauge), which can be shown to exist (Nelson et al. 2010a, b). Clearly, even though the full non-linear equations are not covariantly conserved, its linearized version is, as one can easily show that the divergence of the left-hand side of Eq. (69) vanishes. Because of these features, if one works perturbatively in β^{-1} , then such a theory will only possess the two usual transverse-traceless (spin-2) polarization modes, i.e., it is perturbatively of type N_2 in the $E(2)$ classification (Eardley et al. 1973).

Let us now discuss whether such a theory satisfies the properties discussed in Sect. 2.1. Non-commutative geometry theories clearly possess the fundamental property, as one can always take $\alpha_0 \rightarrow 0$ (or equivalently $\beta^{-2} \rightarrow 0$) to recover GR. Therefore, there must exist a sufficiently small α_0 such that all precision tests carried out to date are satisfied. As for the existence and stability of known solutions, Nelson et al. (2010a, b) have shown that Minkowski spacetime is stable only for $\alpha_0 < 0$, as otherwise a tachyonic term appears in the evolution of the metric perturbation, as can be seen from Eq. (69). This then automatically implies that β must be real.

Current constraints on Weyl terms of this form come mostly from solar system experiments. Ni (2012) recently studied an action of the form of Eq. (65) minimally coupled to matter in light of solar system experiments. He calculated the relativistic Shapiro time-delay and light deflection about a massive body in this theory and found that observations of the Cassini satellite place constraints on $|\alpha_0|^{1/2} < 5.7$ km (Ni 2012). This is currently the strongest bound we are aware of on α_0 .

Many solutions of GR are preserved in non-commutative geometries. Regarding black holes, all solutions that are Ricci flat (vacuum solutions of the Einstein equations) are also solutions to Eq. (68). This is because by the second Bianchi identity, one can show that

$$\nabla^{\kappa\lambda} R_{\mu\lambda\nu\kappa} = \nabla^\kappa {}_\nu R_{\mu\kappa} - \square R_{\mu\nu}, \quad (70)$$

and the right-hand side vanishes in vacuum, forcing the entire left-hand side of Eq. (68) to vanish. However, this is not so for neutron stars, where the equations of motion are likely to be modified, unless they are static (Nelson 2010). Moreover, as

of now there has been no stability analysis of black-hole or stellar solutions and no study of whether the theory is well-posed as an initial-value problem, even as an effective theory. Thus, except for the fundamental property, it is not clear that non-commutative geometries satisfy any of the other criteria listed in Sect. 2.1.

Let us now discuss the second approach of non-commutative theories, the Moyal-type. We promote the coordinates x^μ to an operator \hat{x}^μ and impose the following canonical commutation relation:

$$[\hat{x}^\mu, \hat{x}^\nu] = i \theta^{\mu\nu}, \quad (71)$$

where $\theta^{\mu\nu}$ represents the amount of violation of commutation (like \hbar in quantum mechanics) that corresponds to the “quantum fuzziness” of spacetime. Within this model and working in an effective field theory formulation in which one assumes a black hole is sourced by a massive scalar field (Bjerrum-Bohr et al. 2003; Kobakhidze 2009), the stress-energy tensor for a black hole (assumed to be a point particle) at $\mathbf{y}(t)$ is given by (Kobakhidze et al. 2016)

$$T^{\mu\nu}(\mathbf{x}, t) = m\gamma(t)v^\mu(t)v^\nu(t)\delta^3[\mathbf{x} - \mathbf{y}(t)] + \frac{m^3\Lambda^2}{8}v^\mu(t)v^\nu(t)\theta^k\theta^l\partial_k\partial_l\delta^3[\mathbf{x} - \mathbf{y}(t)], \quad (72)$$

Here $\gamma(t)$ is the Lorentz factor, m and v^μ are the mass and four-velocity of the black hole, while Λ and the unit vector θ^i are defined by

$$\Lambda \theta^i = \frac{\theta^{0i}}{l_p t_p}, \quad (73)$$

where l_p and t_p are the Planck length and time respectively. The above non-commutative correction to the stress-energy tensor leads to modifications in the orbital dynamics at 2nd post-Newtonian order.

We end this section by explaining whether the Moyal-type non-commutative theory satisfies the properties discussed in Sect. 2.1. The theory has a continuous limit to GR ($\Lambda \rightarrow 0$). From the pericenter precession of binary pulsars, Λ has been constrained to $\sqrt{\Lambda} \lesssim \mathcal{O}(10)$ (Jenks et al. 2020), while gravitational wave observations place a slightly stronger bound, as we will discuss in Sec. 4.2.5. The theory possesses the property that the non-GR correction grows as one moves to the extreme gravity regime, as the correction enters at 2nd post-Newtonian order. Further analysis is necessary to reveal the stability of compact objects and well-posedness of the theory.

2.3.9 Gravitational parity violation

Parity, the symmetry transformation that flips the sign of the spatial triad, has been found to be broken in the Standard Model of elementary interactions. Only the combination of a parity transformation, time inversion and charge conjugation (CPT) remains still a true symmetry of the Standard Model. Experimentally, it is curious that the weak interaction exhibits maximal parity violation, while other

fundamental forces seem to not exhibit any. Theoretically, parity violation unavoidably arises in the Standard Model (Bell and Jackiw 1969; Adler 1969; Alvarez-Gaumé and Witten 1984), as there exist one-loop chiral anomalies that give rise to parity violating terms coupled to lepton number (Weinberg 1996). In certain sectors of string theory, such as in heterotic and in Type I superstring theories, parity violation terms are also generated through the Green–Schwarz gauge anomaly-canceling mechanism (Green et al. 1987b; Polchinski 1998b; Alexander and Gates Jr 2006). Finally, in loop quantum gravity (Ashtekar et al. 1989), the scalarization of the Barbero–Immirzi parameter coupled to fermions leads to an effective action that contains parity-violating terms (Taveras and Yunes 2008; Calcagni and Mercuri 2009; Mercuri and Taveras 2009; Gates Jr et al. 2009). Even without a particular theoretical model, one can generically show that effective field theories of inflation generically contain non-vanishing, second-order, parity violating curvature corrections to the Einstein–Hilbert action (Weinberg 2008). Alternatively, phenomenological parity-violating extensions of GR have been proposed through a scalarization of the fundamental constants of nature (Contaldi et al. 2008).

One is then naturally led to ask whether the gravitational interaction is parity invariant in extreme gravity. A violation of parity invariance would occur if the Einstein–Hilbert action were modified through a term that involved a Levi-Civita tensor and parity invariant tensors or scalars. Let us try to construct such terms with only single powers of the Riemann tensor and a single scalar field ϑ :

$$\begin{array}{ll} (\text{ia}) & R_{\alpha\beta\gamma\delta} \epsilon^{\alpha\beta\gamma\delta}, \quad (\text{ib}) R_{\alpha\beta\gamma\mu} \epsilon^{\alpha\beta\gamma\nu} \nabla^\mu{}_\nu \vartheta, \\ (\text{ic}) & R_{\alpha\beta\gamma\mu} \epsilon^{\alpha\beta\delta\nu} \nabla^{\mu\nu}{}_{\delta\vartheta}, \quad (\text{id}) R_{\alpha\beta\gamma\mu} \epsilon^{\alpha\beta\delta\nu} \nabla^{\mu\nu}{}_{\beta\delta}{}^\zeta \vartheta. \end{array}$$

Option (ia) and (ib) vanish by the Bianchi identities. Options (ic) and (id) include the commutator of covariant derivatives, which can be rewritten in terms of a Riemann tensor, and thus it leads to terms that are at least quadratic in the Riemann tensor. Therefore, no scalar can be constructed that includes contractions with the Levi-Civita tensor from a single Riemann curvature tensor and a single field. One can try to construct a scalar from the Ricci tensor

$$(\text{iia}) \quad R_{\alpha\beta} \epsilon^{\alpha\beta\gamma\delta} \nabla_\gamma \nabla_\delta \vartheta, \quad (\text{iib}) R_{\alpha\beta} \epsilon^{\alpha\mu\gamma\delta} \nabla_\gamma \nabla_\delta \vartheta,$$

but again (iia) vanishes by the symmetries of the Ricci tensor, while (iib) involves the commutator of covariant derivatives, which introduces another power of the curvature tensor. Obviously, the only term one can write with the Ricci scalar would lead to a double commutator of covariant derivatives, leading to extra factors of the curvature tensor.

One is then forced to consider either theories with two mutually independent fields or theories with quadratic curvature tensors. Of the latter, the only combination that can be constructed and that does not vanish by the Bianchi identities is the so called Pontryagin density, i.e., R^*R , and therefore, the action (Jackiw and Pi 2003; Alexander and Yunes 2009)

$$S = \int d^4x \sqrt{-g} \left(\kappa R + \frac{\alpha}{4} \vartheta R^* R \right), \quad (74)$$

is the most general, quadratic action with a single scalar field that introduces gravitational parity violation,¹¹ where we have rescaled the α prefactor to follow historical conventions. This action defines non-dynamical Chern–Simons modified gravity, initially proposed by Jackiw and Pi (Jackiw and Pi 2003; Alexander and Yunes 2009). Notice that this is the same as the term proportional to α_4 in the quadratic gravity action of Eq. (44), except that here ϑ is prior geometry, i.e., it does not possess self-consistent dynamics or an evolution equation. Such a term violates parity invariance because the Pontryagin density is a pseudo-scalar, while ϑ is assumed to be a scalar.

The field equations for this theory are¹²

$$G_{\mu\nu} + \frac{\alpha}{4\kappa} \mathcal{K}_{\mu\nu}^{(1)} = \frac{1}{2\kappa} T_{\mu\nu}^{\text{mat}}, \quad (75)$$

which is simply Eq. (45) with $(\alpha_1, \alpha_2, \alpha_3)$ set to zero and no stress-energy for ϑ . Clearly, these field equations are not covariantly conserved in vacuum, i.e., taking the covariant divergence one finds the constraint

$$\alpha R^* R = 0. \quad (76)$$

This constraint restricts the space of allowed solutions, for example disallowing the Kerr metric (Grumiller and Yunes 2008). Therefore, it might seem that the evolution equations for the metric are now overconstrained, given that the field equations provide 10 differential conditions for the 10 independent components of the metric tensor, while the constraint adds one additional, independent differential condition. Moreover, unless the Pontryagin constraint, Eq. (76), is satisfied, matter fields will not evolve according to $\nabla^\mu T_{\mu\nu}^{\text{mat}} = 0$, thus violating the equivalence principle.

From the field equations, we can derive an evolution equation for the metric perturbation when linearizing about a flat background, namely

$$\begin{aligned} \square_\eta h_{\mu\nu} + \frac{\alpha}{\kappa} (\vartheta_{,\gamma} \epsilon_{(\mu}^{\gamma\delta\zeta} \square_\eta h_{\nu)\delta,\zeta} - \vartheta_{,\gamma}^{\zeta} \epsilon_{(\mu}^{\gamma\delta\zeta} h_{|\delta\zeta|,\nu)\zeta} + \vartheta_{,\gamma}^{\zeta} \epsilon_{(\mu}^{\gamma\delta\zeta} h_{\nu)\delta,\zeta}) \\ = -\frac{2}{\kappa} T_{\mu\nu}^{\text{mat}} \end{aligned} \quad (77)$$

in a transverse-traceless gauge, which can be shown to exist in this theory (Alexander et al. 2008; Yunes and Finn 2009). The constraint of Eq. (76) is identically satisfied to second order in the metric perturbation. However, without further information about ϑ , one cannot proceed any further, except for a few general observations. As is clear from Eq. (77), the evolution equation for the metric

¹¹ If we allow for multiple scalar fields or multiple derivatives of the scalar field, one can construct a more general parity-violating gravity theory, including a term with a single curvature tensor in the action (Crisostomi et al. 2018). In fact, one can even construct ghost-free, parity-violating theories that evade the Ostrogradskii instability (Crisostomi et al. 2018), though such theories predict that gravitational waves propagate at speeds different from c in general (Nishizawa and Kobayashi 2018).

¹² The tensor $\mathcal{K}_{\mu\nu}^{(1)}$ is sometimes written as $C_{\mu\nu}$ and referred to as the C-tensor.

perturbation can contain third time derivatives, which generically will lead to instabilities. In fact, as shown in Alexander and Martin (2005) the general solution to these equations will contain exponentially growing and decaying modes. The theory defined by Eq. (74), however, is an effective theory, and thus, there can be higher order operators not included in this action that may stabilize the solution. Regardless, when studying this theory, order-reduction is necessary if one is to consider it an effective model.

Let us now discuss the properties of such an effective theory. Because of the structure of the modification to the field equations, one can always choose a sufficiently small value for α such that all solar system tests are satisfied. In fact, one can see from the equations in this section that in the limit $\alpha \rightarrow 0$, one recovers GR. Non-dynamical Chern–Simons gravity leads to modifications to the non-radiative (near-zone) metric in the gravitomagnetic sector, leading to corrections to Lense–Thirring precession (Alexander and Yunes 2007a, b). This fact has been used to constrain the theory through observations of the orbital motion of the LAGEOS satellites (Smith et al. 2008) to $(\alpha/\kappa)\dot{\vartheta} < 2 \times 10^4$ km, or equivalently $(\kappa/\alpha)\dot{\vartheta}^{-1} \gtrsim 10^{-14}$ eV. Much better constraints, however, can be placed through observations of the double binary pulsar (Yunes and Spergel 2009; Ali-Haïmoud 2011): $(\alpha_4/\kappa)\dot{\vartheta} < 0.8$ km.

Some of the sub-properties of the fundamental requirement are satisfied in non-dynamical Chern–Simons Gravity. On the one hand, all spherically symmetric metrics that are solutions to the Einstein equations are also solutions in this theory for a “canonical” scalar field ($\theta \propto t$) (Grumiller and Yunes 2008). On the other hand, axisymmetric solutions to the Einstein equations are generically not solutions in this theory. Moreover, although spherically symmetric solutions are preserved, perturbations of such spacetimes that are solutions to the Einstein equations are not generically solutions to the modified theory (Yunes and Sopuerta 2008). What is perhaps worse, the evolution of perturbations to non-spinning black holes have been found to be generically overconstrained (Yunes and Sopuerta 2008). This is a consequence of the lack of scalar field dynamics in the modified theory, which via Eq. (76) tends to overconstrain it. Such a conclusion also suggests that this theory does not possess a well-posed initial-value problem. One can argue that non-dynamical Chern–Simons Gravity is well-motivated from fundamental theories (Alexander and Yunes 2009), except that in the latter, the scalar field is always dynamical, instead of having to be prescribed *a priori*. Thus, perhaps the strongest motivation for such a model is as a phenomenological proxy to test whether the gravitational interaction remains parity invariant in extreme gravity, a test that is uniquely suited to this modified model.

2.4 Currently unexplored theories in the gravitational-wave sector

The list of theories we have here described is by no means exhaustive. In fact, there are many fascinating theories that we have chosen to leave out because they have not yet been analyzed in the gravitational wave context in detail. We will update this review with a description of these theories, once a detailed gravitational-wave study

for compact binaries or supernovae sources is carried out and the predictions for the gravitational waveform observables are made for any physical system plausibly detectable by current or near future gravitational-wave experiments. Similarly, there are theories that have only recently began to be studied in the gravitational wave context, such as bigravity and Horndeski gravity. We have chosen to include these theories in this review, as work has already begun to understand their predictions for gravitational waves. Once more work is done, we will update this review to splinter such theories into whole sections in their own right.

3 Detectors and testing techniques

3.1 Gravitational-wave interferometers

Kilometer-scale gravitational-wave interferometers have been in operation for almost two decades. This type of detectors use laser interferometry to monitor the locations of test masses at the ends of the arms with exquisite precision. Gravitational waves change the relative length of the optical cavities in the interferometer (or equivalently, the proper travel time of photons) resulting in a strain

$$h = \frac{\Delta L}{L},$$

where ΔL is the path length difference between the two arms of the interferometer.

Fractional changes in the difference in path lengths along the two arms can be monitored to better than 1 part in 10^{20} . It is not hard to understand how such precision can be achieved. For a simple Michelson interferometer, a difference in path length of order the size of a fringe can easily be detected. For the typically-used, infrared lasers of wavelength $\lambda \sim 1 \mu\text{m}$, and interferometer arms of length $L = 4 \text{ km}$, the minimum detectable strain is

$$h \sim \frac{\lambda}{L} \sim 3 \times 10^{-10}.$$

This is still far off the 10^{-20} mark. In principle, however, changes in the length of the cavities corresponding to fractions of a single fringe can also be measured provided we have a sensitive photodiode at the dark port of the interferometer, and enough photons to perform the measurement. This way we can track changes in the amount of light incident on the photodiode as the lengths of the arms change and we move over a fringe. The rate at which photons arrive at the photodiode is a Poisson process and the fluctuations in the number of photons is $\sim N^{1/2}$, where N is the number of photons. Therefore we can track changes in the path length difference of order

$$\Delta L \sim \frac{\lambda}{N^{1/2}}.$$

The number of photons depends on the laser power P , and the amount of time

available to perform the measurement. For a gravitational wave of frequency f , we can collect photons for a time $t \sim 1/f$, so the number of photons is

$$N \sim \frac{P}{fh_p v},$$

where h_p is Planck's constant and $v = c/\lambda$ is the laser frequency. For a typical laser power $P \sim 1$ W, a gravitational wave frequency $f = 100$ Hz, and $\lambda \sim 1 \mu\text{m}$ the number of photons is

$$N \sim 10^{16},$$

so that the strain we are sensitive to becomes

$$h \sim 10^{-18}.$$

The sensitivity can be further improved by increasing the effective length of the arms. In the LIGO instruments, for example, each of the two arms forms a resonant Fabry-Pérot cavity. For gravitational-wave frequencies smaller than the inverse of the light storage time, the light in the cavities makes many back and forth trips in the arms while the wave is traversing the instrument. For gravitational waves of frequencies around 100 Hz and below, the light makes about a thousand back and forth trips while the gravitational wave is traversing the interferometer, which results in a three-orders-of-magnitude improvement in sensitivity,

$$h \sim 10^{-21}.$$

For frequencies larger than 100 Hz the number of round trips the light makes in the Fabry-Pérot cavities while the gravitational wave is traversing the instrument is reduced and the sensitivity is degraded.

The proper light travel time of photons in interferometers is affected by the metric perturbation, which can be expressed as a sum over polarization modes

$$h_{ij}(t, \vec{x}) = \sum_A h_{ij}^A(t, \vec{x}), \quad (78)$$

where A labels the six possible polarization modes in metric theories of gravity. The metric perturbation for each mode can be written in terms of a plane wave expansion,

$$h_{ij}^A(t, \vec{x}) = \int_{-\infty}^{\infty} df \int_{S^2} d\hat{\Omega} e^{i2\pi f(t - \hat{\Omega} \cdot \vec{x})} \tilde{h}^A(f, \hat{\Omega}) \epsilon_{ij}^A(\hat{\Omega}). \quad (79)$$

Here f is the frequency of the gravitational waves, $\vec{k} = 2\pi f \hat{\Omega}$ is the wave vector, $\hat{\Omega}$ is a unit vector that points in the direction of propagation of the gravitational waves, ϵ_{ij}^A is the A th polarization tensor, with $i, j = x, y, z$ spatial indices. The metric perturbation due to mode A from the direction $\hat{\Omega}$ can be written by integrating over all frequencies,

$$h_{ij}^A(t - \hat{\Omega} \cdot \vec{x}) = \int_{-\infty}^{\infty} df e^{i2\pi f(t - \hat{\Omega} \cdot \vec{x})} \tilde{h}^A(f, \hat{\Omega}) \epsilon_{ij}^A(\hat{\Omega}). \quad (80)$$

By integrating Eq. (79) over all frequencies we have an expression for the metric perturbation from a particular direction $\hat{\Omega}$, i.e., only a function of $t - \hat{\Omega} \cdot \vec{x}$. The full metric perturbation due to a gravitational wave from a direction $\hat{\Omega}$ can be written as a sum over all polarization modes

$$h_{ij}(t - \hat{\Omega} \cdot \vec{x}) = \sum_A h^A(t - \hat{\Omega} \cdot \vec{x}). \quad (81)$$

The response of an interferometer to gravitational waves is generally referred to as the antenna pattern response, and depends on the geometry of the detector and the direction and polarization of the gravitational wave. To derive the antenna pattern response of an interferometer for all six polarization modes we follow the discussion in Nishizawa et al. (2009) closely. For a gravitational wave propagating in the z direction, the polarization tensors are as follows

$$\begin{aligned} \epsilon_{ij}^+ &= \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \epsilon_{ij}^\times = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \\ \epsilon_{ij}^x &= \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix}, \epsilon_{ij}^y = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}, \\ \epsilon_{ij}^b &= \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \epsilon_{ij}^\ell = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \end{aligned} \quad (82)$$

where the superscripts $+$, \times , x , y , b , and ℓ correspond to the plus, cross, vector-x, vector-y, breathing, and longitudinal modes.

Suppose that the coordinate system for the detector is $\hat{x} = (1, 0, 0)$, $\hat{y} = (0, 1, 0)$, $\hat{z} = (0, 0, 1)$, as in Fig. 1. Relative to the detector, the gravitational-wave coordinate system is rotated by angles (θ, ϕ) , $\vec{x}' = (\cos \theta \cos \phi, \cos \theta \sin \phi, -\sin \theta)$, $\vec{y}' = (-\sin \phi, \cos \phi, 0)$, and $\vec{z}' = (\sin \theta \cos \phi, \sin \theta \sin \phi, \cos \theta)$. We still have the freedom to perform a rotation about the gravitational-wave propagation direction which introduces the polarization angle ψ ,

$$\begin{aligned} \hat{m} &= \vec{x}' \cos \psi + \vec{y}' \sin \psi, \\ \hat{n} &= -\vec{x}' \sin \psi + \vec{y}' \cos \psi, \\ \hat{\Omega} &= \vec{z}'. \end{aligned}$$

The coordinate systems $(\hat{x}, \hat{y}, \hat{z})$ and $(\hat{m}, \hat{n}, \hat{\Omega})$ are also shown in Fig. 1. To generalize the polarization tensors in Eq. (82) to a wave coming from a direction $\hat{\Omega}$, we use the unit vectors \hat{m} , \hat{n} , and $\hat{\Omega}$ as follows

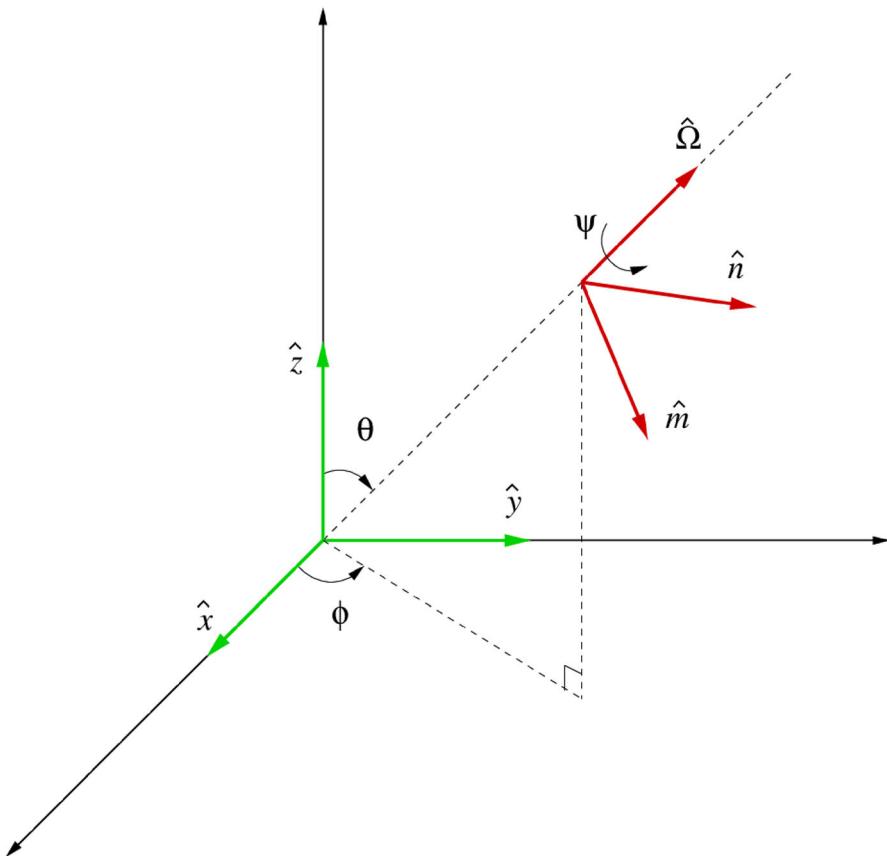


Fig. 1 Detector coordinate system and gravitational-wave coordinate system

$$\begin{aligned}
 \epsilon^+ &= \hat{m} \otimes \hat{m} - \hat{n} \otimes \hat{n}, \\
 \epsilon^\times &= \hat{m} \otimes \hat{n} + \hat{n} \otimes \hat{m}, \\
 \epsilon^x &= \hat{m} \otimes \hat{\Omega} + \hat{\Omega} \otimes \hat{m}, \\
 \epsilon^y &= \hat{n} \otimes \hat{\Omega} + \hat{\Omega} \otimes \hat{n}, \\
 \epsilon^b &= \hat{m} \otimes \hat{m} + \hat{n} \otimes \hat{n}, \\
 \epsilon^\ell &= \hat{\Omega} \otimes \hat{\Omega}.
 \end{aligned} \tag{83}$$

For LIGO and Virgo the arms are perpendicular so that the antenna pattern response can be written as the difference of projection of the polarization tensor onto each of the interferometer arms,

$$F^A(\hat{\Omega}, \psi) = \frac{1}{2} (\hat{x}^i \hat{x}^j - \hat{y}^i \hat{y}^j) \epsilon_{ij}^A(\hat{\Omega}, \psi). \quad (84)$$

This means that the strain measured by an interferometer due to a gravitational wave from direction $\hat{\Omega}$ and polarization angle ψ takes the form

$$h(t) = \sum_A h_A(t - \hat{\Omega} \cdot x) F^A(\hat{\Omega}, \psi). \quad (85)$$

Explicitly, the antenna pattern functions are,

$$\begin{aligned} F^+(\theta, \phi, \psi) &= \frac{1}{2} (1 + \cos^2 \theta) \cos 2\phi \cos 2\psi - \cos \theta \sin 2\phi \sin 2\psi, \\ F^\times(\theta, \phi, \psi) &= -\frac{1}{2} (1 + \cos^2 \theta) \cos 2\phi \sin 2\psi - \cos \theta \sin 2\phi \cos 2\psi, \\ F^x(\theta, \phi, \psi) &= \sin \theta (\cos \theta \cos 2\phi \cos \psi - \sin 2\phi \sin \psi), \\ F^y(\theta, \phi, \psi) &= -\sin \theta (\cos \theta \cos 2\phi \sin \psi + \sin 2\phi \cos \psi), \\ F^b(\theta, \phi) &= -\frac{1}{2} \sin^2 \theta \cos 2\phi, \\ F^\ell(\theta, \phi) &= \frac{1}{2} \sin^2 \theta \cos 2\phi. \end{aligned} \quad (86)$$

The dependence on the polarization angles ψ reveals that the $+$ and \times polarizations are spin-2 tensor modes, the x and y polarizations are spin-1 vector modes, and the b and ℓ polarizations are spin-0 scalar modes. Note that for interferometers the antenna pattern responses of the scalar modes are degenerate. Figure 2 shows the antenna patterns for the various polarizations given in Eq. (86) with $\psi = 0$. The color indicates the strength of the response with red being the strongest and blue being the weakest.

3.2 Pulsar timing arrays

Neutron stars can emit powerful beams of radio waves from their magnetic poles. If the rotational and magnetic axes are not aligned, the beams sweep through space like the beacon on a lighthouse. If the line of sight is aligned with the magnetic axis at any point during the neutron star's rotation the star is observed as a source of periodic radio-wave bursts. Such a neutron star is referred to as a pulsar. Due to their large moment of inertia pulsars are very stable rotators, and their radio pulses arrive at Earth with extraordinary regularity. Pulsar timing experiments exploit this regularity; gravitational waves can cause measurable deviations in the expected times of arrival of radio pulses from pulsars.

The effect of a gravitational wave on the pulses propagating from a pulsar to Earth was first computed in the late 1970s by Sazhin (1978) and Detweiler (1979). Gravitational waves induce a redshift in the pulse train

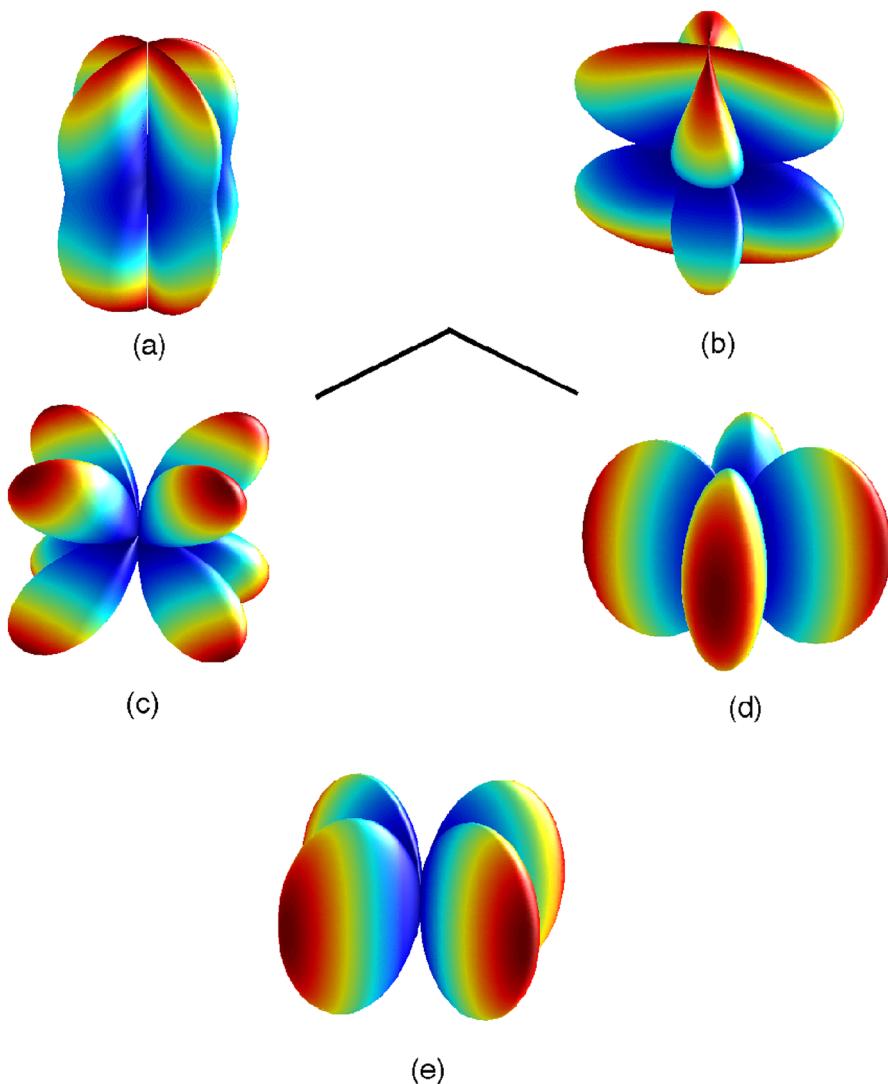


Fig. 2 Antenna pattern response functions of an interferometer (see Eq. (86)) for $\psi = 0$. **a, b** show the plus ($|F_+|$) and cross ($|F_x|$) modes, **c, d** the vector x and vector y modes ($|F_x|$ and $|F_y|$), and panel **e** shows the scalar modes (up to a sign, it is the same for both breathing and longitudinal). Color indicates the strength of the response with red being the strongest and blue being the weakest. The black lines near the center give the orientation of the interferometer arms

$$z(t, \hat{\Omega}) = \frac{1}{2} \frac{\hat{p}^i \hat{p}^j}{1 + \hat{\Omega} \cdot \hat{p}} \Delta h_{ij}, \quad (87)$$

where \hat{p} is a unit vector that points in the direction of the pulsar, $\hat{\Omega}$ is a unit vector in the direction of gravitational wave propagation, and

$$\Delta h_{ij} \equiv h_{ij}(t_e, \hat{\Omega}) - h_{ij}(t_p, \hat{\Omega}), \quad (88)$$

is the difference in the metric perturbation at the pulsar when the pulse was emitted at $t = t_p$ (second term) and the metric perturbation on Earth when the pulse was received at $t = t_e$ (first term). The inner product in Eq. (87) is computed with the Euclidean metric.

In pulsar timing experiments it is not the redshift, but rather the *timing residual* that is measured. The times of arrival (TOAs) of pulses are measured, and the timing residual is produced by subtracting off a model that includes the rotational frequency of the pulsar, the spin-down (frequency derivative), binary parameters if the pulsar is in a binary, sky location and proper motion, etc. The timing residual induced by a gravitational wave, $R(t)$, is just the integral of the redshift

$$R(t) \equiv \int_0^t dt' z(t'). \quad (89)$$

Times-of-arrival are measured a few times a year over the course of several years allowing for gravitational waves in the nano-Hertz band to be detected. Currently, the best timed pulsars have residual RMSs of a few tens of ns over a decade or longer.

The equations above (87) can be used to estimate the strain sensitivity of pulsar timing experiments. For gravitational waves of frequency f the expected induced residual is

$$R \sim \frac{h}{f}, \quad (90)$$

so that for pulsars with RMS residuals $R \sim 100$ ns, and gravitational waves of frequency $f \sim 10^{-8}$ Hz, gravitational waves with strains

$$h \sim Rf \sim 10^{-15} \quad (91)$$

would produce a measurable effect.

To find the antenna pattern response of the pulsar-Earth system, we are free to place the pulsar on the z -axis. The response to gravitational waves of different polarizations can then be written as

$$F^A(\hat{\Omega}, \psi) = \frac{1}{2} \frac{\hat{z}^i \hat{z}^j}{1 + \cos \theta} \epsilon_{ij}^A(\hat{\Omega}, \psi), \quad (92)$$

which allows us to express the Fourier transform of (87) as

$$\tilde{z}(f, \hat{\Omega}) = \left(1 - e^{-2\pi i f L (1 + \hat{\Omega} \cdot \hat{p})}\right) \sum_A \tilde{h}_A(f, \hat{\Omega}) F^A(\hat{\Omega}) \quad (93)$$

where the sum is over all possible gravitational-wave polarizations: $A = +, \times, x, y, b, l$, and L is the distance to the pulsar.

Explicitly,

$$F^+(\theta, \psi) = \sin^2 \frac{\theta}{2} \cos 2\psi \quad (94)$$

$$F^\times(\theta, \psi) = -\sin^2 \frac{\theta}{2} \sin 2\psi \quad (95)$$

$$F^x(\theta, \psi) = -\frac{1}{2} \frac{\sin 2\theta}{1 + \cos \theta} \cos \psi, \quad (96)$$

$$F^y(\theta, \psi) = \frac{1}{2} \frac{\sin 2\theta}{1 + \cos \theta} \sin \psi, \quad (97)$$

$$F^b(\theta) = \sin^2 \frac{\theta}{2} \quad (98)$$

$$F^\ell(\theta) = \frac{1}{2} \frac{\cos^2 \theta}{1 + \cos \theta}. \quad (99)$$

Just like for the interferometer case, the dependence on the polarization angle ψ , reveals that the $+$ and \times polarizations are spin-2 tensor modes, the x and y polarizations are spin-1 vector modes, and the b and ℓ polarizations are spin-0 scalar modes. Unlike interferometers, the antenna pattern responses of the pulsar-Earth system do not depend on the azimuthal angle of the gravitational wave, and the scalar modes are not degenerate.

In the literature, it is common to write the antenna pattern response by fixing the gravitational-wave direction and changing the location of the pulsar. In this case the antenna pattern responses are (Lee et al. 2008; Alves and Tinto 2011; Chamberlin and Siemens 2012),

$$\begin{aligned} \tilde{F}^+(\theta_p, \phi_p) &= \sin^2 \frac{\theta_p}{2} \cos 2\phi_p \\ \tilde{F}^\times(\theta_p, \phi_p) &= \sin^2 \frac{\theta_p}{2} \sin 2\phi_p \\ \tilde{F}^x(\theta_p, \phi_p) &= \frac{1}{2} \frac{\sin 2\theta_p}{1 + \cos \theta_p} \cos \phi_p, \\ \tilde{F}^y(\theta_p, \phi_p) &= \frac{1}{2} \frac{\sin 2\theta_p}{1 + \cos \theta_p} \sin \phi_p, \\ \tilde{F}^b(\theta_p) &= \sin^2 \frac{\theta_p}{2} \\ \tilde{F}^\ell(\theta_p) &= \frac{1}{2} \frac{\cos^2 \theta_p}{1 + \cos \theta_p}, \end{aligned} \quad (100)$$

where θ_p and ϕ_p are the polar and azimuthal angles of the vector pointing to the pulsar, respectively. Up to signs, these expressions are the same as Eq. (99) taking $\theta \rightarrow \theta_p$ and $\psi \rightarrow \phi_p$. This is because fixing the gravitational-wave propagation direction while allowing the pulsar location to change is analogous to fixing the pulsar position while allowing the direction of gravitational-wave propagation to

change—there is degeneracy in the gravitational-wave polarization angle and the pulsar’s azimuthal angle ϕ_p . For example, changing the polarization angle of a gravitational wave traveling in the z -direction is the same as performing a rotation about the z -axis that changes the pulsar’s azimuthal angle. Antenna patterns for the pulsar-Earth system using Eq. (100) are shown in Fig. 3. The color indicates the strength of the response, red being the largest and blue the smallest.

3.3 Compact binary coalescence analysis

Gravitational waves emitted during the inspiral, merger and ringdown of compact binaries are the most studied in the context of data analysis and parameter estimation. In this section, we will review some of the main data analysis techniques employed in the context of parameter estimation and tests of GR. We begin with a discussion of matched filtering and Fisher theory (for a detailed review, see Finn and Chernoff 1993; Chernoff and Finn 1993; Cutler and Flanagan 1994; Finn and Sutton 2002; Jaradowski and Królak 2012). We then continue with a discussion of Bayesian parameter estimation and hypothesis testing (for a detailed review, see Sivia and Skilling 2006; Gregory 2005; Cornish and Littenberg 2007; Littenberg and Cornish 2009; Romano and Cornish 2017).

3.3.1 Matched filtering and Fisher analysis

When the detector noise $n(t)$ is Gaussian and stationary, and when the signal $s(t)$ is known very well, the optimal detection strategy is matched filtering. For any given realization, such noise can be characterized by its power spectral density $S_n(f)$, defined via

$$\langle \tilde{n}(f) \tilde{n}^*(f') \rangle = \frac{1}{2} S_n(f) \delta(f - f'), \quad (101)$$

where recall that the tilde stands for the Fourier transform, the asterisk for complex conjugation and the brackets for the expectation value.

The detectability of a signal is determined by its *signal-to-noise ratio* or SNR, which is defined via

$$\rho^2 = \frac{(s|h)}{\sqrt{(h|h)(n|h)}}, \quad (102)$$

where h is a template with parameters λ^i and we have defined the inner product

$$(A|B) \equiv 4\Re \int_0^\infty \frac{\tilde{A}^* \tilde{B}}{S_n} df. \quad (103)$$

If the templates do not exactly match the signal, then the SNR is reduced by a factor of $\bar{\mathcal{M}}$, called the *match*:

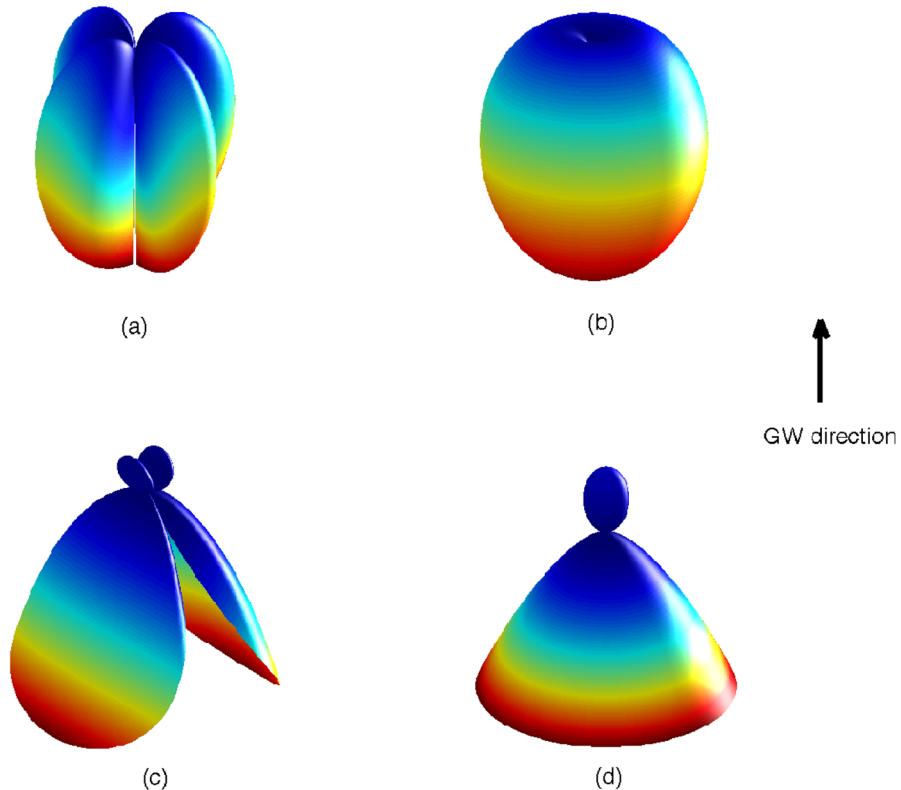


Fig. 3 Antenna patterns for the pulsar-Earth system. The plus mode is shown in (a), breathing modes in (b), the vector-x mode in (c), and longitudinal modes in (d), as computed from Eq. (100). The cross mode and the vector-y mode are rotated versions of the plus mode and the vector-x mode, respectively, so we did not include them here. The gravitational wave propagates in the positive z -direction with the Earth at the origin, and the antenna pattern depends on the pulsar's location. The color indicates the strength of the response, red being the largest and blue the smallest

$$\bar{\mathcal{M}} \equiv \frac{(s|h)}{\sqrt{(s|s)(h|h)}}, \quad (104)$$

where $1 - \bar{\mathcal{M}} = \mathcal{M}\mathcal{M}$ is the mismatch.

For the noise assumptions made here, the probability of measuring $s(t)$ in the detector output, given a template h , is given by

$$p \propto e^{-(s-h|s-h)/2}, \quad (105)$$

and thus the waveform h that best fits the signal is that with best-fit parameters such that the argument of the exponential is minimized. For large SNR, the best-fit parameters will have a multivariate Gaussian distribution centered on the true values of the signal $\hat{\lambda}^i$, and thus, the waveform parameters that best fit the signal minimize

the argument of the exponential. The statistical parameter errors $\delta\lambda^i$ will be distributed according to

$$p(\delta\lambda^i) \propto e^{-\frac{1}{2}\Gamma_{ij}\delta\lambda^i\delta\lambda^j}, \quad (106)$$

where Γ_{ij} is the *Fisher matrix*

$$\Gamma_{ij} \equiv \left(\frac{\partial h}{\partial \lambda^i} \middle| \frac{\partial h}{\partial \lambda^j} \right). \quad (107)$$

The root-mean-squared (1σ) error on a given parameter λ^i is then

$$\sqrt{\langle (\delta\lambda^i)^2 \rangle} = \sqrt{\Sigma^{ii}}, \quad (108)$$

where $\Sigma^{ij} \equiv (\Gamma_{ij})^{-1}$ is the variance-covariance matrix and summation is not implied in Eq. (108) (λ^i denotes a particular element of the vector λ^i). This root-mean-squared error is sometimes referred to as the *statistical* error in the measurement of λ^i . One can use Eq. (108) to estimate how well modified gravity parameters can be measured assuming an observation consistent with Einstein's theory. Put another way, if a gravitational wave were detected and found consistent with GR, Eq. (108) would provide an estimate of how close to zero these modified gravity parameters would have to be consistent with statistical fluctuations.

The Fisher method to estimate projected constraints on modified gravity theory parameters is as follows. First, one constructs a waveform model in the particular modified gravity theory one wishes to constrain. Usually, this waveform will be similar to the GR one, but it will contain an additional parameter, κ , such that the template parameters are now λ^i plus κ . Let us assume that as $\kappa \rightarrow 0$, the modified gravity waveform reduces to the GR expectation. Then, the accuracy to which κ can be measured, or the accuracy to which we can say κ is zero given an observation consistent with GR, is approximately $(\Sigma^{\kappa\kappa})^{1/2}$, where the Fisher matrix associated with this variance-covariance matrix must be computed with the non-GR model evaluated at the GR limit ($\kappa \rightarrow 0$). Such a method for estimating how well modified gravity theories can be constrained was pioneered by Will (Will 1994; Poisson and Will 1995), and since then, it has been widely employed as a first-cut estimate of the power of gravitational wave tests.

The Fisher method described above can dangerously lead to incorrect results if abused (Vallisneri 2008, 2011; Rodriguez et al. 2013). One must understand that this method is suitable only if the noise is stationary and Gaussian and if the SNR is sufficiently large. How large a SNR is required for Fisher methods to work depends somewhat on the signals considered, but usually for applications concerning tests of GR, one would be safe with $\rho \gtrsim 30$. In real data analysis, the first two conditions are rarely satisfied, and one must be lucky to make observations at high SNR. Fortunately, however, the first detection that aLIGO made was at rather high SNR, $\rho \sim 24$ (Abbott et al. 2016b, c), and as shown in Yunes et al. (2016), Cornish et al. (2011), Fisher estimates using the spectral noise of aLIGO during their first

observation run are surprisingly close to constraints obtained with a full Bayesian method (Abbott et al. 2016d).

3.3.2 Bayesian theory and model testing

Bayesian theory is ideal for parameter estimation and model selection. Let us then assume that we have detected a signal and that it can be described by some model \mathcal{M} , parameterized by the vector λ^i . Using Bayes' theorem, the posterior distribution function (PDF) or the probability density function for the model parameters, given data d and model \mathcal{M} , is

$$p(\{\lambda^i\}|d, \mathcal{M}) = \frac{p(d|\{\lambda^i\}, \mathcal{M})p(\{\lambda^i\}|\mathcal{M})}{p(d|\mathcal{M})}. \quad (109)$$

Obviously, the global maximum of the PDF in the parameter manifold gives the best fit parameters for that model. The prior probability density $p(\lambda^i|\mathcal{M})$ represents our prior beliefs of the parameter range in model \mathcal{M} . The marginalized likelihood or *evidence*, is the normalization constant

$$p(d|\mathcal{M}) = \int d\lambda^1 d\lambda^2 \dots d\lambda^i p(d|\{\lambda^i\}, \mathcal{M}) p(\{\lambda^i\}|\mathcal{M}), \quad (110)$$

which clearly guarantees that the integral of Eq. (109) integrates to unity. The quantity $p(d|\lambda^i, \mathcal{M})$ is the likelihood function, which is simply given by Eq. (105), with a given normalization. In that equation we used slightly different notation, with s being the data d and h the template associated with model \mathcal{M} and parameterized by λ^i . The marginalized PDF, which represents the probability density function for a given parameter $\lambda^{\bar{i}}$ (recall that $\lambda^{\bar{i}}$ is a particular element of λ^i), after marginalizing over all other parameters, is given by

$$p(\lambda^{\bar{i}}|d, \mathcal{M}) = \frac{1}{p(d|\mathcal{M})} \int_{i \neq \bar{i}} d\lambda^1 d\lambda^2 \dots d\lambda^{i \neq \bar{i}} p(\{\lambda^{i \neq \bar{i}}\}|\mathcal{M}) p(d|\{\lambda^{i \neq \bar{i}}\}, \mathcal{M}), \quad (111)$$

where the integration is not to be carried out over \bar{i} .

Let us now switch gears to model selection. In hypothesis testing, one wishes to determine whether the data is more consistent with *hypothesis A* (e.g. that a GR waveform correctly models the signal) or with *hypothesis B* (e.g. that a non-GR waveform correctly models the signal). Using Bayes' theorem, the PDF for model *A* given the data is

$$p(A|d) = \frac{p(d|A)p(A)}{p(d)}. \quad (112)$$

As before, $p(A)$ is the prior probability of hypothesis *A*, namely the strength of our prior belief that hypothesis *A* is correct. The normalization constant $p(d)$ is given by

$$p(d) = \int d\mathcal{M} p(d|\mathcal{M}) p(\mathcal{M}), \quad (113)$$

where the integral is to be taken over all models. Thus, it is clear that this normalization constant does not depend on the model. Similar relations hold for hypothesis B by replacing $A \rightarrow B$ in Eq. (112).

When hypothesis A and B refer to fundamental theories of nature we can take different viewpoints regarding the priors. If we argue that we know nothing about whether hypothesis A or B better describes Nature, then we would assign equal priors to both hypotheses. If, on the other hand, we believe GR is the correct theory of Nature, based on all previous experiments performed (including, e.g., those in the Solar System and with binary pulsars), then we would assign $p(A) > p(B)$. This assigning of priors necessarily biases the inferences derived from the calculated posteriors, which is sometimes heavily debated when comparing Bayesian theory to a frequentist approach. However, this “biasing” is really unavoidable and merely a reflection of our state of knowledge of Nature (for a more detailed discussion on such issues, please refer to Littenberg and Cornish 2009).

The integral over all models in Eq. (113) can never be calculated in practice, simply because we do not know all models. Thus, one is forced to investigate *relative* probabilities between models, so that the normalization constant $p(d)$ cancels out. The so-called *odds-ratio* is defined by

$$\mathcal{O}_{A,B} = \frac{p(A|d)}{p(B|d)} = \frac{p(A)}{p(B)} \mathcal{B}_{A,B}, \quad (114)$$

where $\mathcal{B}_{A,B} \equiv p(d|A)/p(d|B)$ is the *Bayes Factor* and the prefactor $p(A)/p(B)$ is the *prior odds*. Vallisneri (2012) investigated the possibility of calculating the odds-ratio using only frequentist tools and without having to compute full evidences. The odds-ratio should be interpreted as the betting-odds of model A over model B . For example, an odds-ratio of unity means that both models are equally supported by the data, while an odds-ratio of 10^2 means that there is a 100 to 1 odds that model A better describes the data than model B .

The main difficulty in Bayesian inference (both in parameter estimation and model selection) is sampling the PDF sufficiently accurately. Several methods have been developed for this purpose, but currently the two main workhorses in gravitational wave data analysis are Markov chain Monte Carlo and Nested Sampling. In the former, one samples the likelihood through the Metropolis–Hastings algorithm (Metropolis 1980; Hastings 1970; Cornish and Crowder 2005; Rover et al. 2006). This is computationally expensive in high-dimensional cases, and thus, there are several techniques to improve the efficiency of the method, e.g., parallel tempering (Swendsen and Wang 1986). Once the PDF has been sampled, one can then calculate the evidence integral, for example via thermodynamic integration (Veitch and Vecchio 2008; Feroz et al. 2009; van der Sluys et al. 2008). In Nested Sampling, the evidence is calculated directly by laying out a fixed number of points in the prior volume, which are then allowed to move and coalesce toward regions of high posterior probability. With the evidence in hand, one can then infer

the PDF. As in the previous case, Nested Sampling can be computationally expensive in high-dimensional cases.

Another recent approach is to implement deep neural network techniques to gravitational-wave data analysis, which can drastically enhance efficiency when used properly. The Markov-chain Monte Carlo and Nested Sampling techniques mentioned above use likelihood-based samplers to draw samples from posteriors, and this can be time-consuming when the dimensionality of the parameter space is high. One can somewhat overcome this issue with simulation-based, likelihood-free inference methods through deep learning, where one trains the neural network with simulated data. The normalizing flows method (Rezende and Mohamed 2015) is an example that can represent complicated probability distributions through neural networks. The main idea here is to “flow” from a simpler distribution (like a normal distribution) to a more complicated one through a change of variables. Dingo (Deep Inference for Gravitational-wave Observations) (Green et al. 2020; Green and Gair 2021; Dax et al. 2021a, b) is an example of a current, open-source Python package that implements normalizing flows to carry out gravitational-wave data analysis. One can, in fact, improve the efficiency and accuracy of the analysis by combining this likelihood-free method with a likelihood-based one through importance sampling. With this approach, one takes samples from normalizing flows and uses them as proposals for likelihood-based sampling (Dax et al. 2023).

Del Pozzo et al. (2011) were the first to carry out a Bayesian implementation of model selection in the context of tests of GR. Their analysis focused on tests of a particular massive graviton theory, using the gravitational wave signal from quasi-circular inspiral of non-spinning black holes. Cornish et al. (2011), Sampson et al. (2013a) extended this analysis by considering model-independent deviations from GR, using the parameterized post-Einsteinian (ppE) approach (Sect. 4.3.6) (Yunes and Pretorius 2009b). This was continued by Li et al. (2012a, b), who carried out a similar analysis to that of Cornish et al. (2011), Sampson et al. (2013a) on a large statistical sample of aLIGO detections using simulated data and a restricted ppE model. All of these studies suggest that Bayesian tests of GR are possible, given sufficiently high SNR events. And indeed, after the first gravitational wave observations, these tests were carried out in Abbott et al. (2016d), Yunes et al. (2016), the signal was shown to be consistent with GR and a plethora of theoretical models were constrained at different levels.

3.3.3 Systematics in model selection

The model selection techniques described above are affected by other systematics present in data analysis. In general, we can classify these into the following (Vallisneri and Yunes 2013; Gupta et al. 2024):

- **Mismodeling Systematic**, caused by inaccurate models of the gravitational-wave template.
- **Instrumental Systematic**, caused by inaccurate models of the gravitational-wave response.

- **Astrophysical Systematic**, caused by inaccurate models of the astrophysical environment.

Mismodeling systematics are introduced due to the lack of an exact solution to the Einstein equations from which to extract an exact template, given a particular astrophysical scenario. Inspiral templates, for example, are approximated through post-Newtonian theory and become increasingly less accurate as the binary components approach each other. Cutler and Vallisneri (2007) were the first to carry out a formal and practical investigation of such a systematic in the context of parameter estimation from a frequentist approach.

Mismodeling systematics will prevent us from testing GR effectively with signals that we do not understand sufficiently well. For example, when considering signals from black hole coalescences, if the total mass of the binary is sufficiently high, the binary will merge in band. The higher the total mass, the fewer the inspiral cycles that will be in band, until eventually only the merger is in band. Since the merger phase is the least understood phase, it stands to reason that our ability to test GR will deteriorate as the total mass increases. But the situation is not so simple, since the higher the mass of the system, the larger the SNR of the event, and thus, the better we can constrain Einstein's theory. Moreover, we do understand the ringdown phase very well, and tests of the no-hair theorem could be done during this phase, provided a sufficiently large SNR (Berti et al. 2007). For neutron star binaries or very low-mass black hole binaries, the merger phase is expected to be essentially out of band for aLIGO (above 1 kHz), and thus, the noise spectrum itself may shield us from our ignorance. See Moore et al. (2021) for recent work on waveform systematics for tests of GR with gravitational waves. We also note that mismodeling of the waveform due to non-GR effects can produce stealth bias to GR parameters (Yunes and Pretorius 2009b; Vallisneri and Yunes 2013).

Instrumental systematics are introduced by our ignorance of the transfer function, which connects the detector response to the incoming gravitational waves. Through sophisticated calibration studies with real data, one can approximate the transfer function very well (Accadia 2011; Abadie et al. 2010; Tuyenbayev et al. 2017; Sun et al. 2020; Vitale et al. 2021; Wade et al. 2023). However, this function is not time-independent, because the noise in the instrument is not stationary or Gaussian (Zackay et al. 2021; Kumar et al. 2022). Thus, un-modeled drifts in the transfer function can still introduce systematics in parameter estimation that, as of now, are as large as 2% in the amplitude and the phase (Accadia et al. 2011; Tuyenbayev et al. 2017; Sun et al. 2020; Vitale et al. 2021; Wade et al. 2023). In fact, the specific realization of the noise during the first gravitational wave observations did introduce systematics in the first tests of GR carried out (Abbott et al. 2016d). GW191109_010717 showed statistically significant deviations in some of the null tests performed by the LIGO-Virgo-KAGRA Collaboration (Abbott et al. 2021c), though it is likely that these are glitch artifacts in the noise. Some of the impact of these systematics is reduced by cross-correlating the output from multiple detectors; although instrumental systematics are present in each instrument, the noise is mostly uncorrelated between them. Therefore, as more instruments join the gravitational wave effort, cross-correlation should help ameliorate instrumental systematics.

Astrophysical systematics are induced by our lack of exact *a priori* knowledge of the gravitational wave source. As explained above, matched filtering requires knowledge of a waveform template with which to filter the data. Usually, we assume the sources are in a perfect vacuum and isolated. For example, when considering inspiral signals, we ignore any third bodies, electric or magnetic fields in black hole spacetimes, the accelerated expansion of the Universe, any intervening gravitational lens between the source and the observer, etc. Fortunately, however, most of these effects are expected to be small: the probability of finding third bodies sufficiently close to a binary system is very small (Yunes et al. 2011b); for low redshift events, the expansion of the Universe induces an acceleration of the center of mass, which is also very small (Yunes et al. 2010c); electromagnetic fields and neutron star hydrodynamic effects may affect the inspiral of black holes and neutron stars, but not until the very last stages, when most signals will be out of band anyway. For example, tidal deformation effects enter a neutron star binary inspiral waveform at 5 post-Newtonian order, which therefore affects the signal outside the most sensitive part of the Adv. LIGO sensitivity bucket. When these effects are not small, such as in the case of lensed gravitational-wave signals, recent work suggests that the combination of a Bayes Factor model-selection analysis and a fitting-factor signal-to-noise ratio residual test would avoid false-positive inferences of a GR deviation (Liu et al. 2024). See Barausse et al. (2014) for a systematic study on environmental effects on gravitational wave astrophysics.

Perhaps the most dangerous source of astrophysical systematics is due to the assumptions made about the astrophysical systems we expect to observe. For example, when considering neutron star binary inspirals, one usually assumes the orbit will have circularized by the time it enters the sensitivity band. Moreover, one assumes that any residual spin angular momentum that the neutron stars may possess is very small and aligned or anti-aligned with the orbital angular momentum. These assumptions certainly simplify the construction of waveform templates, but if they happen to be wrong, they would introduce mismodeling systematics that could also affect parameter estimation and tests of GR. See Saini et al. (2022), Bhat et al. (2023) for recent studies on systematic bias on tests of GR with gravitational waves due to neglect of orbital eccentricity.

3.4 Burst analyses

In alternative theories of gravity, gravitational-wave sources such as core collapse supernovae may result in the production of gravitational waves in more than just the plus- and cross-polarizations (Shibata et al. 1994; Scheel et al. 1995; Harada et al. 1997; Novak and Ibáñez 2000; Novak 1998; Ruiz et al. 2012). Indeed, the near-spherical geometry of the collapse can be a source of scalar breathing-mode gravitational waves. The precise form of the waveform, however, is unknown because it is sensitive to the initial conditions.

When searching for un-modeled bursts in alternative theories of gravity, a general approach involves using linear combinations of data streams from all available detectors to form maximum likelihood estimators for the waveforms in the various polarizations, and the use of *null streams*. In the context of ground-based

detectors and GR, these ideas were first explored by Gürsel and Tinto (1989) and later by Chatterji et al. (2006) with the aim of separating false-alarm events from real detections. The main idea was to construct a linear combination of data streams received by a network of detectors, so that the combination contained only noise. In GR, of course, one need only include h_+ and h_\times polarizations, and thus a network of three detectors is sufficient. This concept can be extended to develop null tests of GR, as originally proposed by Chatzioannou et al. (2012) and later implemented by Hayama and Nishizawa (2013).

Let us consider a network of $D \geq 6$ detectors with uncorrelated noise and a detection by all D detectors. For a source that emits gravitational waves in the direction $\hat{\Omega}$, a single data point (either in the time-domain, or a time-frequency pixel) from an array of D detectors (either pulsars or interferometers) can be written as

$$\mathbf{d} = \mathbf{F}\mathbf{h} + \mathbf{n}. \quad (115)$$

Here

$$\mathbf{d} \equiv \begin{bmatrix} d_1 \\ d_2 \\ \vdots \\ d_D \end{bmatrix}, \quad \mathbf{h} \equiv \begin{bmatrix} h_+ \\ h_\times \\ h_x \\ h_y \\ h_b \\ h_\ell \end{bmatrix}, \quad \mathbf{n} \equiv \begin{bmatrix} n_1 \\ n_1 \\ \vdots \\ n_D \end{bmatrix}, \quad (116)$$

where \mathbf{n} is a vector with the noise. The antenna pattern functions are given by the matrix,

$$[\mathbf{F}^+ \quad \mathbf{F}^\times \quad \mathbf{F}^x \quad \mathbf{F}^y \quad \mathbf{F}^b \quad \mathbf{F}^\ell] \equiv \begin{bmatrix} F_1^+ & F_1^\times & F_1^x & F_1^y & F_1^b & F_1^\ell \\ F_2^+ & F_2^\times & F_2^x & F_2^y & F_2^b & F_2^\ell \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ F_D^+ & F_D^\times & F_D^x & F_D^y & F_D^b & F_D^\ell \end{bmatrix}. \quad (117)$$

For simplicity we have suppressed the sky-location dependence of the antenna pattern functions. These can be either the interferometric antenna pattern functions in Eq. (86), or the pulsar response functions in Eq. (99). For interferometers, since the breathing and longitudinal antenna pattern response functions are degenerate, and even though \mathbf{F} is a $6 \times D$ matrix, there are only 5 linearly-independent vectors (Boyle 2010a, b; Chatzioannou et al. 2012; Hayama and Nishizawa 2013).

If we do not know the form of the signal present in our data, we can obtain maximum likelihood estimators for it. For simplicity, let us assume the data are Gaussian and of unit variance (the latter can be achieved by whitening the data). Just as we did in Eq. (105), we can write the probability of obtaining datum \mathbf{d} , in the presence of a gravitational wave \mathbf{h} as

$$P(\mathbf{d}|\mathbf{h}) = \frac{1}{(2\pi)^{D/2}} \exp\left[-\frac{1}{2}|\mathbf{d} - \mathbf{Fh}|^2\right]. \quad (118)$$

The logarithm of the likelihood ratio, i.e., the logarithm of the ratio of the likelihood when a signal is present to that when a signal is absent, can then be written as

$$L \equiv \ln \frac{P(\mathbf{d}|\mathbf{h})}{P(\mathbf{d}|0)} = \frac{1}{2} \left[|\mathbf{d}|^2 - |\mathbf{d} - \mathbf{Fh}|^2 \right]. \quad (119)$$

If we treat the waveform values for each datum as free parameters, we can maximize the likelihood ratio

$$0 = \left. \frac{\partial L}{\partial \mathbf{h}} \right|_{\mathbf{h}=\mathbf{h}_{\text{MAX}}}, \quad (120)$$

and obtain maximum likelihood estimators for the gravitational wave,

$$\mathbf{h}_{\text{MAX}} = (\mathbf{F}^T \mathbf{F})^{-1} \mathbf{F}^T \mathbf{d}. \quad (121)$$

We can further substitute this solution into the likelihood, to obtain the value of the likelihood at the maximum,

$$E_{\text{SL}} \equiv 2L(\mathbf{h}_{\text{MAX}}) = \mathbf{d}^T \mathbf{P}^{\text{GW}} \mathbf{d}, \quad (122)$$

where

$$\mathbf{P}^{\text{GW}} \equiv \mathbf{F} (\mathbf{F}^T \mathbf{F})^{-1} \mathbf{F}^T. \quad (123)$$

The maximized likelihood can be thought of as the power in the signal, and can be used as a detection statistic. \mathbf{P}^{GW} is a projection operator that projects the data into the subspace spanned by \mathbf{F} . An orthogonal projector can also be constructed,

$$\mathbf{P}^{\text{null}} \equiv (\mathbf{I} - \mathbf{P}^{\text{GW}}), \quad (124)$$

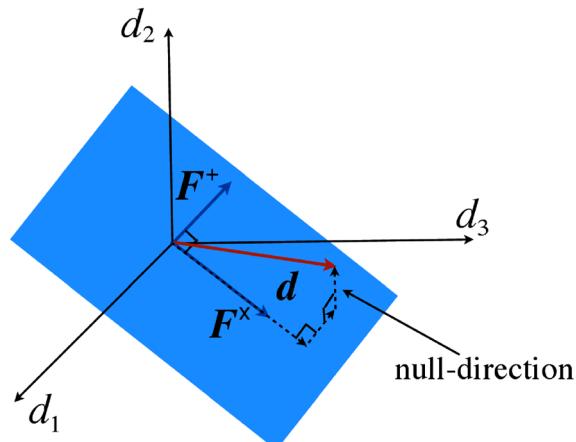
which projects the data onto a subspace orthogonal to \mathbf{F} . Thus, one can construct a certain linear combination of data streams that has no component of a certain polarization by projecting them to a direction orthogonal to the direction defined by the beam pattern functions of this polarization mode

$$\mathbf{d}^{\text{null}} = \mathbf{P}^{\text{null}} \mathbf{d}. \quad (125)$$

This is called a *null stream* and, in the context of GR, it was introduced as a means of separating false-alarm events due, say, to instrumental glitches from real detections (Gürsel and Tinto 1989; Chatterji et al. 2006).

With just three independent detectors, we can choose to eliminate the two tensor modes (the plus- and cross-polarizations) and construct a *GR null stream*: a linear combination of data streams that contains no signal consistent within GR, but could contain a signal in another gravitational theory, as illustrated in Fig. 4. With such a GR null stream, one can carry out null tests of GR and study whether such a stream

Fig. 4 Schematic diagram of the projection of the data stream \mathbf{d} orthogonal to the GR subspace spanned by F^+ and F^\times , along with a perpendicular subspace, for 3 detectors to build the GR null stream



contains any statistically significant deviations from noise. Notice that this approach does not require a template; if one were parametrically constructed, such as in Chatzioannou et al. (2012), more powerful null tests could be applied. As of now, the two aLIGO detectors in the United States, advanced Virgo in Italy, and KAGRA in Japan have started operation, and LIGO-India in India is expected to join in the near future. Given a gravitational wave observation that is detected by all five detectors, one can then construct three GR null streams, each with power in a signal direction. For pulsar timing experiments where one is dealing with the data streams of about a few tens of pulsars, waveform reconstruction for all polarization states, as well as numerous null streams, can be constructed.

3.5 Stochastic background searches

Much work has been done on the response of ground-based interferometers to non-tensorial polarization modes, stochastic background detection prospects, and data analysis techniques (Maggiore and Nicolis 2000; Nakao et al. 2001; Gasperini and Ungarelli 2001; Nishizawa et al. 2009; Corda 2010; Callister et al. 2017; Isi and Stein 2018; Callister et al. 2023). In the context of pulsar timing, the first work to deal with the detection of such backgrounds in the context of alternative theories of gravity is due to Lee et al. (2008), who used a coherence statistic approach to the detection of non-Einsteinian polarizations. They studied the number of pulsars required to detect the various extra polarization modes, and found that pulsar timing arrays are especially sensitive to the longitudinal mode. Alves and Tinto (2011) also found enhanced sensitivity to longitudinal and vector modes. Here we follow the work in Nishizawa et al. (2009), Chamberlin and Siemens (2012) that deals with the LIGO and pulsar timing cases using the optimal statistic, a cross-correlation that maximizes the SNR.

In the context of the optimal statistic, the derivations of the effect of extra polarization states for ground-based instruments and pulsar timing are very similar. We begin with the metric perturbation written in terms of a plane wave expansion,

as in Eq. (79). If we assume that the background is unpolarized, isotropic, and stationary, we have that

$$\langle \tilde{h}_A^*(f, \hat{\Omega}) \tilde{h}_{A'}(f', \hat{\Omega}') \rangle = \delta^2(\hat{\Omega}, \hat{\Omega}') \delta_{AA'} \delta(f - f') H_A(f), \quad (126)$$

where $H_A(f)$ is the gravitational-wave power spectrum for polarization A . $H_A(f)$ is related to the energy density in gravitational waves per logarithmic frequency interval for that polarization through

$$\Omega_A(f) \equiv \frac{1}{\rho_{\text{crit}}} \frac{d\rho_A}{d \ln f}, \quad (127)$$

where $\rho_{\text{crit}} = 3H_0^2/8\pi$ is the closure density of the universe, and

$$\rho_A = \frac{1}{32\pi} \langle \dot{h}_{Aij}(t, \vec{x}) \dot{h}_A^{ij}(t, \vec{x}) \rangle \quad (128)$$

is the energy density in gravitational waves for polarization A . It follows from the plane wave expansion in Eq. (80), along with Eqs. (126) and (127) in Eq. (128), that

$$H_A(f) = \frac{3H_0^2}{16\pi^3} |f|^{-3} \Omega_A(|f|), \quad (129)$$

and therefore

$$\langle \tilde{h}_A^*(f, \hat{\Omega}) \tilde{h}_{A'}(f', \hat{\Omega}') \rangle = \frac{3H_0^2}{16\pi^3} \delta^2(\hat{\Omega}, \hat{\Omega}') \delta_{AA'} \delta(f - f') |f|^{-3} \Omega_A(|f|). \quad (130)$$

For both ground-based interferometers and pulsar timing experiments, an isotropic stochastic background of gravitational waves appears in the data as correlated noise between measurements from different instruments. The data set from the a^{th} instrument is of the form

$$d_a(t) = s_a(t) + n_a(t), \quad (131)$$

where $s_a(t)$ corresponds to the gravitational wave signal and $n_a(t)$ to noise. The noise is assumed in this case to be stationary and Gaussian, and uncorrelated between different detectors,

$$\langle n_a(t) \rangle = 0, \quad (132)$$

$$\langle n_a(t) n_b(t) \rangle = 0, \quad (133)$$

for $a \neq b$.

Since the gravitational wave signal is correlated, we can use cross-correlations to search for it. The cross-correlation statistic is defined as

$$S_{ab} = \int_{-T/2}^{T/2} dt \int_{-T/2}^{T/2} dt' d_a(t) d_b(t') Q_{ab}(t - t'), \quad (134)$$

where $Q_{ab}(t - t')$ is a filter function to be determined. Henceforth, no summation is implied on the detector indices (a, b, \dots). At this stage it is not clear why $Q_{ab}(t - t')$ depends on the pair of data sets being correlated. We will show how this comes about later. The optimal filter is determined by maximizing the expected SNR

$$\text{SNR} = \frac{\mu_{ab}}{\sigma_{ab}}. \quad (135)$$

Here μ_{ab} is the mean $\langle S_{ab} \rangle$ and σ_{ab} is the square root of the variance $\sigma_{ab}^2 = \langle S_{ab}^2 \rangle - \langle S_{ab} \rangle^2$.

The expressions for the mean and variance of the cross-correlation statistic, μ_{ab} and σ_{ab}^2 respectively, take the same form for both pulsar timing and ground-based instruments. In the frequency domain, Eq. (134) becomes

$$S_{ab} = \int_{-\infty}^{\infty} df \int_{-\infty}^{\infty} df' \delta_T(f - f') \tilde{d}_a^*(f) \tilde{d}_b(f') \tilde{Q}_{ab}(f'), \quad (136)$$

by the convolution theorem, and the mean, μ_{ab} , is then

$$\mu_{ab} \equiv \langle S_{ab} \rangle = \int_{-\infty}^{\infty} df \int_{-\infty}^{\infty} df' \delta_T(f - f') \langle \tilde{d}_a^*(f) \tilde{d}_b(f') \rangle \tilde{Q}_{ab}(f'), \quad (137)$$

where δ_T is the finite time approximation to the delta function, $\delta_T(f) = \sin(\pi f t) / (\pi f t)$. With this in hand, the mean of the cross-correlation statistic is

$$\mu_{ab} = \frac{3H_0^2}{16\pi^3} T \sum_A \int_{-\infty}^{\infty} df |f|^{-3} \tilde{Q}_{ab}(f) \Omega_A(f) \Gamma_{ab}^A(f), \quad (138)$$

and the variance in the weak signal limit is

$$\begin{aligned} \sigma_{ab}^2 &\equiv \langle S_{ab}^2 \rangle - \langle S_{ab} \rangle^2 \approx \langle S_{ab}^2 \rangle \\ &\approx \frac{T}{4} \int_{-\infty}^{\infty} df P_a(|f|) P_b(|f|) |\tilde{Q}_{ab}(f)|^2, \end{aligned} \quad (139)$$

where $\Gamma_{ab}^A(f)$ is the overlap reduction function to be discussed in detail later, while the one-sided power spectra of the noise are defined by

$$\langle \tilde{d}_a^*(f) \tilde{d}_a(f') \rangle = \frac{1}{2} \delta(f - f') P_a(|f|), \quad (140)$$

in analogy to Eq. (101), where P_a plays here the role of $S_n(f)$.

The mean and variance can be rewritten more compactly if we define a positive-definite inner product using the noise power spectra of the two data streams

$$(A, B)_{ab} \equiv \int_{-\infty}^{\infty} df A^*(f) B(f) P_a(|f|) P_b(|f|), \quad (141)$$

again in analogy to the inner product in Eq. (103), when considering inspirals. Using this definition

$$\mu_{ab} = \frac{3H_0^2}{16\pi^3} T \left(\tilde{Q}_{ab}, \frac{\sum_A \Omega_A(|f|) \Gamma_{ab}^A(|f|)}{|f|^3 P_a(|f|) P_b(|f|)} \right)_{ab}, \quad (142)$$

$$\sigma_{ab}^2 \approx \frac{T}{4} (\tilde{Q}, \tilde{Q})_{ab}, \quad (143)$$

where we recall that the capital Latin indices (A, B, \dots) stand for the polarization content. From the definition of the SNR and the Schwartz's inequality, it follows that the optimal filter is given by

$$\tilde{Q}_{ab}(f) = N \frac{\sum_A \Omega_A(|f|) \Gamma_{ab}^A(|f|)}{|f|^3 P_a(|f|) P_b(|f|)}, \quad (144)$$

where N is an arbitrary normalization constant, normally chosen so that the mean of the statistic gives the amplitude of the stochastic background.

The differences in the optimal filter between interferometers and pulsars arise only from differences in the so-called *overlap reduction functions*, $\Gamma_{ab}^A(f)$. For ground-based instruments, the signal data s_a are the strains given by Eq. (85). The overlap reduction functions are then given by

$$\Gamma_{ab}^A(f) = \int_{S^2} d\hat{\Omega} F_a^A(\hat{\Omega}) F_b^A(\hat{\Omega}) e^{2\pi i f \hat{\Omega} \cdot (\vec{x}_a - \vec{x}_b)}, \quad (145)$$

where \vec{x}_a and \vec{x}_b are the locations of the two interferometers. The integrals in this case all have solutions in terms of spherical Bessel functions (Nishizawa et al. 2009), which we do not summarize here for brevity.

For pulsar timing arrays, the signal data s_a are the redshifts z_a , given by Eq. (93). The overlap reduction functions are then given by

$$\Gamma_{ab}^A(f) = \frac{3}{4\pi} \int_{S^2} d\hat{\Omega} \left(e^{i2\pi f L_a(1+\hat{\Omega} \cdot \hat{p}_a)} - 1 \right) \left(e^{-i2\pi f L_b(1+\hat{\Omega} \cdot \hat{p}_b)} - 1 \right) F_a^A(\hat{\Omega}) F_b^A(\hat{\Omega}), \quad (146)$$

where L_a and L_b are the distances to the two pulsars. For all transverse modes pulsar timing experiments are in a regime where the exponential factors in Eq. (146) can be neglected (Anholm et al. 2009; Chamberlin and Siemens 2012), and the overlap reduction functions effectively become frequency independent (see Boitier et al. 2021, 2022; Hu et al. 2022 for recent works on extensions beyond this short wavelength approximation). For the + and \times mode the overlap reduction function becomes

$$\Gamma_{ab}^+ = 3 \left\{ \frac{1}{3} + \frac{1 - \cos \xi_{ab}}{2} \left[\ln \left(\frac{1 - \cos \xi_{ab}}{2} \right) - \frac{1}{6} \right] \right\}, \quad (147)$$

where $\xi_{ab} = \cos^{-1}(\hat{p}_a \cdot \hat{p}_b)$ is the angle between the two pulsars. This quantity is proportional to the Hellings and Downs curve (Hellings and Downs 1983). For the breathing mode, the overlap reduction function takes the closed form expression (Lee et al. 2008; Chamberlin and Siemens 2012):

$$\Gamma_{ab}^b = \frac{1}{4} (3 + \cos \xi_{ab}), \quad (148)$$

and for the vector modes

$$\Gamma_{ab}^v \approx 3 \log \left(\frac{2}{1 - \cos(\xi_{ab})} \right) - 4 \cos(\xi_{ab}) - 3. \quad (149)$$

For the longitudinal mode the overlap functions retains significant frequency dependence and full analytic expressions for all overlap reduction functions including the frequency dependence were found relatively recently (Hu et al. 2022).

The result for the combination of cross-correlation pairs to form an optimal network statistic is also the same in both ground-based interferometer and pulsar timing cases: a sum of the cross-correlations of all detector pairs weighted by their variances. The detector network optimal statistic is,

$$S_{\text{opt}} = \frac{\sum_{ab} \sigma_{ab}^{-2} S_{ab}}{\sum_{ab} \sigma_{ab}^{-2}}, \quad (150)$$

where \sum_{ab} is a sum over all detector pairs.

In order to perform a search for a given polarization mode one first needs to compute the overlap reduction functions (using either Eq. (145) or (146)) for that mode. With that in hand and a form for the stochastic background spectrum $\Omega_A(f)$, one can construct optimal filters for all pairs in the detector network using Eq. (144), and perform the cross-correlations using either Eq. (134) (or equivalently Eq. (136)). Finally, we can calculate the overall network statistic Eq. (150), by first finding the variances using Eq. (139).

It is important to point out that the procedure outlined above is straightforward for ground-based interferometers. Pulsar timing data, however, are irregularly sampled, and have a pulsar timing model subtracted out. This needs to be accounted for, and generally, a time-domain approach is more appropriate for these data sets. The procedure is similar to what we have outlined above, but power spectra and gravitational-wave spectra in the frequency domain need to be replaced by auto-covariance and cross-covariance matrices in the time domain that account for the model fitting (for an example of how to do this see Ellis et al. 2013). A full description of the pulsar timing data analysis (Bayesian and frequentist) methods used in the most recent analyses can be found in Johnson et al. (2024).

Let us summarize some recent studies of the capabilities of pulsar timing arrays to probe non-GR, gravitational-wave polarizations. Nishizawa et al. (2009) showed that with three spatially separated detectors the tensor, vector, and scalar

contributions to the energy density in gravitational waves can be measured independently. Lee et al. (2008) and Alves and Tinto (2011) extended this analysis to show that pulsar timing experiments are especially sensitive to the longitudinal mode, and, to a lesser extent, to the vector modes. Recently, O’Beirne et al. (2019) proved that the modeling of possible additional polarizations together with modifications to the gravitational wave phase evolution (Cornish et al. 2018) can be used to separate polarization modes if more than tensor ones are present. Cornish et al. (2018), however, demonstrated that longitudinal modes could in practice be difficult to detect due to very large variances in their pulsar-pulsar correlation patterns. Chamberlin and Siemens (2012) explained that the sensitivity of the cross-correlation to the longitudinal mode using nearby pulsar pairs can be enhanced significantly compared to that of the transverse modes. For example, for the NANOGrav pulsar timing array, two pulsar pairs separated by 3° result in an enhancement of 4 orders of magnitude in sensitivity to the longitudinal mode relative to the transverse modes. The main contribution to this effect is due to gravitational waves that are coming from roughly the same direction as the pulses from the pulsars. In this case, the induced redshift for any gravitational-wave polarization mode is proportional to $f L$, the product of the gravitational-wave frequency and the distance to the pulsar, which can be large. When the gravitational waves and the pulse direction are exactly parallel, the redshift for the transverse and vector modes vanishes, but it is proportional to $f L$ for the scalar-longitudinal mode. Another interesting polarization mode one may wish to detect are circularly polarized tensor modes, which would be useful for probing e.g. parity violation through amplitude birefringence (Alexander et al. 2008; Alexander and Yunes 2009; Yunes et al. 2010b; Alexander and Yunes 2018). Pulsar timing arrays are not sensitive to circular polarization if the background is isotropic, although they have some sensitivity to this mode for anisotropic backgrounds (Kato and Soda 2016; Belgacem and Kamionkowski 2020; Sato-Polito and Kamionkowski 2022).

Let us now discuss probing specific fundamental pillars in GR or modified theories of gravity with pulsar timing arrays. Lee et al. (2010), Lee (2013) studied the detectability of massive gravitons in pulsar timing arrays through stochastic background searches. They introduced a modification to Eq. (87) to account for graviton dispersion, and found the modified overlap reduction functions (i.e., modifications to the Hellings–Downs curves Eq. (147)) for various values of the graviton mass for both tensorial (Lee et al. 2010) and non-tensorial (Lee 2013) polarization modes. They conclude that many stable pulsars (≥ 60) are required to distinguish between the massive and massless cases, and that future pulsar timing experiments could be sensitive to graviton masses of about 10^{-22} eV ($\sim 10^{13}$ km). This method is competitive with some of the compact binary tests described later in Sect. 4.3.1 (see Table 2). In addition, since the method of Lee et al. (2010) only depends on the form of the overlap reduction functions, it is advantageous in that it does not involve matched filtering (and therefore prior knowledge of the waveforms), and generally makes few assumptions about the gravitational-wave source properties. See Liang and Trodden (2021) for a recent follow-up work on computing overlap reduction functions and modified Hellings–Downs curves in a

complete analytical form in massive gravity. Qin et al. (2021) studied subluminal stochastic gravitational wave background in pulsar timing arrays and its application to $f(R)$ gravity that contains a massive scalar degree of freedom. Gong et al. (2018) derived the modified Hellings–Downs curves in Einstein–æther theory. Full analytic expressions for all overlap reduction functions were found relatively recently by Hu et al. (2022), and can be elegantly cast in the language of spherical harmonics (see the work of Anil Kumar and Kamionkowski 2024).

Gravitational waves have recently been discovered in the nanohertz band using pulsar timing arrays (see, for example, Agazie et al. 2023), and some studies have been implemented to place new constraints on these modified theories (Agazie et al. 2024). We summarize these results in Sect. 5.

4 Bestiary of gravitational-wave tests

In this section, we present a descriptive treatise on various kinds of tests of GR with gravitational waves. Due to the uneven proportion of studies that deal with compact binary systems, the latter will be emphasized in this section. We begin by explaining the difference between direct and generic tests. We then proceed to describe the many direct or top-down tests and generic or bottom-up tests that have been proposed once gravitational waves are detected, including tests of the no-hair theorems. We concentrate here only on binaries composed of compact objects, such as neutron stars, black holes or other compact exotica. We will not discuss tests one could carry out with electromagnetic information from binary (or double) pulsars, as these are already described in Will (2014). We will also not review tests of GR with accretion disk observations, for which we refer the interested reader to Psaltis (2008b).

4.1 Direct versus generic tests and propagation versus generation

Gravitational-wave tests of Einstein’s theory can be classed into two distinct subgroups: direct tests and generic tests. Direct tests employ a top-down approach, where one starts from a particular modified gravity theory with a known action, derives the modified field equations and solves them for a particular gravitational wave-emitting system. On the other hand, generic tests adopt a bottom-up approach, where one takes a particular feature of GR and asks what type of signature its absence would leave on the gravitational-wave observable; one then asks whether the data presents a statistically-significant anomaly pointing to that particular signature.

Historically, direct tests have by far been the traditional approach to testing GR with gravitational waves. The prototypical examples here are tests of Jordan–Fierz–Brans–Dicke theory. As described in Sect. 2, one can solve the modified field equations for a binary system in the post-Newtonian approximation to find a prediction for the gravitational-wave observable, as we will see in more detail later in this section. Other examples of direct tests include those concerning modified quadratic gravity models and non-commutative geometry theories.

The main advantage of such direct tests is also its main disadvantage: one has to pick a particular modified gravity theory. Because of this, one has a well-defined set of field equations that one can solve, but at the same time, one can only make predictions about that modified gravity model. Unfortunately, we currently lack a particular modified gravity theory that is particularly compelling; many modified gravity theories exist, but none possess all the criteria described in Sect. 2, except perhaps for the subclass of scalar-tensor theories with spontaneous scalarization. Lacking a clear alternative to GR, it is not obvious which theory one should pick. Given that the full development (from the action to the gravitational wave observable) of any particular theory can be incredibly difficult, time and computationally consuming, carrying out direct tests of all possible modified gravity models now that gravitational waves have been detected is clearly unfeasible.

Given this, one is led to generic tests of GR, where one asks how the absence of specific features contained in GR could impact the gravitational wave observable. For example, one can ask how such an observable would be modified if the graviton had a mass, if the gravitational interaction were Lorentz or parity violating, or if there existed large extra dimensions. From these general considerations, one can then construct a “meta”-observable, i.e., one that does not belong to a particular theory, but that interpolates over all known possibilities in a well-defined way. This model has come to be known as the parameterized post-Einsteinian framework (Yunes and Pretorius 2009b), in analogy to the parameterized post-Newtonian scheme used to test GR in the solar system (Will 2014). Given such a construction, one can then ask whether the data points to a statistically-significant GR deviation.

The main advantage of generic tests is precisely that one does not have to specify a particular model, but instead one lets the data select whether it contains any statistically-significant deviations from our canonical beliefs. Such an approach is, of course, not new to physics, having most recently been successfully employed by the WMAP team (Bennett et al. 2011). The intrinsic disadvantage of this method is that, if a deviation is found, there is no one-to-one mapping between it and a particular action, but instead one has to point to a class of possible models. Of course, such a disadvantage is not that limiting, since it would provide strong hints as to what type of symmetries or properties of GR would have to be violated in an ultraviolet completion of Einstein’s theory.

Whether one is considering direct tests or generic tests, modifications to GR can always be classified into those that affect the generation of gravitational waves and those that affect their propagation. The study of the generation of gravitational waves involves the linearization of the modified field equations about a fixed (Minkowski or cosmological) background, and their solution either through a multipolar post-Newtonian formalism (see Blanchet 2014 for a review) or through purely numerical methods. Such a task is very difficult and time-consuming, which is why it has only been tackled in a few modified gravity cases. The study of the propagation of gravitational waves involves the linearization of the field equations in flat spacetime to derive the wave’s dispersion relation or its propagator. Typically, this is a much more straightforward calculation that has been carried out in many specific modified gravity theories and phenomenological models.

Given these two generic types of modifications to gravity, which one is more important when carrying out gravitational wave tests? The answer to this question depends strongly on the particular modification to gravity that one is considering. Indeed, there are modified theories, such as scalar-tensor theories, in which the propagation of gravitational waves is not modified at all, while the generation is. In such cases, the modifications to the generation of gravitational waves is all that matters. In general, however, a modified theory of gravity will introduce modifications to both the generation and propagation of gravitational waves. In this case, typically the modifications to the propagation lead to a stronger constraint than the modifications to the generation simply because the former accumulate with distance traveled, while the latter only accumulate with coalescence time, which is typically proportional to the binary's total mass. Indeed, in simple massive gravity theories the ratio of the modification in the Fourier phase introduced by generation to that introduced by propagation effects is roughly (Finn and Sutton 2002; Yunes et al. 2016)

$$\frac{\Psi_{\text{prop}}(f)}{\Psi_{\text{gen}}(f)} = 10^{18} \left(\frac{\mathcal{M}}{28 M_{\odot}} \right)^{5/3} \left(\frac{D_L}{380 \text{ Mpc}} \right) \left(\frac{f}{100 \text{ Hz}} \right)^{8/3}, \quad (151)$$

where \mathcal{M} is the binary's chirp mass, D_L is the luminosity distance and we have evaluated the ratio at 100 Hz. One sees clearly that the propagation effect is clearly dominant, in spite of the propagation effect entering at higher post-Newtonian order than the generation effect. One is thus drawn to conclude that if both generation and propagation effects are present in a modified gravity theory, then typically propagation effects dominate irrespective of the post-Newtonian order they enter at.

4.2 Direct tests

4.2.1 Scalar-tensor theories

Let us first concentrate on Jordan–Fierz–Brans–Dicke theory, where black holes and neutron stars have been shown to exist. In this theory, the gravitational mass depends on the value of the scalar field, as Newton's constant is effectively promoted to a function, thus leading to violations of the weak-equivalence principle (Eardley 1975; Will 1977; Will and Zaglauer 1989). The usual prescription for the modeling of binary systems in this theory is due to Eardley (1975).¹³ He showed that such a scalar-field effect can be captured by replacing the constant inertial mass by a function of the scalar field in the distributional stress-energy tensor and then Taylor expanding about the cosmological constant value of the scalar field at spatial infinity, i.e.,

¹³ A modern interpretation in terms of effective field theory can be found in Goldberger and Rothstein (2006a, b).

$$m_a \rightarrow m_a(\phi) = m_a(\phi_0) \left\{ 1 + s_a \frac{\psi}{\phi_0} - \frac{1}{2} (s'_a - s_a^2 + s_a) \left(\frac{\psi}{\phi_0} \right)^2 + \mathcal{O} \left[\left(\frac{\psi}{\phi_0} \right)^3 \right] \right\}, \quad (152)$$

where the subscript a stands for a different sources, while $\psi \equiv \phi - \phi_0 \ll 1$ and the sensitivities s_a and s'_a are defined by

$$s_a \equiv - \left[\frac{\partial(\ln m_a)}{\partial(\ln G)} \right]_0, \quad s'_a \equiv - \left[\frac{\partial^2(\ln m_a)}{\partial(\ln G)^2} \right]_0, \quad (153)$$

where we remind the reader that $G = 1/\phi$, the derivatives are to be taken with the baryon number held fixed and evaluated at $\phi = \phi_0$. These sensitivities encode how the gravitational mass changes due to a non-constant scalar field; one can think of them as measuring the gravitational binding energy per unit mass. The internal gravitational field of each body leads to a non-trivial variation of the scalar field, which then leads to modifications to the gravitational binding energies of the bodies. In carrying out this expansion, one assumes that the scalar field takes on a constant value at spatial infinity $\phi \rightarrow \phi_0$, disallowing any homogeneous, cosmological solution to the scalar field evolution equation [Eq. (20)].

With this at hand, one can solve the massless Jordan–Fierz–Brans–Dicke modified field equations [Eq. (20)] for the non-dynamical, near-zone field of N compact objects to obtain (Will and Zaglauer 1989)

$$\frac{\psi}{\phi_0} = \frac{1}{2 + \omega_{\text{BD}}} \sum_a (1 - 2s_a) \frac{m_a}{r_a} + \dots, \quad (154)$$

$$g_{00} = -1 + \sum_a \left(1 - \frac{s_a}{2 + \omega_{\text{BD}}} \right) \frac{2m_a}{r_a} + \dots, \quad (155)$$

$$g_{0i} = -2(1 + \gamma) \sum_a \frac{m_a}{r_a} v_a^i + \dots, \quad (156)$$

$$g_{ij} = \delta_{ij} \left[1 + 2\gamma \sum_a \left(1 + \frac{s_a}{1 + \omega_{\text{BD}}} \right) \frac{m_a}{r_a} + \dots \right], \quad (157)$$

where a runs from 1 to N , we have defined the spatial field point distance $r_a \equiv |x^i - x_a^i|$, the parameterized post-Newtonian quantity $\gamma = (1 + \omega_{\text{BD}})(2 + \omega_{\text{BD}})^{-1}$ and we have chosen units in which $G = c = 1$. This solution is obtained in a post-Newtonian expansion (Blanchet 2014), where the ellipses represent higher-order terms in v_a/c and m_a/r_a . From such an analysis, one can also show that compact objects follow geodesics of such a spacetime, to leading order in the post-Newtonian approximation (Eardley 1975), except that Newton's constant in the

coupling between matter and gravity is replaced by $G \rightarrow \mathcal{G}_{12} = 1 - (s_1 + s_2 - 2s_1s_2)(2 + \omega_{\text{BD}})^{-1}$, in geometric units.

As is clear from the above analysis, black-hole and neutron-star solutions in this theory generically depend on the quantities ω_{BD} and s_a . The former characterizes the coupling between the scalar and matter fields and determines the strength of the correction, with the theory reducing to GR in the $\omega_{\text{BD}} \rightarrow \infty$ limit (Faraoni 1999). The latter depends on the compact object that is being studied. For neutron stars, this quantity can be computed as follows. First, neglecting scalar corrections to neutron-star structure and using the Tolman–Oppenheimer–Volkoff equation, one notes that the mass $m \propto N \propto G^{-3/2}$, for a fixed equation of state and central density, with N the total baryon number. Thus, using Eq. (153), one has that

$$s_a \equiv \frac{3}{2} \left[1 - \left(\frac{\partial \ln m_a}{\partial \ln N} \right)_G \right], \quad (158)$$

where the derivative is to be taken holding G fixed. In this way, given an equation of state and central density, one can compute the gravitational mass as a function of baryon number, and from this, obtain the neutron star sensitivities. Eardley (1975), Will and Zaglauer (1989), and Zaglauer (1992) have shown that these sensitivities are always in the range $s_a \in (0.19, 0.3)$ for a soft equation of state and $s_a \in (0.1, 0.14)$ for a stiff one, in both cases monotonically increasing with mass in $m_a \in (1.1, 1.5) M_\odot$. Gralla (2010) has found a more general method to compute sensitivities in generic modified gravity theories.

What is the sensitivity of black holes in generic scalar-tensor theories? Zaglauer (1992) have argued that the no-hair theorems require $s_a = 1/2$ for all black holes, no matter what their mass or spin is. As already explained in Sect. 2, stationary black holes that are the byproduct of gravitational collapse (i.e., with matter that satisfies the energy conditions) in a general class of scalar-tensor theories are identical to their GR counterparts (Hawking 1972b; Thorne and Dykla 1971; Dykla 1972; Sotiriou and Faraoni 2012).¹⁴ This is because the scalar field satisfies a free wave equation in vacuum, which forces the scalar field to be constant in the exterior of a stationary, asymptotically-flat spacetime, provided one neglects a homogeneous, cosmological solution. If the scalar field is to be constant, then by Eq. (154), $s_a = 1/2$ for a single black-hole spacetime.

Such an argument formally applies only to stationary scenarios, so one might wonder whether a similar argument holds for binary systems that are in a quasi-stationary arrangement. Zaglauer (1992) and Mirshekari and Will (2013) extended this discussion to quasi-stationary spacetimes describing black-hole binaries to higher post-Newtonian order. They argued that the only possible deviations from $\psi = 0$ are due to tidal deformations of the horizon due to the companion, which are known to arise at very high order in post-Newtonian theory, $\psi = \mathcal{O}[(m_a/r_a)^5]$. Yunes et al. (2012) extended this argument further by showing that to all orders in

¹⁴ One should note in passing that more general black-hole solutions in scalar-tensor theories have been found (Kim 1999; Campanelli and Lousto 1993). However, these usually violate the weak-energy condition, and sometimes they require unreasonably small values of ω_{BD} that have already been ruled out by observation.

post-Newtonian theory, but in the extreme mass-ratio limit, black holes cannot have scalar hair in generic scalar-tensor theories. Finally, Healy et al. (2012) have carried out a full numerical simulation of the non-linear field equations, confirming this argument in the full non-linear regime.

The activation of dynamics in the scalar field for a vacuum spacetime requires either a non-constant distribution of initial scalar field (violating the constant cosmological scalar field condition at spatial infinity) or a pure geometrical source to the scalar field evolution equation. The latter would lead to the quadratic modified gravity theories discussed in Sect. 2.3.4. As for the former, Horbatsch and Burgess (2011) have argued that if, for example, one lets $\psi = \mu t$, which clearly satisfies $\square\psi = 0$ in a Minkowski background,¹⁵ then a Schwarzschild black hole will acquire modifications that are proportional to μ . Alternatively, scalar hair could also be induced by spatial gradients in the scalar field (Berti et al. 2013), possibly anchored in matter at galactic scales. Such cosmological hair, however, is likely to be suppressed by a long timescale; in the example above μ must have units of inverse time, and if it is to be associated with the expansion of the universe, then it would be natural to assume $\mu = \mathcal{O}(H)$, where H is the Hubble parameter. Therefore, although such cosmological hair might have an effect on black holes in the early universe, it should not affect black hole observations at moderate to low redshifts.

Scalar field dynamics can be activated in non-vacuum spacetimes, even if initially the stars are not scalarized provided one considers a more general scalar-tensor theory, like the one introduced by Damour and Esposito-Farèse (1992), Damour and Esposito-Farèse (1993). As discussed in Sect. 2.3.1, when the conformal factor takes on a particular functional form, non-linear effects induced when the gravitational energy exceeds a certain threshold can dynamically scalarize merging neutron stars, as demonstrated by Barausse et al. (2013), Palenzuela et al. (2014). Therefore, neutron stars in binaries are likely to have hair in generic scalar-tensor theories, even if they start their inspiral unscalarized. One must be careful, however, to make sure that the scalarized stars found are actually stable to perturbations. This is the case in the standard model of Damour and Esposito-Farèse (1992), Damour and Esposito-Farèse (1993) when $\beta < 0$, but it is no longer true when $\beta > 0$ (Mendes 2015; Palenzuela and Liebling 2016; Mendes and Ortiz 2016).

Putting the issue of stability aside, what do gravitational waves look like in (massless) Jordan–Fierz–Brans–Dicke theory? As described in Sect. 2.3.1, both the scalar field perturbation ψ and the new metric perturbation $\theta^{\mu\nu}$ satisfy a sourced wave equation [Eq. (20)], whose leading-order solution for a two-body inspiral is (Will 1994)

¹⁵ The scalar field of Horbatsch and Burgess satisfies $\square\psi = \mu g^{\mu\nu} \Gamma_{\mu\nu}^t$, and thus $\square\psi = 0$ for stationary and axisymmetric spacetimes, since the metric is independent of time and azimuthal coordinate. However, notice that is not necessarily needed for Jacobson's construction (Jacobson 1999) to be possible.

$$\theta^{ij} = 2(1 + \gamma) \frac{\mu}{R} \left(v_{12}^{ij} - \mathcal{G}_{12} m \frac{x_{12}^{ij}}{r^3} \right), \quad (159)$$

$$\frac{\psi}{\phi_0} = (1 - \gamma) \frac{\mu}{R} \left[\Gamma (n_i v_{12}^i)^2 - \mathcal{G}_{12} \Gamma \frac{m}{r^3} (n_i x^i)^2 - \frac{m}{r} (\mathcal{G}_{12} \Gamma + 2A) - 2S n_i v_{12}^i \right], \quad (160)$$

where R is the distance to the detector, n^i is a unit vector pointing toward the detector, r is the magnitude of relative position vector $x^i \equiv x_1^i - x_2^i$, with x_a^i the trajectory of body a , $\mu = m_1 m_2 / m$ is the reduced mass and $m = m_1 + m_2$ is the total mass, $v_{12}^i \equiv v_1^i - v_2^i$ is the relative velocity vector, and we have defined the shorthands

$$\Gamma \equiv 1 - 2 \frac{m_1 s_2 + m_2 s_1}{m}, \quad S \equiv s_2 - s_1, \quad (161)$$

$$A \equiv \mathcal{G}_{12} (1 - s_1 - s_2) - (2 + \omega_{\text{BD}})^{-1} [(1 - 2s_1)s_2' + (1 - 2s_2)s_1']. \quad (162)$$

We have also introduced multi-index notation here, such that $A^{ij\dots} = A^i A^j \dots$. Such a solution is derived using the Lorenz gauge condition $\theta_{,v}^{\mu\nu} = 0$ and in a post-Newtonian expansion, where we have left out subleading terms of relative order v_{12}^2 or m/r . Lang and others (Mirshekari and Will 2013; Lang 2014, 2015; Sennett et al. 2016) have completed this calculation to second post-Newtonian order, which were further extended by Bernard and others to find the equations of motion up to third post-Newtonian (Bernard 2018, 2019), tidal effects (Bernard 2020; Bernard et al. 2024), and scalar modes and non-linear memory effects to 1.5 post-Newtonian order (Bernard et al. 2022). Spin-orbit effects on orbital dynamics and gravitational waves in scalar-tensor theories were studied in detail in Brax et al. (2021). Julié et al. (2023) constructed the Hamiltonian of a binary system in scalar-tensor theories (and scalar Gauss–Bonnet theory) within the effective-one-body formalism up to third post-Newtonian order. Almeida (2024) derived the dynamics of binaries in scalar-tensor theories up to 2 post-Newtonian order using effective field theory. Trestini (2024) studied eccentric compact binaries in these theories at 2nd post-Newtonian order within the post-Keplerian framework.

Given the new metric perturbation θ^{ij} , one can reconstruct the gravitational wave metric perturbation h^{ij} , and from this, the response function, associated with the quasi-circular inspiral of compact binaries. After using Kepler’s third law to simplify expressions [$\omega = (\mathcal{G}_{12} m / r^3)^{1/2}$, where ω is the orbital angular frequency and m is the total mass and r is the orbital separation], one finds for a ground-based L-shaped detector (Chatzioannou et al. 2012):

$$\begin{aligned}
h(t) = & -\frac{\mathcal{M}}{R} u^2 e^{-2i\Phi} \left\{ \left[F_+ (1 + \cos^2 \iota) + 2iF_\times \cos \iota \right] \left[1 - \frac{1-\gamma}{2} \left(1 + \frac{4}{3} S^2 \right) \right] \right. \\
& \left. - \frac{1-\gamma}{2} \Gamma F_b \sin^2 \iota \right\} - \eta^{1/5} \frac{\mathcal{M}}{R} u e^{-i\Phi} S (1-\gamma) F_b \sin \iota \\
& - \frac{\mathcal{M}}{R} u^2 \frac{1-\gamma}{2} F_b (\Gamma + 2A) + \text{c.c.} ,
\end{aligned} \tag{163}$$

where we have defined $u \equiv (2\pi\mathcal{M}F)^{1/3}$, $\eta \equiv \mu/m$ is the symmetric mass ratio, $\mathcal{M} \equiv \eta^{3/5}m$ is the chirp mass, ι is the inclination angle, c.c. stands for the complex conjugate, and where we have used the beam-pattern functions in Eq. (86). In Eq. (163) and henceforth, we linearize all expressions in $1-\gamma \ll 1$. Jordan–Fierz–Brans–Dicke theory predicts the generic excitation of three polarizations: the usual plus and cross polarizations, and a breathing, scalar mode. We see that the latter contributes to the response at two, one and zero times the orbital frequency. One should note that all of these corrections arise during the generation of gravitational waves, and not due to a propagation effect. In fact, gravitational waves travel at the speed of light (and the graviton remains massless) in standard Jordan–Fierz–Brans–Dicke theory.

The quantities Φ and F are the orbital phase and frequency respectively, which are to be found by solving the differential equation

$$\frac{dF}{dt} = (1-\gamma) S^2 \frac{\eta^{2/5}}{\pi} \mathcal{M}^{-2} u^9 + \frac{48}{5\pi} \mathcal{M}^{-2} u^{11} \left[1 - \frac{1-\gamma}{2} \left(1 - \frac{\Gamma^2}{6} + \frac{4}{3} S^2 \right) \right] \dots, \tag{164}$$

where the ellipses stand for higher-order terms in the post-Newtonian approximation. In this expression, and henceforth, we have kept only the leading-order dipole term and all known post-Newtonian, GR terms. If one wished to include higher post-Newtonian–order Jordan–Fierz–Brans–Dicke terms, one would have to include monopole contributions as well as post-Newtonian corrections to the dipole term. The first term in Eq. (164) corresponds to dipole radiation, which is activated by the scalar mode. That is, the scalar field carries energy away from the system modifying the energy balance law to (Will 1994; Scharre and Will 2002; Will and Yunes 2004)

$$\dot{E}_{\text{BD}} = -\frac{2}{3} \mathcal{G}_{12}^2 \eta^2 \frac{m^4}{r^4} (1-\gamma) S^2 - \frac{32}{5} \mathcal{G}_{12}^2 \eta^2 \left(\frac{m}{r} \right)^5 \left[1 - \frac{1-\gamma}{2} \left(1 - \frac{\Gamma^2}{6} \right) \right] + \dots, \tag{165}$$

where the ellipses stand again for higher-order terms in the post-Newtonian approximation. Solving the frequency evolution equation perturbatively in $1/\omega_{\text{BD}} \ll 1$, one finds

$$\frac{256}{5} \frac{t_c - t}{\mathcal{M}} = u^{-8} \left[1 - \frac{1}{12} (1 - \gamma) S^2 \eta^{2/5} u^{-2} + \dots \right], \quad (166)$$

$$\Phi = -\frac{1}{64\pi} \left(\frac{256}{5} \frac{t_c - t}{\mathcal{M}} \right)^{5/8} \left[1 - \frac{5}{224} (1 - \gamma) S^2 \eta^{2/5} \left(\frac{256}{5} \frac{t_c - t}{\mathcal{M}} \right)^{1/4} + \dots \right]. \quad (167)$$

In deriving these equations, we have neglected the last term in Eq. (164), as this is a constant that can be reabsorbed into the chirp mass. Notice that since the two definitions of chirp mass differ only by a term of $\mathcal{O}(\omega_{\text{BD}}^{-1})$, the first term of Eq. (164) is not modified.

One of the main ingredients that goes into parameter estimation is the Fourier transform of the response function. This can be estimated in the *stationary-phase* approximation, for a simple, non-spinning, quasi-circular inspiral. In this approximation, one assumes the phase is changing much more rapidly than the amplitude (Bender and Orszag 1999; Cutler and Flanagan 1994; Droz et al. 1999; Yunes et al. 2009). One finds (Chatzioannou et al. 2012)

$$\tilde{h}(f) = \mathcal{A}_{\text{BD}} (\pi \mathcal{M} f)^{-7/6} \left[1 - \frac{5}{96} \frac{S^2}{\omega_{\text{BD}}} \eta^{2/5} (\pi \mathcal{M} f)^{-2/3} \right] e^{-i\psi_{\text{BD}}^{(2)}} + \gamma_{\text{BD}} (\pi \mathcal{M} f)^{-3/2} e^{-i\psi_{\text{BD}}^{(1)}} \quad (168)$$

where we have defined the amplitudes

$$\mathcal{A}_{\text{BD}} \equiv \left(\frac{5\pi}{96} \right)^{1/2} \frac{\mathcal{M}^2}{R} \left[F_+^2 (1 + \cos^2 \iota)^2 + 4F_\times^2 \cos^2 \iota - F_+ F_b (1 - \cos^4 \iota) \frac{\Gamma}{\omega_{\text{BD}}} \right]^{1/2}, \quad (169)$$

$$\gamma_{\text{BD}} \equiv - \left(\frac{5\pi}{48} \right)^{1/2} \frac{\mathcal{M}^2}{R} \eta^{1/5} \frac{S}{\omega_{\text{BD}}} F_b \sin \iota, \quad (170)$$

and the Fourier phase

$$\begin{aligned} \psi_{\text{BD}}^{(\ell)} = & -2\pi f t_c + \ell \Phi_c^{(\ell)} + \frac{\pi}{4} \\ & - \frac{3\ell}{256} \left(\frac{2\pi \mathcal{M} f}{\ell} \right)^{-5/3} \sum_{n=0}^7 \left(\frac{2\pi \mathcal{M} f}{\ell} \right)^{n/3} (c_n^{\text{PN}} + l_n^{\text{PN}} \ln f) \\ & + \frac{5\ell}{7168} \frac{S^2}{\omega_{\text{BD}}} \eta^{2/5} \left(\frac{2\pi \mathcal{M} f}{\ell} \right)^{-7/3}, \end{aligned} \quad (171)$$

where the Jordan–Fierz–Brans–Dicke correction is kept only to leading order in ω_{BD}^{-1} and ν , while $(c_n^{\text{PN}}, l_n^{\text{PN}})$ are post-Newtonian GR coefficients (see, e.g., Klein

et al. 2013). In writing the Fourier response in this way, we had to redefine the phase of coalescence via

$$\Phi_c^{(\ell)} = \Phi_c - \delta_{\ell,2} \left\{ \arctan \left[\frac{2 \cos \iota F_{\times}}{(1 + \cos^2 \iota) F_{+}} \right] + \frac{\Gamma}{\omega_{\text{BD}}} \frac{\cos \iota (1 - \cos^2 \iota) F_{\times} F_{\text{b}}}{(1 + \cos^2 \iota)^2 F_{+}^2 + 4 \cos^2 \iota F_{\times}^2} \right\}, \quad (172)$$

where $\delta_{\ell,m}$ is the Kronecker delta and Φ_c is the GR phase of coalescence (defined as an integration constant when the frequency diverges). Of course, in this calculation we have neglected amplitude corrections that arise purely in GR, if one were to carry out the post-Newtonian approximation to higher order.

Many studies have been carried out to determine the level at which such corrections to the waveform could be measured or constrained once a gravitational wave from a non-vacuum system has been detected. The first such study was carried out by Will (1994), who determined that given a LIGO detection at SNR $\rho = 10$ of a $(1.4, 3) M_{\odot}$ black-hole/neutron-star non-spinning, quasi-circular inspiral, one could constrain $\omega_{\text{BD}} > 10^3$. Scharre and Will (2002) carried out a similar analysis but for a LISA detection with $\rho = 10$ of a $(1.4, 10^3) M_{\odot}$ intermediate-mass black-hole/neutron-star, non-spinning, quasi-circular inspiral, and found that one could constrain $\omega_{\text{BD}} > 2.1 \times 10^4$. Such an analysis was then repeated by Will and Yunes (2004) but as a function of the classic LISA instrument. They found that the bound is independent of the LISA arm length, but inversely proportional to the LISA position noise error, if the position error noise dominates over laser shot noise. All such studies considered an angle-averaged signal that neglected the spin of either body, assumptions that were relaxed by Berti et al. (2005a), Berti et al. (2005b). They carried out Monte-Carlo simulations over all signal sky positions that included spin-orbit precession to find that the projected bound with LISA deteriorates to $\omega_{\text{BD}} > 0.7 \times 10^4$ for the same system and SNR. This was confirmed and extended by Yagi and Tanaka (2010a), who in addition to spin-orbit precession allowed for non-circular (eccentric) inspirals. In fact, when eccentricity is included, the bound deteriorates even further to $\omega_{\text{BD}} > 0.5 \times 10^4$. The same authors also found that similar gravitational-wave observations with the next-generation detector DECIGO could constrain $\omega_{\text{BD}} > 1.6 \times 10^6$. Similarly, for a non-spinning neutron-star/black-hole binary, the future ground-based detector, the Einstein Telescope (ET) (Punturo et al. 2010), could place constraints about 5 times stronger than the Cassini bound, as shown in Arun and Pai (2013), and the bound will further improve by stacking many events (Zhang et al. 2017b).

All such projected constraints are to be compared with the current solar system bound of $\omega_{\text{BD}} > 4 \times 10^4$ placed through the tracking of the Cassini spacecraft (Bertotti et al. 2003), and current pulsar bound of $\omega_{\text{BD}} > 1.4 \times 10^5$ placed through the absence of the Nordtvedt effect in the pulsar triple system (Voisin et al. 2020). Table 1 presents all such bounds for ease of comparison, normalized to an SNR of 10. As it should be clear, it is unlikely that LIGO observations will be able to constrain ω_{BD} better than current bounds. In fact, even LISA would probably not be able to do better than the Cassini bound. Table 1 also shows that the inclusion of

more complexity in the waveform seems to dilute the level at which ω_{BD} can be constrained. This is because the inclusion of eccentricity and spin forces one to introduce more parameters in the waveform, without these modifications truly adding enough waveform complexity to break the induced degeneracies. One would then expect that the inclusion of amplitude modulation due to precession and higher harmonics should break such degeneracies, at least partially, as was found for massive black-hole binary (Lang and Hughes 2006; Lang et al. 2011). However, even then it seems reasonable to expect that only third-generation detectors will be able to constrain ω_{BD} beyond solar-system and pulsar levels, as shown in Chamberlain and Yunes (2017).

The main reason that solar-system and pulsar constraints of Jordan–Fierz–Brans–Dicke theory cannot be beaten with current gravitational-wave observations is that the former are particularly well-suited to constrain weak-field deviations of GR. One might have thought that scalar-tensor theories constitute extreme gravity tests of Einstein's theory, but this is not quite true, as argued in Sect. 2.3.1. One can see this clearly by noting that scalar-tensor theory predicts dipolar radiation, which dominates at low velocities over the GR prediction (precisely the opposite behavior that one would expect from an extreme-gravity modification to Einstein's theory).

Another interesting aspect of gravitational waves can be studied through gravitational-wave memory, which is a permanent shift in the gravitational-wave strain after the passage of a burst of gravitational waves. Gravitational memory is related to asymptotic symmetries and conserved quantities. The phenomenology of the memory effects in Jordan–Fierz–Brans–Dicke theory were recently studied in Hou and Zhu (2021), Tahura et al. (2021a, b) (memory effects in Jordan–Fierz–Brans–Dicke theory are also discussed in Lang 2014; Bernard et al. 2022). They

Table 1 Comparison of proposed tests of scalar-tensor theories. (All LISA bounds refer to the classic LISA configuration)

References	Binary mass	$\omega_{\text{BD}}[10^4]$	Properties
Bertotti et al. (2003)	x	4	Solar system
Voisin et al. (2020)	(1.44, 0.198, 0.410)	14	Pulsar triple system
Will (1994)	$(1.4, 3) M_{\odot}$	0.1	LIGO, Fisher, Ang. Ave. circular, non-spinning
Scharre and Will (2002)	$(1.4, 10^3) M_{\odot}$	24	LISA, Fisher, Ang. Ave. circular, non-spinning
Will and Yunes (2004)	$(1.4, 10^3) M_{\odot}$	20	LISA, Fisher, Ang. Ave. circular, non-spinning
Berti et al. (2005a)	$(1.4, 10^3) M_{\odot}$	0.7	LISA, Fisher, Monte-Carlo circular, w/spin-orbit
Yagi and Tanaka (2010a)	$(1.4, 10^3) M_{\odot}$	0.5	LISA, Fisher, Monte-Carlo eccentric, spin-orbit
Yagi and Tanaka (2010b)	$(1.4, 10) M_{\odot}$	160	DECIGO, Fisher, Monte-Carlo eccentric, spin-orbit
Arun and Pai (2013)	$(1.4, 10) M_{\odot}$	10	ET, Fisher, Ang. Ave. circular, non-spinning

found that the asymptotic symmetry group is the same as the Bondi–Metzner–Sachs group in GR. However, there are new memory effects due to the presence of the scalar polarization mode (the breathing mode), and they are not related to asymptotic symmetries nor conserved quantities (Hou and Zhu 2021; Tahura et al. 2021a). Gravitational waveforms due to memory in the tensor mode were derived in Tahura et al. (2021b) up to the Newtonian order. Due to the scalar dipole radiation, the waveform acquires a correction that has a log dependence. The waveform has a different dependence on the inclination angle from the GR case, which may be used to probe the theory (Yang and Martynov 2018). Heisenberg et al. (2023) recently derived the gravitational wave memory in the most general scalar–vector–tensor theory with second-order equations of motion and vanishing potentials. They also proved a theorem stating that the structure of the memory equation remains unchanged in any metric theories of gravity in which massless gravitational fields satisfy decoupled wave equations to first order in perturbation theory.

However, one should note that all the above analysis considered only the inspiral phase of coalescence, usually truncating the study at the innermost stable-circular orbit. The merger and ringdown phases, where most of the gravitational wave power resides, have so far been mostly neglected. One might expect that an increase in power will be accompanied by an increase in SNR, thus allowing us to constrain ω_{BD} further, as this scales with 1/SNR (Keppel and Ajith 2010). Moreover, during merger and ringdown, extreme gravity effects in scalar–tensor theories could affect neutron star parameters and their oscillations (Sotani and Kokkotas 2005), as well as possibly induce dynamical scalarization (Barausse et al. 2013; Palenzuela et al. 2014). Sennett and Buonanno (2016) has attempted to construct an effective-one-body type waveform model to 2PN order that accounts both for the merger–ringdown, and scalarization. All of these non-linear effects could easily lead to a strengthening of projected bounds. However, to date, no detailed analysis has attempted to determine how well one could constrain scalar–tensor theories using full information about the entire coalescence of a compact binary.

The subclass of scalar–tensor models described by (massless) Jordan–Fierz–Brans–Dicke theory is not the only type of model that can be constrained with gravitational-wave observations. In the extreme–mass–ratio limit, for binaries consisting of a stellar-mass compact object spiraling into a supermassive black hole, Yunes et al. (2012) have shown that generic scalar–tensor theories reduce to either massless or massive Jordan–Fierz–Brans–Dicke theory. Of course, in this case, the sensitivities need to be calculated from the equations of structure within the full scalar–tensor theory. The inclusion of a scalar field mass leads to an interesting possibility: floating orbits (Cardoso et al. 2011). Such orbits arise when the small compact object experiences superradiance, leading to resonances in the scalar flux that can momentarily counteract the gravitational-wave flux, leading to a temporarily-stalled orbit that greatly modifies the orbital-phase evolution. These authors showed that if an extreme mass–ratio inspiral is detected with a template consistent with GR, this alone allows us to rule out a large region of $(m_s, \omega_{\text{BD}})$ phase space, where m_s is the mass of the scalar field (see Fig. 1 in Yunes et al. 2012). This is because if such an inspiral had gone through a resonance, a GR template would be grossly different from the signal. Such bounds are dramatically stronger than one of

the current most stringent bounds $\omega_{\text{BD}} > 4 \times 10^4$ and $m_s < 2.5 \times 10^{-20}$ eV obtained from Cassini measurements of the Shapiro time-delay in the solar system (Alsing et al. 2012). Even if resonances are not hit, Berti et al. (2012) have estimated that second-generation ground-based interferometers could constrain the combination $m_s/(\omega_{\text{BD}})^{1/2} \lesssim 10^{-15}$ eV with the observation of gravitational waves from neutron-star/binary inspirals at an SNR of 10. These bounds can also be stronger than current constraints, especially for large scalar mass. Numerical relativity simulations of binary neutron star mergers in massive scalar-tensor theories have been carried out in Kuan et al. (2023b), Lam et al. (2024).

Let us now mention possible gravitational-wave constraints on other types of scalar tensor theories. Let us first consider Jordan–Fierz–Brans–Dicke type scalar-tensor theories, where the coupling constant is allowed to vary. Will (1994) has argued that the constraints described in Table 1 go through, with the change

$$\frac{2\mathcal{G}_{1,2}}{2 + \omega_{\text{BD}}} \rightarrow \frac{2\mathcal{G}_{1,2}}{2 + \omega_{\text{BD}}} \left[1 + \frac{2\omega'_{\text{BD}}}{(3 + 2\omega_{\text{BD}})^2} \right]^2, \quad (173)$$

where $\omega'_{\text{BD}} \equiv d\omega_{\text{BD}}/d\phi$. In the $\omega_{\text{BD}} \gg 1$ limit, this implies the replacement $\omega_{\text{BD}} \rightarrow \omega_{\text{BD}}[1 + \omega'_{\text{BD}}/(2\omega_{\text{BD}}^2)]^{-2}$. Of course, this assumes that there is neither a potential nor a geometric source driving the evolution of the scalar field, and is not applicable for theories where spontaneous scalarization is present (Damour and Esposito-Farèse 1992). Regarding Horndeski theory, Figueras and França (2022) carried out binary black hole merger simulations in cubic Horndeski theory and found that the mismatch in gravitational waveforms in the theory and GR can be $\mathcal{O}(10\%)$ for stellar-mass black hole binaries. Higashino and Tsujikawa (2023) carried out a post-Newtonian analysis and derived corrections to the gravitational waveforms in a class of Horndeski theory in which the speed of gravitational waves is the same as that of light (see Quartin et al. 2023 for a follow-up analysis). f(R) gravity is another class of modified gravity theories that can be mapped to scalar-tensor theories, as discussed in Sect. 2.3.1. Gravitational waves in f(R) gravity were studied, e.g. in Vilhena et al. (2021), where correction terms in the action are proportional to R^2 and $R\square R$. Takeda et al. (2024) derived bounds on a subclass of Horndeski theory with luminal GW propagation through the neutron star and black-hole binary merger in the GW200115 event.

Another interesting scalar-tensor theory to consider is that studied by Damour and Esposito-Farèse (1992), Damour and Esposito-Farèse (1993). As explained in Sect. 2.3.1, this theory is defined by the action of Eq. (15) with the conformal factor $A(\psi) = e^{\beta\psi^2}$. In standard Jordan–Fierz–Brans–Dicke theory, only mixed binaries composed of a black hole and a neutron star lead to large deviations from GR due to dipolar emission. This is because dipole emission is proportional to the difference in sensitivities of the binary components. For neutron–star binaries with similar masses, this difference is close to zero, while for black holes it is identically zero (see Eqs. (161) and (171)). Bounds on the theory with GW170817 were studied by Zhao et al. (2019), though such gravitational-wave bounds are much weaker than those from binary pulsars. This work was later improved by Niu et al. (2021) by

considering several neutron star binaries and neutron star-black hole binaries found by the LIGO/Virgo Collaborations and applied these events to Jordan–Fierz–Brans–Dicke theory, Damour–Esposito–Farèse theory and screened modified gravity (that can evade solar system constraints via various screening mechanisms). The authors found that gravitational-wave observations can place bound comparable to binary pulsar ones in Damour–Esposito–Farèse theory, but the constraints are much weaker for Jordan–Fierz–Brans–Dicke and screened modified gravity. Forecasts on projected bounds on these theories with future gravitational-wave observations were made in Zhao et al. (2019), Carson et al. (2020). In the theory considered by Damour and Esposito–Farèse, when the gravitational energy is large enough, as in the very late inspiral, non-linear effects can lead to drastic modifications from the GR expectation, such as dynamical and induced scalarization (Barausse et al. 2013; Palenzuela et al. 2014). Unfortunately, most of this happens at rather high frequency, and thus, they become observable only if the activation of the scalar field occurs in the sensitivity band of detectors (Sampson et al. 2014b).

Although black holes do not acquire scalar charges in typical scalar-tensor theories under stationary configuration, they can acquire these charges under time-dependent situation. This was first pointed out by Jacobson (1999). Such a “miraculous scalar hair growth” in black holes can be probed with gravitational waves from binary black hole mergers. For example, GW151226 places the bound on the rate of the scalar field evolution as $|\dot{\phi}| < 1.09 \times 10^4 \text{ /sec}$ (Tahura et al. 2019).

4.2.2 Bigravity

What has been studied in some detail in massive bigravity is the propagation of gravitational waves in a Minkowski background (De Felice et al. 2014; Narikawa et al. 2015). The propagation field equations in Sect. 2.3.2 can be solved for the two eigenmodes

$$h_{1,+/\times} = \cos \theta_g h_{+/\times} + \sin \theta_g \sqrt{\kappa} \xi_c \tilde{h}_{+/\times}, \quad (174)$$

$$h_{2,+/\times} = -\sin \theta_g h_{+/\times} + \cos \theta_g \sqrt{\kappa} \xi_c \tilde{h}_{+/\times}, \quad (175)$$

where κ is the ratio between the two gravitational constants for the two metrics, while

$$\theta_g = \frac{1}{2} \cot^{-1} \left(\frac{1 + \kappa \xi_c^2}{2\sqrt{\kappa} \xi_c} x + \frac{1 - \kappa \xi_c^2}{2\sqrt{\kappa} \xi_c} \right), \quad (176)$$

and

$$x = \frac{2}{\mu^2} (2\pi f)^2 (\tilde{c} - 1), \quad \mu^2 = \lambda_\mu^{-2} = \frac{(1 + \kappa \xi_c^2) \Gamma_c m^2}{\kappa \xi_c^2}, \quad (177)$$

with f the gravitational wave frequency and \tilde{c} the speed of light in the auxiliary sector (De Felice et al. 2014). The latter is close to unity, with deviations proportional to the matter energy density and pressure

$$\tilde{c} \approx 1 + \frac{\kappa \xi_c^2 (\rho_m + p_m)}{\Gamma_c m^2 \tilde{M}_G^2}, \quad (178)$$

where ρ_m and p_m are the energy density and pressure and $\tilde{M}_G^2 = M_G^2 (1 + \kappa \xi_c^2)$ with $M_G^2 = 1/(8\pi G)$. The constant ξ_c is the critical value of the ratio of the scale factor $\xi = \tilde{a}/a$ between the two metrics, which is found by enforcing the conservation of energy momentum (De Felice et al. 2014) and depends only on the coupling constants of the theory c_i . In turn, Γ_c is a function of the coupling constants c_i and the critical scale factor ratio ξ_c , while m is the mass scaling parameter that enters the bigravity action. What is remarkable about the eigenfunctions presented above is that they are a linear combination of the metric perturbations associated with the physical and auxiliary metrics (h and \tilde{h}). Thus, one finds that as gravitational waves propagate in bigravity, they experience oscillations between the physical and auxiliary sectors (similar to neutrino oscillations), which from the standpoint of the physical metric perturbation will look like artificial oscillations in the waveform amplitude.

The propagation field equations in Sect. 2.3.2 can also be solved for the two eigenfrequencies (De Felice et al. 2014)

$$k_{1,2}^2 = (2\pi f)^2 - \frac{\mu^2}{2} \left(1 + x \mp \sqrt{1 + 2x \frac{1 - \kappa \xi_c^2}{1 + \kappa \xi_c^2} + x^2} \right). \quad (179)$$

Such a modification to the dispersion relation will then introduce the phase correction

$$\delta\Phi_{1,2} = -\frac{\mu D \sqrt{\tilde{c} - 1}}{2\sqrt{2}x} \left(1 + x \mp \sqrt{1 + 2x \frac{1 - \kappa \xi_c^2}{1 + \kappa \xi_c^2} + x^2} \right). \quad (180)$$

Clearly then, the physical metric perturbation $h_{+/\times}$ will not only experience amplitude oscillations, but also phase corrections as the wave propagates a distance D .

But the response function that detectors would observe does not depend on the eigenmodes of the problem, but rather on the reconstructed physical metric perturbation. One can solve for these and construct the Fourier transform of the response function using the stationary phase approximation to find (De Felice et al. 2014)

$$\tilde{h}(f) = \mathcal{A}(f) e^{i\Psi(f)} \left[B_1 e^{i\delta\Phi_1(f)} + B_2 e^{i\delta\Phi_2(f)} \right], \quad (181)$$

after averaging over all sky, where the amplitude coefficients are

$$\mathcal{A}(f) = \sqrt{\frac{5\pi}{24}} \frac{\mathcal{M}^2}{(8\pi M_G^2)^2 D} y^{-7/6}, \quad (182)$$

$$B_1 = \cos \theta_g (\cos \theta_g + \sqrt{\kappa} \xi_c \sin \theta_g), \quad (183)$$

$$B_2 = \sin \theta_g (\sin \theta_g - \sqrt{\kappa} \xi_c \cos \theta_g), \quad (184)$$

and the phases are

$$\Psi(f) = 2\pi f t_c - \phi_c - \frac{\pi}{4} + \frac{3}{128} y^{-5/3} + \frac{5}{96} \left(\frac{743}{336} + \frac{11}{4} \eta \right) \eta^{-2/5} y^{-1} - \frac{3\pi}{8} \eta^{-3/5} y^{-2/3}, \quad (185)$$

up to 1.5 post-Newtonian order, with $y = \mathcal{M}f/(8\tilde{M}_G^2)$. Such a waveform assumes the generation of gravitational waves is not modified in bigravity, which has been justified based on an order-of-magnitude Vainshtein argument.

The bigravity modification to the waveform can be thought of as oscillations between the physical and auxiliary sectors. Since detectors are only sensitive to the physical metric, however, from our viewpoint we would see an unexplained amplitude modulation, reminiscent to that induced by spin precession. The magnitude of the oscillation depends on θ_g , which in turn depends on x . When $x \ll 1$ and when $x \gg 1$, the oscillations are suppressed, as one can see by evaluating the $B_{1,2}$ amplitude functions. Only when $x \sim 1$ does one observe noticeable oscillations between modes. The value of x , however, does not just depend on the frequency and the mass μ , but also on the speed of gravity in the auxiliary sector, which in turn depends on the matter energy density and pressure. One can then expect x to change significantly as the waves leave the environment in which they were generated, where the density is large, and enter a regime of spacetime where the energy density is much smaller.

This bigravity modified gravitational waveform can in principle be used to constrain the theory given gravitational wave observations. Narikawa et al. (2015) predicted that a gravitational wave observations consistent with GR with aLIGO at design sensitivity would lead to a constraint on bigravity of $\mu \lesssim 10^{-17} \text{ cm}^{-1}$ when $\tilde{c} - 1 \gtrsim 10^{-19}$ when one neglects covariances between the bigravity parameters and $\mu \lesssim 10^{-16.5} \text{ cm}^{-1}$ for $\kappa \xi_c^2 \gtrsim \sqrt{10}$ in the full model, which would be stronger than all other bounds imposed on bigravity at the time of Narikawa et al. (2015). These projections were obtained by carrying out a Fisher analysis using non-spinning, quasi-circular inspiral waveforms. Possible degeneracies between bigravity effects and amplitude corrections due to post-Newtonian effects or amplitude modulation due to spin-precession could potentially deteriorate these bounds.

4.2.3 Einstein-Æther theory and Khronometric gravity

Black holes and neutron stars exist in both of these theories, as briefly discussed in Sect. 2.3.3 (Eling et al. 2007; Jacobson 2010; Blas and Sibiryakov 2011; Blas et al. 2011; Wang 2013; Barausse and Sotiriou 2012, 2013a, b; Adam et al. 2022; Ramos and Barausse 2019; Yagi et al. 2014a, b; Barausse 2019; Gupta et al. 2021; Ajith et al. 2022). These bodies have strong self-gravity, and thus, they do not follow a

geodesic path in spacetime, but rather their motion is affected by their internal structure. Such a modification is encoded through sensitivity parameters, which control the difference between the bodies center of (baryonic) mass and its center of energy, where the latter has contributions both from baryons and from the energy in the vector fields of the theory. The calculation of the sensitivity of an isolated body is difficult in these Lorentz-violating gravity theories because it requires that one first solve the field equations for a compact object moving at a constant velocity, and then that one match this solution to a post-Newtonian solution for a binary system close to one of the objects. Foster (2007) calculated the sensitivity s of an isolated body in Einstein-Æther theory in the weak field limit,

$$s^{\text{EA/KG}} = - \left(\alpha_1^{\text{ppN,EA/KG}} - \frac{2}{3} \alpha_2^{\text{ppN,EA/KG}} \right) \frac{C_*}{2}, \quad (186)$$

where C_* is the compactness of the star and $\alpha_{1,2}^{\text{ppN,EA}}$ are the ppN parameter of Eqs. (40) and (41). The sensitivities of neutron stars, however, cannot be modeled by the above formula, since they are not weak-field objects. Instead, one must compute the sensitivities numerically, as done in Yagi et al. (2014a). Having said this, analytic expressions for the neutron star sensitivities are now available in Gupta et al. (2021) for the Tolman VII neutron star models. The sensitivities for black holes have not yet been computed in Einstein-Æther theory. For khronometric theory, Ramos and Barausse (2019) found that the black hole sensitivities vanish when two of the coupling constants (α, β) (which have been constrained stringently from current experiments and observations) are set to zero.

Neglecting radiation reaction, the leading-order modification in a post-Newtonian expansion to the motion of compact objects can be captured by a redefinition of Newton's gravitational constant. In Einstein-Æther theory, Foster (2007), Yagi et al. (2014a) showed that the constant \mathcal{G} in Kepler's third law for a binary system is different from the constant G_N in Newton's third law for a Cavendish-type experiment, and these two are different from the bare constant $G_{\text{EA/KG}}$ that enters the action. One can relate these constants via¹⁶

$$\mathcal{G}_{\text{EA/KG}} = G_N \left(1 - s_1^{\text{EA/KG}} \right) \left(1 - s_2^{\text{EA/KG}} \right), \quad G_N = \frac{2G_{\text{EA}}}{2 - c_{14}} = \frac{2G_{\text{KG}}}{2 - \alpha_{\text{KG}}}, \quad (187)$$

where s_i are the sensitivities of the bodies. At higher post-Newtonian order, these theories introduce other corrections that cannot probably be absorbed via a redefinition of constants. The conservative dynamics of binaries in these theories, however, has not yet been studied beyond Newtonian order.

Gravitational waves exist in both of these theories, but they are not the only propagating degrees of freedom. In Einstein-Æther theory, Jacobson and Mattingly (2004) showed that there are five propagating degrees of freedom: two tensor ones, two vector ones and one scalar mode. In khronometric gravity, there are only three propagating modes (the two tensor ones and the scalar mode), because the

¹⁶ These expressions follow e.g. Zhang et al. (2020) and correct typos in Hansen et al. (2015).

hypersurface orthogonality condition eliminates the vector modes. The speed of propagation of these modes is (Foster 2006)

$$w_0^{\text{EA}} = \left[\frac{(2 - c_{14}c_{123})}{(2 + 3c_2 + c_+)(1 - c_+)c_{14}} \right]^{1/2}, \quad (188)$$

$$w_1^{\text{EA}} = \left[\frac{2c_1 - c_+c_-}{2(1 - c_+)c_{14}} \right]^{1/2}, \quad (189)$$

$$w_2^{\text{EA}} = \left(\frac{1}{1 - c_+} \right)^{1/2}, \quad (190)$$

in Einstein- \mathcal{A} ether theory and

$$w_0^{\text{KG}} = \left[\frac{(\alpha_{\text{KG}} - 2)(\beta_{\text{KG}} + \lambda_{\text{KG}})}{\alpha_{\text{KG}}(\beta_{\text{KG}} - 1)(2 + \beta_{\text{KG}} + 3\lambda_{\text{KG}})} \right]^{1/2}, \quad (191)$$

$$w_2^{\text{KG}} = \left(\frac{1}{1 - \beta_{\text{KG}}} \right)^{1/2}, \quad (192)$$

in khronometric gravity. Gravitational Cherenkov radiation can be evaded, and energy positivity can be enforced if $w_0^{\text{EA/KG}}$, $w_1^{\text{EA/KG}}$ and $w_2^{\text{EA/KG}}$ are all greater than unity (Jacobson 2008b; Elliott et al. 2005).

Let us now consider binary systems in a quasi-circular orbit. In Einstein- \mathcal{A} ether theory, the response function in the time-domain is (Hansen et al. 2015)

$$h_{\text{EA}}(t) = A_2^{\text{EA}} \frac{\mathcal{M}}{r} u^2 (e^{-2i\Phi+i\Theta} + e^{2i\Phi-i\Theta}) + A_1^{\text{EA}} \bar{\alpha}^{\text{EA}} \frac{\mathcal{M}}{r} \eta^{1/5} u (e^{-i\Phi} + e^{+i\Phi}), \quad (193)$$

where $\Theta = \tan^{-1}[2F_\times \cos \iota / F_+(1 + \cos^2 \iota)]$, and to leading post-Newtonian order,

$$A_2^{\text{EA}} = G_{\text{EA}} \left[F_+^2 (1 + \cos^2 \iota)^2 + 4F_\times^2 \cos^2 \iota \right]^{1/2}, \quad (194)$$

$$A_1^{\text{EA}} = 2G_{\text{EA}}(s_1 - s_2), \quad (195)$$

$$\begin{aligned} \bar{\alpha}^{\text{EA}} \equiv & \left[\frac{4c_+}{2c_1 - c_+c_-} F_l - \frac{c_2 + 1}{c_{123}(c_{14} - 2)w_0^{\text{EA}}} \right. \\ & \times (F_b + 2F_l) + \frac{1}{(c_{14} - 2)c_+w_0^{\text{EA}}} (F_b - 2F_l) \Big] \sin \iota \\ & + \frac{c_+}{2c_1 - c_+c_-} [iF_{\text{sn}} + \cos \iota F_{\text{se}}], \end{aligned} \quad (196)$$

and where $(F_+, F_\times, F_b, F_l, F_{\text{se}}, F_{\text{sn}})$ are beam pattern functions. One can show that the breathing and the longitudinal modes in the response function above are not

linearly independent, leaving only 5 independent degrees of freedom. In khronometric gravity, the time-domain response is

$$h(t)^{\text{KG}} = A_2^{\text{KG}} \frac{\mathcal{M}}{r} u (e^{-2i\phi+i\theta} + e^{+2i\phi-i\theta}) + A_1^{\text{KG}} \bar{\alpha}^{\text{KG}} \frac{\mathcal{M}}{r} \eta^{1/5} u^2 (e^{-i\phi} + e^{i\phi}), \quad (197)$$

where

$$A_2^{\text{KG}} = A_2^{\text{EA}}, \quad A_1^{\text{KG}} = 4 G_{\text{EA}} (s_1^{\text{KG}} - s_2^{\text{KG}}), \quad (198)$$

$$\bar{\alpha}^{\text{KG}} = \left[\frac{\sqrt{\alpha^{\text{KG}}} (\lambda^{\text{KG}} + 1)}{\beta^{\text{KG}} + \lambda^{\text{KG}}} (F_b + 2F_l) + \frac{1}{\sqrt{\alpha^{\text{KG}}}} (F_b - 2F_l) \right]. \quad (199)$$

Comparing these response functions, we note that although the two expressions for $A_{1,2}$ are very similar, the expressions for $\bar{\alpha}$ are quite different because of the absence of vector modes in khronometric gravity.

The presence of scalar and vector modes enhances the energy and angular momentum loss. Let us consider then again binary systems in a quasi-circular inspiral. In both Lorentz-violating theories, the total rate of energy carried away by all propagating degrees of freedom can be written as (Hansen et al. 2015)

$$\dot{E}_{\text{EA/KG}}(u) = \dot{E}_{\text{GR}}(u) \left[1 + \frac{7}{4} \eta^{2/5} u_{\text{EA/KG}}^{-2} E_{-1\text{PN}}^{\text{EA/KG}} + E_{0\text{PN}}^{\text{EA/KG}} \right], \quad (200)$$

where $\dot{E}_{\text{GR}}(u) \equiv -(32/5)u^{10}[1 + \mathcal{O}(c^{-2})]$ is the leading post-Newtonian order prediction, with $u_{\text{EA/KG}} = (2\pi\mathcal{G}_{\text{EA/KG}}\mathcal{M}F)^{1/3}$ and F the orbital frequency, and where

$$\dot{E}_{-1\text{PN}}^{\text{EA}} = \frac{5}{84} \mathcal{G} (s_1 - s_2)^2 \frac{(c_{14} - 2)(w_0^{\text{EA}})^3 - (w_1^{\text{EA}})^3}{c_{14}(w_0^{\text{EA}})^3(w_1^{\text{EA}})^3}, \quad (201)$$

$$\begin{aligned} \dot{E}_{0\text{PN}}^{\text{EA}} = & \mathcal{G} \left(1 - \frac{c_{14}}{2} \right) \left(\frac{1}{w_2^{\text{EA}}} + \frac{2c_{14}c_+^2}{(2c_1 - c_-c_+)^2 w_1^{\text{EA}}} \right. \\ & \left. + \frac{3c_{14}(Z_{\text{EA}} - 1)^2}{2w_0^{\text{EA}}(2 - c_{14})} + S\mathcal{A}_2^{\text{EA}} + S^2\mathcal{A}_3^{\text{EA}} \right) - 1, \end{aligned} \quad (202)$$

in Einstein-Æther theory and

$$\dot{E}_{-1\text{PN}}^{\text{KG}} = \frac{5}{84} \mathcal{G} (s_1 - s_2)^2 \sqrt{\alpha^{\text{KG}}} \left[\frac{(\beta^{\text{KG}} - 1)(2 + \beta^{\text{KG}} + 3\lambda^{\text{KG}})}{(\alpha^{\text{KG}} - 2)(\beta^{\text{KG}} + \lambda^{\text{KG}})} \right]^{3/2}, \quad (203)$$

$$\dot{\beta}_{\text{OPN}}^{\text{KG}} \equiv \tilde{\beta}_{\text{OPN}}^{\text{KG}} = \mathcal{G} \left(1 - \frac{2}{\beta_{\text{KG}}} \right) \left(\frac{1}{w_2^{\text{KG}}} + \frac{3\alpha_{\text{KG}}(Z_{\text{KG}} - 1)^2}{2w_0^{\text{KG}}(2 - \alpha_{\text{KG}})} + S\mathcal{A}_2^{\text{KG}} + S^2\mathcal{A}_3^{\text{KG}} \right) - 1, \quad (204)$$

in khronometric gravity. In these expressions, $S \equiv (s_1 m_2 + s_2 m_1)/m$ is the sum of the mass-weighted sensitivities, $\mathcal{A}_{2,3}^{\text{EA/KG}}$ are functions of the coupling parameters given explicitly in Yagi et al. (2014a), and

$$Z_{\text{EA}} = \frac{(\alpha_1^{\text{ppN}} - 2\alpha_2^{\text{ppN}})(1 - c_+)}{3(2c_+ - c14)}, \quad Z_{\text{KG}} = \frac{(\alpha_1^{\text{ppN}} - 2\alpha_2^{\text{ppN}})(1 - \beta_{\text{KG}})}{3(2\beta_{\text{KG}} - \alpha_{\text{KG}})}. \quad (205)$$

With this in hand, we can compute the Fourier transform of the response function in the stationary-phase approximation. Focusing again on quasi-circular binary system, one finds (Hansen et al. 2015)

$$\tilde{h}_{\text{EA/KG}}(f) = \mathcal{A}_{(1)}^{\text{EA/KG}} e^{-i\Psi_{\text{EA/KG}}^{(1)}} + \mathcal{A}_{(2)}^{\text{EA/KG}} e^{-i\Psi_{\text{EA/KG}}^{(2)}}, \quad (206)$$

where

$$\begin{aligned} \Psi_{\text{EA}}^{(\ell)} = & 2\pi f t_c + \Phi_c - \frac{\pi}{4} - \frac{3\ell}{256} u_{\ell,\text{EA}}^{-5} [1 + \mathcal{O}(c^{-2})] \\ & - \frac{3\ell}{256} u_{\ell,\text{EA}}^{-5} \left[\dot{E}_{-1\text{PN}}^{\text{EA}} \eta^{2/5} u_{\ell,\text{EA}}^{-2} + \dot{E}_{0\text{PN}}^{\text{EA}} + \mathcal{O}(c^{-2}) \right], \end{aligned} \quad (207)$$

$$\mathcal{A}_{(1)}^{\text{EA}} = - \left(\frac{5\pi}{48} \right)^{1/2} A_1^{\text{EA}} \bar{\alpha}^{\text{EA}} \frac{\mathcal{M}^2}{r_{12}} \eta^{1/5} u_{1,\text{EA}}^{-9/2}, \quad \mathcal{A}_{(2)}^{\text{EA}} = \left(\frac{5\pi}{96} \right)^{1/2} A_2^{\text{EA}} \frac{\mathcal{M}^2}{r_{12}} u_{2,\text{EA}}^{-7/2}, \quad (208)$$

in Einstein-Æther theory and

$$\begin{aligned} \Psi_{\text{KG}}^{(\ell)} = & 2\pi f t_c + \Phi_c - \frac{\pi}{4} - \frac{3\ell}{256} u_{\ell}^{-5} [1 + \mathcal{O}(c^{-2})] \\ & - \frac{3\ell}{256} u_{\ell}^{-5} \left[\dot{E}_{-1\text{PN}}^{\text{KG}} \eta^{2/5} u_{\ell,\text{KG}}^{-2} + \dot{E}_{0\text{PN}}^{\text{KG}} + \mathcal{O}(c^{-2}) \right], \end{aligned} \quad (209)$$

$$\mathcal{A}_{(1)}^{\text{KG}} = \left(\frac{5\pi}{48} \right)^{1/2} A_1^{\text{KG}} \bar{\alpha}^{\text{KG}} \frac{\mathcal{M}^2}{r_{12}} \eta^{1/5} u_{1,\text{KG}}^{-9/2}, \quad \mathcal{A}_{(2)}^{\text{KG}} = \left(\frac{5\pi}{96} \right)^{1/2} A_2^{\text{KG}} \frac{\mathcal{M}^2}{r_{12}} u_{2,\text{KG}}^{-7/2}. \quad (210)$$

in khronometric gravity. In these expressions, $u_{\ell,\text{EA/KG}} \equiv (2\pi\mathcal{G}_{\text{EA/KG}}\mathcal{M}f/\ell)^{1/3}$ and (t_c, ϕ_c) are constant time and phase offsets. One can of course keep higher order terms in the post-Newtonian expansion in the GR sector easily.

The above calculations in Einstein-Æther theory were later updated by a few different groups. Zhang et al. (2020) derived the response function in both the time and frequency domains. For the former, the $\ell = 2$ harmonic depends not only on the tensor modes but also on the scalar and vector modes, even to leading post-

Newtonian order, though such scalar and vector modes vanish when $c_{14} = 0$ and $c_+ = 0$, respectively. The expression for the $\ell = 1$ harmonic is also corrected. For the response function in the frequency domain, the dominant $\ell = 2$ harmonic for the tensor mode is given by

$$\begin{aligned} \tilde{h}_{\text{EA}}(f) = & -\sqrt{\frac{5\pi}{96}} \frac{(G_N \mathcal{M})^2}{R} \mathcal{U}_{2,\text{EA}}^{-7/2} [F_+ (1 + \cos^2 \iota) + 2iF_\times \cos \iota] \\ & \times \left(1 - \frac{1}{2\sqrt{\kappa_3}} \eta^{2/5} \epsilon_x \mathcal{U}_{2,\text{EA}}^{-2}\right) e^{i\Psi_{\text{EA}}^{(2)}}, \end{aligned} \quad (211)$$

with

$$\begin{aligned} \Psi_{\text{EA}}^{(2)} = & 2\pi f \left(t_c + \frac{r}{w_2^{\text{EA}}} \right) - \Phi_c - \frac{\pi}{4} + \frac{3}{128} \mathcal{U}_{2,\text{EA}}^{-5} [1 + \mathcal{O}(c^{-2})] \\ & - \frac{3}{224} \frac{\eta^{2/5} \epsilon_x}{\kappa_3} \mathcal{U}_{2,\text{EA}}^{-7} - \frac{3}{128} \left[-\frac{2}{3} (s_1 + s_2) - \frac{1}{2} c_{14} + \kappa_3 - 1 \right] \mathcal{U}_{2,\text{EA}}^{-5} [1 + \mathcal{O}(c^{-2})], \end{aligned} \quad (212)$$

$$\mathcal{U}_{2,\text{EA}} = (\pi G_N \mathcal{M} f)^{1/3}, \quad (213)$$

while κ_3 and ϵ_x are given in Zhang et al. (2020). Taherasghari and Will (2023) carried out a direct integration of the relaxed field equations up to 2.5 post-Newtonian order, while Hou et al. (2024) studied the GW memory effect in Einstein-Æther theory.

As one can see from the description above, the propagation speed of the tensor modes is different from the speed of light by a *constant* factor, which makes this effect difficult to measure with detections by a single instrument. However, the detection of a single event by more than one instrument can be used to place a bound on the speed of gravity. Given N detectors located at different places on Earth, a gravitational wave will hit every detector at different times. The time difference between the detection at each instrument (measured for example as the time at which the amplitude of the wave reaches its maximum at the given instrument) is then related to the speed of the wave and the distance between detectors. A time difference that is consistent with waves traveling at the speed of light can place a constraint on the speed of gravity of $\mathcal{O}(1)$ in units of the speed of light (Blas et al. 2016).

Einstein-Æther theory and khronometric gravity can also be constrained using information about the precise functional form of the response function presented above. Hansen et al. (2015) carried out the first analysis to investigate this possibility with aLIGO at design sensitivity and with the Einstein Telescope. Chamberlain and Yunes (2017) expanded this analysis by considering a wider range of third-generation future ground-based detectors, as well as space-based detectors. Both analysis first considered the quasi-circular inspiral of binary neutron stars, because the sensitivities for these systems are known (Yagi et al. 2014a). For such binaries, the -1PN order term in the phase of the response function (the one

proportional to $\dot{E}_{-1\text{PN}}^{\text{EA/KG}}$ in Eqs. (207) and (209)) is suppressed by the square of the difference of the sensitivities as shown in Eqs. (201) and (203). This is both because $s_1 \sim s_2$ for binary neutron stars because their masses are similar and because $s_{1,2} \ll 1$ for neutron stars to begin with. Thus, when considering binary neutron stars, the bounds are weaker than one would have expected, since the phase modification is dominated by a term of Newtonian order in the phase. Hansen et al. (2015) found that aLIGO could not place constraints on (c_+, c_-) or $(\lambda_{\text{KG}}, \beta_{\text{KG}})$ that are better than current binary pulsar constraints. However, both Hansen et al. (2015) and Chamberlain and Yunes (2017) found that third-generation detectors will obtain constraints comparable to binary pulsar ones in the future. Chamberlain and Yunes (2017) also found that if binary black hole inspirals are considered and if the sensitivities do not suppress the GR modification, then the bounds become roughly an order of magnitude better, since then the modification enters at -1PN order. These analyses assumed that the post-Newtonian parameters characterizing the preferred-frame effect vanish, and probed only (c_+, c_-) or $(\lambda_{\text{KG}}, \beta_{\text{KG}})$. However, the multi-messenger observations of GW170817 have constrained the deviation in the propagation speed of gravitational waves away from the speed of light to $\sim 10^{-15}$ or smaller (Abbott et al. 2017a). From Eqs. (190) and (192), this means c_+ and β_{KG} have been constrained effectively to zero. Therefore, the bounds on these theories with gravitational waves need to be reanalyzed by imposing $c_+ = 0$ or $\beta_{\text{KG}} = 0$ and varying over the remaining parameters. Schumacher et al. (2023a) carried out such an analysis for the GW170817 event in Einstein-AEther theory, and found that current GW observations do not place bounds that are stronger than Solar System experiments, or binary pulsar and cosmological observations.

4.2.4 Modified quadratic gravity

Gravitational waves are modified in quadratic modified gravity. In dynamical Chern–Simons gravity, Garfinkle et al. (2010) have shown that the propagation of such waves on a Minkowski background remains unaltered, and thus, all modifications arise during the generation stage. In Einstein–dilaton–Gauss–Bonnet theory, a similar analysis shows that gravitational waves can travel at phase velocities different from that of light, but such effects become negligible in the very far-away radiation zone (Ayzenberg et al. 2014). Yagi et al. (2012b) studied the generation mechanism in both theories during the quasi-circular inspiral of comparable-mass, spinning black holes in the post-Newtonian and small-coupling approximations. They found that a standard post-Newtonian analysis fails for such theories because the assumption that black holes can be described by a distributional stress-energy tensor without any further structure fails. They also found that since black holes acquire scalar hair in these theories, and this scalar field is anchored to the curvature profiles, as black holes move, the scalar fields must follow the singularities, leading to dipole scalar-field emission. Julié and Berti (2019) studied the post-Newtonian dynamics of a two-body system in scalar Gauss–Bonnet gravity through a “skeltonization” of black holes. That is, one approximates a black hole

with a point-particle that has a mass that depends on the scalar field (Eardley 1975). The scalar hair is related to the derivative of this mass through the scalar field.

During a quasi-circular inspiral of spinning black holes in dynamical Chern–Simons gravity, the total gravitational wave energy flux carried out to spatial infinity (equal to minus the rate of change of a binary’s binding energy by the balance law) is modified from the GR expectation to leading order by (Yagi et al. 2012b)

$$\frac{\delta \dot{E}_{\text{spin}}^{\text{CS}}}{\dot{E}_{\text{GR}}} = \frac{25}{1236} \zeta_4 \eta^{-2} \left[\bar{A}^2 + 27 \langle (\bar{A} \cdot \hat{v}_{12})^2 \rangle \right] \quad (214)$$

due to scalar field radiation and corrections to the metric perturbation that are of magnetic-type, quadrupole form. In this equation, $\dot{E}_{\text{GR}} = (32/5)\eta^2 m^2 v^4 \omega^2$ is the leading-order GR prediction for the total energy flux, $\zeta_4 = \alpha_4^2/(\beta km^4)$ is the dimensionless Chern–Simons coupling parameter, \hat{v}_{12} is the unit relative velocity vector, $\bar{A}^i = (m_2/m)(a_1/m_1)\hat{S}_1^i - (m_1/m)(a_2/m_2)\hat{S}_2^i$, where a_A is the Kerr spin parameter of the A th black hole and \hat{S}_A^i is the unit vector in the direction of the spin angular momentum, and the angle brackets stand for an average over several gravitational wave wavelengths. If the black holes are not spinning, then the correction to the scalar energy flux is greatly suppressed (Yagi et al. 2012b)

$$\frac{\delta \dot{E}_{\text{no-spin}}^{\text{CS}}}{\dot{E}_{\text{GR}}} = \frac{2}{3} \delta_m^2 \zeta_4 v_{12}^{14}, \quad (215)$$

where we have defined the reduced mass difference $\delta_m \equiv (m_1 - m_2)/m$. Notice that this is a 7 post-Newtonian–order correction, instead of a 2 post-Newtonian correction as in Eq. (214). In the non-spinning limit, the dynamical Chern–Simons correction to the metric tensor induces a 6 post-Newtonian–order correction to the gravitational energy flux (Yagi et al. 2012b), which is consistent with the numerical results of Pani et al. (2011b).

On the other hand, in Einstein–dilaton–Gauss–Bonnet gravity, the corrections to the energy flux are (Yagi et al. 2012b)

$$\frac{\delta \dot{E}_{\text{no-spin}}^{\text{EDGB}}}{\dot{E}_{\text{GR}}} = \frac{5}{96} \eta^{-4} \delta_m^2 \zeta_3 v_{12}^{-2}, \quad (216)$$

which is a -1 post-Newtonian correction. This is because the scalar field ϑ_{EDGB} behaves like a monopole (see Eq. (54)), and when such a scalar monopole is dragged by the black hole, it emits electric-type, dipole scalar radiation. Any hairy black hole with monopole hair will thus emit dipolar radiation, leading to -1 post-Newtonian corrections in the energy flux carried to spatial infinity.

Such modifications to the energy flux modify the rate of change of the binary’s binding energy through the balance law, $\dot{E} = -\dot{E}_b$, which in turn modify the rate of change of the gravitational wave frequency and phase, $\dot{F} = -\dot{E} (dE_b/dF)^{-1}$. For dynamical Chern–Simons gravity (when the spins are aligned with the orbital angular momentum) and for Einstein–dilaton–Gauss–Bonnet theory (in the non-spinning case), the Fourier transform of the gravitational-wave response function in

the stationary phase approximation for binary black holes becomes (Yagi et al. 2012b, c)

$$\tilde{h}_{\text{dCS,EDGB}} = \tilde{h}_{\text{GR}}(1 + \alpha_{\text{dCS,EDGB}} u^{a_{\text{dCS,EDGB}}} e^{i\beta_{\text{dCS,EDGB}} u^{b_{\text{dCS,EDGB}}}}), \quad (217)$$

where \tilde{h}_{GR} is the Fourier transform of the response in GR, $u \equiv (\pi \mathcal{M} f)^{1/3}$ with f the gravitational wave frequency. For dynamical Chern–Simons theory, the phase corrections are given by (Yagi et al. 2012c)

$$\begin{aligned} \beta_{\text{dCS}} &= -\frac{507775}{7340032} \frac{\zeta_4}{\eta^{4/5}} \frac{m^2 a_1^2}{m_1^2 m_2^2} \left[1 - \frac{58833}{20311} (\hat{S}_1 \cdot \hat{L})^2 \right] \\ &\quad + \frac{63625}{1048576} \frac{\zeta_4}{\eta^{9/5}} \frac{a_1 a_2}{m_1 m_2} \left[(\hat{S}_1 \cdot \hat{S}_2) - \frac{1467}{509} (\hat{S}_1 \cdot \hat{L})(\hat{S}_2 \cdot \hat{L}) \right] + 1 \rightarrow 2, \\ b_{\text{dCS}} &= -1, \end{aligned} \quad (218)$$

where $\hat{S}_{1,2}$ and \hat{L} are the unit spin and orbital angular momenta respectively. For the spin-aligned case, the above expression reduces to (Tahura and Yagi 2018)

$$\begin{aligned} \beta_{\text{dCS}} &= \frac{481525}{3670016} \eta^{-14/5} \zeta_4 \left[-2\delta_m \chi_a \chi_s + \left(1 - \frac{4992\eta}{19261} \right) \chi_a^2 + \left(1 - \frac{72052\eta}{19261} \right) \chi_s^2 \right], \\ b_{\text{dCS}} &= -1, \end{aligned} \quad (219)$$

where $\chi_s \equiv (\chi_1 + \chi_2)/2$, $\chi_a \equiv (\chi_1 - \chi_2)/2$ with $\chi_A \equiv a_A/m_A$, and the amplitude correction is given by (Tahura and Yagi 2018)

$$\begin{aligned} \alpha_{\text{dCS}} &= \frac{57713}{344064} \eta^{-14/5} \zeta_4 \left[-2\delta_m \chi_a \chi_s + \left(1 - \frac{14976\eta}{57713} \right) \chi_a^2 + \left(1 - \frac{215876\eta}{57713} \right) \chi_s^2 \right], \\ a_{\text{dCS}} &= +4. \end{aligned} \quad (220)$$

For Einstein–dilaton–Gauss–Bonnet theory, the phase and amplitude corrections are given by

$$\beta_{\text{EDGB}} = -\frac{5}{7168} \zeta_3 \eta^{-18/5} \delta_m^2, \quad b_{\text{EDGB}} = -7, \quad (221)$$

$$\alpha_{\text{EDGB}} = -\frac{5}{192} \zeta_3 \eta^{-18/5} \delta_m^2, \quad a_{\text{EDGB}} = -2, \quad (222)$$

We have included both deformations to the binding energy and Kepler’s third law, in addition to changes in the energy flux, when computing the phase correction. However, in Einstein–dilaton–Gauss–Bonnet theory the binding energy is modified at higher post-Newtonian order, and thus, corrections to the energy flux control the leading modifications to the gravitational-wave response function.

Can we go beyond leading corrections to the waveforms in these theories? Higher post-Newtonian corrections in Einstein–dilaton–Gauss–Bonnet gravity were derived in Shiralilou et al. (2021), Shiralilou et al. (2022) to first post-Newtonian order higher than the leading, tensor non-dipole and scalar dipole emission respectively. This was later corrected and extended to second post-Newtonian order relative to the leading tensor/scalar contribution by Lyu et al. (2022), which used the results in Sennett et al. (2016) for scalar-tensor theories, but the corresponding scalar charges for black holes in Einstein–dilaton–Gauss–Bonnet gravity. For spin-precessing binaries, the precession equations are modified. Loutrel et al. (2018), Loutrel et al. (2019), Loutrel and Yunes (2022) solved such equations and derived gravitational waveforms in dynamical Chern–Simons gravity, including spin precession (see also Li et al. 2023b for related work). Li et al. (2024b) studied gravitational waves from eccentric compact binaries in dynamical Chern–Simons gravity. Going beyond the inspiral, numerical relativity simulations have been carried out in quadratic gravity to find gravitational waves and scalar waves during the merger-ringdown stage. Okounkova et al. (2017), Okounkova et al. (2019), Okounkova et al. (2020) carried out such simulations in dynamical Chern–Simons gravity within the small-coupling approximation. Treating the theory as an effective field theory has the advantage that the principal parts of the modified Einstein equations are the same as in GR, and thus, are well-posed. In Einstein–dilaton–Gauss–Bonnet gravity, Witek et al. (2019) derived the scalar dynamics, while Okounkova (2020) found merger-ringdown gravitational waveforms within the small coupling approximation. Ripley and Pretorius (2020), East and Ripley (2021b), Corman et al. (2023) performed similar simulations by fully solving the field equations to find waveforms without using the small-coupling approximation. Watarai et al. (2024) recently constructed a parameterized merger waveform via a principal component analysis, and applied their formulation to Einstein–dilaton–Gauss–Bonnet gravity. The ringdown can also be studied through black hole perturbation theory. Quasi-normal mode frequencies were computed for slowly-rotating black holes in dynamical Chern–Simons gravity to first order in spin in Wagle et al. (2022), Srivastava et al. (2021), while those in Einstein–dilaton–Gauss–Bonnet gravity were derived to zeroth-order (Blázquez-Salcedo et al. 2016; Bryant et al. 2021; Luna et al. 2024), first-order (Pierini and Gualtieri 2021) and second-order (Pierini and Gualtieri 2022) in spin, as well as for rapidly-rotating black holes for the first time in Chung and Yunes (2024a), which was recently extended in Blázquez-Salcedo et al. (2024). East and Pretorius (2022) performed numerical relativity simulations for binary neutron star mergers in (shift-symmetric) Einstein–dilaton–Gauss–Bonnet gravity and found that, while the non-GR corrections during the inspiral are small (because neutron stars do not possess scalar charges in this theory), there can be strong scalar effects during the post-merger phase. Kuan et al. (2023a) carried out numerical relativity simulations for binary neutron star mergers in scalar-Gauss-Bonnet gravity with dynamical scalarization and found a universal relation between the compactness of an isolated neutron star and the critical coupling strength for scalarization.

From the above analysis, it should be clear that the corrections to the gravitational-wave observable in quadratic modified gravity are always proportional

to the quantity $\zeta_{3,4} \equiv \xi_{3,4}/m^4 = \alpha_{3,4}^2/(\beta\kappa m^4)$. Thus, any measurement that is consistent with GR will allow a constraint of the form $\zeta_{3,4} < N\delta$, where N is a number of order unity, and δ is the accuracy of the measurement. Solving for the coupling constants of the theory, such a measurement would lead to $\xi_{3,4}^{1/4} < (N\delta)^{1/4}m$ (Sopuerta and Yunes 2009). Therefore, constraints on quadratic modified gravity will weaken for systems with larger characteristic mass. This can be understood by noticing that the corrections to the action scale with positive powers of the Riemann tensor, while this scales inversely with the mass of the object, i.e., the smaller a compact object is, the larger its curvature. Such an analysis then automatically predicts that LIGO will be able to place stronger constraints than LISA-like missions on such theories, because LIGO operates in the 100 Hz frequency band, allowing for the detection of stellar-mass inspirals, while LISA-like missions operate in the mHz band, and are limited to supermassive black-holes inspirals. This reasoning is valid, except for extreme mass-ratio inspirals detectable with LISA, which consist of a stellar mass black hole inspiraling into a supermassive one; in this case, the constraints achievable with LISA can be comparable or in some cases better than those that can be obtained with ground-based instruments (Chamberlain and Yunes 2017; Perkins et al. 2021b; Maselli et al. 2020a, 2022; Barsanti et al. 2022).

How well can these modifications be measured with gravitational-wave observations? Yagi et al. (2012b) predicted, based on the results of Cornish et al. (2011), that a sky-averaged LIGO gravitational-wave observation with SNR of 10 of the quasi-circular inspiral of non-spinning black holes with masses $(6, 12)M_\odot$ would allow a constraint of $\xi_3^{1/4} \lesssim 20$ km, where we recall that $\xi_3 = \alpha_3^2/(\beta\kappa)$. A similar sky-averaged, eLISA observation of a quasi-circular, spin-aligned black-hole inspiral with masses $(10^6, 3 \times 10^6)M_\odot$ would constrain $\xi_3^{1/4} < 10^7$ km (Yagi et al. 2012b). The loss in constraining power comes from the fact that the constraint on ξ_3 will scale with the total mass of the binary, which is six orders of magnitude larger for equal-mass binaries detectable with space-borne sources. Similarly, the observation of the ringdown part of the signal, instead of the inspiral, can also lead to constraints on the theory, since the ringdown spectrum is shifted from the GR one by ξ_3 . Blázquez-Salcedo et al. (2016) have argued that a ringdown observation with ringdown SNR of 50 could allow for a constraint of $\xi_3^{1/4} \lesssim 30$ km. More recently, Chung and Yunes (2024a, b) updated this estimate through the calculation of the ringdown frequencies for $10M_\odot$ black holes of moderate spins, finding that an SNR 10 event should allow a constraint of $\xi_3^{1/4} \lesssim 30$ km. As already discussed in Sect. 2.3.4, existing gravitational-wave events from O1–O3 runs can place bounds that are stronger than the above estimates because of the stacking of multiple events (which leads to an enhancement of roughly $1/N^{1/2}$ after stacking N events of the same SNR). Using inspiral-only waveforms, one arrives at the stacked bound $\xi_3^{1/4} \lesssim 3$ km (Nair et al. 2019; Perkins et al. 2021a; Wang et al. 2021a, 2023a; Lyu et al. 2022). The most up-to-date stacked gravitational-wave bound is $\xi_3^{1/4} \lesssim 0.3$ km, which was found by Julié et al. (2025) through the construction of an inspiral-

merger-ringdown waveform in scalar Gauss–Bonnet gravity via the effective-one-body framework that was compared to O1–O3 events. This bound stronger than other non-gravitational-wave bounds from the existence of compact objects (Pani et al. 2011a) ($\xi_3^{1/4} < 26$ km) and from the change in the orbital period of the low-mass X-ray binary A0620–00 ($\xi_3^{1/4} < 1.9$ km) (Yagi 2012a). Future gravitational-wave detectors will be able to probe the theory even more stringently (Carson and Yagi 2020b, c, e, f; Carson et al. 2020; Perkins et al. 2021b). For example, future multiband observations with ground-based and space-based detectors (Sesana 2016; Barausse et al. 2016; Liu et al. 2020) may probe the theory to $\xi_3^{1/4} \lesssim 10^{-1}$ km or better (Carson et al. 2020; Perkins et al. 2021b), while a population of GW events with third-generation gravitational-wave detectors can place the bound $\xi_3^{1/4} \lesssim 10^{-3} - 10^{-2}$ km (Perkins et al. 2021b).

In dynamical Chern–Simons gravity, one expects similar projected gravitational-wave constraints on ξ_4 , namely $\xi_4^{1/4} < \mathcal{O}(M)$, where M is the total mass of the binary system in kilometers. Therefore, for binaries detectable with ground-based interferometers, one expects constraints of order $\xi_4^{1/4} < 10$ km. In this case, such a constraint would be roughly six orders of magnitude stronger than current LAGEOS bounds (Ali-Haïmoud and Chen 2011). Dynamical Chern–Simons gravity cannot be constrained with binary pulsar observations, since the theory’s corrections to the post-Keplerian observables are too high post-Newtonian order, given the current observational uncertainties (Yagi et al. 2013). However, the gravitational wave constraint is more difficult to achieve in the dynamical Chern–Simons case, because the correction to the gravitational wave phase is degenerate with spin. However, Yagi et al. (2012c) argued that precession should break this degeneracy, and if a signal with sufficiently high SNR is observed, such bounds would be possible. One must be careful, of course, to check that the small-coupling approximation is still satisfied when saturating such a constraint (Yagi et al. 2012c). When using current gravitational-wave observations, the bounds from the correction to the inspiral are too weak and do not satisfy the small-coupling approximation (Nair et al. 2019; Perkins et al. 2021a; Wang et al. 2021a), making such bounds unreliable. When focusing on the correction to the ringdown, Silva et al. (2023) derived the bound as $\xi_4^{1/4} \lesssim 100$ km, but this relies on a small spin expansion (which may not be accurate for remnant black holes that spin fast). Similar to the Einstein–dilaton–Gauss–Bonnet case, future gravitational-wave observations are expected to improve the bound further (Yagi et al. 2012c; Carson and Yagi 2020b, c; Perkins et al. 2021b). For example, a population of GW events with third-generation gravitational-wave detectors can place the bound of $\xi_4^{1/4} \lesssim 10^{-2} - 10^{-1}$ km (Perkins et al. 2021b).

Although the main focus of this subsection is quadratic gravity theories, in which the action is corrected at quadratic order in curvature, in principle, there are also higher-order curvature corrections that one could study. Endlich et al. (2017) constructed an effective field theory extension to GR that can be tested with gravitational waves. This effective field theory does not involve additional fields, so it does not reduce to Einstein–dilaton–Gauss–Bonnet or dynamical Chern–Simons

gravity, even if one truncates the effective theory at quadratic order in curvature. Sennett et al. (2020) included quartic order corrections and derived bounds on the theory with existing gravitational-wave observations. Silva et al. (2023) derived constraints on the characteristic length scale of the cubic (ℓ_{cEFT}) and quartic (ℓ_{qEFT}) order effective field theory from ringdown observations of GW150914 and GW200129, namely $\ell_{\text{cEFT}} \leq 38.2$ km and $\ell_{\text{qEFT}} \leq 51.3$ km respectively, again assuming a small spin expansion. Liu and Yunes (2024) constructed an approximate inspiral-merger-ringdown waveform in cubic effective field theory of gravity and derived a new bound from the GW170608 event that is 3.5 times stronger than previous constraints. The curvature dependence of gravitational-wave tests of GR has recently been carried out by Payne et al. (2024) in a model-independent framework that is similar to the one developed by Stein and Yagi (2014), which parameterizes scalar-interactions in the gravitational action.

4.2.5 Non-commutative geometry

As described in Sect. 2.3.6, there are two main approaches of non-commutative geometry. We will review gravitational waves in each of these classes below:

(I) Spectral Geometry

Black holes exist in the spectral non-commutative geometry theories. What is more, the usual Schwarzschild and Kerr solutions of GR persist in these theories. This is not because such solutions have vanishing Weyl tensor, but because the quantity $\nabla^{\alpha\beta}C_{\mu\nu\alpha\beta}$ happens to vanish for such metrics. Similarly, one would expect that the two-body, post-Newtonian metric that describes a black-hole–binary system should also satisfy the non-commutative geometry field equations, although this has not been proven explicitly. Moreover, although neutron-star spacetimes have not yet been considered in non-commutative geometries, it is likely that if such spacetimes are stationary and satisfy the Einstein equations, they will also satisfy the modified field equations. Much more work on this is still needed to put all of these concepts on a firmer basis.

Gravitational waves exist in non-commutative gravity. Their generation for a compact binary system in a circular orbit was analyzed by in Nelson et al. (2010a, b). They began by showing that a transverse-traceless gauge exists in this theory, although the transverse-traceless operator is slightly different from that in GR. They then proceeded to solve the modified field equations for the metric perturbation [Eq. (69)] via a Green’s function approach:

$$h^{ik} = 2\beta \int \frac{dt'}{\sqrt{(t-t')^2 - |r|^2}} I^{ik}(t') \mathcal{J}_1(\beta \sqrt{(t-t')^2 - |r|^2}), \quad (223)$$

where recall that $\beta^2 = (-32\pi\alpha_0)^{-1}$ acts like a mass term, the integral is taken over the entire past light cone, $\mathcal{J}_1(\cdot)$ is the Bessel function of the first kind, $|r|$ is the distance from the source to the observer and the quadrupole moment is defined as usual:

$$I^{ik} = \int d^3x T_{\text{mat}}^{00} x^{ik}, \quad (224)$$

where T^{00} is the time-time component of the matter stress-energy tensor. Of course, this is only the first term in an infinite multipole expansion.

Although the integral in Eq. (223) has not yet been solved in the post-Newtonian approximation, Nelson et al. (2010a, b) did solve for its time derivative to find

$$\dot{h}^{xx} = -\dot{h}^{yy} = 32\beta\mu r_{12}^2\Omega^4 \left[\sin(2\phi)f_c\left(\beta|r|, \frac{\Omega}{\beta}\right) + \cos(2\phi)f_s\left(\beta|r|, \frac{2\Omega}{\beta}\right) \right], \quad (225a)$$

$$\dot{h}^{xy} = -32\beta\mu r_{12}^2\Omega^4 \left[\sin\left(2\phi - \frac{\pi}{2}\right)f_c\left(\beta|r|, \frac{\Omega}{\beta}\right) + \cos\left(2\phi - \frac{\pi}{2}\right)f_s\left(\beta|r|, \frac{2\Omega}{\beta}\right) \right], \quad (225b)$$

where $\Omega = 2\pi F$ is the orbital angular frequency, we have defined

$$f_s(x, z) = \int_0^\infty \frac{ds}{\sqrt{s^2 + x^2}} \mathcal{J}_1(s) \sin\left(z\sqrt{s^2 + x^2}\right), \quad (226)$$

$$f_c(x, z) = \int_0^\infty \frac{ds}{\sqrt{s^2 + x^2}} \mathcal{J}_1(s) \cos\left(z\sqrt{s^2 + x^2}\right), \quad (227)$$

and one has assumed that the binary is in the x - y plane and the observer is on the z -axis. However, if one expands these expressions about $\beta = \infty$, one recovers the GR solution to leading order, plus corrections that decay faster than $1/r$. This then automatically implies that such modifications to the generation mechanism will be difficult to observe for sources at astronomical distances.

Given such a solution, one can compute the flux of energy carried by gravitational waves to spatial infinity. Stein and Yunes (2011) have shown that in quadratic gravity theories, this flux is still given by

$$\dot{E} = \frac{\kappa}{2} \int d\Omega r^2 \langle \dot{\bar{h}}_{\mu\nu} \dot{h}^{\mu\nu} \rangle, \quad (228)$$

where $\bar{h}_{\mu\nu}$ is the trace-reversed metric perturbation, the integral is taken over a 2-sphere at spatial infinity, and we recall that the angle brackets stand for an average over several wavelengths. Given the solution in Eq. (225), one finds that the energy flux is

$$\dot{E} = \frac{9}{20} \mu^2 r_{12}^2 \Omega^4 \beta^2 \left[|r|^2 f_c^2\left(\beta|r|, \frac{2\Omega}{\beta}\right) + |r|^2 f_s^2\left(\beta|r|, \frac{2\Omega}{\beta}\right) \right]. \quad (229)$$

The asymptotic expansion of the term in between square brackets about $\beta = \infty$ is

$$|r|^2 \left[f_c^2\left(\beta|r|, \frac{2\Omega}{\beta}\right) + f_s^2\left(\beta|r|, \frac{2\Omega}{\beta}\right) \right] \sim |r|^2 \left\{ \frac{1}{\beta^2 |r|^2} \left[1 + \mathcal{O}\left(\frac{1}{|r|}\right) \right] \right\}, \quad (230)$$

which then leads to an energy flux identical to that in GR, as any subdominant term

goes to zero when the 2-sphere of integration is taken to spatial infinity. In that case, there are no modifications to the rate of change of the orbital frequency. Of course, if one were not to expand about $\beta = \infty$, then the energy flux would lead to certain resonances at $\beta = 2\Omega$, but the energy flux is only well-defined at future null infinity.

The above analysis was used by Nelson et al. (2010a, b) to compute the rate of change of the orbital period of binary pulsars, in the hopes of using this to constrain β . Using data from the binary pulsar, they stipulated an order-of-magnitude constraint of $\beta \geq 10^{-13} \text{ m}^{-1}$. However, such an analysis could be revisited to relax a few assumptions used in Nelson et al. (2010b), Nelson et al. (2010a). First, binary pulsar constraints on modified gravity theories require the use of at least three observables. These observables can be, for example, the rate of change of the period \dot{P} , the line of nodes $\dot{\Omega}$ and the perihelion shift \dot{w} . Any one observable depends on the parameters (m_1, m_2) in GR or (m_1, m_2, β) in non-commutative geometries, where $m_{1,2}$ are the component masses. Therefore, each observable corresponds to a surface of co-dimension one, i.e., a two-dimensional surface or sheet in the three-dimensional space (m_1, m_2, β) . If the binary pulsar observations are consistent with Einstein's theory, then all sheets will intersect at some point, within a certain uncertainty volume given by the observational error. The simultaneous fitting of all these observables is what allows one to place a bound on β . The analysis of Nelson et al. (2010a, b) assumed that all binary pulsar observables were known, except for β , but degeneracies between (m_1, m_2, β) could potentially dilute constraints on these quantities. Moreover, this analysis should be generalized to eccentric and inclined binaries, since binary pulsars are known to not be on exactly circular orbits.

But perhaps the most important modification that ought to be made has to do with the calculation of the energy flux itself. The expression for \dot{E} in Eq. (228) in terms of derivatives of the metric perturbation derives from the effective gravitational-wave stress-energy tensor, obtained by perturbatively expanding the action or the field equations and averaging over several wavelengths (the *Isaacson* procedure, see Isaacson 1968a, b). In modified gravity theories, the definition of the effective stress-energy tensor in terms of the metric perturbation is usually modified, as found for example in Stein and Yunes (2011). In the case of non-commutative geometries, Stein and Yunes (2011) showed that Eq. (228) still holds, provided one considers fluxes at spatial infinity. However, the analysis of Nelson et al. (2010a, b) evaluated this energy flux at a fixed distance, instead of taking the $r \rightarrow \infty$ limit.

The balance law relates the rate of change of a binary's binding energy with the gravitational wave flux emitted by the binary, but for it to hold, one must require the following: (i) that the binary be isolated and possess a well-defined binding energy, and (ii) that the total stress-energy of the spacetime satisfies a local covariant conservation law. If (ii) holds, one can use this conservation law to relate the rate of change of the volume integral of the energy density, i.e., the energy flux, to the volume integral of the current density, which can be rewritten as an integral over the boundary of the volume through Stokes' theorem. Since in principle one can choose any integration volume, any physically-meaningful result should be independent of the surface of that volume. This is indeed the case in GR, provided one takes the integration 2-sphere to spatial infinity. Presumably, if one included all the relevant

terms in \dot{E} , without taking the limit to i^0 , one would still find a result that is independent of the surface of this two-sphere. However, this has not yet been verified. Therefore, the analysis of Nelson et al. (2010b), Nelson et al. (2010a) should be taken as an interesting first step toward understanding possible changes in the gravitational-wave metric perturbation in non-commutative geometries.

Not much beyond this has been done regarding non-commutative geometries and gravitational waves. In particular, one lacks a study of what the final response function would be if the gravitational-wave propagation were modified, which of course depends on the time-evolution of all propagating gravitational-wave degrees of freedom, and whether there are only the two usual dynamical degrees of freedom in the metric perturbation.

(II) Moyal-type Non-commutative Geometry

Gravitational waves from compact binary inspirals in the Moyal-type non-commutative geometry were first derived in Kobakhidze et al. (2016), and were improved by Jenks et al. (2020) by relaxing some of the assumptions made in Kobakhidze et al. (2016). Using the stress-energy tensor for a black hole in Eq. (72) and orbital averaging, the binding energy of a binary is given by

$$E = E_{\text{GR}} - \frac{m^4 \eta (1 - 2\eta) \Lambda^2}{16r^3} [1 - 3(\hat{L} \cdot \theta)^2], \quad (231)$$

where E_{GR} is the GR contribution, while \hat{L} is the unit orbital angular momentum. We recall that Λ and θ are defined in Eq. (73). The above correction to the binding energy further modifies Kepler's third law. The gravitational-wave luminosity is still given through the quadrupole formula and is not modified from GR, modulo the modifications coming from Kepler's third law. To leading order in small deviations from GR, the luminosity is given by

$$\dot{E} = \frac{32}{5} \eta^2 x^5 \left[1 + \frac{\Lambda^2 (1 - 2\eta)}{32} (23 - 39(\hat{L} \cdot \theta)^2) x^2 \right], \quad (232)$$

with $x \equiv (\pi m f)^{2/3}$. From these expressions, we can compute $\dot{f} = (df/dE)(dE/dt)$ and the Fourier phase in the frequency domain becomes

$$\Psi(f) = \Psi_{\text{GR}} - \frac{75}{2048} \frac{1 - 2\eta}{\eta} \Lambda^2 [7 - 15(\hat{L} \cdot \theta)^2] x^{-1/2}. \quad (233)$$

Given that the GR phase $\Psi_{\text{GR}} \propto x^{-5/2}$ to leading post-Newtonian order, the correction term enters at second post-Newtonian order relative to GR. When $\hat{L} \cdot \theta = 1$, the waveform in the frequency domain is given by

$$\tilde{h}_{\text{NC}} = \tilde{h}_{\text{GR}} (1 + \alpha_{\text{NC}} u^{a_{\text{NC}}}) e^{i \beta_{\text{NC}} u^{b_{\text{NC}}}}, \quad (234)$$

with (Tahura and Yagi 2018)

$$\begin{aligned}\beta_{\text{NC}} &= -\frac{75}{256}\eta^{-4/5}(2\eta-1)\Lambda^2, & b_{\text{NC}} &= -1, \\ \alpha_{\text{NC}} &= -\frac{3}{8}\eta^{-4/5}(2\eta-1)\Lambda^2, & a_{\text{NC}} &= +4,\end{aligned}\tag{235}$$

clearly mapping to the ppE framework.

Let us now discuss the bound on the Moyal-type non-commutative geometry. Kobakhidze et al. (2016) used the bound on the second post-Newtonian order correction from GW150914, obtained by the LIGO/Virgo Collaboration (Abbott et al. 2016d), and found $\sqrt{\Lambda} \lesssim 3.5$. Jenks et al. (2020) rederived the bounds from the posterior samples from several events in the GWTC-1 catalog, including the second post-Newtonian, non-GR correction term, and found a probability distribution on $\Lambda^2[7 - 15(\hat{\mathbf{L}} \cdot \boldsymbol{\theta})^2]$. Finding 90%-credible limits, the authors then derived the bound on $\sqrt{\Lambda}$ as a function of $(\hat{\mathbf{L}} \cdot \boldsymbol{\theta})$. In most cases, the bound on $\sqrt{\Lambda}$ is of order unity and is consistent with Kobakhidze et al. (2016). Jenks et al. (2020) also derived the non-commutative correction to the pericenter precession of a binary and applied the result to the double binary pulsar PSR J0737-3039. Using the measurements of pericenter precession together with the measurements of the Shapiro delay, mass ratio and mass functions for determining the masses of the pulsars, the authors derived a bound on $\sqrt{\Lambda}$ that ended up being weaker than the gravitational-wave bounds by roughly a factor of 5. Perkins et al. (2021b) gave a future forecast on probing non-commutative gravity with gravitational waves. Through a population of gravitational-wave events, the authors found that the theory can be probed to the $\sqrt{\Lambda} \lesssim 10^{-3}$ level.

4.3 Generic tests

4.3.1 Massive graviton theories

Several massive graviton theories have been proposed to later be discarded due to ghosts, non-linear or radiative instabilities. Thus, little work has gone into studying whether black holes and neutron stars in these theories persist and are stable, and how the generation of gravitational waves is modified. Such questions will depend on the specific massive gravity model considered, and of course, if a Vainshtein mechanism is active and effective, then there will not be any significant modifications.

However, a few generic properties of such theories can still be stated. One of them is that the non-dynamical (near-zone) gravitational field will be corrected, leading to Yukawa-like modifications to the gravitational potential (Will 1998)

$$V_{\text{MG}}(r) = \frac{M}{r} e^{-r/\lambda_g}, \quad \text{or} \quad V_{\text{MG}}(r) = \frac{M}{r} \left(1 + \gamma_{\text{MG}} e^{-r/\lambda_g}\right), \tag{236}$$

where r is the distance from the source to a field point. For example, the latter parameterization arises in gravitational theories with compactified extra dimensions (Kehagias and Sfetsos 2000). Such corrections lead to a *fifth force*, which then in

turn allows us to place constraints on m_g through solar system observations (Talmadge et al. 1988). Nobody has yet considered how such modifications to the near-zone metric could affect the binding energy of compact binaries and their associated gravitational waves.

Another generic consequence of a graviton mass is the appearance of additional propagating degrees of freedom in the gravitational wave metric perturbation. In particular, one expects scalar, longitudinal modes to be excited (see, e.g., Dilkes et al. 2001). This is, for example, the case if the action is of Pauli–Fierz type (Fierz and Pauli 1939; Dilkes et al. 2001). Such longitudinal modes arise due to the non-vanishing of the Ψ_2 and Ψ_3 Newman–Penrose scalars, and can be associated with the presence of spin-0 particles, if the theory is of Type N in the $E(2)$ classification (Will 2014). The specific form of the scalar mode will depend on the structure of the modified field equations, and thus, it is not possible to generically predict its associated contribution to the response function.

A robust prediction of massive graviton theories relates to how the propagation of gravitational waves is affected. If the graviton has a mass, its velocity of propagation will differ from the speed of light, as given for example in Eq. (26). Will (1998) showed that such a modification in the dispersion relation leads to a correction in the relation between the difference in time of emission Δt_e and arrival Δt_a of two gravitons:

$$\Delta t_a = (1+z) \left[\Delta t_e + \frac{D}{2\lambda_g^2} \left(\frac{1}{f_e^2} + \frac{1}{f_e'^2} \right) \right], \quad (237)$$

where z is the redshift, λ_g is the graviton's Compton wavelength, f_e and f_e' are the emission frequencies of the two gravitons and D is the distance measure

$$D = \frac{1+z}{H_0} \int_0^z \frac{dz'}{(1+z')^2 [\Omega_M(1+z')^3 + \Omega_A]^{1/2}}, \quad (238)$$

where H_0 is the present value of the Hubble parameter, Ω_M is the matter energy density and Ω_A is the vacuum energy density (for a zero spatial-curvature universe).

Even if the gravitational wave at the source is unmodified, the graviton time delay will leave an imprint on the Fourier transform of the response function by the time it reaches the detector (Will 1998). This is because the Fourier phase is proportional to

$$\Psi \propto 2\pi \int_{f_c}^f [t(f) - t_c] df', \quad (239)$$

where t is now not a constant but a function of frequency as given by Eq. (237). Carrying out the integration, one finds that the Fourier transform of the response function becomes

$$\tilde{h}_{\text{MG}} = \tilde{h}_{\text{GR}} e^{i\beta_{\text{MG}} u^{b_{\text{MG}}}}, \quad (240)$$

where \tilde{h}_{GR} is the Fourier transform of the response function in GR, we recall that $u = (\pi \mathcal{M} f)^{1/3}$ and we have defined

$$\beta_{\text{MG}} = -\frac{\pi^2 D \mathcal{M}}{\lambda_g^2 (1+z)}, \quad b_{\text{MG}} = -3. \quad (241)$$

Such a correction is of 1 post-Newtonian order relative to the leading-order, Newtonian term in the Fourier phase. Notice also that there are no modifications to the amplitude at all.

Numerous studies have considered possible bounds on λ_g . The most stringent solar system constraint is $\lambda_g > 3.9 \times 10^{13}$ km (Will 2018a; Bernus et al. 2020) and it comes from observations of Kepler's third law, which if the graviton had a mass would be modified by the Yukawa factor in Eq. (236). Observations of the rate of decay of the period in binary pulsars (Finn and Sutton 2002; Baskaran et al. 2008) can also be used to place the more stringent constraint $\lambda > 1.5 \times 10^{14}$ km. Similarly, studies of the stability of Kerr black holes in Pauli–Fierz theory (Fierz and Pauli 1939) have yielded constraints of $\lambda_g > 2.4 \times 10^{13}$ km (Brito et al. 2013b).

Gravitational-wave observations of binary systems can also be used to constrain the mass of the graviton. One possible test is to compare the times of arrival of coincident gravitational wave and electromagnetic signals, for example in white-dwarf binary systems. Larson and Hiscock (2000) and Cutler et al. (2003) estimated that one could constrain $\lambda_g > 3 \times 10^{13}$ km with classic LISA. Will (1998) was the first to consider constraints on λ_g from gravitational-wave observations only, a test that was indeed carried out with the first aLIGO observations leading to the constraint $\lambda_g > 10^{13}$ km at 90% confidence with GW150914 (Abbott et al. 2016d). Using 43 gravitational-wave events in the catalog GWTC-3, the above bound has been updated to $\lambda_g > 9.4 \times 10^{13}$ km (Abbott et al. 2021c). Will considered sky-averaged, quasi-circular inspirals and found that LIGO observations of $10 M_{\odot}$ equal-mass black holes would lead to a constraint of $\lambda_g > 6 \times 10^{12}$ km with a Fisher analysis, a projection that was quite close to the bound that aLIGO obtained.

Constraints on the mass of the graviton can of course improve with future observations. For example, constraints are improved to $\lambda_g > 6.9 \times 10^{16}$ km with classic LISA observations of $10^7 M_{\odot}$, equal-mass black holes because the massive graviton correction accumulates with distance traveled (see Eq. (240)). Will's study was later generalized by Will and Yunes (2004) and by Chamberlain and Yunes (2017), who considered how different detector characteristics affected the possible bounds on λ_g . Will and Yunes found that the bound scales with the square-root of the LISA arm length and inversely with the square root of the LISA acceleration noise (Will and Yunes 2004). Chamberlain and Yunes (2017) found that the bound can increase to $\lambda_g > 10^{15}$ km with single gravitational-wave observations with third-generation ground-based detectors and up to $\lambda_g > 10^{18}$ km with certain

gravitational-wave observations with space-based detectors. Carson and Yagi (2020c) showed that multiband observations of GW150914-like events with ground-based and space-based detectors can constrain the graviton Compton wavelength to $\lambda_g \gtrsim 10^{14}$ km, while Perkins et al. (2021b) found that the bound can be as strong as $\lambda_g \gtrsim 10^{16} - 10^{17}$ km with a population of gravitational-wave events detected by a network of third-generation ground-based detectors.

The initial projections of Will have been refined by Berti et al. (2005a), Yagi and Tanaka (2010a), Arun and Will (2009), Stavridis and Will (2010), Berti et al. (2011) to allow for non-sky-averaged responses, spin-orbit and spin-spin coupling, higher harmonics in the gravitational wave amplitude, eccentricity and multiple detections. Although the bound deteriorates on average for sources that are not optimally oriented relative to the detector, the bound improves when one includes spin couplings, higher harmonics, eccentricity, and multiple detections as the additional information and power encoded in the waveform increases, helping to break parameter degeneracies. However, all of these studies neglected the merger and ringdown phases of the coalescence, an assumption that was relaxed by Keppel and Ajith (2010), leading to the strongest projected bounds $\lambda_g > 4 \times 10^{17}$ km. Moreover, all studies until then had computed bounds using a Fisher analysis prescription, an assumption relaxed by Del Pozzo et al. (2011), who found that a Bayesian analysis with priors consistent with solar system experiments leads to bounds stronger than Fisher ones by roughly a factor of two. Perkins and Yunes (2019) took into account the effect of screening inside the Milky Way and the host galaxy of a source binary. They found that future gravitational-wave observations can place constraints on λ_g and the screening radius of $\mathcal{O}(10^{13}) - \mathcal{O}(10^{17})$ km and $\mathcal{O}(10^2) - \mathcal{O}(10^4)$ Mpc respectively.

In summary, projected constraints on λ_g are generically stronger than current solar system or binary pulsar constraints by several orders of magnitude, given a LISA observation of massive black-hole mergers. Even aLIGO observations can and have done better than current solar system constraints by factors between a few (Del Pozzo et al. 2011) to an order of magnitude (Keppel and Ajith 2010; Abbott et al. 2016d), depending on the source. All of these results are summarized in Table 2, normalizing everything to an SNR of 10.

Before proceeding, we should note that the correction to the propagation of gravitational waves due to a non-zero graviton mass are not exclusive to binary systems. In fact, any gravitational wave that propagates a significant distance from the source will suffer from the time delays described in this section. Binary inspirals are particularly useful as probes of this effect because one knows the functional form of the waveform, and thus, one can employ matched filtering to obtain a strong constraint. But, in principle, one could use gravitational-wave bursts from supernovae or other sources.

4.3.2 Massive boson fields and superradiance

Black holes in the presence of massive boson fields are unstable to the superradiant instability (Zeldovich and Starobinsky 1972; Misner 1972; Damour et al. 1976;

Table 2 Comparison of constraints and projected constraints on massive graviton theories

References	Binary mass	$\lambda_g [10^{15} \text{ km}]$	Properties
Will (2018a), Bernus et al. (2020), Mariani et al. (2023)	x	0.039, 1.22	Solar-system dynamics
Finn and Sutton (2002)	x	1.6×10^{-5}	Binary pulsar orbital period in Visser's theory (Visser 1998)
Brito et al. (2013b)	x	0.024	Stability of black holes in Pauli-Fierz theory (Fierz and Pauli 1939)
Zakharov et al. (2016)	x	0.00043	S2 orbit
Abbott et al. (2016d)	$(32, 39) M_\odot$	0.01	GW150914 aLIGO observation
Abbott et al. (2021c)	x	0.094	43 gravitational-wave events from GWTC-3
Will (1998)	$(10, 10) M_\odot$	0.006	LIGO, Fisher, Ang. Ave. circular, non-spinning
Del Pozzo et al. (2011)	$(13, 3) M_\odot$	0.006 – 0.014	LIGO, Bayesian, Ang. Ave. circular, non-spinning
Chamberlain and Yunes (2017)	$(30, 30) M_\odot$	1	third-generation ground-based, Fisher, Ang. Ave., circular, non-spinning
Larson and Hiscock (2000), Cutler et al. (2003)	$(0.5, 0.5) M_\odot$	0.03	LISA, WD-WD, coincident with electromagnetic signal
Will (1998), Will and Yunes (2004), Chamberlain and Yunes (2017)	$(10^7, 10^7) M_\odot$	50–70	LISA, Fisher, Ang. Ave. circular, non-spinning
Berti et al. (2005a)	$(10^6, 10^6) M_\odot$	10	LISA, Fisher, Monte-Carlo circular, w/spin-orbit
Arun and Will (2009)	$(10^5, 10^5) M_\odot$	10	LISA, Fisher, Ang. Ave. higher-harmonics, circular, non-spinning
Yagi and Tanaka (2010a)	$(10^6, 10^7) M_\odot$	22	LISA, Fisher, Monte-Carlo eccentric, spin-orbit
Yagi and Tanaka (2010b)	$(10^6, 10^7) M_\odot$	2.4	DECIGO, Fisher, Monte-Carlo eccentric, spin-orbit
Stavridis and Will (2010)	$(10^6, 10^6) M_\odot$	50	LISA, Fisher, Monte-Carlo circular, w/spin modulations
Keppel and Ajith (2010)	$(10^7, 10^7) M_\odot$	400	LISA, Fisher, Ang. Ave. circular, non-spinning, w/merger
Berti et al. (2011)	$(13, 3) M_\odot$	30	eLISA, Fisher, Monte-Carlo multiple detections, circular, non-spinning

Entries above the double line correspond to actual bounds, while those below correspond to projected bounds with gravitational-wave observations (normalized to an SNR of 10). Ang. Ave. stands for an angular average over all sky locations

Ternov et al. 1978) (see Brito et al. 2015 for a review). When the Compton wavelength of the massive boson is comparable to the size of the black hole's horizon, the boson field gains energy (exponentially populating bound Bohr orbits

around the black hole; Arvanitaki and Dubovsky 2011; Arvanitaki et al. 2015) at the expense of the black hole's rotational energy, forming a Bose–Einstein condensate cloud around it. For stellar mass black holes, this occurs if the boson field is extremely light, with a mass in the range $(10^{-14}, 10^{-10})$ eV. Bosons in this mass range include the QCD axion (Weinberg 1978; Wilczek 1978; Peccei and Quinn 1977), string theory axions (Arvanitaki et al. 2010) and dark photons (Holdom 1986; Pani et al. 2012).

The discovery of superradiant instabilities would be a smoking gun for the existence of some type of exotic physics, which has therefore prompted many studies that investigate its signature in astrophysical environments. For example, if superradiance is active, then rapidly rotating black holes should not exist, as the black holes should be spun down and energy is dumped into the boson field. This would appear as a drastic deficit in the spin-population of black holes, which could be observed given a large enough catalog of gravitational wave observations from compact binary coalescence (Arvanitaki et al. 2010; Arvanitaki and Dubovsky 2011; Arvanitaki et al. 2015). In fact, the measurement of spin from X-ray observations from accretion disks around rotating black holes has been used to place constraints on the mass of such light bosons (Brito et al. 2013b; Arvanitaki et al. 2015).

Superradiance and massive boson fields would also have an effect in the emission of gravitational waves. The latter can produce gravitational waves in several ways. One possibility is for the Bose–Einstein condensate cloud to completely collapse if the attractive boson self-interactions become stronger than the gravitational binding energy, producing a *Bosenova*. The resulting gravitational waves are expected to be burst-like, although a quantitative dynamical analysis has not yet been carried out. Another way for the massive bosons to generate gravitational waves is through transitions between energy levels and via bosonic annihilation. In both cases, the emitted gravitational waves are coherent, monochromatic and long-lasting, producing signals that could be observed by ground-based detectors through continuous searches (Arvanitaki et al. 2017). These waves would also produce a stochastic background that could also be detected with ground-based instruments (Brito et al. 2017b). Recent works on probing ultralight bosons with gravitational-wave observations include Brito et al. (2017a, b), Tsukada et al. (2019), East (2018), Ikeda et al. (2019), Dergachev and Papa (2019), Ng et al. (2021a), Chen et al. (2020), Palomba et al. (2019), Brito et al. (2020), Dergachev and Papa (2020), Zhu et al. (2020a), Tsukada et al. (2021), Ng et al. (2021b), Yuan et al. (2021), Guo et al. (2022b), Kalogera et al. (2021), Abbott et al. (2022), Zhang et al. (2021), Yuan et al. (2022). For example, Tsukada et al. (2019) carried out the first search of a stochastic gravitational-wave background from boson clouds with the first observing run of LIGO/Virgo and excluded scalar bosons with masses $[2.0, 3.8] \times 10^{-13}$ eV, while Yuan et al. (2022) updated the results to rule out the mass range $[1.5, 15] \times 10^{-13}$ eV with the first and third observing runs.

4.3.3 Lorentz-violating gravity

We have so far concentrated on massive graviton theories, but, as discussed in Sect. 2.3.2, there is a strong connection between such theories and Lorentz violation. Modifications to the dispersion relation are usually a result of a modification of the Lorentz group or its action in real or momentum space. For this reason, it is interesting to consider generic Lorentz-violating-inspired, modified dispersion relations of the form of Eq. (27), or more precisely (Mirshekari et al. 2012)

$$\frac{v_g^2}{c^2} = 1 - AE^{\alpha_{\text{LV}}-2}, \quad (242)$$

where α_{LV} controls the structure of the modification and A its amplitude.

A plethora of models that violate Lorentz symmetry in the gravitational sector can be modeled with the generic modified dispersion relation presented above. Clearly, when $\alpha_{\text{LV}} = 0$ and $A = m_g^2 c^2$ one recovers the standard modified dispersion relation of Eq. (26). On the other hand, one can reproduce the predictions of the SME when $A = -2\overset{\circ}{k}_{(I)}^{(d)}$ for even $d \geq 4$ and $A = \pm 2\overset{\circ}{k}_{(V)}^{(d)}$ for odd $d \geq 5$ with $\alpha = d - 2$ in the rotation-invariant limit to linear order in $\overset{\circ}{k}_{(V)}^{(d)}$. Here, $\overset{\circ}{k}_{(I)}^{(d)}$ and $\overset{\circ}{k}_{(V)}^{(d)}$ are constant coefficients to quantify the degree of Lorentz violation. In the rotational invariant case, the modified dispersion relation in the SME is given in Eq. (5) of Kostelecky and Mewes (2016). The mapping between Eq. (242) and other modified gravity models is given in Table 3. Niu et al. (2022) constrained anisotropy, birefringence and dispersion in gravitational-wave propagation within the context of the SME with GWTC-3. Gong et al. (2023) derived similar constraints on non-birefringent dispersions with GWTC-3.

Such a modification to the propagation of gravitational waves introduces a generalized time delay between subsequent gravitons of the form (Mirshekari et al. 2012)

$$\Delta t_a = (1+z) \left[\Delta t_e + \frac{D_{\alpha_{\text{LV}}}}{2\lambda_a^{2-\alpha_{\text{LV}}}} \left(\frac{1}{f_e^{2-\alpha_{\text{LV}}}} - \frac{1}{f_e'^{2-\alpha_{\text{LV}}}} \right) \right], \quad (243)$$

where we have defined $\lambda_A \equiv h_p A^{1/(\alpha_{\text{LV}}-2)}$, with h_p Planck's constant, and the generalized distance measure (Mirshekari et al. 2012)

$$D_{\alpha_{\text{LV}}} = \frac{(1+z)^{1-\alpha_{\text{LV}}}}{H_0} \int_0^z \frac{(1+z')^{\alpha_{\text{LV}}-2}}{\left[\Omega_M (1+z')^3 + \Omega_A \right]^{1/2}} dz'. \quad (244)$$

Such a modification then leads to the following correction to the Fourier transform of the response function (Mirshekari et al. 2012)

$$\tilde{h}_{\text{LV}} = \tilde{h}_{\text{GR}} e^{i\beta_{\text{LV}} u^b_{\text{LV}}}, \quad (245)$$

where \tilde{h}_{GR} is the Fourier transform of the response function in GR, and we have defined (Mirshekari et al. 2012)

$$\beta_{\text{LV}}^{\alpha_{\text{LV}} \neq 1} = -\frac{\pi^{2-\alpha_{\text{LV}}}}{1-\alpha_{\text{LV}}} \frac{D_{\alpha_{\text{LV}}}}{\lambda_A^{2-\alpha_{\text{LV}}}} \frac{\mathcal{M}^{1-\alpha_{\text{LV}}}}{(1+z)^{1-\alpha_{\text{LV}}}}, \quad b_{\text{LV}}^{\alpha_{\text{LV}} \neq 1} = 3(\alpha_{\text{LV}} - 1). \quad (246)$$

The case $\alpha_{\text{LV}} = 1$ is special leading to the Fourier phase correction (Mirshekari et al. 2012)

$$\delta \Psi_{\alpha_{\text{LV}}=1} = \frac{3\pi D_1}{\lambda_A} \ln u. \quad (247)$$

The reason for this is that when $\alpha_{\text{LV}} = 1$ the Fourier phase is proportional to the integral of $1/f$, which then leads to a natural logarithm.

The constraints one can place on Lorentz-violating gravity depend on the particular value of α_{LV} . Of course, when $\alpha_{\text{LV}} = 0$, one recovers the standard massive graviton result with the mapping $\lambda_g^{-2} \rightarrow \lambda_g^{-2} + \lambda_A^{-2}$. When $\alpha_{\text{LV}} = 2$, the dispersion relation is identical to that in Eq. (26), but with a redefinition of the speed of light, and should thus be unobservable. Indeed, in this limit the correction to the Fourier phase in Eq. (245) becomes linear in frequency, and this is 100% degenerate with the time of coalescence parameter in the standard GR Fourier phase. Finally, relative to the standard GR terms that arise in the post-Newtonian expansion of the

Table 3 Mapping between different modified gravity models and the modified dispersion relation of Eq. (242)

Theory	A	α_{LV}
Double Special Relativity (Amelino-Camelia 2001; Magueijo and Smolin 2002; Amelino-Camelia 2002, 2010)	η_{dsrt}	3
Extra-Dimensional Theories (Sefiedgar et al. 2011b)	$-\alpha_{\text{edt}}$	4
Hořava–Lifshitz Gravity (Hořava 2009a, b; Vacaru 2012; Blas and Sanctuary 2011)	$\kappa_{\text{hl}}^4 \mu_{\text{hl}}^2 / 16$	4
Massive Graviton (Will 1998; Rubakov and Tinyakov 2008; Hinterbichler 2012; de Rham 2014)	$m_g^2 c^4$	0
Multifractional Spacetime Theory (timelike) (Calcagni 2010, 2012b, a, 2017)	$2E_*^{2-\alpha} / (3 - \alpha)$	2 – 3
Multifractional Spacetime Theory (spacelike) (Calcagni 2010, 2012b, a, 2017)	$-2 \cdot 3^{1-\alpha/2} E_*^{2-\alpha} / (3 - \alpha)$	2 – 3
Even SME (Kostelecky and Mewes 2016)	$-2\hat{k}_{(I)}^{(d)}$	$d - 2$
Odd SME (Kostelecky and Mewes 2016)	$\pm 2\hat{k}_{(V)}^{(d)}$	$d - 2$

In double special relativity, η_{dsrt} characterizes an observer-independent length scale. In extra-dimensional theories, α_{edt} represents the square of the Planck length. In Hořava–Lifshitz gravity, κ_{hl} is related to the bare gravitational constant, while μ_{hl} is related to the deformation in the “detailed balance” condition. In multifractional spacetimes, E_* is the characteristic length scale above which spacetime is discrete

Fourier phase, the new corrections are of $(1 + 3\alpha_{\text{LV}}/2)$ post-Newtonian order. Then, if LIGO gravitational-wave observations were incapable of discerning between a 4 post-Newtonian and a 5 post-Newtonian waveform, then such observations would not be able to see the modified dispersion effect if $\alpha_{\text{LV}} > 2$. Mirshekari et al. (2012) confirmed this expectation with a Fisher analysis of non-spinning, comparable-mass quasi-circular inspirals. They found that for $\alpha_{\text{LV}} = 3$, one can place very weak bounds on λ_A , namely $A < 10^{-7} \text{ eV}^{-1}$ with a LIGO observation of a $(1.4, 1.4) M_\odot$ neutron star inspiral, $A < 0.2 \text{ eV}^{-1}$ with an enhanced-LISA or NGO observation of a $(10^5, 10^5) M_\odot$ black-hole inspiral, assuming a SNR of 10 and 100 respectively. A word of caution is due here, though, as these analyses neglect any Lorentz-violating correction to the generation of gravitational waves, including the excitation of additional polarization modes. One would expect that the inclusion of such effects would only strengthen the bounds one could place on Lorentz-violating theories, but this must be done on a theory by theory basis. Bounds on the modified dispersion relation parameter A have been derived with GW150914 and GW151226 by Yunes et al. (2016) and with catalogs of binary black hole merger events by the LIGO/Virgo Collaboration (Abbott et al. 2019c, 2021b, c). Regarding the Standard Model Extension, one can consider not only isotropic dispersion, but also anisotropic and birefringent ones. Kostelecky and Mewes (2016) derived the first bounds on gravitational Lorentz violation within the Standard Model Extension. This analysis was later improved by Wang et al. (2021c), Niu et al. (2022), Haegel et al. (2023) for gravitational-wave events in GWTC-1, 2 and 3. Gong et al. (2022) derived bounds on Lorentz (and parity) violation effects in the Standard Model Extension due to fifth and sixth spatial derivatives in the action, motivated by Hořava-Lifshitz gravity, using gravitational-wave events from GWTC-1 and 2.

The modified dispersion relation in Eq. (242) can be further generalized. For example, a generic evolution equation for a single tensor perturbation under a cosmological background spacetime is given by (Saltas et al. 2014; Nishizawa 2018)

$$h_{ij}'' + (2 + v)\mathcal{H}h_{ij}' + (c_T^2 k^2 + a^2 m_g^2)h_{ij} = a^2 \gamma_{ij}, \quad (248)$$

where a is the scale factor, a prime represents the conformal time derivative, v is the Planck mass run rate, and c_T is the gravitational-wave propagation speed. When c_T is a function of E , the group velocity of the graviton v_g can be mapped to Eq. (242), after expanding the former about the GR case. Equation (248) can be mapped to various example theories, including theories with extra dimension, Horndeski theory, f(R) gravity and Einstein-Æther theory. The parameter v modifies the Hubble friction rate and changes the amplitude of gravitational waves. Thus, this parameter effectively modifies the luminosity distance measured by gravitational waves $d_L^{(\text{GW})}$ relative to that measured by electromagnetic observations $d_L^{(\text{EM})}$. For example, a generic modification to $d_L^{(\text{GW})}$ can be parameterized as (Belgacem et al. 2018)

$$\frac{d_L^{(\text{GW})}}{d_L^{(\text{EM})}} = \Xi_0 + \frac{1 - \Xi_0}{(1 + z)^n}, \quad (249)$$

where z is the redshift, Ξ_0 corresponds to the ratio at $z \rightarrow \infty$, and n shows the redshift dependence of the ratio. GR is recovered when $\Xi_0 \rightarrow 1$, which is the case when $z \rightarrow 0$. This parameterization has been tested with the GW170817 event and studied with future events (Belgacem et al. 2018; Mukherjee et al. 2021; Finke et al. 2021a; Jiang and Yagi 2021; Mancarella et al. 2022; Finke et al. 2022, 2021b). If there are multiple fields that couple to each other, the evolution equation in Eq. (248) can be further generalized. For example, when there are two tensor perturbations, h and s (omitting the tensor indices for simplicity), the evolution equations can be expressed as (Beltrán Jiménez et al. 2020; Ezquiaga et al. 2021)

$$\left[\hat{I} \frac{d^2}{d\eta^2} + \hat{v}(\eta) \frac{d}{d\eta} + \hat{C}(\eta)k^2 + \hat{P}(\eta)k + \hat{M}(\eta) \right] \begin{pmatrix} h \\ s \end{pmatrix} = 0. \quad (250)$$

Here \hat{I} is the identity matrix while \hat{v} , \hat{C} , \hat{P} and \hat{M} are the friction, velocity, chiral and mass mixing matrices respectively. This mixing induces echoes, distortions, oscillations and birefringence in gravitational waves. For example, the gravitational wave oscillation in bigravity, described in Sect. 4.2.2, corresponds to having non-vanishing off-diagonal components in \hat{M} .

4.3.4 Variable G theories and large extra dimensions

The lack of a particular Lagrangian associated with variable G theories, excluding scalar-tensor theories and theories with large extra dimensions, makes it difficult to ascertain whether black-hole or neutron-star binaries exist in such theories. Whether this is so will depend on the particular variable G model considered. In spite of this, if such binaries do exist, the gravitational waves emitted by such systems will carry some generic modifications relative to the GR expectation.

Most current tests of the variability of Newton's gravitational constant rely on electromagnetic observations of massive bodies, such as neutron stars. As discussed in Sect. 2.3.5, scalar-tensor theories can be interpreted as variable- G theories, where the variability of G is really a scalar-field-induced variation in the coupling between gravity and matter. However, Newton's constant serves the more fundamental role of defining the relationship between geometry or length and energy, and such a relationship is not altered in most scalar-tensor theories, unless the scalar fields are allowed to vary on a cosmological scale (background, homogeneous scalar solution).

For this reason, one might wish to consider a possible temporal variation of Newton's constant in pure vacuum spacetimes, such as in black-hole-binary inspirals. Such temporal variation would encode (\dot{G}/G) at the time and location of the merger event. Thus, once a sufficiently large number of gravitational wave events has been observed and found consistent with GR, one could reconstruct a

constraint map that bounds (\dot{G}/G) along our past light cone (as a function of redshift and sky position). Since our past-light cone with gravitational waves will extend to roughly redshift 10 with LISA (limited by the existence of merger events at such high redshifts), such a constraint map will be more complete than what one can achieve with current tests at redshifts of almost zero. Big Bang nucleosynthesis constraints also allow us to bound a linear drift in (\dot{G}/G) from $z \sim 10^3$ to zero, but these become degenerate with limits on the number of relativistic species. Moreover, these bounds exploit the huge lever-arm provided by integrating over cosmic time, but they are insensitive to local, oscillatory variations of G with periods much less than the cosmic observation time. Thus, gravitational-wave constraint maps would test one of the pillars of GR: local position invariance. This principle (encoded in the equivalence principle) states that the laws of physics (and thus the fundamental constants of nature) are the same everywhere in the universe.

Let us then promote G to a function of time of the form (Yunes et al. 2010c)

$$G(t, x, y, z) \approx G_c + \dot{G}_c(t_c - t), \quad (251)$$

where $G_c = G(t_c, x_c, y_c, z_c)$ and $\dot{G}_c = (\partial G / \partial t)(t_c, x_c, y_c, z_c)$ are constants, and the sub-index c means that these quantities are evaluated at coalescence. Clearly, this is a Taylor expansion to first order in time and position about the coalescence event (t_c, x_c^i) , which is valid provided the spatial variation of G is much smaller than its temporal variation, i.e., $|\nabla^i G| \ll \dot{G}$, and the characteristic period of the temporal variation is longer than the observation window (at most, $T_{\text{obs}} \leq 3$ years for LISA), so that $\dot{G}_c T_{\text{obs}} \ll G_c$. Similar parameterization of $G(t)$ have been used to study deviations from Newton's second law in the solar system (Dirac 1937; Wetterich 1988; Weinberg 1989; Uzan 2003). Thus, one can think of this modification as the consequence of some effective theory that could represent the predictions of several different alternative theories.

The promotion of Newton's constant to a function of time changes the rate of change of the orbital frequency, which then directly impacts the gravitational-wave phase evolution. To leading order, Yunes et al. (2010c) find

$$\dot{F} = \dot{F}_{\text{GR}} + \frac{195}{256\pi} \mathcal{M}^{-2} x^3 \eta^{3/5} (\dot{G}_c \mathcal{M}), \quad (252)$$

where \dot{F}_{GR} is the rate of change of the orbital frequency in GR, due to the emission of gravitational waves and $x = (2\pi Mf)^{1/3}$. Such a modification to the orbital frequency evolution leads to the following modification (Yunes et al. 2010c) to the Fourier transform of the response function in the stationary-phase approximation (Bender and Orszag 1999; Cutler and Flanagan 1994; Droz et al. 1999; Yunes et al. 2009)

$$\tilde{h} = \tilde{h}_{\text{GR}} (1 + \alpha_{\dot{G}} u^{a_{\dot{G}}}) e^{i \beta_{\dot{G}} \dot{u}^{\dot{G}}}, \quad (253)$$

where we recall again that $u = (\pi \mathcal{M} f)^{1/3}$ and have defined the constant parameters (Yunes et al. 2010c; Tahura and Yagi 2018)

$$\alpha_{\dot{G}} = -\frac{35}{512} \frac{\dot{G}_c}{G_c} (G_c \mathcal{M}_z), \quad \beta_{\dot{G}} = -\frac{275}{851968} \frac{\dot{G}_c}{G_c} (G_c \mathcal{M}_z), \quad a = -8, \quad b = -13, \quad (254)$$

to leading order in the post-Newtonian approximation. Tahura and Yagi (2018) generalized the above corrections by allowing the gravitational constant in the conservative and dissipative sectors to be different (which is the case for example in Jordan–Fierz–Brans–Dicke theory with a time-varying scalar field) and including sensitivities as the gravitational self-energy of a body is a function of the gravitational constant. We note that this corresponds to a correction of -4 post-Newtonian order in the phase, relative to the leading-order term, and that the corrections are independent of the symmetric mass ratio, scaling only with the redshifted chirp mass \mathcal{M}_z . Due to this, one expects the strongest effects to be seen in low-frequency gravitational waves, such as those one could detect with LISA or DECIGO/BBO.

Given such corrections to the gravitational-wave response function, one can investigate the level to which a gravitational-wave observation consistent with GR would allow us to constrain \dot{G}_c . Yunes et al. (2016) and Tahura et al. (2019) used the first two gravitational-wave events and derived the constraint of $\dot{G}_c/G_c \leq 2.2 \times 10^{-4} \text{ yr}^{-1}$. Yunes et al. (2010c) carried out a study for future detectors and found that for comparable-mass black-hole inspirals of total redshifted mass $m_z = 10^6 M_\odot$ with LISA, one could constrain $(\dot{G}_c/G_c) \lesssim 10^{-9} \text{ yr}^{-1}$ or better to redshift 10, assuming an SNR of 10^3 (see also Carson and Yagi 2020c and Perkins et al. 2021b for similar bounds). The constraint is strengthened when one considers intermediate-mass black-hole inspirals and extreme mass-ratio inspirals, where one would be able to achieve a bound of $(\dot{G}_c/G_c) \lesssim 10^{-11} \text{ yr}^{-1}$ and $(\dot{G}_c/G_c) \lesssim 10^{-16} \text{ yr}^{-1}$ respectively (Chamberlain and Yunes 2017). Although this is not as stringent as the strongest constraints from other observations (see Sect. 2.3.5), we recall that gravitational-wave constraints would measure local variations at the source, as opposed to local variations at zero redshift or integrated variations from the very early universe.

There are other interesting ways to measure the time variation of G with gravitational waves. For example, Zhao et al. (2018) proposed a method that combines the gravitational-wave standard siren and supernova standard candle measurements as follows. Through gravitational waves from a binary neutron star with associated electromagnetic counterparts, one can determine the luminosity distance and redshift of the source independently (as was the case for GW170817). If there is a known type Ia supernova with a similar redshift, one can identify the luminosity distance of this supernova to be roughly the same as the binary neutron star, which leads one to determine the peak luminosity of the supernova. This peak luminosity depends on the Chandrasekhar mass, and thus, it is proportional to $G^{-3/2}$, so the combination of the gravitational-wave and supernova observations allows one to measure G at a certain redshift. For example, if a future third-generation gravitational-wave interferometer detects a signal at $z = 0.4$ and a supernova is known at a similar redshift, the time variation in G can be constrained to $\dot{G}/G \lesssim 3 \times 10^{-12} \text{ yr}^{-1}$. Another interesting method was proposed by Vijaykumar et al. (2021) and it relies on the measurement of the

minimum and maximum mass of neutron stars, which depends on G at a particular cosmic epoch. From GW170817, the authors derived the bound $-7 \times 10^{-9} \text{ yr}^{-1} < \dot{G}/G < 5 \times 10^{-8} \text{ yr}^{-1}$. An et al. (2023); Sun et al. (2024) further studied the effect of time variation in G in GW propagation.

The effect of promoting Newton's constant to a function of time is degenerate with several different effects. One such effect is a temporal variability of the black hole masses, i.e., if $\dot{m} \neq 0$. Such time-variation could be induced by gravitational leakage into the bulk in certain brane-world scenarios (Johannsen et al. 2009), as explained in Sect. 2.3.5. For a single black hole of mass M , the rate of black hole evaporation is given by

$$\frac{dM}{dt} = -2.8 \times 10^{-7} \left(\frac{1 M_{\odot}}{M} \right)^2 \left(\frac{\ell}{10 \mu\text{m}} \right)^2 M_{\odot} \text{ yr}^{-1}, \quad (255)$$

where ℓ is the size of the large extra dimension. As expected, such a modification to a black-hole-binary inspiral will lead to a correction to the Fourier transform of the response function that is identical in structure to that of Eq. (253), but the parameters $(\beta_{\dot{G}}, b_{\dot{G}}) \rightarrow (\beta_{\text{ED}}, b_{\text{ED}})$ with (Yagi et al. 2011; Chamberlain and Yunes 2017)

$$\beta_{\text{ED}} = -1.3 \times 10^{-24} \left[\left(\frac{M_{\odot}}{m_1} \right)^2 + \left(\frac{M_{\odot}}{m_2} \right)^2 \right] \left(\frac{\ell}{10 \mu\text{m}} \right)^2 \left(\frac{3 - 26\eta + 34\eta^2}{\eta^{2/5}(1 - 2\eta)} \right), \quad (256)$$

$$b_{\text{ED}} = -13.$$

A similar expression is found for a neutron-star/black-hole inspiral, except that the η -dependent factor in between parenthesis is corrected.

Given a gravitational-wave detection consistent with GR, one could then, in principle, place an upper bound on ℓ . Yunes et al. (2016) showed that the two first gravitational wave observations by aLIGO require $\ell \lesssim 10^9 \mu\text{m}$, a constraint that is many orders of magnitude weaker than current table-top bounds (Adelberger et al. 2007). Chamberlain and Yunes (2017) predicted that this constraint would only improve by three orders of magnitude with future ground-based detectors. Yagi et al. (2011), however, predicted that this bound could be improved to $\ell \leq 10^3 \mu\text{m}$ with a one-year LISA observation of a $(10, 10^5) M_{\odot}$ binary inspiral at an SNR of 100. A similar observation with the third generation, space-based detector DECIGO/BBO should be able to beat current constraints by roughly one order of magnitude. All of these constraints could be strengthened by roughly one order of magnitude further, if one included the statistical enhancement in parameter estimation due to detection of order 10^5 sources by DECIGO/BBO. Care must be taken, however, since the constraints described above weaken somewhat for more generic inspirals, due to degeneracies between ℓ and eccentricity and spin. Carson and Yagi (2020c) and Perkins et al. (2021b) derived projected bounds on the black hole evaporation rate \dot{M} and found that future space-based detectors can constrain such a rate as $\dot{M} \lesssim (10^{-8} - 10^{-7}) M_{\odot}/\text{yr}$.

Another way to place a constraint on ℓ is to consider the effect of mass loss in the orbital dynamics (McWilliams 2010). When a system loses mass, the evolution of

its semi-major axis a will acquire a correction of the form $\dot{a} = -(\dot{M}/M)a$, due to conservation of specific orbital angular momentum. There is then a critical semi-major axis a_c at which this correction balances the semi-major decay rate due to gravitational wave emission. McWilliams (2010) argues that systems with $a < a_c$ are then gravitational-wave dominated and will thus inspiral, while systems with $a > a_c$ will be mass-loss dominated and will thus outspiral. If a gravitational wave arising from an inspiraling binary is detected at a given semi-major axis, then ℓ can be automatically constrained. Yagi et al. (2011) extended this analysis to find that such a constraint is weaker than what one could achieve via matched filtering with a waveform in the form of Eq. (253), using the DECIGO detector.

There are other ways to constrain the extra dimension models with gravitational waves. For example, if there are non-compact additional spatial dimensions, gravitational waves can leak into such dimensions, while electromagnetic waves are constrained to four dimensions. Therefore, the amplitude of gravitational waves are smaller than when spacetime is four dimensional, which effectively enhances the luminosity distance compared to that measured from electromagnetic waves. Using the multimessenger observations of GW170817, Pardo et al. (2018) placed a bound on the number of spacetime dimensions, namely $D = 3.98^{+0.07}_{-0.09}$, which is consistent with a similar analysis by the LIGO/Virgo Collaboration (Abbott et al. 2019b). Hernandez Magana Hernandez (2023) carried out a similar analysis but using binary black hole mergers. Using some theoretical features on the pair instability mass gap, the authors were able to break the degeneracy between the mass and redshift of binary black holes. Using gravitational-wave events in GWTC-3, the authors placed the bound $D = 3.95^{+0.07}_{-0.09}$, which is comparable to the one from GW170817 mentioned above. Corman et al. (2022) improved these analyses by taking into account the effect of redshift for cosmological sources. One can also probe extra dimensions by counting the number of gravitational-wave sources and studying the distribution of their SNRs (Calabrese et al. 2016; García-Bellido et al. 2016). Du et al. (2021) studied gravitational waves in simple compactified extra dimension models and showed that such models are inconsistent with GW150914. For brane-world models, paths for gravitational waves are considered to be different from those for electromagnetic waves, so one can constrain the models through multimessenger observations of binary neutron stars. For example, assuming the bulk spacetime is anti-de Sitter, Visinelli et al. (2018) derived a bound on ℓ using GW170817, namely $\ell < 0.535$ Mpc, which is much weaker than that from table-top experiments (see Yu et al. 2019 for a short review on this topic). Extra dimensions can also be probed through quasinormal modes (Chakraborty et al. 2018; Mishra et al. 2022). Du et al. (2024) derived the stress-energy tensor for GWs without imposing the standard, Isaacson's short-wavelength approximation. This could be useful for deriving GWs in higher-dimensional theories, where the size of extra dimensions is typically constrained to μm level from table-top experiments, which is much shorter than the typical GW wavelength.

The \dot{G} correction to the gravitational-wave phase evolution is also degenerate with cosmological acceleration. That is, if a gravitational wave is generated at high-redshift, its phase will be affected by the acceleration of the universe. To zeroth-

order, the correction is a simple redshift of all physical scales. However, if one allows the redshift to be a function of time

$$z \sim z_c + \dot{z}_c(t - t_c) \sim z_c + H_0 \left[(1 + z_c)^2 - (1 + z_c)^{5/2} \Omega_M^{1/2} \right] (t - t_c), \quad (257)$$

then the observed waveform at the detector becomes structurally identical to Eq. (253) but with the parameters Seto et al. (2001), Takahashi and Nakamura (2005), Yagi et al. (2012a), Nishizawa et al. (2012), Bonvin et al. (2017), Yunes et al. (2010c)

$$\beta_{\dot{z}} = \frac{25}{32768} \dot{z}_c \mathcal{M}_z, \quad b_{\dot{z}} = -13. \quad (258)$$

Using the measured values of the cosmological parameters from the WMAP analysis (Komatsu et al. 2009; Dunkley et al. 2009), one finds that this effect is roughly 10^{-3} times smaller than that of a possible \dot{G} correction at the level of the possible bounds quoted above (Yunes et al. 2010c). Of course, as one begins to consider observations with space-based detectors, which allow for fairly stringent constraints on \dot{G} , one must then also account for possible degeneracies with \dot{z} .

A final possible degeneracy arises with modifications to the gravitational waves due to the presence of a third body (Yunes et al. 2011b; Robson et al. 2018; Kuntz and Leyde 2023; Xuan et al. 2023), due to migration if the binary is in an accretion disk (Kocsis et al. 2011; Yunes et al. 2011c), and due to the interaction of a binary with a circumbinary accretion disk (Hayasaki et al. 2013). All of these effects introduce corrections to the gravitational-wave phase at negative post-Newtonian order, just like the effect of a variable gravitational constant. However, degeneracies of this type are only expected to affect a small subset of black-hole-binary observations, namely those with a third body sufficiently close to the binary, or a sufficiently massive accretion disk.

4.3.5 Parity violation

As discussed in Sect. 2.3.7 the simplest action to model parity violation in the gravitational interaction is given in Eq. (74). Black holes and neutron stars exist in this theory. A generic feature of this theory is that parity violation imprints onto the propagation of gravitational waves, an effect that has been dubbed *amplitude birefringence*. Such birefringence is not to be confused with optical or electromagnetic birefringence, in which the gauge boson interacts with a medium and is doubly-refracted into two separate rays. In amplitude birefringence, right- (left)-circularly polarized gravitational waves are enhanced or suppressed (suppressed or enhanced) relative to the GR expectation as they propagate (Jackiw and Pi 2003; Lue et al. 1999; Alexander et al. 2008; Yunes and Finn 2009; Alexander and Yunes 2009; Yunes et al. 2010b).

One can understand amplitude birefringence in gravitational wave propagation as a result of the non-commutativity of the parity operator and the Hamiltonian. The

Hamiltonian is the generator of time evolution, and thus, one can write (Yunes et al. 2010b)

$$\begin{pmatrix} h_{+,k}(t) \\ h_{\times,k}(t) \end{pmatrix} = e^{-ift} \begin{pmatrix} u_c & -iv \\ iv & u_c \end{pmatrix} \begin{pmatrix} h_{+,k}(0) \\ h_{\times,k}(0) \end{pmatrix}, \quad (259)$$

where f is the gravitational-wave angular frequency, t is time, and $h_{+, \times, k}$ are the gravitational wave Fourier components with wavenumber k . The quantity u_c models possible background curvature effects, with $u_c = 1$ for propagation on a Minkowski metric, and u_c proportional to redshift for propagation on a Friedman–Robertson–Walker metric (Laguna et al. 2009). The quantity v models possible parity-violating effects, with $v = 0$ in GR. One can rewrite the above equation in terms of right and left-circular polarizations, $h_{R,L} = (h_+ \mp ih_\times)/\sqrt{2}$ to find

$$\begin{pmatrix} h_{R,k}(t) \\ h_{L,k}(t) \end{pmatrix} = e^{-ift} \begin{pmatrix} u_c + v & 0 \\ 0 & u_c - v \end{pmatrix} \begin{pmatrix} h_{R,k}(0) \\ h_{L,k}(0) \end{pmatrix}. \quad (260)$$

Amplitude birefringence has the effect of modifying the eigenvalues of the diagonal propagator matrix for right- and left-polarized waves, with right modes amplified or suppressed and left modes suppressed or amplified relative to GR, depending on the sign of v . In addition to these parity-violating propagation effects, parity violation should also leave an imprint in the generation of gravitational waves. However, such effects need to be analyzed on a theory by theory basis. Moreover, the propagation-distance-independent nature of generation effects should make them easily distinguishable from the propagation effects we consider here.

The degree of parity violation, v , can be expressed entirely in terms of the waveform observables via (Yunes et al. 2010b)

$$v = \frac{1}{2} \left(\frac{h_R}{h_R^{\text{GR}}} - \frac{h_L}{h_L^{\text{GR}}} \right) = \frac{i}{2} (\delta\phi_L - \delta\phi_R), \quad (261)$$

where $h_{R,L}^{\text{GR}}$ is the GR expectation for a right or left-polarized gravitational wave. In the last equality we have also introduced the notation $\delta\phi \equiv \phi - \phi^{\text{GR}}$, where ϕ^{GR} is the GR gravitational-wave phase and

$$h_{R,L} = h_{0,R,L} e^{-i[\phi(\eta) - \kappa\chi^i]}, \quad (262)$$

where $h_{0,R,L}$ is a constant factor, κ is the conformal wave number and (η, χ^i) are conformal coordinates for propagation in a Friedman–Robertson–Walker universe. The precise form of v will depend on the particular theory under consideration. For example, in non-dynamical Chern–Simons gravity with a field $\vartheta = \vartheta(t)$, and in an expansion about $z \ll 1$, one finds¹⁷ (Yunes et al. 2010b)

¹⁷ We have here explicitly pulled out a factor of α/κ to make the continuous GR limit explicit.

$$\nu = \frac{\alpha}{\kappa} \pi f z \left(\dot{\vartheta}_0 - \frac{\ddot{\vartheta}_0}{H_0} \right) = \frac{\alpha}{\kappa} \pi f D (H_0 \dot{\vartheta}_0 - \ddot{\vartheta}_0), \quad (263)$$

where ϑ_0 is the Chern–Simons scalar field at the detector, with α the Chern–Simons coupling constant [see, e.g., Eq. (74)], z is redshift, D is the comoving distance and H_0 is the value of the Hubble parameter today and f is the observed gravitational-wave frequency. When considering propagation on a Minkowski background, one obtains the above equation in the limit as $\dot{a} \rightarrow 0$, so the second term dominates, where a is the scale factor. To leading-order in a curvature expansion, the parity-violating coefficient ν will always be linear in frequency, as shown in Eq. (263). For more general parity violation and flat-spacetime propagation, ν will be proportional to $(fD)^n \alpha$, where α is a coupling constant of the theory (or a certain derivative of a coupling field) with units of $[\text{Length}]^n$ (in the previous case, $n = 0$, so the correction was simply proportional to $fD\alpha$, where $\alpha \propto \ddot{\vartheta}$).

How does such parity violation affect the waveform? By using Eq. (260) one can easily show that the Fourier transform of the response function becomes (Alexander et al. 2008; Yunes and Finn 2009; Yunes et al. 2010b; Yagi and Yang 2018)

$$\tilde{h}_{\text{PV}} = (F_+ + i \nu F_\times) \tilde{h}_+ + (F_\times - i \nu F_+) \tilde{h}_\times. \quad (264)$$

Of course, one can rewrite this in terms of a real amplitude correction and a real phase correction. Expanding in $\nu \ll 1$ to leading order, we find (Yunes et al. 2010b; Yagi and Yang 2018)

$$\tilde{h}_{\text{PV}} = \tilde{h}^{\text{GR}} (1 + \nu \delta Q_{\text{PV}}) e^{i \nu \delta \psi_{\text{PV}}}, \quad (265)$$

where \tilde{h}_{GR} is the Fourier transform of the response function in GR and we have defined

$$Q_{\text{GR}} = \sqrt{F_+^2 (1 + \cos^2 \iota)^2 + 4 \cos^2 \iota F_\times^2}, \quad (266)$$

$$\delta Q_{\text{PV}} = \frac{2 \cos \iota (1 + \cos^2 \iota) (F_+^2 + F_\times^2)}{Q_{\text{GR}}^2}, \quad (267)$$

$$\delta \psi_{\text{PV}} = \frac{(1 - \cos^2 \iota)^2 F_+ F_\times}{Q_{\text{GR}}^2}. \quad (268)$$

We see then that amplitude birefringence modifies both the amplitude and the phase of the response function. Using the non-dynamical Chern–Simons expression for ν in Eq. (263), we can rewrite Eq. (265) as (Yunes et al. 2010b)

$$\tilde{h}_{\text{PV}} = \tilde{h}^{\text{GR}} (1 + \alpha_{\text{PV}} u^{a_{\text{PV}}}) e^{i \beta_{\text{PV}} u^{b_{\text{PV}}}}, \quad (269)$$

where we have defined the coefficients

$$\alpha_{\text{PV}} = \left(\frac{D}{\mathcal{M}} \right) \left[\frac{2 \cos \iota (1 + \cos^2 \iota) (F_+^2 + F_\times^2)}{Q_{\text{GR}}^2} \right] \left(\frac{\alpha}{\kappa} \right) (H_0 \dot{\vartheta}_0 - \ddot{\vartheta}_0), \quad a_{\text{PV}} = 3, \quad (270)$$

$$\beta_{\text{PV}} = \left(\frac{D}{\mathcal{M}} \right) \left[\frac{(1 - \cos^2 \iota)^2 F_+ F_\times}{Q_{\text{GR}}^2} \right] \left(\frac{\alpha}{\kappa} \right) (H_0 \dot{\vartheta}_0 - \ddot{\vartheta}_0)^2, \quad b_{\text{PV}} = 3, \quad (271)$$

where we recall that $u = (\pi \mathcal{M} f)^{1/3}$. The phase correction corresponds to a term of 4 post-Newtonian order relative to the Newtonian contribution, and it scales quadratically with the Chern–Simons coupling field ϑ , which is why it was left out in Yunes et al. (2010b). The amplitude correction, on the other hand, is of 1.5 post-Newtonian order relative to the Newtonian contribution. Since both of these appear as positive-order, post-Newtonian corrections, there is a possibility of degeneracy between them and standard waveform template parameters.

Given such a modification to the response function, one can ask whether parity violation is observable with current detectors. Yagi and Yang (2018) carried out a Fisher analysis on GW150914 and found that the SNR is too small and one cannot place any meaningful bound within the weak parity-violation approximation. Okounkova et al. (2022) used gravitational-wave events in GWTC-2 and placed a constraint on amplitude birefringence, in particular the opacity parameter $\bar{\kappa} \lesssim 0.74 \text{ Gpc}^{-1}$. Here $\bar{\kappa}$ is defined through

$$\frac{h_R}{h_L} = \frac{e^{-d_c \bar{\kappa}} (1 + \cos \iota)^2}{e^{d_c \bar{\kappa}} (1 - \cos \iota)^2}, \quad (272)$$

where d_c is the comoving distance to the source. The bound was derived assuming that all events in the catalog have the same distance and using a phenomenological model for parity violation. Ng et al. (2023) further derived the updated constraint on amplitude birefringence with GWTC-3 that is ~ 25 times more stringent than the constraint in Okounkova et al. (2022). The effect of parity violation has also been studied in Calderón Bustillo et al. (2025), where the authors measured the emission of net circular polarization across 47 binary black-hole mergers and found that the average is consistent with zero. A future prospect of how well this can be constrained is given in Califano et al. (2024).

Yagi and Yang (2018), Callister et al. (2023) also considered the possibility of probing the parity-violating polarization mode (V-mode) (Seto 2006, 2007; Seto and Taruya 2007, 2008; Crowder et al. 2013; Smith and Caldwell 2017) in stochastic gravitational-wave background from binary black hole mergers. Martinovic et al. (2021) proposed a method to search for parity violation in the stochastic gravitational-wave background and applied it to LIGO/Virgo O3 data.

For future prospects on probing amplitude birefringence with gravitational waves, Alexander et al. (2008), Yunes and Finn (2009) argued that a gravitational wave observation with LISA would be able to constrain an integrated measure of ν , because LISA can observe massive–black-hole mergers to cosmological distances, while amplitude birefringence accumulates with distance traveled. For such an

analysis, one cannot Taylor expand ϑ about its present value, and instead, one finds that

$$\frac{1+v}{1-v} = e^{2\pi f\zeta(z)}, \quad (273)$$

where we have defined

$$\zeta(z) = \frac{\alpha H_0}{\kappa} \int_0^z dz (1+z)^{5/2} \left[\frac{7}{2} \frac{d\vartheta}{dz} + (1+z) \frac{d^2\vartheta}{dz^2} \right]. \quad (274)$$

We can solve the above equation to find

$$v = \frac{e^{2\pi f\zeta(z)} - 1}{1 + e^{2\pi f\zeta(z)}} \sim \pi f\zeta(z), \quad (275)$$

where in the second equality we have linearized about $v \ll 1$ and $f\zeta \ll 1$. Alexander et al. (2008), Yunes and Finn (2009) realized that this induces a time-dependent change in the inclination angle (i.e., the apparent orientation of the binary's orbital angular momentum with respect to the observer's line-of-sight), since the latter can be defined by the ratio h_R/h_L . They then carried out a simplified Fisher analysis and found that a LISA observation of the inspiral of two massive black holes with component masses $10^6 M_\odot (1+z)^{-1}$ at redshift $z = 15$ would allow us to constrain the integrated dimensionless measure $\zeta < 10^{-19}$ to 1σ . One might worry that such an effect would be degenerate with other standard GR processes that induce similar time-dependencies, such as spin-orbit coupling. However, this time-dependence is very different from that of the parity-violating effect, and thus, Alexander et al. (2008), Yunes and Finn (2009) argued that these effects would be weakly correlated.

Another test of parity violation was proposed by Yunes et al. (2010b), who considered the coincident detection of a gravitational wave and a gamma-ray burst with the SWIFT (Gehrels 2004) and GLAST/Fermi (Carson 2007) gamma-ray satellites, and the ground-based LIGO (Abbott et al. 2009) and Virgo (Acernese et al. 2007) gravitational wave detectors. If the progenitor of the gamma-ray burst is a neutron-star/neutron-star or neutron-star/black-hole merger, the gamma-ray jet is expected to be collimated. Therefore, an electromagnetic observation of such an event implies that the binary's orbital angular momentum at merger must be pointing along the line of sight to Earth, leading to a strongly-circularly-polarized gravitational-wave signal and to maximal parity violation. If an afterglow from the gamma-ray burst observation were to provide an accurate sky location via galaxy identification, one would be able to obtain an accurate distance measurement from the gravitational wave signal alone. Moreover, since GLAST/Fermi observations of gamma-ray bursts occur at low redshift, one would also possess a purely electromagnetic measurement of the distance to the source. Amplitude birefringence would manifest as a discrepancy between these two distance measurements. Therefore, if no discrepancy is found, the error ellipse on the distance measurement would allow us to place an upper limit on any possible gravitational parity violation. Because of the nature of such a test, one is constraining generic parity violation over

distances of hundreds of Mpc, along the light cone on which the gravitational waves propagate.

The coincident gamma-ray burst/gravitational-wave test compares favorably to the pure LISA test, with the sensitivity to parity violation being about 2 – 3 orders of magnitude better in the former case. This is because, although the fractional error in the gravitational-wave distance measurement is much smaller for LISA than for LIGO, since it is inversely proportional to the SNR, the parity violating effect also depends on the gravitational-wave frequency, which is much larger for neutron-star inspirals than massive black-hole coalescences. Mathematically, the simplest models of gravitational parity violation will lead to a signature in the response function that is proportional to the gravitational-wave wavelength¹⁸ $\lambda_{\text{GW}} \propto Df$. Although the coincident test requires small distances and low SNRs (by roughly 1 – 2 orders of magnitude), the frequency is also larger by a factor of 5 – 6 orders of magnitude for the LIGO-Virgo network.

The coincident gamma-ray burst/gravitational-wave test also compares favorably to current solar system constraints. Using the motion of the LAGEOS satellites, Smith et al. (2008) have placed the 1σ bound $\dot{\vartheta}_0 < 2000$ km assuming $\ddot{\vartheta}_0 = 0$. A similar assumption leads to a 2σ bound of $\dot{\vartheta}_0 < 200$ km with a coincident gamma-ray burst/gravitational-wave observation. Moreover, the latter test also allows us to constrain the second time-derivative of the scalar field. Finally, a LISA observation would constrain the integrated history of ϑ along the past light cone on which the gravitational wave propagated. However, these tests are not as stringent as the recently proposed test by Dyda et al. (2012), $\dot{\vartheta}_0 < 10^{-7}$ km, assuming the effective theory cut-off scale is less than 10 eV and obtained by demanding that the energy density in photons created by vacuum decay over the lifetime of the universe not violate observational bounds.

The coincident test is somewhat idealistic in that there are certain astrophysical uncertainties that could hamper the degree to which we could constrain parity violation. One of the most important uncertainties relates to our knowledge of the inclination angle, as gamma-ray burst jets are not perfectly aligned with the line of sight (which was indeed the case for GW170817). If the inclination angle is not known *a priori*, it will become degenerate with the distance in the waveform template, decreasing the accuracy to which the luminosity could be extracted from a pure gravitational wave observation by at least a factor of two. Even after taking such uncertainties into account, Yunes et al. (2010b) found that $\dot{\vartheta}_0$ could be constrained much better with gravitational waves than with current solar system observations.

So far, we have focused on amplitude birefringence, though there is another possible type of birefringence: velocity birefringence. In a general parity-violating gravitational theory, circular polarizations of tensor perturbations in a flat Friedmann-Robertson-Walker spacetime satisfy the following equation (Wang et al. 2013; Zhu et al. 2013):

¹⁸ Even if it is not linear, the effect should scale with positive powers of λ_{GW} . It is difficult to think of any parity-violating theory that would lead to an inversely proportional relation.

$$\ddot{h}_A'' + (2 + v_A)\mathcal{H}\dot{h}_A' + (1 + \mu_A)k^2\tilde{h}_A = 0, \quad (A = R, L). \quad (276)$$

Here primes represent derivatives with respect to conformal time and $\mathcal{H} = a'/a$. The parameters v_A and μ_A characterize the parity violation in the amplitude and velocity respectively. In particular, the latter can be further parameterized as (Zhao et al. 2022b)

$$\mu_A = \bar{\alpha}\lambda_A \left(\frac{k}{aM_{PV}} \right)^{\bar{\beta}}, \quad (277)$$

where $\lambda_R = +1$, $\lambda_L = -1$ and the parameters $\bar{\alpha}$ and $\bar{\beta}$ depend on specific theories of gravitational parity violation. Bounds on velocity birefringence with current gravitational-wave observations can be found in Wang and Zhao (2020), Wang et al. (2021b, 2022), Zhao et al. (2022b). For example, Wang et al. (2022) used the 4th-Open Gravitational-wave Catalog and derived a constraint on the energy scale of parity violation $M_{PV} > 0.05\text{GeV}$ for $\bar{\beta} = 1$ and assuming $\bar{\alpha} = \mathcal{O}(1)$. This bound improves the previous one by a factor of 5. The authors also found that the two most massive events in the catalog (GW190521 and GW191109) showed some evidence for birefringence, with a false alarm rate of a few per 100 observations. However, further analysis is needed because GW190521 may not be a standard, quasi-circular binary (Romero-Shaw et al. 2020; Gayathri et al. 2022; Gamba et al. 2023). Lagos et al. (2024) carried out a multi-messenger tests of birefringence with GW170817 and its associated radio observations. The authors derived a new bound on amplitude birefringence, while velocity birefringence remained unconstrained. They also revealed that such velocity birefringence effects are in general difficult to constrain with dark binary mergers even with future-generation detectors.

Parity violation has also been studied in theory-agnostic, parameterized ways. Jenks et al. (2023) developed a parameterized framework (similar to the parameterized post-Einsteinian waveform to be discussed in Sect. 4.3.6) to study amplitude and velocity birefringence in GW propagation, which was further extended in Daniel et al. (2024) to account for the presence of the Gauss-Bonnet term in the action. Califano et al. (2024) further applied this framework to study future prospects of probing a few different parity-violating theories of gravity with future GW detectors. Yamada and Tanaka (2020) constructed a parameterized gravitational-waveform in parity-violating gravity (also similar to the parameterized post-Einsteinian waveform) by deriving gravitational waveforms from an evolution equation of the tensor perturbations similar to Eq. (276). The authors then derived bounds on the generic parity-violating parameter at different post-Newtonian orders from gravitational-wave events in GWTC-1.

4.3.6 Parameterized post-Einsteinian framework

One of the biggest disadvantages of a top-down or direct approach toward testing GR is that one must pick a particular theory from the beginning of the analysis. However, given the large number of possible modifications to Einstein's theory and the lack of a particularly compelling alternative, it is entirely possible that none of

these will represent the correct gravitational theory in the extreme gravity regime. Thus, if one carries out a top-down approach, one will be forced to make the assumption that we, as physicists, know which modifications of gravity are possible and which are not (Yunes and Pretorius 2009b). The parameterized post-Einsteinian (ppE) approach is a framework developed specifically to alleviate such a bias by allowing the data to select the correct theory of nature through the systematic study of statistically significant anomalies.

For detection purposes, one usually expects to use match filters that are consistent with GR. But if GR happened to be wrong in the extreme gravity regime, it is possible that a GR template would still extract the signal, but with the wrong parameters. That is, the best fit parameters obtained from a matched filtering analysis with GR templates will be biased by the assumption that GR is sufficiently accurate to model the entire coalescence. This *fundamental bias* could lead to a highly distorted image of the gravitational-wave universe. In fact, recent work by Vallisneri and Yunes (2013) indicates that such fundamental bias could indeed be present in observations of neutron star inspirals, if GR is not quite the right theory in the extreme gravity regime.

One of the primary motivations for the development of the ppE scheme was to alleviate fundamental bias, and one of its most dangerous incarnations: *stealth-bias* (Cornish et al. 2011). If GR is not the right theory of nature, yet all our future detections are of low SNR, we may estimate the wrong parameters from a matched-filtering analysis, yet without being able to identify that there is a non-GR anomaly in the data. Thus, stealth bias is nothing but fundamental bias hidden by our limited SNR observations. Vallisneri and Yunes (2013) have found that such stealth-bias is indeed possible in a certain sector of parameter space, inducing errors in parameter estimation that could be larger than statistical ones, without us being able to identify the presence of a non-GR anomaly.

4.3.6.1 Historical development The ppE scheme was designed in close analogy with the parameterized post-Newtonian (ppN) framework, developed in the 1970 s to test GR with solar system observations (see, e.g., Will 2014 for a review). In the solar system, all direct observables depend on a single quantity, the metric, which can be obtained by a small-velocity/weak-field post-Newtonian expansion of the field equations of whatever theory one is considering. Thus, Nordtvedt Jr (1968b), Will (1971), Will and Nordtvedt Jr (1972), Nordtvedt Jr and Will (1972), Will (1973) proposed the generalization of the solar system metric into a *meta-metric* that could effectively interpolate between the predictions of many different alternative theories. This meta-metric depends on the product of certain Green function potentials and ppN parameters. For example, the spatial-spatial components of the meta-metric take the form

$$g_{ij} = \delta_{ij}(1 + 2\gamma U + \dots), \quad (278)$$

where δ_{ij} is the Kronecker delta, U is the Newtonian potential and γ is one of the ppN parameters, which acquires different values in different theories: $\gamma = 1$ in GR, $\gamma = (1 + \omega_{\text{BD}})(2 + \omega_{\text{BD}})^{-1} \sim 1 - \omega_{\text{BD}}^{-1} + \mathcal{O}(\omega_{\text{BD}}^{-2})$ in Jordan–Fierz–Brans–Dicke

theory, etc. Therefore, any solar system observable could then be written in terms of system parameters, such as the masses of the planets, and the ppN parameters. An observation consistent with GR allows for a bound on these parameters, thus simultaneously constraining a large class of modified gravity theories.

The idea behind the ppE framework was to develop a formalism that allowed for similar generic tests but with gravitational waves instead of solar system observations. The first pre-ppE attempts were by Arun et al. (2006), Mishra et al. (2010), who considered the quasi-circular inspiral of compact objects. They suggested the waveform template family

$$\tilde{h}_{\text{PNT}} = \tilde{h}^{\text{GR}} e^{i\beta_{\text{PNT}} u^{b_{\text{PN}}}}. \quad (279)$$

This waveform depends on the standard system parameters that are always present in GR waveforms, plus one theory parameter β_{PNT} that is to be constrained. The quantity b_{PN} is a number chosen by the data analyst and is restricted to be equal to one of the post-Newtonian predictions for the phase frequency exponents, i.e., $b_{\text{PN}} = (-5, -3, -2, -1, \dots)$.

The template family in Eq. (279) allows for *post-Newtonian tests of GR*, i.e., consistency checks of the signal with the post-Newtonian expansion. For example, let us imagine that a gravitational wave has been detected with sufficient SNR that the chirp mass and mass ratio have been measured from the Newtonian and 1 post-Newtonian terms in the waveform phase. One can then ask whether the 1.5 post-Newtonian term in the phase is consistent with these values of chirp mass and mass ratio. Put another way, each term in the phase can be thought of as a curve in (\mathcal{M}, η) space. If GR is correct, all these curves should intersect inside some uncertainty box, just like when one tests GR with binary pulsar observations. From that standpoint, these tests can be thought of as null-tests of GR and one can ask: given an event, is the data consistent with the hypothesis $\beta_{\text{PNT}} = 0$ for the restricted set of frequency exponents b_{PN} ?

A Fisher and a Bayesian data analysis study of how well β_{PNT} could be constrained given a certain b_{PN} was carried out in Mishra et al. (2010), Huwyler et al. (2012), Li et al. (2012a). Mishra et al. (2010) considered the quasi-circular inspiral of non-spinning compact objects and showed that aLIGO observations would allow one to constrain β_{PNT} to 6% up to the 1.5 post-Newtonian order correction ($b_{\text{PN}} = -2$). Third-generation detectors, such as ET, should allow for better constraints on all post-Newtonian coefficients to roughly 2%. Clearly, the higher the value of b_{PN} , the worse the bound on β_{PNT} because the signal power contained in higher frequency exponent terms decreases, i.e., the number of useful additional cycles induced by the $\beta_{\text{PNT}} u^{b_{\text{PN}}}$ term decreases as b_{PN} increases. Huwyler et al. (2012) repeated this analysis but for LISA observations of the quasi-circular inspiral of black hole binaries with spin precession. They found that the inclusion of precessing spins forces one to introduce more parameters into the waveform, which dilutes information and weakens constraints on β_{PNT} by as much as a factor of 5. Li et al. (2012a) carried out a Bayesian analysis of the odds-ratio between GR and these templates given a non-spinning, quasi-circular compact binary inspiral observation with aLIGO and advanced Virgo. They calculated the odds ratio for

each value of b_{PN} listed above and then combined all of this into a single probability measure that allows one to quantify how likely the data is to be consistent with GR.

4.3.6.2 The simplest ppE model One of the main disadvantages of the post-Newtonian template family in Eq. (279) is that it is not rooted on a theoretical understanding of modified gravity theories. To alleviate this problem, Yunes and Pretorius (2009b) re-considered the quasi-circular inspiral of compact objects. They proposed a more general, ppE template family through generic deformations of the $\ell = 2$ harmonic of the response function in Fourier space:

$$\tilde{h}_{\text{ppE,insp,1}}^{(\ell=2)} = \tilde{h}^{\text{GR}} (1 + \alpha_{\text{ppE}} u^a_{\text{ppE}}) e^{i \beta_{\text{ppE}} u^b_{\text{ppE}}}, \quad (280)$$

where now $(\alpha_{\text{ppE}}, a_{\text{ppE}}, \beta_{\text{ppE}}, b_{\text{ppE}})$ are all free parameters to be fitted by the data, in addition to the usual system parameters. This waveform family reproduces all predictions from known modified gravity theories: when $(\alpha_{\text{ppE}}, \beta_{\text{ppE}}) = (0, 0)$, the waveform reduces exactly to GR, while for other parameters one reproduces the modified gravity predictions of Table 4.

In Table 4, recall the following definitions of constants: S is the difference in the square of the sensitivities, ω_{BD} is the Jordan–Fierz–Brans–Dicke coupling parameter (see Sect. 4.2.1; we have here neglected the scalar mode) and η is the symmetric mass ratio; ζ_3 is the coupling parameter in Einstein–dilaton–Gauss–Bonnet theory (see Sect. 4.2.4), where we have here included both the dissipative and the conservative corrections and δ_m is the normalized mass difference parameter; D is a certain distance measure, z is the cosmological redshift factor and λ_g is the Compton wavelength of the graviton (see Sect. 4.3.1); λ_{LV} is a distance

Table 4 Parameters that define the deformation of the response function in a variety of modified gravity theories

Theory	α_{ppE}	a_{ppE}	β_{ppE}	b_{ppE}
Jordan–Fierz–Brans–Dicke	$-\frac{5}{96} \frac{S^2}{\omega_{\text{BD}}} \eta^{2/5}$	-2	$-\frac{5}{3584} \frac{S^2}{\omega_{\text{BD}}} \eta^{2/5}$	-7
Dissipative Einstein–dilaton–Gauss–Bonnet Gravity	$-\frac{5}{192} \zeta_3 \eta^{-18/5} \delta_m^2$	-2	$-\frac{5}{7168} \zeta_3 \eta^{-18/5} \delta_m^2$	-7
Massive Graviton	0	.	$-\frac{\pi^2 D \mathcal{M}}{\lambda_g^2 (1+z)}$	-3
Lorentz Violation	0	.	$-\frac{\pi^{2-\gamma_{\text{LV}}}}{(1-\gamma_{\text{LV}})} \frac{D_{\text{LV}}}{\lambda_{\text{LV}}^{2-\gamma_{\text{LV}}}} \frac{\mathcal{M}^{1-\gamma_{\text{LV}}}}{(1+z)^{1-\gamma_{\text{LV}}}}$	$-3\gamma_{\text{LV}} - 3$
$G(t)$ Theory	$-\frac{35}{512} \dot{G}_c \mathcal{M}$	-8	$-\frac{275}{851968} \dot{G}_c \mathcal{M}$	-13
Extra Dimensions	.	.	β_{ED}	-13
Non-Dynamical Chern–Simons Gravity	α_{PV}	3	β_{PV}	3
Dynamical Chern–Simons Gravity	α_{dCS}	+4	β_{dCS}	-1
Non-commutative Gravity	α_{NC}	+4	$-\frac{75}{256} \eta^{-4/5} (2\eta - 1) \Lambda^2$	-1
Einstein–Ether Theory	$-\frac{1}{2\sqrt{\kappa_3}} \eta^{2/5} \epsilon_x$	-1	$-\frac{3}{224} \frac{\eta^{2/5} \epsilon_x}{\kappa_3}$	-7
Khronometric Gravity	.	.	$\frac{3}{128} E_{-1\text{PN}}^{\text{KG}} \eta^{2/5}$	-7

The notation · means that a value for this parameter is either irrelevant, as its amplitude is zero, or it has not yet been calculated

scale at which Lorentz-violation becomes important and γ_{LV} is the graviton momentum exponent in the deformation of the dispersion relation (see Sect. 4.3.1); \dot{G}_c is the value of the time derivative of Newton's constant at coalescence (see Sect. 4.3.4); β_{ED} is given in Eq. (256); β_{dCS} is given in Eq. (218); $(\alpha_{\text{PV}}, \beta_{\text{PV}})$ are given in Eqs. (270) and (271) of Sect. 4.3.5; $E_{0,1\text{PN}}^{\text{EA/KG}}$ is given in Eqs. (201)–(204) of Sect. 4.2.3.

Although there are only a few modified gravity theories where the leading-order post-Newtonian correction to the Fourier transform of the response function can be parameterized by post-Newtonian waveforms of Eq. (279), all such predictions can be modeled with the ppE templates of Eq. (280). In fact, only massive graviton theories, certain classes of Lorentz-violating theories and dynamical Chern–Simons gravity lead to waveform corrections that can be parameterized via Eq. (279). For example, the lack of amplitude corrections in Eq. (279) does not allow for tests of gravitational parity violation or non-dynamical Chern–Simons gravity.

However, this does not imply that Eq. (280) can parameterize all possible deformations of GR. First, Eq. (280) can be understood as a single-parameter deformation away from Einstein's theory. If the correct theory of nature happens to be a deformation of GR with several parameters (e.g., several coupling constants, mass terms, potentials, etc.), then Eq. (280) will only be able to parameterize the one that leads to the most useful cycles. This was recently verified by Sampson et al. (2013a). Second, Eq. (280) assumes that the modification can be represented as a power series in velocity, with possibly non-integer values. Such an assumption does not allow for possible logarithmic terms, which are known to arise due to non-linear hereditary interactions at sufficiently-high post-Newtonian order. It also does not allow for interactions that are screened, e.g., in theories with massive degrees of freedom. Nonetheless, the parameterization in Eq. (280) will still be able to signal that the detection is not a pure Einstein event, at the cost of biasing their true value (Sampson et al. 2014a).

The inspiral ppE model of Eq. (280) is motivated not only from examples of modified gravity predictions, but from generic modifications to the physical quantities that drive the inspiral: the reduced effective potential and the radiation-reaction force or the fluxes of the constants of the motion. Yunes and Pretorius (2009b) and Chatzioannou et al. (2012) considered generic modifications of the form

$$V_{\text{eff}} = \left(-\frac{m}{r} + \frac{L_z^2}{2r^2} \right) \left[1 + A_{\text{ppE}} \left(\frac{m}{r} \right)^{p_{\text{ppE}}} \right], \quad \dot{E} = \dot{E}_{\text{GR}} \left[1 + B_{\text{ppE}} \left(\frac{m}{r} \right)^{q_{\text{ppE}}} \right], \quad (281)$$

where L_z is the z -component of the orbital angular momentum, $\dot{E}_{\text{GR}} \propto v^2(m/r)^4$ with v and r being the relative velocity and orbital separation, $(p_{\text{ppE}}, q_{\text{ppE}}) \in \mathbb{Z}$, since otherwise one would lose analytically in the limit of zero velocities for circular inspirals, and where $(A_{\text{ppE}}, B_{\text{ppE}})$ are parameters that depend on the modified gravity theory and, in principle, could depend on dimensionless quantities like the symmetric mass ratio. Such modifications lead to the following corrections to the SPA

Fourier transform of the $\ell = 2$ time-domain response function for a quasi-circular binary inspiral template (to leading order in the deformations and in post-Newtonian theory)

$$\tilde{h} = A(\pi\mathcal{M}f)^{-7/6}e^{-i\Psi_{\text{GR}}}\left[1 - \frac{B_{\text{ppE}}}{2}\eta^{-2q_{\text{ppE}}/5}(\pi\mathcal{M}f)^{2q_{\text{ppE}}} + \frac{A_{\text{ppE}}}{6}\left(3 + 4p_{\text{ppE}} - 2p_{\text{ppE}}^2\right)\eta^{-2p_{\text{ppE}}/5}(\pi\mathcal{M}f)^{2p_{\text{ppE}}}\right]e^{-i\delta\Psi_{\text{ppE}}}, \quad (282)$$

$$\delta\Psi_{\text{ppE}} = \frac{5}{32}A_{\text{ppE}}\frac{2p_{\text{ppE}}^2 - 2p_{\text{ppE}} - 3}{(4 - p_{\text{ppE}})(5 - 2p_{\text{ppE}})}\eta^{-2p_{\text{ppE}}/5}(\pi\mathcal{M}f)^{2p_{\text{ppE}} - 5} + \frac{15}{32}\frac{B_{\text{ppE}}}{(4 - q_{\text{ppE}})(5 - 2q_{\text{ppE}})}\eta^{-2q_{\text{ppE}}/5}(\pi\mathcal{M}f)^{2q_{\text{ppE}} - 5}. \quad (283)$$

Of course, usually one of these two modifications dominates over the other, depending on whether $q_{\text{ppE}} > p_{\text{ppE}}$ or $p_{\text{ppE}} < q_{\text{ppE}}$. In Jordan–Fierz–Brans–Dicke theory, for example, the radiation-reaction correction dominates as $q_{\text{ppE}} < p_{\text{ppE}}$. If, in addition to these modifications in the generation of gravitational waves, one also allows for modifications in the propagation, one is then led to the following template family (Chatzioannou et al. 2012)

$$\tilde{h}_{\text{ppE,insp},2}^{(\ell=2)} = \mathcal{A}(\pi\mathcal{M}f)^{-7/6}e^{-i\Psi_{\text{GR}}}\left[1 + c\beta_{\text{ppE}}(\pi\mathcal{M}f)^{b_{\text{ppE}}/3 + 5/3}\right]e^{2i\beta_{\text{ppE}}u^{b_{\text{ppE}}}}e^{ik_{\text{ppE}}u^{k_{\text{ppE}}}}. \quad (284)$$

Here $(b_{\text{ppE}}, \beta_{\text{ppE}})$ and $(k_{\text{ppE}}, \kappa_{\text{ppE}})$ are ppE parameters induced by modifications to the generation and propagation of gravitational waves respectively, where still $(b_{\text{ppE}}, k_{\text{ppE}}) \in \mathbb{Z}$, while c is fully determined by the former set via

$$c_{\text{cons}} = -\frac{8}{15}\frac{b_{\text{ppE}}(3 - b_{\text{ppE}})(b_{\text{ppE}}^2 + 6b_{\text{ppE}} - 1)}{b_{\text{ppE}}^2 + 8b_{\text{ppE}} + 9}, \quad (285)$$

if the modifications to the binding energy dominate,

$$c_{\text{diss}} = -\frac{16}{15}(3 - b_{\text{ppE}})b_{\text{ppE}}, \quad (286)$$

if the modifications to the energy flux dominate, or

$$c_{\text{both}} = -\frac{16}{15}\frac{b_{\text{ppE}}(3 - b_{\text{ppE}})(b_{\text{ppE}}^2 + 7b_{\text{ppE}} + 4)}{b_{\text{ppE}}^2 + 8b_{\text{ppE}} + 9}. \quad (287)$$

if both corrections enter at the same post-Newtonian order. Noticing again that if only a single term in the phase correction dominates in the post-Newtonian approximation (or both will enter at the same post-Newtonian order), one can map Eq. (282) to Eq. (280) by a suitable redefinition of constants.

The model presented above contains modifications to the propagation of gravitational waves, which enter through frequency-dependent changes in the

dispersion relation. The first generic analysis of such effects was in fact carried out by Mirshekari et al. (2012), which was then adopted in the model of Chatzioannou et al. (2012). One could, however, be more general than this and allow for propagation direction-dependent modifications to the dispersion relation. This was indeed considered by Tso et al. (2017), who found the modified waveform does indeed take the form of Eq. (284), but where the ppE amplitude parameters now also depend on a unit vector that points in the direction of wave propagation. See Zhu et al. (2024), Romano and Sakellariadou (2023) other related works.

4.3.6.3 More complex ppE models Of course, one can introduce more ppE parameters to increase the complexity of the waveform family, and thus, Eq. (280) should be thought of as a minimal choice. In fact, one expects any modified theory of gravity to introduce not just a single parametric modification to the amplitude and the phase of the signal, but two new functional degrees of freedom:

$$\alpha_{\text{ppE}} u^{a_{\text{ppE}}} \rightarrow \delta A_{\text{ppE}}(\lambda^a, \theta^a; u), \quad \beta_{\text{ppE}} u^{b_{\text{ppE}}} \rightarrow \delta \Psi_{\text{ppE}}(\lambda^a, \theta^a; u), \quad (288)$$

where these functions will depend on the frequency u , as well as on system parameters λ^a and theory parameters θ^a . In a post-Newtonian expansion, one expects these functions to reduce to leading-order on the left-hand sides of Eqs. (288), but also to acquire post-Newtonian corrections of the form

$$\delta A_{\text{ppE}}(\lambda^a, \theta^a; u) = \alpha_{\text{ppE}}(\lambda^a, \theta^a) u^{a_{\text{ppE}}} \sum_n \alpha_{n,\text{ppE}}(\lambda^a, \theta^a) u^n, \quad (289)$$

$$\delta \Psi_{\text{ppE}}(\lambda^a, \theta^a; u) = \beta_{\text{ppE}}(\lambda^a, \theta^a) u^{b_{\text{ppE}}} \sum_n \beta_{n,\text{ppE}}(\lambda^a, \theta^a) u^n, \quad (290)$$

where here the structure of the series is assumed to be of the form u^n with $u > 0$. Such a model, also suggested by Yunes and Pretorius (2009b), would introduce too many new parameters that would dilute the information content of the waveform model. Sampson et al. (2013a) demonstrated that the simplest ppE model of Eq. (280) suffices to signal a deviation from GR, even if the injection contains three terms in the phase. Indeed, this simple ppE model was the one used in the first aLIGO detections to test for parametric deformations of GR (Abbott et al. 2016d), albeit in a restricted regime of ppE space, as Yunes et al. (2016) recently proved explicitly.

The number of parameters that can be included in the model is precisely one of the most important differences between the ppE and ppN frameworks. In ppN, it does not matter how many ppN parameters are introduced, because the observations are of very high SNR, and thus, templates are not needed to extract the signal from the noise. On the other hand, in gravitational wave astrophysics, templates are essential to make detections and do parameter estimation. Spurious parameters in these templates that are not needed to match the signal will deteriorate the accuracy to which *all* parameters can be measured because of an Occam penalty. Thus, in gravitational wave astrophysics and data analysis one wishes to minimize the number of theory parameters when testing GR (Cornish et al. 2011; Sampson et al.

2013a). One must then find a balance between the number of additional theory parameters to introduce and the amount of bias contained in the templates.

A curious fact of the generalizations proposed above is that the frequency exponents in the amplitude and phase correction were assumed to be integers, i.e., $(a_{\text{ppE}}, b_{\text{ppE}}, n) \in \mathbb{Z}$. This must be the case if these corrections arise due to modifications that can be represented as integer powers of the momenta or velocity. We are not aware of any theory that predicts corrections proportional to fractional powers of the velocity for circular inspirals. Moreover, one can show that theories that introduce non-integer powers of the velocity into the equations of motion will lead to issues with analyticity at zero velocity and a breakdown of uniqueness of solutions (Chatzioannou et al. 2012). In spite of this, modified theories can introduce logarithmic terms, that for example enter at high post-Newtonian order in GR due to non-linear propagation effects (see, e.g., Blanchet 2024 and references therein). Moreover, certain modified gravity theories introduce *screened* modifications that become “active” only above a certain frequency due to certain non-linearities. Such effects could be modeled through a Heaviside function, which is for example needed when dealing with massive Jordan–Fierz–Brans–Dicke gravity (Detweiler 1980b; Cardoso et al. 2011; Alsing et al. 2012; Yunes et al. 2012). However, even these non-polynomial injections would be detectable with the simplest ppE model. In essence, one finds similar results as if one were trying to fit a 3-parameter injection with the simplest 1-parameter ppE model (Sampson et al. 2013a). One weakness of the ppE framework is that one can only test non-GR deviations that follow a post-Newtonian series representation in the inspiral. Moreover, one needs to test modifications at different post-Newtonian orders one at a time, making the analysis inefficient and time-consuming. To overcome these issues, Xie et al. (2024) recently proposed a novel neural post-Einstein framework. Using deep-learning neural network, the new framework allows one to test many different theories simultaneously and identify the best theory in a single run, allowing for the search of deviations that are not power-series in velocity.

Of course, one can also generalize the inspiral ppE waveform families to more general orbits, for example through the inclusion of spins aligned or counter-aligned with the orbital angular momentum. More general inspirals would still lead to waveform families of the form of Eq. (280) or (284), but where the parameters $(\alpha_{\text{ppE}}, \beta_{\text{ppE}})$ would now depend on the mass ratio, mass difference, and the spin parameters of the black holes. With a single detection, one cannot break the degeneracy in the ppE parameters and separately fit for its system parameter dependencies. However, given multiple detections one should be able to break such a degeneracy, at least to a certain degree (Cornish et al. 2011). Such breaking of degeneracies begins to become possible when the number of detections exceeds the number of additional parameters required to capture the physical parameter dependencies of $(\alpha_{\text{ppE}}, \beta_{\text{ppE}})$. The ppE framework was also recently extended to include spin precession (Loutrel et al. 2023) and higher harmonics (Mezzasoma and Yunes 2022) (see also Mehta et al. 2023 for a related work to the latter extension). Bonilla et al. (2023) extended the simplest ppE waveform that includes a leading non-GR parameter in the inspiral by introducing an additional non-GR parameter in

the post-inspiral phase. Maggio et al. (2023) recently constructed a parameterized waveform during plunge-merger-ringdown based on the effective-one-body formulation.

PpE waveforms can be extended to account for the merger and ringdown phases of coalescence. Yunes and Pretorius have suggested the following template family to account for this as well (Yunes and Pretorius 2009b)

$$\tilde{h}_{\text{ppE,full}}^{(\ell=2)} = \begin{cases} \tilde{h}_{\text{ppE}} & f < f_{\text{IM}}, \\ \gamma u^c e^{i(\delta+\epsilon u)} & f_{\text{IM}} < f < f_{\text{MRD}}, \\ \zeta \frac{\tau}{1 + 4\pi^2 \tau^2 \kappa (f - f_{\text{RD}})^d} & f > f_{\text{MRD}}, \end{cases} \quad (291)$$

where the subscripts IM and MRD stand for inspiral merger and merger ringdown, respectively. The merger phase ($f_{\text{IM}} < f < f_{\text{MRD}}$) is modeled here as an interpolating region between the inspiral and ringdown, where the merger parameters (γ, δ) are set by continuity and differentiability, and the ppE merger parameters (c, ϵ) should be fit for. In the ringdown phase ($f > f_{\text{MRD}}$), the response function is modeled as a single-mode generalized Lorentzian, with real and imaginary dominant frequencies f_{RD} and τ , ringdown parameter ζ also set by continuity and differentiability, and the ppE ringdown parameters (κ, d) are to be fit for. The transition frequencies ($f_{\text{IM}}, f_{\text{MRD}}$) can either be treated as ppE parameters or set via some physical criteria, such as at the light-ring frequency and the fundamental ringdown frequency, respectively.

Another generalization of the ppE model that includes merger and ringdown is the hybridization of the so-called IMRPhenom models (Ajith et al. 2007, 2011; Santamaría et al. 2010; Husa et al. 2016; Khan et al. 2016; Schmidt et al. 2012). The latter is given by

$$\tilde{h}_{\text{gIMR}}(f) = \begin{cases} A_{\text{I}}(f) e^{i\phi_{\text{I}}(f)} e^{i\delta\phi_{\text{I,gIMR}}} & f \leq f_{\text{Int}}, \\ A_{\text{Int}}(f) e^{i\phi_{\text{Int}}(f)} & f_{\text{Int}} \leq f \leq f_{\text{MR}}, \\ A_{\text{MR}}(f) e^{i\phi_{\text{MR}}(f)} & f_{\text{MR}} \leq f, \end{cases} \quad (292)$$

where

$$\delta\phi_{\text{I,gIMR}} = \frac{3}{128\eta} \sum_{i=0}^7 \phi_i \delta\phi_i (\pi m f)^{(i-5)/3}. \quad (293)$$

Here ϕ_i are the phase coefficients in GR while $\delta\phi_i$ are their fractional non-GR corrections. f_{Int} and f_{MR} are transition frequencies from the inspiral to an intermediate phase, and from the latter to merger and ringdown. The Fourier phases above are continuous and differentiable at the transitions. This generalized ppE model is identical to that of Eq. (280) in the inspiral, with modifications in the merger and ringdown phases only (Yunes et al. 2016).

There has also been effort to generalize the ppE templates to allow for the excitation of non-GR gravitational-wave polarizations. Modifications to only the two GR polarizations map to corrections to terms in the time-domain Fourier

transform that are proportional to the $\ell = 2$ harmonic of the orbital phase. However, Arun suggested that if additional polarizations are present, other terms proportional to the $\ell = 0$ and $\ell = 1$ harmonic will also arise (Arun 2012). Chatzioannou et al. (2012) have found that the presence of such harmonics can be captured through the more complete single-detector template family

$$\begin{aligned} h_{\text{ppE,insp}}^{\text{all } \ell}(f) = & \mathcal{A} (\pi \mathcal{M}f)^{-7/6} e^{-i\Psi^{(2)\text{GR}}} \left[1 + c \beta_{\text{ppE}} (\pi \mathcal{M}f)^{b_{\text{ppE}}/3+5/3} \right] e^{2i\beta_{\text{ppE}} u_2^{b_{\text{ppE}}}} e^{2ik_{\text{ppE}} u_2^{\kappa_{\text{ppE}}}} \\ & + \gamma_{\text{ppE}} u_1^{-9/2} e^{-i\Psi^{(1)\text{GR}}} e^{i\beta_{\text{ppE}} u_1^{b_{\text{ppE}}}} e^{2ik_{\text{ppE}} u_1^{\kappa_{\text{ppE}}}}, \end{aligned} \quad (294)$$

$$\Psi_{\text{GR}}^{(\ell)} = -2\pi f t_c + \ell \Phi_c^{(\ell)} + \frac{\pi}{4} - \frac{3\ell}{256 u_\ell^5} \sum_{n=0}^7 u_\ell^{n/3} (c_n^{\text{PN}} + l_n^{\text{PN}} \ln u_\ell), \quad (295)$$

where we have defined $u_\ell = (2\pi \mathcal{M}f/\ell)^{1/3}$. The ppE theory parameters are now $\vec{\theta} = (b_{\text{ppE}}, \beta_{\text{ppE}}, k_{\text{ppE}}, \kappa_{\text{ppE}}, \gamma_{\text{ppE}}, \Phi_c^{(1)})$. Of course, one may ignore $(k_{\text{ppE}}, \kappa_{\text{ppE}})$ altogether, if one wishes to ignore propagation effects. Such a parameterization recovers the predictions of Jordan–Fierz–Brans–Dicke theory for a single-detector response function (Chatzioannou et al. 2012), as well as Arun’s analysis for generic dipole radiation (Arun 2012). The above framework was recently extended by Schumacher et al. (2023b) to account for gravitational-wave polarizations with different propagation speeds.

One might worry that the corrections introduced by the $\ell = 1$ harmonic, i.e., terms proportional to γ_{ppE} in Eq. (294), will be degenerate with post-Newtonian corrections to the amplitude of the $\ell = 2$ mode (not displayed in Eq. (294)). However, this is clearly not the case, as the latter scale as $(\pi \mathcal{M}f)^{-7/6+n/3}$ with n an integer greater than 0, while the $\ell = 1$ mode is proportional to $(\pi \mathcal{M}f)^{-3/2}$, which would correspond to a (−0.5) post-Newtonian order correction, i.e., $n = -1$. On the other hand, the ppE amplitude corrections to the $\ell = 2$ mode, i.e., terms proportional to β_{ppE} in the amplitude of Eq. (294), can be degenerate with such post-Newtonian corrections when b_{ppE} is an integer greater than −4.

4.3.6.4 Applications of the ppE formalism The different models presented above answer different questions. For example, the model of Eq. (284) contains a stronger prior (that ppE frequency exponents be integers) than that of Eq. (280), and thus, it is ideal for fitting a particular set of theoretical models. On the other hand, the model of Eq. (280) with continuous ppE frequency exponents allows one to search for *generic* deviations that are statistically significant, without imposing such theoretical priors. That is, if a deviation from GR is present, then Eq. (280) is more likely to be able to fit it, than Eq. (284). If one prioritizes the introduction of the least number of new parameters, Eq. (280) with $(a_{\text{ppE}}, b_{\text{ppE}}) \in \mathbb{R}$ can still recover deviations from GR, even if the latter cannot be represented as a correction proportional to an integer power of velocity.

Given these ppE waveforms, how should they be used in a data analysis pipeline? The main idea behind the ppE framework is to match-filter or perform Bayesian statistics with ppE enhanced template banks to allow the data to select the best-fit values of θ^a . As discussed in Yunes and Pretorius (2009b), Cornish et al. (2011) and then later in Li et al. (2012a), one might wish to first run detection searches with GR template banks, and then, once a signal has been found, do a Bayesian model selection analysis with ppE templates. The first study to carry out such a Bayesian analysis was by Cornish et al. (2011), who concluded that an aLIGO detection at SNR of 20 for a quasi-circular, non-spinning black-hole inspiral would allow us to constrain α_{ppE} and β_{ppE} much better than existent constraints for sufficiently strong-field corrections, e.g., $b_{\text{ppE}} > -5$. This is because for lower values of the frequency exponents, the corrections to the waveform are weak-field and better constrained with Solar System (Sampson et al. 2013b) and binary pulsar observations (Yunes and Hughes 2010). These predictions were shown to be very accurate with the first aLIGO observations (Abbott et al. 2016d; Yunes et al. 2016). The large statistical study of Li et al. (2012a) used a reduced set of ppE waveforms and investigated our ability to detect deviations of GR when considering a future catalog of aLIGO/advanced Virgo detections. The LIGO/Virgo Collaboration derived bounds on non-GR parameters in a generalized inspiral-merger-ringdown formalism with GW150914 (Abbott et al. 2016d), GW170817 (Abbott et al. 2019b), and gravitational-wave events in the GWTC catalogs (Abbott et al. 2016a, 2019c, 2021b, c), mostly on corrections entering at positive post-Newtonian orders. Yunes et al. (2016) derived the bounds on the ppE parameters from GW150914 and GW151226 including negative post-Newtonian corrections (see Fig. 5). The bounds from gravitational-wave observations are much stronger than those from solar system or binary pulsar observations for non-GR effects entering first at positive post-Newtonian orders. Perkins et al. (2021b) gave a forecast on constraining ppE parameters with a population of events for future observations, while a future forecast with multiband observations is discussed in Carson and Yagi (2020b, c), Perkins et al. (2021b), Gupta et al. (2020), Datta et al. (2021). In general, phase corrections are more important than amplitude corrections (Tahura et al. 2019), but the latter can be important e.g. when testing GR with astrophysical stochastic gravitational wave backgrounds (Maselli et al. 2016b; Saffer and Yagi 2020; Chen et al. 2024). When searching over multiple ppE parameters simultaneously, it is more efficient to apply a principal component decomposition to break degeneracies among these ppE parameters (Saleem et al. 2022; Datta et al. 2024; Shoom et al. 2023).

Let us now review the parameterized tests of gravity carried out by the LIGO/Virgo Collaboration in more detail.¹⁹ The first analysis was done on GW150914 (Abbott et al. 2016d). On top of the GR parameters, they added an extra non-GR parameter $\delta\phi_i$ in Eq. (293) in the inspiral waveform to search over and derived posterior distributions on this parameter assuming it entered at positive post-Newtonian orders. The collaboration repeated the analysis for similar non-GR

¹⁹ KAGRA joined the collaboration for tests of GR with gravitational waves with the GWTC-3 data set (Abbott et al. 2021c).

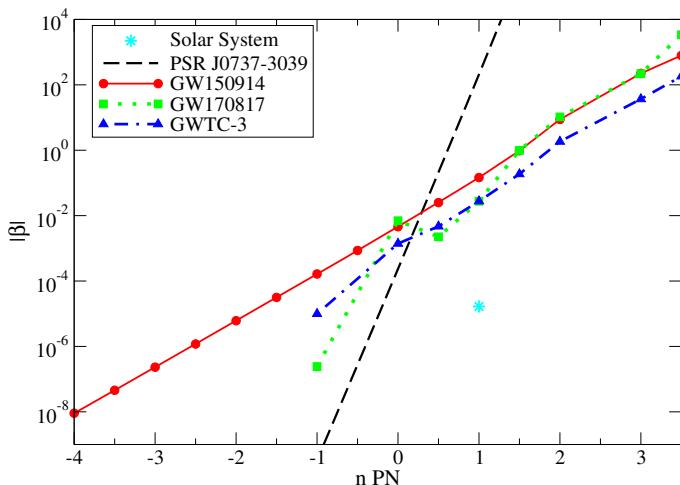


Fig. 5 90%-confidence constraints on the ppE parameter $|\beta|$ at n th post-Newtonian order. The red solid lines are those from GW150914 (Yunes et al. 2016) (that is consistent with the analysis at positive post-Newtonian orders by the LIGO/Virgo Collaboration (Abbott et al. 2016a, d). The green dotted line are bounds from GW170817 (Abbott et al. 2019b), while the blue dotted-dashed line are those obtained by combining binary black hole merger events in the GWTC-3 catalog (Abbott et al. 2021c). We also present the bounds from Solar system experiments (cyan star) (Sampson et al. 2013b) and binary pulsar observations (black line) (Yunes and Hughes 2010)

parameters entering the intermediate and merger-ringdown portions of the waveform. They also carried out an analysis with multiple $\delta\phi_i$ varied simultaneously. In this case, the constraint was much weaker than when a single $\delta\phi_i$ parameter is included due to the huge degeneracies among different non-GR parameters. Later, the LIGO/Virgo Collaboration derived bounds on $\delta\phi_{-2}$ (the correction at -1 post-Newtonian order) with gravitational-wave events in the catalogs (Abbott et al. 2019b, c, 2021b, c). The most stringent bound on this parameter comes from GW170817 (Abbott et al. 2019b). This is because the total mass of the binary is smaller than that of binary black holes, leading to smaller relative velocity of binary constituents at a fixed frequency and making the -1 post-Newtonian term relatively larger. Figure 5 shows the bound on the parameterized post-Einsteinian parameters β with GW150914, GW170817, and combined binary black hole merger events in the GWTC-3 catalog.²⁰ The Collaboration further derived combined bounds using multiple events in the gravitational-wave catalogs (Abbott et al. 2019b, c, 2021b, c). They considered two ways to obtain such combined bounds. The first way was to simply multiply together the posterior distribution from each event. This is meaningful if the $\delta\phi_i$ parameters are common to all sources. The second way was a hierarchical analysis, where one assumes that the $\delta\phi_i$ parameters are drawn from a common underlying distribution and tries to constrain the latter (Zimmerman et al. 2019; Isi et al. 2019a). The LIGO/Virgo

²⁰ For the latter two, we assumed all the binaries are equal-mass systems to convert the bounds on $\delta\phi_i$ to β .

Collaboration assumed such a distribution to be Gaussian and derived posterior distributions on the mean and standard deviation of the distribution (Abbott et al. 2021b, c). A Gaussian parameterization is reasonable as it is the least informative distribution, and it has been shown to work efficiently, even when the true distribution is non-Gaussian (Isi et al. 2019a).

A built-in problem with the ppE and the ppN formalisms is that if a non-zero ppE or ppN parameter is detected, then one cannot necessarily map it back to a particular modified gravity action. On the contrary, as suggested in Table 4, there can be more than one theory that predicts structurally-similar corrections to the Fourier transform of the response function. For example, both Jordan–Fierz–Brans–Dicke theory and the dissipative sector of Einstein–dilaton–Gauss–Bonnet theory predict the same type of leading-order correction to the waveform phase. However, if a given ppE parameter is measured to be non-zero, this could provide very useful information as to the type of correction that should be investigated further at the level of the action. The information that could be extracted is presented in Table 5, which is derived from knowledge of the type of corrections that lead to Table 4 (Yunes et al. 2016). Moreover, if a follow-up search is done with the ppE model in Eq. (284), one could infer whether the correction is due to modifications to the generation or the propagation of gravitational waves. In this way, a non-zero ppE detection could inform theories of what type of GR modification is preferred by nature.

4.3.6.5 Degeneracies Much care must be taken to avoid confusing a ppE theory modification with some other systematic, such as an astrophysical, a mismodeling or an instrumental effect. Instrumental effects can be easily remedied by requiring that several instruments, with presumably unrelated instrumental systematics, independently derive a posterior probability for $(\alpha_{\text{ppE}}, \beta_{\text{ppE}})$ that peaks away from zero. Astrophysical uncertainties can also be alleviated by requiring that different astrophysical events lead to the same posteriors for ppE parameters (after breaking degeneracies with system parameters). However, astrophysically there are a limited number of scenarios that could lead to corrections in the waveforms that are large enough to interfere with these tests. For comparable-mass–ratio inspirals, this is usually not a problem as the inertia of each binary component is too large for any astrophysical environment to affect the orbital trajectory (Hayasaki et al. 2013). Magnetohydrodynamic effects could affect the merger of neutron-star binaries, but

Table 5 Interpretation of non-zero ppE parameters

a_{ppE}	b_{ppE}	Interpretation
1	−1	Gravitational parity violation by activation of pseudo-scalar field, non-commutative geometry
−8	−13	Anomalous acceleration, large extra dimensions, mass leakage, violation of position invariance
·	−7	Dipole gravitational radiation by activation of scalar field, black hole hair
·	(−7, −5)	Gravitational Lorentz violation by activation of dynamical vector field
·	(−3, +3, +6, +9)	Massive graviton propagation, modified dispersion relations

this usually does not affect the inspiral. In extreme-mass-ratio inspirals, however, the small compact object can be easily nudged away by astrophysical effects, such as the presence of an accretion disk (Yunes et al. 2011c; Kocsis et al. 2011) or a third supermassive black hole (Yunes et al. 2011b). These astrophysical effects present the interesting feature that they correct the waveform in a form similar to Eq. (280) but with $b_{\text{ppE}} < -5$. This is because the larger the orbital separation, the stronger the perturbations of the astrophysical environment, either because the compact object gets closer to the third body or because it leaves the inner edge of the accretion disk and the disk density increases with separation. Such effects are not likely to be present in all sources observed, as few extreme-mass-ratio inspirals are expected to be embedded in an accretion disk or sufficiently close to a third body ($\lesssim 0.1$ pc) for the latter to have an effect on the waveform.

Perhaps the most dangerous systematic is mismodeling, which is due to the use of approximation schemes when constructing waveform templates. For example, in the inspiral one builds models using the post-Newtonian approximation, which expands and truncates the waveform at a given power of orbital velocity. These models are typically calibrated to numerical relativity simulations in the late inspiral, so that they can be joined smoothly to ringdown waves. Thus, inspiral-merger-ringdown models can have uncertainties that originate in either the truncation of the post-Newtonian approximation, numerical error or calibration error. Moreover, neutron stars are usually modeled as test-particles (with a Dirac distributional density profile), when in reality they have a finite radius, which will depend on its equation of state. Such finite-size effects enter at 5 post-Newtonian order (due to the *effacement* principle, see Hawking and Israel 1987; Damour 1988), but with a post-Newtonian coefficient that can be rather large (Mora and Will 2004; Berti et al. 2008; Flanagan and Hinderer 2008). Ignorance of the post-Newtonian series beyond 3 post-Newtonian order can lead to systematics in the determination of physical parameters and possibly also to confusion when carrying out ppE-like tests. Moore et al. (2021) estimated the amount of systematic errors in tests of GR due to waveform mismodeling and found that such errors may be evident when stacking as few as 10–30 gravitational events. This result shows how important the accurate modeling of the waveform in GR is.

In spite of these problems with the modeling of signals, recent work indicates that current waveforms are accurate enough to allow for robust tests of GR in a large region of parameter space with aLIGO observations. In particular, if one is interested in constraining GR deformations that enter below 2nd post-Newtonian order, then ppE-type models, which include deformations only in the inspiral, are sufficient to place conservative constraints with events of modest signal-to-noise ratio (Yunes et al. 2016; Perkins and Yunes 2022). Better constraints could of course be obtained if one could also include deformations in the merger and ringdown phases, but doing so would only strengthen ppE-type constraints in all cases investigated thus far. This situation holds for current ground-based observations, since signal-to-noise ratios are not too large. Third generation ground-based detectors, as well as space-based detectors are expected to detect much louder signals. For such events, precise tests of GR will require an improvement in the

accuracy of the GR modeling. The importance of including eccentricity in parameterized test of GR has been pointed out in Narayan et al. (2023), Saini et al. (2024). Payne et al. (2023) proposed a framework to simultaneously infer non-GR deviations, as well as the astrophysical population, to avoid bias from prior assumptions on the latter, while Magee et al. (2024) addressed the issue of selection biases on parameterized tests of GR with gravitational waves.

4.3.7 Searching for non-tensorial gravitational-wave polarizations

Another way to search for generic deviations from GR is to ask whether any gravitational-wave signal detected contains more than the two traditional polarizations expected in GR. Indeed, this is expected in theories with degrees of freedom in addition to the metric tensor, since these tend to source non-tensorial modes in the metric perturbation. For example, the merger of compact objects, as well as supernova explosion, tend to activate a scalar mode in the metric perturbation of scalar-tensor theories (Gerosa et al. 2016). A general approach to answer this question is through null streams, as discussed in Sect. 3.5. This concept was first studied by Gürsel and Tinto (1989) and later by Chatterji et al. (2006) with the aim to separate false-alarm events from real detections. Chatzioannou et al. (2012) proposed the extension of the idea of null streams to develop null tests of GR, which had also been studied with stochastic gravitational wave backgrounds in Nishizawa et al. (2009), Nishizawa et al. (2010) and implemented in Hayama and Nishizawa (2013) to reconstruct the independent polarization modes in time-series data of a ground-based detector network.

Given a gravitational-wave detection, one can ask whether the data is consistent with two polarizations by constructing a null stream through the combination of data streams from 3 or more detectors. As explained in Sect. 3.5, such a null stream should be consistent with noise in GR, while it would present a systematic deviation from noise if the gravitational wave metric perturbation possessed more than two polarizations. Notice that such a test would not require a template; if one were parametrically constructed, such as in Chatzioannou et al. (2012), more powerful null tests could be applied to such a null stream. In the future, as several gravitational wave detectors go online (the two aLIGO ones in the United States, advanced Virgo in Italy, LIGO-India in India, and KAGRA in Japan), gravitational-wave observations from multiple detectors could be used to construct three enhanced GR null streams, each with power in a signal null direction. Pang et al. (2020) developed two methods for probing additional polarizations based on null streams with electromagnetic counterparts and applied them to GW170817. The LIGO/Virgo Collaboration has probed the existence of additional polarization modes with GW150914 (Abbott et al. 2016d), GW170814 (Abbott et al. 2017b), GW170817 (Abbott et al. 2019b), and gravitational-wave events in the GWTC catalogs (Abbott et al. 2016a, 2019c, 2021b, c). Similar analyses are done in Hagiwara et al. (2019), Takeda et al. (2021), while future prospects are given in Takeda et al. (2018), Takeda et al. (2019), Philippoz et al. (2018), Hu et al. (2024), including multiband observations with space- and ground-based detectors (Philippoz et al. 2018). Chatzioannou et al. (2021) proposed a new method for constraining additional

polarization modes on top of the GR tensor modes. The method is model independent (does not rely on waveform templates), phase coherent and no prior-information is needed for the sky location of a transient source. Isi et al. (2015), Isi et al. (2017) and Kuwahara and Asada (2022) proposed the use of continuous gravitational waves to probe extra polarizations. Nishizawa et al. (2009) studied the detectability of various polarization modes with observations of stochastic gravitational-wave backgrounds with a network of ground-based interferometers. Omiya and Seto (2021), Omiya and Seto (2023) studied the overlap reduction functions of even and odd-parity components of the tensor, vector and scalar polarizations for isotropic stochastic gravitational-wave background observations with ground-based detectors. If gravitational-wave signals are lensed, multiple copies of the same signal effectively increase the number of detectors in a network thanks to Earth's rotation (Goyal et al. 2021), which can help separate different polarization modes.

Let us review the polarization tests carried out by the LIGO/Virgo Collaboration in more detail. The first test was performed on the GW150914 event (Abbott et al. 2016d), though the results were inconclusive because the number of GR tensorial (plus and cross) modes are equal to the number of detectors that observed this event (LIGO Hanford and Livingston). The first informative test of polarization asked whether certain loud events supported the hypothesis that gravity contains only tensorial polarizations versus the hypotheses that it contains only scalar or only vectorial polarizations. Such a test should be understood as purely null test because no viable theory currently exists that predicts purely scalar or purely vectorial gravitational waves; such theories existed in the 1970 s, but they were stringently constrained by solar system experiments over 50 years ago (Will 2018b). Nonetheless, such a null test was performed on the GW170814 event (Abbott et al. 2017b) and the collaboration found that the tensor modes are preferred over pure-scalar or pure-vector modes with Bayes factors (B_S^T and B_V^T) of more than 1000 and 200 respectively. This analysis was improved with the GW170817 event (Abbott et al. 2019b), where the Bayes factors found were $\log_{10} B_S^T = +23.09 \pm 0.08$ and $\log_{10} B_V^T = +20.81 \pm 0.08$. The improvement is due to (i) the sky position of the binary neutron star source relative to the detectors, and (ii) the fact that the sky position is measured precisely from the electromagnetic counterparts. The asymmetry in the measurement of B_S^T and B_V^T is due to the intrinsic geometries of the detector antenna patterns, making scalar modes easier to distinguish than vector modes.

The null-stream technique mentioned earlier was applied to binary black hole merger events in the GWTC-2 catalog (Abbott et al. 2021b). The Collaboration found $\log_{10} B_S^T = \mathcal{O}(1)$, indicating that the pure-scalar hypothesis is disfavored over the pure-tensorial one, while the pure-vector hypothesis could not be ruled out (in fact, some binaries slightly preferred the pure-vector hypothesis over the pure-tensor one). The Bayes factors with the null stream analysis are much smaller than those obtained for the GW170814 and GW170817 events because the former relies on an incoherent stacking of signal power and does not coherently track the phase over time. The LIGO/Virgo Collaboration further applied the null stream analysis to test

mixed polarization states of tensor, vector, and scalar modes with binary black hole merger events in the GWTC-3 catalog (Abbott et al. 2021c). The method uses an effective antenna pattern function constructed by choosing a subset L of polarization modes and projecting the relevant polarization state to be tested into the chosen basis in this subspace (Wong et al. 2021). Each polarization mode can then be described by a linear combination of the basis modes plus an additional orthogonal component. By choosing the dimension of the subset as $L = 1$,²¹ the collaboration found that the pure-scalar, pure-vector and vector-scalar mixed hypotheses are strongly disfavored, while any mixed hypothesis containing tensor modes cannot be ruled out. On the other hand, by choosing $L = 2$, they found that mixed hypotheses can be more strongly disfavored than the pure-vector hypothesis (the pure-scalar hypothesis cannot be tested because the longitudinal and breathing modes for interferometers are linearly dependent). This is because mixed hypotheses involve a larger number of free parameters that leads to a larger Occam penalty. The bottom line is that the population of events in GTWC-3 is consistent with the pure tensorial hypothesis.

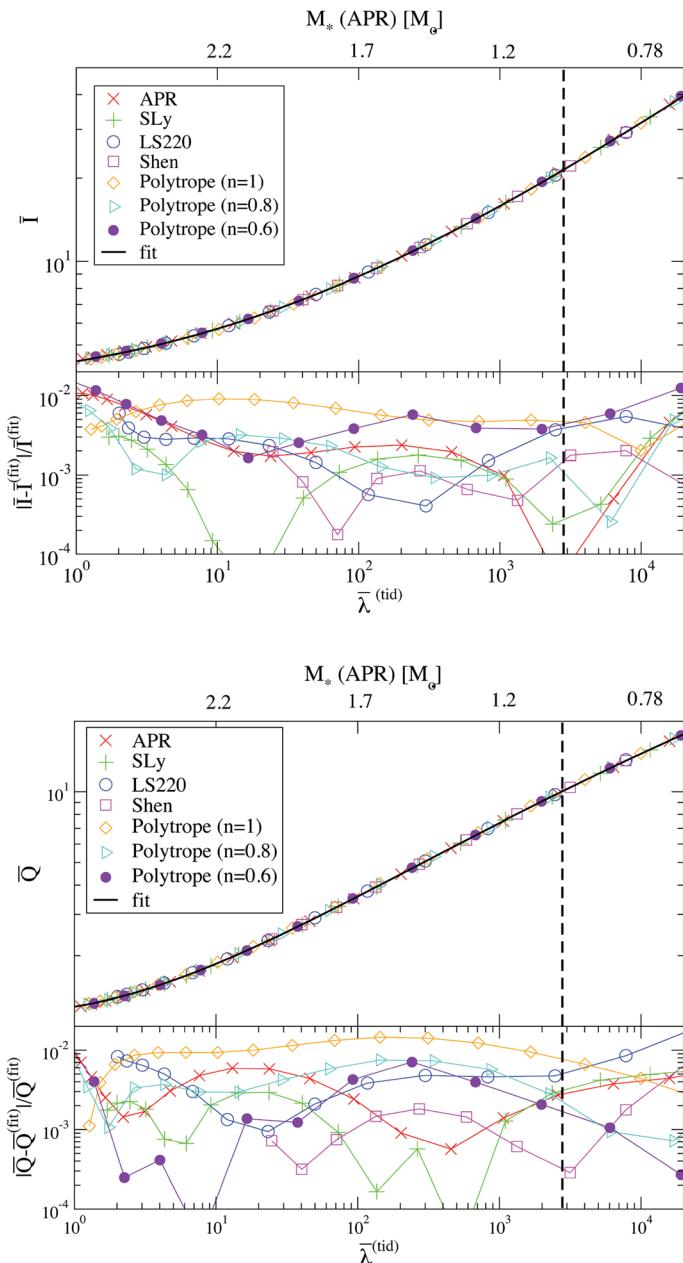
4.3.8 I-Love-Q tests

Neutron stars in the slow-rotation limit can be characterized by their mass and radius (to zeroth-order in spin), by their moment of inertia (to first-order in spin), and by their quadrupole moment and Love numbers (to second-order in spin). One may expect these quantities to be quite sensitive to the neutron star's internal structure, which can be parameterized by its equation of state, i.e., the relation between its internal pressure and its internal energy density. Since the equation of state cannot be well-constrained in the laboratory at super-nuclear densities, one is left with a variety of possibilities that predict different neutron-star mass-radius relations.

Recently, however, Yagi and Yunes (2013a, b, 2017) have demonstrated that there are relations between the moment of inertia (I), the Love numbers (λ), and the quadrupole moment (Q), the *I-Love-Q relations* that are essentially insensitive to the equation of state. Figure 6 shows two of these relations (the normalized I-Love and Q-Love relations—see caption) for a variety of equations of state, including APR (Akmal et al. 1998), SLy (Douchin and Haensel 2001; Shibata et al. 2005), Lattimer–Swesty with nuclear incompressibility of 220 MeV (LS220) (Lattimer and Swesty 1991; O'Connor and Ott 2010), Shen et al. (1998a), Shen et al. (1998b), O'Connor and Ott (2010), the latter two with temperature of 0.01 MeV and an electron fraction of 30%, and polytropic equations of state with indices of $n = 0.6, 0.8$ and 1^{22} . The bottom panels show the difference between the numerical results and the analytical, fitting curve. Observe that all equations of state lead to the same

²¹ A single basis is sufficient to capture the two tensorial polarizations. This is because, in the quadrupolar approximation, the plus and cross modes only differ by a relative amplitude and phase that can be marginalized over when computing the evidence.

²² Notice that these relations are independent of the polytropic constant K , where $p = K\rho^{(1+1/n)}$, as shown in Yagi and Yunes (2013a).



◀ Fig. 6 *Top:* Fitting curves (solid curve) and numerical results (points) of the universal I-Love (left) and Q-Love (right) relations for various equations of state, normalized as $\bar{I} = I/M_{\text{NS}}^3$, $\bar{\lambda}^{(\text{tid})} = \lambda^{(\text{tid})}/M_{\text{NS}}^5$ and $\bar{Q} = -Q^{(\text{rot})}/[M_{\text{NS}}^3(S/M_{\text{NS}}^2)^2]$, M_{NS} is the neutron-star mass, $\lambda^{(\text{tid})}$ is the tidal Love number, $Q^{(\text{rot})}$ is the rotation-induced quadrupole moment, and S is the magnitude of the neutron-star spin angular momentum. The neutron-star central density is the parameter varied along each curve, or equivalently the neutron-star compactness. The top axis shows the neutron star mass for the APR equation of state, with the vertical dashed line showing $M_{\text{NS}} = 1 M_{\odot}$. *Bottom:* Relative fractional errors between the fitting curve and the numerical results. Observe that these relations are essentially independent of the equation of state, with loss of universality at the 1% level. Image reproduced by permission from Yagi and Yunes (2013a), copyright by APS

I-Love and Q-Love relations, with discrepancies smaller than 1% for realistic neutron-star masses. These results have been verified by many groups: in Lattimer and Lim (2013) to a wide range of equations of state, in Yagi and Yunes (2013a), Chan et al. (2015), Chan et al. (2016) via a post-Minkowskian analysis, in Pappas and Apostolatos (2014), Stein et al. (2014), Yagi et al. (2014c) to higher multiple order, in Haskell et al. (2014), Zhu et al. (2020b) to weakly-magnetized neutron stars, in Doneva et al. (2013), Pappas and Apostolatos (2014), Chakrabarti et al. (2014), Yagi et al. (2014c) to rapidly rotating neutron stars, in Maselli et al. (2013) to dynamical tides during coalescence (Ferrari et al. 2012; Maselli et al. 2012), in Bretz et al. (2015) to differential rotation, in Majumder et al. (2015) for different normalizations, in stellar oscillations (Chan et al. 2014; Benitez et al. 2021; Sotani and Kumar 2021), in hybrid stars (Paschalidis et al. 2018; Tan et al. 2022). See Yagi and Yunes (2017) for a review on universal relations for neutron stars. The universal relations were revisited and improved in Carson et al. (2019) after GW170817.

Given the independent measurement of any two members of the I-Love-Q trio, Yagi and Yunes proposed that one could carry out a (null) model-independent and equation-of-state-independent test of GR (Yagi and Yunes 2013b, a) (see Yagi and Yunes 2017; Doneva and Pappas 2018 for reviews on tests of GR with neutron star universal relations). For example, assume that electromagnetic observations of the binary pulsar J0737–3039 have measured the moment of inertia to 10% accuracy (Lattimer and Schutz 2005; Kramer and Wex 2009; Kramer et al. 2006). The slow-rotation approximation is perfectly valid for this binary pulsar, due to its relatively long spin period. Assume further that a gravitational-wave observation of a neutron-star-binary inspiral, with individual masses similar to that of the primary in J0737–3039, manages to measure the neutron star tidal Love number to 60% accuracy (Yagi and Yunes 2013b, a). These observations then lead to an error box in the I-Love plane, which must contain the curve in the left-panel of Fig. 6.

A similar test could be carried out by using data from only binary pulsar observations or only gravitational wave detections. In the case of the latter, one would have to simultaneously measure or constrain the value of the quadrupole moment and the Love number, since the moment of inertia is not measurable with gravitational wave observations. In the case of the former, one would have to extract the moment of inertia and the quadrupole moment, the latter of which will be difficult to measure. Therefore, the combination of electromagnetic and gravitational wave observations would be the ideal way to carry out such tests.

I-Love-Q tests of GR are powerful only as long as modified gravity theories predict I-Love-Q relations that are not degenerate with the general relativistic ones. Yagi and Yunes (2013a, b) investigated such a relation in dynamical Chern–Simons gravity and found that such degeneracy is only present in the limit $\zeta_{\text{CS}} \rightarrow 0$ (see also Gupta et al. (2018) for a related work). That is, for any finite value of ζ_{CS} , the dynamical Chern–Simons I-Love-Q relation differs from that of GR, with the distance to the GR expectation increasing for larger ζ_{CS} . Yagi and Yunes (2013a, b) predicted that a test similar to the one described above could constrain dynamical Chern–Simons gravity to roughly $\zeta_{\text{CS}}^{1/4} < 10M_{\text{NS}} \sim 15$ km, where recall that $\zeta_{\text{CS}} = \alpha_{\text{CS}}^2 / (\beta\kappa)$. This has been demonstrated in Silva et al. (2021a), who combined the tidal deformability measurement of GW170817 through gravitational waves and the compactness measurement through X-ray observations with NICER and converted the latter to that of moment of inertia using the universal relation between the compactness and moment of inertia assuming the GR relation holds. Silva et al. (2021a) also developed a parameterized I-Love relation that can capture deviations from GR in the relation in a model-independent way and found the mapping between phenomenological parameters and the coupling constant in dCS gravity. Pan et al. (2023) studied the possibility of using fast radio burst emitters (like magnetars) in binary neutron stars to measure the quadrupole moment from radio observations and tidal deformability from gravitational wave observations. The authors then pointed out that one can probe non-GR theories like dCS gravity with the universal Q-Love relation. Pan et al. (2023) also constructed a parameterized Q-Love relation similar to the parameterized I-Love one in Silva et al. (2021a). Universal relations for neutron stars have also been studied in Einstein–dilaton–Gauss–Bonnet gravity (Kleinhuis et al. 2014, 2016b; Yagi and Yunes 2017; Saffer and Yagi 2021), massless and massive scalar-tensor theories (Doneva et al. 2014; Pani and Berti 2014; Doneva and Yazadjiev 2016; Yagi and Yunes 2017; Hu et al. 2021), $f(R)$ theories (Doneva et al. 2015; Staykov et al. 2015; Yagi and Yunes 2017), Eddington-inspired Born–Infeld gravity (Sham et al. 2014), higher-dimensional theories (Chakravarti et al. 2020), Eistein–Æther theory (Vylet et al. 2024), and Hořava gravity (Ajith et al. 2022). Unlike dynamical Chern–Simons gravity, however, these theories are very well-constrained from prior Solar System and binary pulsar observations, and thus, the I-Love-Q relations are much closer to the general-relativity ones.

The tests described above, of course, only hold provided the I-Love-Q relations are valid in general relativity and in modified gravity theories. Establishing this analytically is difficult in general, but possible when making some simplifying assumptions and using approximations. In particular, Yagi and Yunes (2013b), Yagi and Yunes (2013a) assumed that the neutron stars are uniformly and slowly rotating, as well as only slightly tidally deformed by their rotational velocity or companion. These assumptions have by now been relaxed and the I-Love-Q relations have been seen to hold (Lattimer and Lim 2013; Yagi and Yunes 2013a; Chan et al. 2015, 2016; Pappas and Apostolatos 2014; Stein et al. 2014; Yagi et al. 2014c; Haskell et al. 2014; Doneva et al. 2013; Pappas and Apostolatos 2014; Chakrabarti et al. 2014; Yagi et al. 2014c; Maselli et al. 2013). However, the relations clearly

do not hold for newly-born neutron stars, which are rapidly and differentially rotating (Martinon et al. 2014), or for magnetars, which have strong magnetic fields that contribute to the quadrupolar deformation (Haskell et al. 2014). Martinon et al. (2014) have found that the I-Love-Q deviate from universality by roughly 20% in proto-neutron stars, but this non-universality effaces away within 2 s of evolution, as the stellar entropy relaxes and the star slowly settles down to a barotropic equilibrium (see Lenka et al. 2019; Marques et al. 2017; Torres-Forné et al. 2019; Raduta et al. 2020 for related works). Moreover, the radio waves and gravitational waves emitted by millisecond pulsars and neutron-star inspirals are expected to have binary components with normal magnetic fields, for which the magnetic quadrupolar deformation will be small. Therefore, the universal relations should still hold in the systems one would observe to carry out I-Love-Q tests.

4.3.9 Consistency tests

We now review two consistency tests of GR performed by the LIGO/Virgo Collaboration: residual tests and inspiral-merger-ringdown consistency tests. Let us first focus on the former. One can subtract the most probable binary black hole waveform in GR from the signal and test whether the resulting residual is consistent with noise. For the GW150914 event, the collaboration used the BayesWave algorithm (Cornish and Littenberg 2015; Littenberg and Cornish 2015) to rank three different hypotheses: the data contains (i) only Gaussian noise, (ii) Gaussian noise plus uncorrelated noise transients, and (iii) Gaussian noise and an elliptically polarized gravitational-wave signal (Abbott et al. 2016d). The collaboration computed the signal-to-noise Bayes factor (a measure of significance for the excess power in the data), and the signal-to-glitch Bayes factor (a measure of the coherence of the excess power between Hanford and Livingston detectors). They found that the GW150914 data prefers the first hypothesis over the second and third ones, leading to the conclusion that all the measured power is consistent with the GR prediction. The 95% upper bound on the residual signal-to-noise ratio was found to be 7.3. This can be translated to a lower bound on the fitting factor of 0.96, which, in turn, means that GR violations in the GW150914 data, if present, are limited to less than 4% for effects that cannot be captured by redefinition of physical parameters.

The collaboration carried out residual tests for other events in the gravitational-wave catalogs (Abbott et al. 2019c, 2021b, c). For example, using GWTC-3, they compared the signal-to-noise ratios of the signals and residuals for various events and found no correlation between these two signal-to-noise ratios. This indicates that the data is consistent with the GR templates and the residual signal-to-noise ratios depend purely on the detector noise. They also estimated the p -values of residual signal-to-noise ratios for each event. This corresponds to the probability of obtaining a background value of the residual signal-to-noise ratio higher than that of the event. They found no significant deviation in the residual data from the expected noise distribution in the individual interferometers.

The second type of consistency test is the inspiral-merger-ringdown one (Ghosh et al. 2016, 2018). In this consistency test, one compares inferences on the final mass and spin of the remnant black hole in a binary black hole merger obtained

from the inspiral and from the post-inspiral parts of a waveform separately. This can be realized as follows. First, one estimates the “inspiral” masses and spins of the black hole binary components through a phenomenological inspiral-merger-ringdown waveform. With this in hand, one then infers the final mass/spin of the black hole remnant again, but this time through empirical relations between the initial masses/spins and the final mass/spin, which are obtained through numerical relativity simulations in GR (Healy and Lousto 2017; Hofmann et al. 2016; Jiménez-Forteza et al. 2017). One then repeats this analysis for the “post-inspiral” signal to find another set of the final mass and spin measurement. Suppose there is an overlap region in the posterior distributions for the final mass and spin from inspiral and post-inspiral. In that case, this indicates that the procedure described above (including that GR is correct) is consistent with the data. One can go one step further and combine such posterior distributions to find a single posterior distribution in $\Delta M_f / \bar{M}_f$ and $\Delta \chi_f / \bar{\chi}_f$. Here, ΔM_f and $\Delta \chi_f$ are the difference in the final mass and dimensionless spin of the remnant black hole estimated with the post-inspiral only and the inspiral plus numerical relativity fitting formula. The quantities \bar{M}_f and $\bar{\chi}_f$ are either the best-fit value of the final mass and dimensionless spin obtained through the best-fit inspiral-merger-ringdown template or the average of the final mass and dimensionless spin between inspiral and post-inspiral methods. Madekar et al. (2024) extended the original inspiral-merger-ringdown consistency tests to a *meta* inspiral-merger-ringdown consistency tests that checks for the

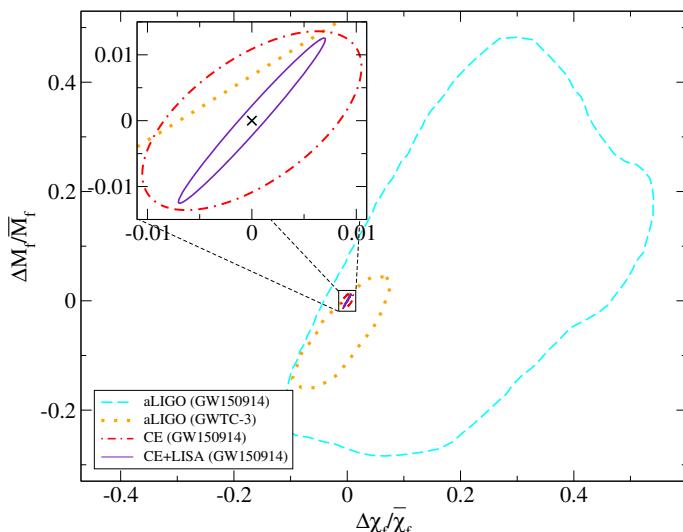


Fig. 7 Inspiral-merger-ringdown consistency tests of GR in the parameter space of the fractional difference in the estimate of the final mass and spin of the remnant black hole between inspiral and post-inspiral. We present 90% credible posterior distributions for GW150914 (Abbott et al. 2016d) and the combined one for events in GWTC-3 (Abbott et al. 2021c). We also present future forecasts with Cosmic Explorer and multiband observations of Cosmic Explorer plus LISA, both assuming they detect signals from GW150914-like events (Carson and Yagi 2020b, g)

inferred final mass and spin from two independent tests of GR and checks for consistency.

We now show results obtained by applying this second consistency test to existing gravitational-wave events. Such a result for GW150914 (Abbott et al. 2019c, 2016d) is shown in Fig. 7. Observe that the origin (corresponding to GR) is within the 90% credible region, indicating that data is consistent with the GR assumption. The two-dimensional GR quantile value (defined as the fraction of the posterior enclosed by the isoprobability contour passing through the origin; smaller values mean better consistency with GR) is 28%. The LIGO/Virgo Collaboration also carried out this test for other events in the catalog (Abbott et al. 2021b, c). The combined posterior distribution for selected events in GWTC-3 (assuming the deviation is the same for all events) is also shown in Fig. 7, with $\Delta M_f/\bar{M}_f = -0.02^{+0.07}_{-0.06}$ and $\Delta \chi_f/\bar{\chi}_f = -0.06^{+0.10}_{-0.07}$ (Abbott et al. 2021c). The two-dimensional GR quantile in this case is 79.6% (see also Zhong et al. (2024), who proposed multidimensional hierarchical tests of GR and applied the framework to a two-dimensional inspiral-merger-ringdown consistency tests with GW events in GWTC-3). Figure 7 also presents results for future forecasts obtained through a Fisher analysis computed in Carson and Yagi (2020b, g), who assumed that a signal from a GW150914-like event is detected with Cosmic Explorer alone and with multiband observations of Cosmic Explorer and LISA. All of these works assume binaries are quasi-circular. Bhat et al. (2023) studied systematic errors on the inspiral-merger-ringdown consistency tests due to ignoring the effect of eccentricities. They found that the eccentricity e at 10 Hz can bring a significant bias in the inferred final mass and spin when $e \gtrsim 0.1$ for aLIGO and $e \gtrsim 0.015$ for Cosmic Explorer. The effect of eccentricity on consistency tests has been studied in Shaikh et al. (2024).

Although the inspiral-merger-ringdown tests were designed as consistency tests of GR, one can tweak them to test specific theories and models. This has been investigated by Carson and Yagi for Einstein–dilaton–Gauss–Bonnet gravity (Carson and Yagi 2020f) and parameterized Kerr black holes (Carson and Yagi 2020d). They constructed gravitational waveforms including the leading corrections to the inspiral and the ringdown frequency and damping time. They then injected these signals and recovered them with GR templates to estimate systematic and statistical errors on the final mass and spin of the remnant black hole. This allowed them to find upper bounds on the theory and the model if observations are consistent with GR. They found that constraints on Einstein–dilaton–Gauss–Bonnet gravity can be improved by an order of magnitude from current bounds with future multiband observations (Carson and Yagi 2020f), while those on the Johannsen–Psaltis metric parameters can be improved by up to three orders of magnitude with future LISA observations (Carson and Yagi 2020d).

4.4 Tests of the no-hair theorems

Another important class of generic tests of GR are those that concern the *no-hair* theorems. Since much work has been done on this area, we have separated this topic from the main generic tests section (4.3). In what follows, we describe what these

theorems are and the possible tests one could carry out with gravitational-wave observations emitted by black-hole-binary systems.

4.4.1 The no-hair theorems

The *no-hair* theorems state that the only stationary, vacuum solution to the Einstein equations that is non-singular outside the event horizon is completely characterized by three quantities: its mass M , its spin S and its charge Q . This conclusion is arrived at by combining several different theorems. First, Hawking (1971, 1972a) proved that a stationary black hole must have an event horizon with a spherical topology and that it must be either static or axially symmetric. Israel (1967, 1968) then proved that the exterior gravitational field of such static black holes is uniquely determined by M and Q and it must be given by the Schwarzschild or the Reissner–Nordström metrics. Carter (1971) constructed a similar proof for uncharged, stationary, axially-symmetric black holes, where this time black holes fall into disjoint families, not deformable into each other and with an exterior gravitational field uniquely determined by M and S . Robinson (1975) and Mazur (1982) later proved that such black holes must be described by either the Kerr or the Kerr–Newman metric. See also Misner et al. (1973), Poisson (2004) for more details.

The no-hair theorems apply under a restrictive set of conditions (Cardoso and Gualtieri 2016). First, the theorems only apply in stationary situations. Black-hole horizons can be dynamically deformed in coalescing situations, and if so, Hawking’s theorems (Hawking 1971, 1972a) about spherical horizon topologies do not apply. This then implies that all other theorems described above also do not apply. Second, the theorems only apply in electro-vacuum. Consider, for example, an axially-symmetric black hole in the presence of a non-symmetrical matter distribution outside the event horizon. One might naively think that this would tidally distort the event horizon, leading to a rotating, stationary black hole that is not axisymmetric. However, Hawking and Hartle (1972) showed that in such a case the matter distribution torques the black hole forcing it to spin down, thus leading to a non-stationary scenario. If the black hole is non-stationary, then again the no-hair theorems do not apply by the arguments described at the beginning of this paragraph, and thus non-isolated black holes can have hair. Third, the theorems only apply within GR, i.e., through the use of the Einstein equations. Therefore, it is plausible that black holes in modified gravity theories or in GR with singularities outside any event horizons (naked singularities) will have hair.

The no-hair theorems imply that the exterior gravitational field of isolated, stationary, uncharged and vacuum black holes (in GR and provided the spacetime is regular outside all event horizons) can be written as an infinite sum of mass and current multipole moments, where only two of them are independent: the mass monopole moment M and the current dipole moment S . One can extend these relations to include charge, but astrophysical black holes are expected to be essentially neutral due to charge accretion. If the no-hair theorems hold, all other multipole moments can be determined from (Geroch 1970a, b; Hansen 1974)

$$M_\ell + iS_\ell = M(ia)^\ell, \quad (296)$$

where M_ℓ and S_ℓ are the ℓ th mass and current multipole moments. Even if the black-hole progenitor was not stationary or axisymmetric, the no-hair theorems guarantee that any excess multipole moments will be shed-off during gravitational collapse (Price 1972a, b). Eventually, after the black hole has settled down and reached an equilibrium configuration, it will be described purely in terms of $M_0 = M$ and $S_1 = S = Ma^2$, where a is the Kerr spin parameter.

An astrophysical observation of a hairy black hole would not imply that the no-hair theorems are wrong, but rather that one of the assumptions made in deriving these theorems is not appropriate to describe nature. The three main assumptions are stationarity, vacuum and that GR and the regularity condition hold. Astrophysical black holes will generically be hairy due to a violation of the first two assumptions, since they will neither be perfectly stationary, nor exist in a perfect vacuum. Astrophysical black holes will always suffer small perturbations by other stars, electromagnetic fields, other forms of matter, like dust, plasma or dark matter, etc., which will induce non-zero deviations from Eq. (296) and thus evade the no-hair theorems. However, in all cases of interest such perturbations are expected to be too small to be observable, which is why one argues that even astrophysical black holes should obey the no-hair theorems if GR holds. Put another way, an observation of the violation of the no-hair theorems would be more likely to indicate a failure of GR in the extreme gravity regime, than an unreasonably large amount of astrophysical hair.

Tests of the no-hair theorems come in two flavors: through electromagnetic observations (Johannsen and Psaltis 2010a, b, 2011b, 2013; Qi et al. 2021; Alush and Stone 2022) and through gravitational wave observations (Ryan 1995, 1997a; Collins and Hughes 2004; Glampedakis and Babak 2006; Babak et al. 2007; Barack and Cutler 2007; Li and Lovelace 2008; Sopuerta and Yunes 2009; Yunes and Sopuerta 2010; Vigeland and Hughes 2010; Vigeland 2010; Gair and Yunes 2011; Vigeland et al. 2011; Rodriguez et al. 2012). The former rely on radiation emitted by accelerating particles in an accretion disk around black holes. However, such tests are not clean as they require the modeling of complicated astrophysics associated with accretion disks, matter and electromagnetic fields. Other electromagnetic tests of the no-hair theorems exist, for example through the observation of close stellar orbits around Sgr A* (Merritt et al. 2010, 2011; Sadeghian and Will 2011; Ajith et al. 2020; Qi et al. 2021; Alush and Stone 2022) and pulsar–black-hole binaries (Wex and Kopeikin 1999), and through direct images of black holes (Johannsen and Psaltis 2010b; Broderick et al. 2014; Psaltis et al. 2016; Psaltis 2019; Akiyama et al. 2022b). See Psaltis (2008b) for reviews on these topics. Unlike electromagnetic tests, gravitational wave tests are clean, without much contamination from their astrophysical environment (Yunes et al. 2011b, c; Kocsis et al. 2011; Barausse et al. 2014); little work, however, has gone into quantitatively comparing electromagnetic and gravitational wave tests of the no-hair theorem (Cardenas-Avendano et al. 2016). Gravitational wave tests of the no-hair theorem

can be classified into those carried out with inspirals and with ringdown waves. We will describe below both of these in some detail.

4.4.2 Inspiral tests of the no-hair theorem

Gravitational wave tests of the no-hair theorems can be performed with the detection of either extreme or comparable mass-ratio inspirals and with the ringdown of comparable-mass black-hole mergers with current ground-based (Krishnendu et al. 2017, 2019a, b) and future space-borne gravitational-wave detectors (Amaro-Seoane et al. 2013, 2012). Extreme mass-ratio inspirals consist of a stellar-mass compact object spiraling into a supermassive black hole in a generic orbit within astronomical units from the event horizon of the supermassive object (Amaro-Seoane et al. 2007). These events outlive the observation time of future detectors, emitting millions of gravitational wave cycles, with the stellar-mass compact object essentially acting as a tracer of the supermassive black hole spacetime (Sotiriou and Apostolatos 2005) (see Cárdenas-Avendaño and Sopuerta 2024 for a recent review on tests of GR with extreme mass-ratio inspirals.) Ringdown gravitational waves are always emitted after black holes merge, as the remnant settles down into its final configuration. During the ringdown, the highly-distorted remnant radiates all excess degrees of freedom and this radiation carries a signature of whether the no-hair theorems hold in its quasi-normal mode spectrum (see, e.g., Berti et al. 2009 for a recent review).

Both electromagnetic and gravitational wave tests need a metric with which to model accretion disks, quasi-periodic oscillations, or extreme mass-ratio inspirals. One can classify these metrics as *direct* or *generic*, paralleling the discussion in Sect. 4.2. Direct metrics are exact solutions to a specific set of field equations, with which one can derive observables. Examples of such metrics are the Manko–Novikov metric (Manko and Novikov 1992) and the slowly-spinning black-hole metric in dynamical Chern–Simons gravity (Yunes and Pretorius 2009a; Konno et al. 2009; Yagi et al. 2012d; Maselli et al. 2015a) and in Einstein–dilaton–Gauss–Bonnet gravity (Yunes and Stein 2011; Pani et al. 2011c; Maselli et al. 2015a). Generic metrics are those that parametrically modify the Kerr spacetime, such that for certain parameter choices one recovers identically the Kerr metric, while for others, one has a deformation of Kerr. Generic metrics can be further classified into two subclasses, Ricci-flat versus non-Ricci-flat, depending on whether they satisfy $R_{\mu\nu} = 0$.

One might be concerned that such no-hair tests of GR cannot constrain modified gravity theories, because Kerr black holes can also be solutions in the latter (Psaltis et al. 2008). This is indeed true provided the modified field equations depend only on the Ricci tensor or scalar. In Einstein–dilaton–Gauss–Bonnet or dynamical Chern–Simons gravity, the modified field equations depend on the Riemann tensor, and thus, Ricci-flat metric need not solve these modified set (Yunes and Stein 2011). Moreover, just because the metric background is identically Kerr does not imply that inspiral gravitational waves will be identical to those predicted in GR. Most studies carried out to date, be it direct metric tests or generic metric tests, assume

that the only quantity that is modified is the metric tensor, or equivalently, the Hamiltonian or binding energy. Inspiral motion, of course, does not depend just on this quantity, but also on the radiation-reaction force that pushes the small object from geodesic to geodesic. Moreover, the gravitational waves generated during such an inspiral depend on the field equations of the theory considered. Therefore, most of metric tests should be considered as partial tests in this sense; in general, modifications in extreme gravity will induce corrections to the Hamiltonian, the radiation-reaction force and wave generation.

4.4.2.1 Direct metric tests of the no-hair theorem Let us first consider direct metric tests of the no-hair theorem. The most studied direct metric is the Manko–Novikov one, which although an exact, stationary and axisymmetric solution to the vacuum Einstein equations, does not represent a black hole, as the event horizon is broken along the equator by a ring singularity (Manko and Novikov 1992). Just like the Kerr metric, the Manko–Novikov metric possesses an ergoregion, but unlike the former, it also possesses regions of closed time-like curves that overlap the ergoregion. Nonetheless, an appealing property of this metric is that it deviates continuously from the Kerr metric through certain parameters that characterize the higher multiple moments of the solution.

The first geodesic study of Manko–Novikov spacetimes was carried out by Gair et al. (2008). They found that there are two ring-like regions of bound orbits: an outer one where orbits look regular and integrable, as there exist four isolating integrals of the motion; and an inner one where orbits are chaotic and thus ergodic. Gair et al. (2008) suggested that orbits that transition from the integrable to the chaotic region would leave a clear observable signature in the frequency spectrum of the emitted gravitational waves. However, they also noted that chaotic regions exist only very close to the central body and are probably not astrophysically accessible. The study of Gair et al. (2008) was recently confirmed and followed up by Contopoulos et al. (2011). They studied a wide range of geodesics and found that, in addition to an inner chaotic region and an outer regular region, there are also certain Birkhoff islands of stability. When an extreme mass-ratio inspiral traverses such a region, the ratio of resonant fundamental frequencies would remain constant in time, instead of increasing monotonically. Such a feature would impact the gravitational waves emitted by such a system, and it would signal that the orbit equations are non-integrable and the central object is not a Kerr black hole. Destounis and Kokkotas (2021) also derived gravitational waveforms for extreme mass ratio inspirals for Manko–Novikov spacetimes and found that fundamental frequencies undergo sudden jumps when the companion crosses a resonant island.

The study of chaotic motion in geodesics of non-Kerr spacetimes is by no means new. Chaos has also been found in geodesics of Zipoy–Voorhees–Weyl and Curzon spacetimes with multiple singularities (Sota et al. 1996a, b) and in general for Zipoy–Voorhees spacetimes in Lukes-Gerakopoulos (2012), of perturbed Schwarzschild spacetimes (Letelier and Vieira 1997b), of Schwarzschild spacetimes with a dipolar halo (Letelier and Vieira 1997a, 1998; Guéron and Letelier 2001) of Erez–Rosen spacetimes (Guéron and Letelier 2002), and of deformed

generalizations of the Tomimatsu–Sato spacetime (Dubeibe et al. 2007). One might worry that such chaotic orbits will depend on the particular spacetime considered, but recently Apostolatos et al. (2009) and Lukes–Lukes-Gerakopoulos et al. (2010) have argued that the Birkhoff islands of stability are a general feature. Although the Kolmogorov, Arnold, and Moser theorem (Kolmogorov 1954; Arnold 1963; Moser 1962) states that phase orbit tori of an integrable system are only deformed if the Hamiltonian is perturbed, the Poincaré–Birkhoff theorem (Lichtenberg and Lieberman 1992) states that resonant tori of integrable systems actually disintegrate, leaving behind a chain of Birkhoff islands. These islands are only characterized by the ratio of winding frequencies that equals a rational number, and thus, they constitute a distinct and generic feature of non-integrable systems (Apostolatos et al. 2009; Lukes-Gerakopoulos et al. 2010). Given an extreme mass-ratio gravitational-wave detection, one can monitor the ratio of fundamental frequencies and search for plateaus in their evolution, which would signal non-integrability. Of course, whether detectors can resolve such plateaus depends on the initial conditions of the orbits and the physical system under consideration (these determine the thickness of the islands), as well as the mass ratio (this determines the radiation-reaction timescale) and the distance and mass of the central black hole (this determines the SNR).

Another example of a direct metric test of the no-hair theorem is through the use of the slowly-rotating dynamical Chern–Simons black hole metric (Yunes and Pretorius 2009a). Unlike the Manko–Novikov metric, the dynamical Chern–Simons one does represent a black hole, i.e., it possesses an event horizon, but it evades the no-hair theorems because it is not a solution to the Einstein equations. Sopuerta and Yunes (2009) carried out the first extreme mass-ratio inspiral analysis when the background supermassive black hole object is taken to be such a Chern–Simons black hole. They used a semi-relativistic model (Ruffini and Sasaki 1981) to evolve extreme mass-ratio inspirals and found that the leading-order modification comes from a modification to the geodesic trajectories, induced by the non-Kerr modifications of the background. Because the latter correspond to an extreme-gravity modification to GR, modifications in the trajectories are most prominent for zoom-whirl orbits, as the small compact object zooms around the supermassive black hole in a region of unstable orbits, close to the event horizon. These modifications were then found to propagate into the gravitational waves emitted, leading to a dephasing that could be observed or ruled out with future gravitational-wave observations to roughly the horizon scale of the supermassive black hole, as has been recently confirmed by Canizares et al. (2012b), Canizares et al. (2012a). However, these studies may be underestimates, given that they treat the black hole background in dynamical Chern–Simons gravity only to first-order in spin and neglect any scalar field charge on the small object. Chaotic orbits in quadratic gravity were studied in Cárdenas-Avendaño et al. (2018), Deich et al. (2022), where the effect of chaos was found to be greatly suppressed relative to that in Manko–Novikov spacetimes. Similar to the dynamical Chern–Simons case, one can also probe other quadratic gravity theories, such as Einstein–dilaton–Gauss–Bonnet gravity, with extreme mass-ratio inspirals. In fact, one can consider the more general setup of a smaller mass black hole endowed with a scalar charge, without

choosing a particular theory of gravity and choosing the central black hole to be Kerr (Maselli et al. 2020a, 2022; Guo et al. 2022a; Lestingi et al. 2024; Speri et al. 2024).

A final example of a direct metric test of the no-hair theorems is to consider black holes that are not in vacuum. Barausse et al. (2007) studied extreme-mass-ratio inspirals in a Kerr-black-hole background that is perturbed by a self-gravitating, homogeneous torus that is compact, massive and close to the Kerr black hole. They found that the presence of this torus impacts the gravitational waves emitted during such inspirals, but only weakly, making it difficult to distinguish the presence of matter. Yunes et al. (2011c) and Kocsis et al. (2011) carried out a similar study, where this time they considered a small compact object inspiraling completely within a geometrically thin, radiation-pressure dominated accretion disk. They found that disk-induced migration can modify the radiation-reaction force sufficiently to leave observable signatures in the waveform, provided the accretion disk is sufficiently dense in the radiation-dominated regime and a gap opens up. However, these tests of the no-hair theorem will be rather difficult as most extreme-mass-ratio inspirals are not expected to be in an accretion disk.

4.4.2.2 Generic metric tests of the no-hair theorem Let us now consider generic metric tests of the no-hair theorem. Generic Ricci-flat deformed metrics will lead to Laplace-type equations for the deformation functions in the far-field since they must satisfy $R_{\mu\nu} = 0$ to linear order in the perturbations. The solution to such an equation can be expanded in a sum of mass and current multipole moments, when expressed in asymptotically Cartesian and mass-centered coordinates (Thorne 1980). These multipoles can be expressed via (Collins and Hughes 2004; Vigeland and Hughes 2010; Vigeland 2010)

$$M_\ell + iS_\ell = M(ia)^\ell + \delta M_\ell + i\delta S_\ell, \quad (297)$$

where δM_ℓ and δS_ℓ are mass and current multipole deformations. Ryan (1995), Ryan (1997a) showed that the measurement of three or more multipole moments would allow for a test of the no-hair theorem. Generic non-Ricci flat metrics, on the other hand, will not necessarily lead to Laplace-type equations for the deformation functions in the far field, and thus, the far-field solution and Eq. (297) will depend on a sum of ℓ and m multipole moments. Barack and Cutler (2007) studied how well one can measure the mass, spin and quadrupole moment of a black hole with extreme mass ratio inspirals using LISA. Gravitational waveforms of inspiralling compact objects with generic, non-axisymmetric quadrupole moments with spin-precessing and eccentric orbits were constructed in Loutrel et al. (2022).

No-hair tests can also be performed with gravitational waves from stellar-mass binary black holes using ground-based detectors (Krishnendu et al. 2017, 2019a, b). In particular, one can constrain deviations of the quadrupole moment Q from Kerr. In order to explain this idea, let us introduce the dimensionless quadrupole moment κ (same as \bar{Q} in Sect. 4.3.8) as $Q = -\kappa m^3 \chi^2$ for the mass m and dimensionless spin χ of a black hole, where $\kappa = 1$ for a Kerr black hole. The gravitational waves emitted during compact binary inspirals depend on κ_s and κ_a which are symmetric

and antisymmetric combinations of κ_1 and κ_2 for the dimensionless quadrupole moments of binary components. Due to large degeneracies between κ_s and κ_a , it would be extremely challenging to independently measure both quadrupole parameters simultaneously. Thus, one typically assumes $\kappa_a = 0$ and measures $\delta\kappa_s \equiv \kappa_s - 1$, the deviation in the symmetric combination of the dimensionless quadrupole moment from the Kerr expectation. This assumption corresponds to having compact stars with identical spin-induced deformations in a binary. The LIGO/Virgo Collaboration has derived bounds on $\delta\kappa_s$ with gravitational-wave events in the catalogs collected (Abbott et al. 2021b, c). Multiplying the likelihood of κ_s of each signal in selected events in GWTC-3, the collaboration found $\delta\kappa_s = -16.0_{-16.7}^{+13.6}$ (Abbott et al. 2021c). On the other hand, with the hierarchical analysis discussed in Sect. 4.3.6, the combined bound becomes $\delta\kappa_s = -26.3_{-52.9}^{+45.8}$ (Abbott et al. 2021c). The bounds on the positive $\delta\kappa_s$ side are stronger because of how $\delta\kappa_s$ is correlated with the effective inspiral spin parameter. Li et al. (2024a) carried out a no-hair test with GW150914 and GW200129 and reported a significant deviation in the quadrupole moment from the Kerr case for the latter event, though more events and further analyses are necessary to validate the deviation. The no-hair test can be extended to include the octupole moment (Saini and Krishnendu 2024). The importance of precession on no-hair tests for the inspiral is discussed in Loutrel et al. (2024). Mahapatra and Kastha (2024) studied the effect of amplitude corrections to multipolar tests of GR with gravitational waves, as well as carrying out multiparameter tests (Mahapatra et al. 2024).

Let us now return to tests of the no-hair relations from extreme mass-ratio inspirals, which require the construction of a parametrically-deformed black hole metric. The first attempt to construct a generic, Ricci-flat metric was by Collins and Hughes (2004): the *bumpy black-hole metric*. In this approach, the metric is assumed to be of the form

$$g_{\mu\nu} = g_{\mu\nu}^{(\text{Kerr})} + \epsilon \delta g_{\mu\nu}, \quad (298)$$

where $\epsilon \ll 1$ is a bookkeeping parameter that enforces that $\delta g_{\mu\nu}$ is a perturbation of the Kerr background. This metric is then required to satisfy the Einstein equations linearized in ϵ , which then leads to differential equations for the metric deformation. Collins and Hughes (2004) assumed a non-spinning, stationary spacetime, and thus $\delta g_{\mu\nu}$ only possessed two degrees of freedom, both of which were functions of radius only: $\psi_1(r)$, which must be a harmonic function and which changes the Newtonian part of the gravitational field at spatial infinity; and $\gamma_1(r)$ which is completely determined through the linearized Einstein equations once ψ_1 is specified. One then has the freedom to choose how to prescribe ψ_1 and Collins and Hughes (2004) Hughes investigate two choices that correspond physically to point-like and ring-like naked singularities, thus violating cosmic censorship (Penrose 1969). Vigeland and Hughes (2010) and Vigeland (2010) then extend this analysis to stationary, axisymmetric spacetimes via the Newman–Janis method (Newman and Janis 1965; Drake and Szekeres 2000), showing how such metric deformations modify Eq. (297), and computing how these bumps imprint themselves onto the orbital

frequencies and thus the gravitational waves emitted during an extreme-mass-ratio inspiral.

That the bumps represent unphysical matter should not be a surprise, since by the no-hair theorems, if the bumps are to satisfy the vacuum Einstein equations they must either break stationarity or violate the regularity condition. Naked singularities are an example of the latter. A Lorentz-violating massive field coupled to the Einstein tensor is another example (Dubovsky et al. 2007). Gravitational wave tests with bumpy black holes must then be understood as *null tests*: one assumes the default hypothesis that GR is correct and then sets out to test whether the data rejects or fails to reject this hypothesis (a null hypothesis can never be proven). Unfortunately, however, bumpy black hole metrics cannot parameterize spacetimes in modified gravity theories that lead to corrections in the field equations that are not proportional to the Ricci tensor, such as for example in dynamical Chern–Simons or in Einstein–dilaton–Gauss–Bonnet modified gravity.

Other bumpy black hole metrics have also been proposed. Glampedakis and Babak (2006) proposed a different type of stationary and axisymmetric bumpy black hole through the Hartle–Thorne metric (Hartle and Thorne 1968), with modifications to the quadrupole moment. They then constructed a “kludge” extreme mass-ratio inspiral waveform and estimated how well the quadrupole deformation could be measured (Babak et al. 2007). However, this metric is valid only when the supermassive black hole is slowly-rotating, as it derives from the Hartle–Thorne ansatz. Johannsen and Psaltis (2011a) proposed yet another metric to represent bumpy stationary and spherically-symmetric spacetimes. This metric introduces one new degree of freedom, which is a function of radius only and assumed to be a series in M/r . Johannsen and Psaltis then rotated this metric via the Newman–Janis method (Newman and Janis 1965; Drake and Szekeres 2000) to obtain a new bumpy metric for axially-symmetric spacetimes. However, such a metric possesses a naked ring singularity on the equator, and naked singularities on the poles. As before, none of these bumpy metrics can be mapped to known modified gravity black hole solutions, in the Glampedakis and Babak (2006) case because the Einstein equations are assumed to hold to leading order in the spin, while in the Johannsen and Psaltis (2011a) case because a single degree of freedom is not sufficient to model the three degrees of freedom contained in stationary and axisymmetric spacetimes (Stephani et al. 2003; Vigeland et al. 2011).

The first generic non-Ricci-flat bumpy black-hole metric so far is that of Vigeland et al. (2011), and its simplified extension by Johannsen (2013), which was further extended by Carson and Yagi (2020a), Yagi et al. (2024) and a similar black-hole metric with Kerr symmetry found by Papadopoulos and Kokkotas (2018, 2021), Chen (2020) (breaking the Z_2 symmetry of the spacetime), and Delaporte et al. (2022) (breaking the circularity of spacetime). Vigeland et al. (2011) allowed generic deformations in the metric tensor, only requiring that the new metric perturbatively retained the Killing symmetries of the Kerr spacetime: the existence of two Killing vectors associated with stationarity and axisymmetry, as well as the perturbative existence of a Killing tensor (and thus a Carter-like constant), at least to leading order in the metric deformation. Such requirements imply that the geodesic equations in this new background are fully integrable, at

least perturbatively in the metric deformation, which then allows one to solve for the orbital motion of extreme-mass-ratio inspirals by adapting previously existing tools. Brink (2008a, b, 2010a, b, 2011) studied the existence of such a second-order Killing tensor in generic, vacuum, stationary and axisymmetric spacetimes in Einstein's theory and found that these are difficult to construct exactly. By relaxing this exact requirement, Vigeland et al. (2011) found that the existence of a perturbative Killing tensor poses simple differential conditions on the metric perturbation that can be analytically solved. Moreover, they also showed how this new bumpy metric can reproduce all known modified gravity black hole solutions in the appropriate limits, provided these have an at least approximate Killing tensor; thus, these metrics are still vacuum solutions even though $R \neq 0$, since they satisfy a set of modified field equations. The imposition that the spacetime retains the Kerr Killing symmetries also leads to a bumpy metric that is well-behaved everywhere outside the event horizon (no singularities, no closed-time-like curves, no loss of Lorentz signature). Gair and Yunes (2011) studied how the geodesic equations are modified for a test-particle in a generic orbit in such a spacetime and showed that the bumps are indeed encoded in the orbital motion, and thus, in the gravitational waves emitted during an extreme-mass-ratio inspiral. This work was extended by Moore et al. (2017) for probing a parameterized black hole spacetime preserving Kerr symmetry with gravitational waves from extreme mass ratio inspirals. Destounis et al. (2020) constructed a new metric that contains a parameter characterizing the violation of the Kerr symmetry and studied how well one can constrain this parameter with future gravitational-wave observations from extreme mass-ratio inspirals. Carson and Yagi (2020d) derived the leading correction to the inspiral waveform for a generic modification to non-Kerr spacetime. The authors also derived corrections to ringdown following the post-Kerr formulation (Glampedakis et al. 2017). They then provided a future forecast on tests of non-Kerr spacetime with future gravitational-wave observations by performing parameterized tests and inspiral-merger-ringdown consistency tests of GR. Non-Kerr corrections to the waveform found in Carson and Yagi (2020d) were used by Santos et al. (2024) to place bounds on deviations from Kerr with GWTC-3 (see also Das et al. 2024). Kumar et al. (2024) constructed gravitational waves from extreme-mass-ratio inspirals with the central black hole represented by the parameterized Kerr spacetime developed by Yagi et al. (2024), and studied the prospect for probing such a spacetime with LISA.

Another approach to construct generic, non-Ricci-flat bumpy black hole-metrics is that recently pursued by Rezzolla and Zhidenko (2014), Konoplya et al. (2016), Konoplya et al. (2018), Konoplya and Zhidenko (2020), Ma and Rezzolla (2024). In this approach, one models the bumpy metric with the most general, stationary and axisymmetric line element, which is typically parametrized in terms of five free metric functions. These functions are expressed in terms of a compact radial coordinate (equivalent to the Schwarzschild factor in general relativity) and an infinite continuous fraction. Rezzolla, Zhidenko and Konoplya have shown that this metric is capable of reproducing the predictions of a large class of modified theories, including Einstein–dilaton–Gauss–Bonnet black holes, dilatonic black holes and Kerr black holes (Rezzolla and Zhidenko 2014; Konoplya et al. 2016). Moreover,

this parametrized metric has also been used to model the shadows cast by the light-ring of this metric on the light emitted by an accretion disk (Younsi et al. 2016). Cardenas-Avendano et al. (2020) compared gravitational-wave versus X-ray observations to test the parameterized spacetime of Rezzolla and Zhidenko. The authors derived corrections to the gravitational waveforms and also simulated X-ray observations for the parameterized spacetime. They found that current gravitational-wave observations place stronger bounds on the spacetime than future X-ray observations can. The gravitational-wave bounds will further improve with future gravitational-wave detectors. The Konoplya–Rezzolla–Zhidenko metric was constrained with GWTC-2 by Shashank and Bambi (2022).

4.4.3 Ringdown tests of the no-hair theorem

Let us now consider tests of the no-hair theorems with gravitational waves emitted by comparable-mass binaries during the ringdown phase. Gravitational waves emitted during ringdown can be described by a superposition of exponentially-damped sinusoids (Berti et al. 2006):

$$h_+(t) + i h_\times(t) = \frac{M}{r} \sum_{\ell mn} \left\{ \mathcal{A}_{\ell mn} e^{i(\omega_{\ell mn} t + \phi_{\ell mn})} e^{-t/\tau_{\ell mn}} S_{\ell mn} \right. \\ \left. + \mathcal{A}'_{\ell mn} e^{i(-\omega_{\ell mn} t + \phi'_{\ell mn})} e^{-t/\tau_{\ell mn}} S_{\ell mn}^* \right\}, \quad (299)$$

where r is the distance from the source to the detector, the asterisk stands for complex conjugation, the real mode amplitudes $\mathcal{A}_{\ell mn}$ and $\mathcal{A}'_{\ell mn}$ and the real phases $\phi_{\ell mn}$ and $\phi'_{\ell mn}$ depend on the initial conditions, $S_{\ell mn}$ are spheroidal functions evaluated at the complex quasinormal ringdown frequencies $\omega_{\ell mn} = 2\pi f_{\ell mn} + i/\tau_{\ell mn}$, and the real physical frequency $f_{\ell mn}$ and the real damping times $\tau_{\ell mn}$ are both functions of the mass M and the Kerr spin parameter a only, provided the no-hair theorems hold. These frequencies and damping times can be computed numerically or semi-analytically, given a particular black-hole metric (see Berti et al. 2009 for a review). The Fourier transform of a given (ℓ, m, n) mode is (Berti et al. 2006)

$$\tilde{h}_+^{(\ell, m, n)}(\omega) = \frac{M}{r} \mathcal{A}_{\ell mn}^+ \left[e^{i\phi_{\ell mn}^+} S_{\ell mn} b_+(\omega) + e^{-i\phi_{\ell mn}^+} S_{\ell mn}^* b_-(\omega) \right], \quad (300)$$

$$\tilde{h}_\times^{(\ell, m, n)}(\omega) = \frac{M}{r} \mathcal{A}_{\ell mn}^\times \left[e^{i\phi_{\ell mn}^\times} S_{\ell mn} b_+(\omega) + e^{-i\phi_{\ell mn}^\times} S_{\ell mn}^* b_-(\omega) \right], \quad (301)$$

where we have defined $\mathcal{A}_{\ell mn}^{+,\times} e^{i\phi_{\ell mn}^{+,\times}} \equiv \mathcal{A}_{\ell mn} e^{i\phi_{\ell mn}} \pm \mathcal{A}' e^{-i\phi'_{\ell mn}}$ as well as the Lorentzian functions

$$b_\pm(\omega) = \frac{\tau_{\ell mn}}{1 + \tau_{\ell mn}^2 (\omega \pm \omega_{\ell mn})^2}. \quad (302)$$

Ringdown gravitational waves will all be of the form of Eq. (299) provided that the characteristic nature of the differential equation that controls the evolution of

ringdown modes is not modified, i.e., provided that one only modifies the potential in the Teukolsky equation or other subdominant terms, which in turn depend on the modified field equations.

Tests of the no-hair theorems through the observation of black-hole ringdown date back to Detweiler (1980a), and it has been worked out in detail by Dreyer et al. (2004). Let us first imagine that a single complex mode is detected $\omega_{\ell_1 m_1 n_1}$ and one measures separately its real and imaginary parts. Of course, from such a measurement, one cannot extract the measured harmonic triplet (ℓ_1, m_1, n_1) , but instead one only measures the complex frequency $\omega_{\ell_1 m_1 n_1}$. This information is not sufficient to extract the mass and spin angular momentum of the black hole because different quintuplets (M, a, ℓ, m, n) can lead to the same complex frequency $\omega_{\ell_1 m_1 n_1}$. The best way to think of this is graphically: a given observation of $\omega_{\ell_1 m_1 n_1}^{(1)}$ traces a line in the complex $\Omega_{\ell_1 m_1 n_1} = M\omega_{\ell_1 m_1 n_1}^{(1)}$ plane; a given (ℓ, m, n) triplet defines a complex frequency $\omega_{\ell m n}$ that also traces a curve in the complex $\Omega_{\ell m n}$ plane; each intersection of the measured line $\Omega_{\ell_1 m_1 n_1}$ with $\Omega_{\ell m n}$ defines a possible doublet (M, a) ; since different (ℓ, m, n) triplets lead to different $\omega_{\ell m n}$ curves and thus different intersections, one ends up with a set of doublets S_1 , out of which only one represents the correct black-hole parameters. We thus conclude that a single mode observation of ringdown gravitational waves is not sufficient to test the no-hair theorem (Dreyer et al. 2004; Berti et al. 2006).

Let us then imagine that one has detected two complex modes, $\omega_{\ell_1 m_1 n_1}$ and $\omega_{\ell_2 m_2 n_2}$. Each detection leads to a separate line $\Omega_{\ell_1 m_1 n_1}$ and $\Omega_{\ell_2 m_2 n_2}$ in the complex plane. As before, each (n, ℓ, m) triplet leads to separate curves $\Omega_{\ell m n}$ which will intersect with both $\Omega_{\ell_1 m_1 n_1}$ and $\Omega_{\ell_2 m_2 n_2}$ in the complex plane. Each intersection between $\Omega_{\ell m n}$ and $\Omega_{\ell_1 m_1 n_1}$ leads to a set of doublets S_1 , while each intersection between $\Omega_{\ell m n}$ and $\Omega_{\ell_2 m_2 n_2}$ leads to another set of doublets S_2 . However, if the no-hair theorems hold sets S_1 and S_2 must have at least one element in common. Therefore, a two-mode detection allows for tests of the no-hair theorem (Dreyer et al. 2004; Berti et al. 2006). However, when dealing with a quasi-circular black-hole-binary inspiral within GR one knows that the dominant mode is $\ell = 2 = m$. In such a case, the observation of this complex mode by itself allows one to extract the mass and spin angular momentum of the black hole. Then, the detection of the real frequency in an additional mode, such as the $\ell = 3 = m$, $\ell = 4 = m$ or $(\ell, m) = (2, 1)$ modes that are the next subleading modes (Bhagwat et al. 2016), can be used to test the no-hair theorem (Berti et al. 2006, 2007; Kamaretsos et al. 2012). Generally, detecting higher harmonic modes of $\ell \neq 2$ or $m \neq 2$ is more promising than detecting overtone modes of $n > 0$ for unequal-mass binaries, while the latter is easier to detect for nearly equal-mass systems (Jiménez Forteza et al. 2020; Ota and Chirenti 2022; Ota 2022). One can also perform a no-hair test by studying the consistency between the mode amplitude ratio and the phase difference that can only be in narrow regions in parameter space in GR (Jiménez Forteza et al. 2023). No-hair tests through ringdown observations can probe non-Kerr black holes (Carson and Yagi 2020d; Dey et al. 2023), as discussed in Sect. 4.4.2, through e.g. the post-Kerr formalism (Glampedakis et al. 2017), and exotic compact objects (Westerweck et al. 2021) (see Sect. 4.4.4 for more details).

Although the logic behind these tests is clear, one must study them carefully to determine whether all systematic and statistical errors are sufficiently under control so that they are feasible. Berti et al. (2006, 2007) investigated such tests carefully through a frequentist approach. First, they found that a matched-filtering type analysis with two-mode ringdown templates would increase the volume of the template manifold by roughly three orders of magnitude. A better strategy then is perhaps to carry out a Bayesian analysis, like that of Gossan et al. (2012); through such a study one can determine whether a given detection is consistent with a two-mode or a one-mode hypothesis. Berti et al. (2006), Berti et al. (2007) also calculated that a SNR of $\mathcal{O}(10^2)$ in the ringdown part of the signal would be needed to detect the presence of two ringdown modes in the signal and to resolve their frequencies, so that no-hair tests would be possible. Although this is difficult to imagine with single detections by aLIGO, such tests would be possible with third-generation ground-based detectors, and they should be routine with space-based GW detectors (Berti et al. 2016). Strong signals are necessary because one must be able to distinguish at least two modes in the signal. Unfortunately, however, whether the ringdown leads to such strong SNRs and whether the sub-dominant ringdown modes are of a sufficiently large amplitude depends on a plethora of conditions: the location of the source in the sky, the mass of the final black hole, which depends on the rest mass fraction that is converted into ringdown gravitational waves (the ringdown efficiency), the mass ratio of the progenitor, the magnitude and direction of the spin angular momentum of the final remnant and probably also of the progenitor and the initial conditions that lead to ringdown. Thus, although such tests are possible, one would have to be quite fortunate to detect a sufficiently loud signal with the right properties so that a two-mode extraction and a test of the no-hair theorems is feasible. See Carullo et al. (2018), Baibhav and Berti (2019), Bhagwat et al. (2020), Ota and Chirenti (2022), Pacilio and Bhagwat (2023) for other works on future prospects for testing GR with ringdown.

Another approach is then to combine multiple events in the hopes to tease out enough information to carry out a ringdown test Yang et al. (2017). Given a single observation, one can construct the posterior of a parameter that quantifies deformations away from the quasinormal frequencies predicted in GR, given a remnant mass and spin. If the no-hair theorems hold, then this posterior would be peaked at zero, with some width that can be used to compute a confidence region, and thus, a constraint on deviations from black hole baldness. Meidam et al. (2014) considered adding the posteriors from a catalog of N detections with the third-generation Einstein Telescope (ET) detector to compute the odds-ratio between the hypothesis that the no-hair theorems are satisfied and the hypothesis that they deviate by a constant frequency factor. The authors found that when $\mathcal{O}(10)$ ET posteriors are stacked in this way, then one can test the no-hair theorem to a few percent with the first sub-dominant ringdown modes. Yang et al. (2017) carried out a different analysis: they still considered N inspiral-merger-ringdown detections, but instead of adding the posteriors together, they (i) time- and phase-shifted the events with respect to a fiducial one to align one of the sub-leading modes across the events and (ii) coherently stacked the time- and phase-shifted signals to produce a single

“mega”-signal that would boost the power in the sub-dominant mode. The time- and phase-shifting requires knowledge of how the sub-dominant mode depends on the remnant mass and spin, which Yang et al. (2017) modeled assuming GR, making this a null test. They found that coherently stacking significantly boosts the ability to test the no-hair theorem, allowing a null-test of GR with only $\mathcal{O}(5)$ events using aLIGO at designed sensitivity. They also showed that a significantly smaller number of events are required to test the no-hair relations when coherently stacking because the signal-to-noise ratio of the stacked signal scales as $N^{1/4}$ instead of $N^{1/2}$ (Yang et al. 2017; Kalmus et al. 2009) (see Da Silva Costa et al. 2018 for a related work).

No-hair tests of black holes with ringdown observations have been carried out with the existing gravitational-wave events. Carullo et al. (2019) performed a Bayesian inference on the GW150914 data and found no evidence for more than one quasinormal mode. Isi et al. (2019b) focused on the $\ell = 2 = m$ modes and found evidence in the GW150914 data for both the fundamental mode ($n = 0$) and at least one overtone mode ($n = 1$) (see Isi and Farr 2021 for a more comprehensive analysis by the same authors). This allowed them to probe the no-hair property of the remnant black hole to a $\sim 10\%$ level. On the other hand, Cotesta et al. (2022) performed an independent study and found no evidence for the presence of the overtone mode. They pointed out that the analysis for the existence of such a mode is sensitive to the starting time of the ringdown (see Bhagwat et al. (2018) for the importance of the choice of the starting time of the ringdown) and the claim for the detection of the overtone in Isi et al. (2019b) is likely to be dominated by the noise. Their claim was more thoroughly investigated in Baibhav et al. (2023). Isi and Farr (2022) revisited their analysis and reported that they could not reproduce the results in Cotesta et al. (2022) and their previous analysis in Isi et al. (2019b) should be robust (see also Carullo et al. 2023; Baibhav et al. 2023; Isi and Farr 2023 for further debate by the two groups.) Yet another independent analysis was carried out by Finch and Moore (2022). They took a frequency-domain approach developed in Finch and Moore (2021) by the same authors, as opposed to the time-domain one that had been used previously, and marginalized over the source sky position and the ringdown starting time. The authors found some tentative evidence for the overtone mode but at a much weaker significance than previously reported by Isi et al. (2019b), Isi and Farr (2022). Ma et al. (2023b), Ma et al. (2023a) developed a “rational filter”, a method to clean a particular mode from a ringdown signal. Applying this to GW150914, they removed the fundamental mode and found that the remaining filtered data is consistent with the template that only includes the first overtone. Calderón Bustillo et al. (2021) imposed the prior knowledge that the ringdown of GW150914 is sourced by a binary black hole merger and found that the hairy black hole hypothesis is disfavored over the Kerr black hole hypothesis with an odds ratio of 1:600. Wang et al. (2023b) carried out an independent analysis in frequency domain by removing contamination before ringdown. Their results support the existence of the overtone mode and are more consistent with those of Isi et al. (2019b). On the other hand, Correia et al. (2024) marginalized over merger time and sky location uncertainties, and found that the evidence for the existence of

the overtone mode is rather low. Regarding no-hair test with just the $n = 0$ fundamental mode, Capano et al. (2023) found evidence for the existence of the $\ell = 3 = m$ mode in GW190521 with a Bayes factor of 56 (see Capano et al. 2024 for their follow-up analysis). The fractional deviation from GR on the subdominant mode frequency was constrained to $-0.01^{+0.08}_{-0.09}$ to 90% confidence.

Recently, parameterized ringdown formulations have been developed to test the assumptions of the no-hair theorem (Cardoso et al. 2019; McManus et al. 2019; Maselli et al. 2020b; Carullo 2021; Franchini and Völkel 2023). Cardoso et al. (2019) assumed a spherically-symmetric background black hole solution, that all GR deviations are small, and that the perturbed equations decouple from each other. The authors then parameterized deviations in the perturbation potential from GR, where generic parameters are coefficients of the potential deviation expanded about spatial infinity. One can then solve such perturbed equations and find ringdown frequencies perturbatively. McManus et al. (2019) improved Cardoso et al. (2019) by allowing the perturbed equations to couple to each other and by going to second order in perturbation parameters. They showed that their framework can be applied to various non-GR theories, including dynamical Chern–Simons gravity, Horndeski theories and effective field theories. The original work by Cardoso et al. (2019) was refined by Franchini and Völkel (2023) to include additional coefficients that have some advantage when doing parameter estimation. The parameterized quasi-normal mode framework was further extended to include overtones (Hirano et al. 2024) and even to include tidal Love numbers of black holes (Katagiri et al. 2024). Maselli et al. (2020b), Maselli et al. (2024) further extended these previous works by including spin to the background black hole solution. The spin is here treated perturbatively and the framework is known as the parameterized ringdown spin expansion coefficients (PARSPEC). Carullo (2021) then applied this framework to existing gravitational-wave events and derived bounds on the correction to the ringdown frequency of the $(\ell, m, n) = (2, 2, 0)$ mode and the length scales (for various mass dimensions) at which new physics may arise. The parameterized quasi-normal mode framework in Cardoso et al. (2019) has recently been extended to include arbitrary spin of black holes by Cano et al. (2024). The authors introduced a parameterized deviation to the potential in the radial Teukolsky equation for the Kerr background. A parameterized waveform was also constructed using the effective-one-body framework by leaving the complex quasinormal mode frequencies to be free parameters (Brito et al. 2018). This is, thus, an inspiral–merger–ringdown waveform, and one can correctly estimate the time at which the signal starts to be dominated by the quasinormal modes, unlike the case where one models the ringdown signal through a superposition of damped sinusoids.

The LIGO/Virgo Collaboration has carried out parameterized tests of ringdown with GWTC-2 (Abbott et al. 2021b) and GWTC-3 (Abbott et al. 2021c) adopting two different methods. The first method is the time-domain ringdown analysis `pyRing` (Carullo et al. 2019; Isi et al. 2019b), which is based on damped sinusoids. For example, the collaboration took the Kerr₂₂₁ template (containing the fundamental and first overtone modes for $(\ell, |m|) = (2, 2)$) and introduced parameterized deviations from GR, $\delta\hat{f}_{221}$ for the frequency and $\delta\hat{t}_{221}$ for the

damping time of the overtone mode. Combining 21 gravitational events in GWTC-3 that pass certain criteria, the collaboration found the hierarchically combined bound of $\delta\hat{f}_{221} = 0.01^{+0.27}_{-0.28}$ (Abbott et al. 2021c) for the frequency deviation, while the damping time deviation could not be constrained. The combined log odds ratio between non-GR versus GR hypotheses was $\log_{10} \mathcal{O}_{\text{GR}}^{\text{modGR}} = -0.90 \pm 0.44$ at 90% uncertainty (Abbott et al. 2021c), indicating that the GR hypothesis is favored. The second analysis uses the pSEOBNRv4HM waveform model (Cotesta et al. 2018; Ghosh et al. 2021) (a spinning, non-precessing effective-one-body waveform model with higher modes) in the time domain and the likelihood function in the frequency domain. The frequency and damping time of the fundamental mode with $(\ell, |m|) = (2, 2)$ is modified from the GR ones as $f_{220} = f_{220}^{\text{GR}}(1 + \delta\hat{f}_{220})$ and $\tau_{220} = \tau_{220}^{\text{GR}}(1 + \delta\hat{\tau}_{220})$. The GR values are predicted from the initial binary's masses and spins through numerical relativity fits (Taracchini et al. 2014; Hofmann et al. 2016). By multiplying posteriors from multiple events in GWTC-3, the collaboration found the bound $\delta\hat{f}_{220} = 0.02^{+0.03}_{-0.03}$ and $\delta\hat{\tau}_{220} = 0.13^{+0.11}_{-0.11}$, while hierarchically-combined bounds were $\delta\hat{f}_{220} = 0.02^{+0.07}_{-0.07}$ and $\delta\hat{\tau}_{220} = 0.13^{+0.21}_{-0.22}$ (Abbott et al. 2021c). Notice that the bound on $\delta\hat{\tau}_{220}$ from multiplying posteriors does not contain the GR value within the 90%-credible region. This may be due to the asymmetric prior on $(\delta\hat{f}_{220}, \delta\hat{\tau}_{220})$, correlations among remnant parameters, imperfect noise modelling, or statistical uncertainties of using only ~ 10 events (Abbott et al. 2021c).

Recently, the problem of understanding the quasinormal frequency spectrum of spinning perturbed black holes in theories beyond general relativity has begun to be studied in detail. This problem is extremely difficult because the usual methods that lead to the Teukolsky equation (Teukolsky 1973) break down outside general relativity, either because the black hole background spacetime is not Petrov type D or because the field equations are not Einstein's. For example, spinning black holes in dynamical Chern–Simons gravity (Yunes and Pretorius 2009a; Konno et al. 2009; Yagi et al. 2012d; Maselli et al. 2015a) and Einstein–dilaton–Gauss–Bonnet gravity (Ayzenberg and Yunes 2014), computed in the slow-rotational approximation, remain Petrov Type D to linear order in spin Sopuerta and Yunes (2009), Yagi et al. (2012d), Ayzenberg and Yunes (2014), but become Petrov Type I at second and higher orders in spin Yagi et al. (2012d), Ayzenberg and Yunes (2014), Owen et al. (2021). In order to overcome this problem, several groups have calculated the quasinormal frequency spectrum of spinning perturbed black holes in the slow-rotation approximation (Wagle et al. 2022; Blázquez-Salcedo et al. 2016; Pierini and Gualtieri 2021, 2022). The problem with these analyses is that they are based on a slow-rotation approximation, while black hole remnant generated in binary coalescence are typically not rotating slowly. For this reason, a new effort has recently been put underway to compute perturbations of arbitrarily-fast rotating black holes outside general relativity. Li et al. (2023a) and Hussain and Zimmerman (2022) have taken the first steps in this direction, deriving a modified Teukolsky equation for a large class of theories outside Einstein's, which holds irrespective of the Petrov type (see also Cano et al. 2023 for related work). The left-hand side of

this equation has the same structure as the original Teukolsky equation, but it is now sourced (in the right-hand side) by terms that depend on derivatives of additional fields that may be present in the theory and spin coefficients and other curvature quantities that require metric reconstruction. Work is currently underway to separate this modified equation in a couple of example theories and then to solve the separated equations to find the eigenfrequencies without the slow-rotation approximation. The application of this method to dynamical Chern–Simons gravity for a slowly-spinning black hole has recently been completed by Wagle et al. (2024). A different approach was taken by Chung et al. (2023), Chung et al. (2024), Chung and Yunes (2024b), Petrov Type I at second and higher orders in spinChung:2024vaf where one can use a spectral decomposition to solve black hole perturbation equations that are coupled and are not separated into radial and angular sectors. This novel framework was first developed for the Schwarzschild background case (Chung et al. 2023), and then further extended to the Kerr background (Chung et al. 2024), as well as to modified theories of gravity (Chung and Yunes 2024b), such as scalar Gauss–Bonnet gravity (Chung and Yunes 2024a). With the spectral method established, recent work has begun to implement it in other theories of gravity, such as in scalar Gauss–Bonnet with strong coupling (Blázquez-Salcedo et al. 2025).

4.4.4 The hairy search for exotica

Another way to test GR is to modify the matter sector of the theory through the introduction of matter corrections to the Einstein–Hilbert action that violate the assumptions made in the no-hair theorems. More precisely, one can study whether gravitational waves emitted by binaries composed of strange stars, like quark stars, or exotic compact objects that lack a horizon, such as boson stars or gravastars, are different from waves emitted by more traditional neutron-star or black-hole binaries. Horizonless compact objects have been proposed as a way to probe the quantum nature of black holes (see e.g. Wang et al. 2020; Oshita et al. 2020; Abedi et al. 2020; Addazi et al. 2022; Chakraborty et al. 2022). In what follows, we will describe such hairy tests of the existence of compact exotica.

Boson stars are a classic example of an exotic compact object that is essentially indistinguishable from a black hole in the weak field, but which differs drastically from one in the strong field due to its lack of an event horizon. A boson star is a coherent scalar-field configuration supported against gravitational collapse by its self-interaction. One can construct several Lagrangian densities that would allow for the existence of such an object, including mini-boson stars (Friedberg et al. 1987a, b), axially-symmetric solitons (Ryan 1997b), and nonsolitonic stars supported by a non-canonical scalar potential energy (Colpi et al. 1986). Boson stars are well-motivated from fundamental theory, since they are the gravitationally-coupled limit of q-balls (Coleman 1985; Kusenko 1999), a coherent scalar condensate that can be described classically as a non-topological soliton and that arises unavoidably in viable supersymmetric extensions of the standard model (Kusenko 1997). In all studies carried out to date, boson stars have been studied

within GR, but they are also allowed in scalar-tensor theories (Balakrishna and Shinkai 1998).

As before, two types of gravitational wave tests for boson stars have been proposed: inspiral tests and ringdown tests. The first studies in the inspiral test class were those that considered extreme-mass-ratio inspirals of a small compact object into a supermassive boson star. Kesden et al. (2005) showed that stable circular orbits exist both outside and inside the surface of the boson star, provided the small compact object interacts with the background only gravitationally. This is because the effective potential for geodesic motion in such a boson-star background lacks the Schwarzschild-like singular behavior at small radius, instead turning over and allowing for a new minimum. Gravitational waves emitted in such a system would then stably continue beyond what one would expect if the background had been a supermassive black hole; in the latter case the small compact object would simply disappear into the horizon. Kesden et al. (2005) found that orbits inside the boson star exhibit strong precession, exciting high frequency harmonics in the waveform, and thus allowing one to easily distinguish between such boson stars from black-hole backgrounds. Kesden et al. (2005) neglected accretion and dynamical friction, and these effects are expected to be larger than those of radiation reaction inside the boson star (Macedo et al. 2013b). Palenzuela, Bezares and their collaborators derived gravitational waves from binary boson star mergers for compact solitonic boson stars (Palenzuela et al. 2017) and dark boson stars (Bezares and Palenzuela 2018). Siemonsen and East (2023) carried out boson star merger simulations and studied the properties of the remnant. They showed, for the first time, that a remnant rotating boson star can form from a merger of two boson stars. Destounis et al. (2023) studied non-integrability, chaos and resonances for extreme-mass-ratio inspirals into rotating boson stars.

The late inspiral, merger and ringdown of boson stars is also quite different from that of regular compact objects. and Maselli et al. (2016a), Cardoso et al. (2017) suggested that one could use the effect of tidal deformability on the gravitational waves to non-Kerr features of spacetime and to distinguish between boson stars and black holes or neutron stars. Tidal effects modify the orbital dynamics, thus imprinting onto the emitted gravitational waves, once the binary components are close enough together that they deform each other and change the gravitational potential. A class of massive boson stars has a minimum tidal deformability that can be much larger than the typical deformability of neutron stars and black holes. Sennett et al. (2017) argued that aLIGO at design sensitivity could distinguish between such massive boson stars and neutron stars or black holes provided an inspiral of a binary of sufficiently large mass or large mass ratio is observed. Moreover, a few studies have found that the merger of boson stars leads to a spinning bar configuration that either fragments or collapses into a Kerr black hole (Palenzuela et al. 2007, 2008). Pacilio et al. (2020) constructed gravitational waveforms from binary boson star inspirals by including both quadrupole moment and tidal deformability, which was used in Vaglio et al. (2023) for a Bayesian parameter estimation study. Of course, the gravitational waves emitted during such a merger, and the subsequent ringdown will be drastically different from those produced when black holes merge. Indeed, Berti and Cardoso (2006) calculated the

quasi-normal mode spectrum of boson stars and found that it is different from that of a Kerr black hole ; see also [Macedo et al. \(2013a\)](#) for a more detailed analysis.

Another exotic compact object that has been considered in the past are gravastars (see e.g. [Mottola 2023](#) for a review). Gravitational vacuum stars, or gravastars for short, are compact objects that consist of a Schwarzschild exterior and a de Sitter interior, separated by an infinitely thin shell with finite tension and anisotropic pressure ([Mazur and Mottola 2023](#); [Chapline et al. 2003](#); [Cattoen et al. 2005](#)). The Lagrangian density for a gravastar is simply the Einstein–Hilbert action, but with a suitable stress-energy tensor that allow for a phase transition at or near where the Schwarzschild event horizon would have been. [Mazur and Mottola \(2023\)](#) and later [Visser and Wiltshire \(2004\)](#) were able to construct appropriate stress-energy tensors such that the resulting object was thermodynamically and dynamically stable (see also [Chirenti and Rezzolla 2007](#)), given a physically reasonable equation of state for the matter degrees of freedom. The current motivation for the gravastar picture comes from attempting to resolve the information loss problem, for example through quantum phase transitions ([Chapline et al. 2003](#)).

As in the boson star case, the gravastar picture can also be tested with gravitational waves emitted in their inspiral and merger. [Pani et al. \(2009\)](#), [Pani et al. \(2010b\)](#) calculated the gravitational waves emitted by a small compact object in a quasi-circular orbit around a supermassive gravastar, using a radiative-adiabatic waveform generation model ([Poisson 1993](#); [Hughes 2000, 2001](#); [Yunes et al. 2010a, 2011a](#); [Yunes 2009](#)), instead of the kludge scheme used by [Barack and Cutler \(2004\)](#), [Babak et al. \(2007\)](#), [Yunes \(2009\)](#). They concluded that the waves emitted during such inspirals are sufficiently different that they could be used to discern between a Kerr black hole and a gravastar. The quasinormal ringdown of gravastars has also been found to be drastically different from that of Kerr black holes, opening the possibility of using such waves for a test of their existence ([Chirenti and Rezzolla 2007](#); [Pani et al. 2009](#)). Such quasinormal modes of gravastars were tested against the GW150914 event by [Chirenti and Rezzolla \(2016\)](#), who concluded it was unlikely that the remnant of GW150914 was a gravastar.

Unfortunately, these exotic compact object alternatives typically encounter theoretical difficulties, for example due to instabilities in their stellar evolution or due to their own rotation. [Cardoso et al. \(2008a\)](#), [Cardoso et al. \(2008b\)](#) and [Pani et al. \(2010a\)](#) have pointed out that *all* horizonless compact objects with stable circular photon orbits, including boson stars and gravastars, are likely to be unstable to ergoregion instabilities if spinning rapidly, unless their surface is sufficiently absorbing ([Maggio et al. 2017](#)) (see [Chirenti and Rezzolla 2008](#); [Hod 2017](#); [Maggio et al. 2019](#); [Vicente et al. 2018](#); [Zhong et al. 2023](#) for related works on ergoregion instabilities). On top of these ergoregion instabilities, there are nonlinear trapping instabilities even for non-rotating horizonless compact objects ([Keir 2016](#); [Cardoso et al. 2014](#); [Cunha et al. 2017](#)). Moreover, the dynamical and non-linear stability of these objects in coalescence events is not clear. For example, in the case of an extreme mass-ratio inspiral into a supermassive boson star, the small compact object will accrete scalar field once it has entered the boson star’s surface, possibly forcing the boson star to collapse into a black hole. Linear stability

analysis of boson stars are not sufficient to prove that such objects are also non-linearly stable. Finally, horizonless objects typically encounter observational difficulties when considering accreting systems. Broderick and Narayan (2007) have argued that the heating of gravastars due to accretion should be enough to stringently constrain them observationally.

What is worse, for entire classes of exotic compact objects the scenarios discussed above cannot be even considered because of a lack of a definite Lagrangian density from which to derive their dynamics. For example, the gravastar model is sometimes referred to as a “cut-and-paste” spacetime, in that the interior de Sitter metric is glued to an exterior BH metric through a boundary layer of exotic matter. To date, nobody has yet shown that such objects arise naturally in dynamical gravitational collapse in a given theory of gravity. Of course, nobody has studied either how such objects would behave dynamically and what the associated gravitational waves would look like in the highly non-linear regime of merger (special cases of boson stars being the only exception). Efforts have been made to consider such exotic objects as “straw-men” to rule out using gravitational wave data. However, the use of such pathological objects as an even “in-principle” caveat to the evidence of black holes in gravitational wave data is questionable (Yunes et al. 2016).

When a merger remnant is a horizonless exotic compact object, gravitational waves can get trapped between the potential barrier and the surface, reflecting back and forth many times and producing gravitational-wave echoes (Cardoso et al. 2016a; Cardoso and Pani 2017; Cardoso et al. 2016b). Abedi et al. (2017) analyzed the data for GW150914, GW151226 and LVT151012 (now GW151012) and found some evidence for the presence of echoes in the data at a false alarm rate of 1% (corresponding to a 2.5σ detection). This analysis was later challenged by Ashton et al. (2016), Westerweck et al. (2021) and Nielsen et al. (2019), who reanalyzed the data and did not find such evidence for the echoes. Other groups conducted independent analyses and also found no significant evidence of echoes (Lo et al. 2019; Uchikata et al. 2019; Wang and Piao 2020). On the other hand, Abedi and Afshordi (2019) further claimed to find tentative evidence of echoes with GW170817 one second after the merger at a 4.2σ confidence level and mentioned that the null results by other groups can be consistent with theirs if echoes contribute the most at lower frequencies and/or in binary mergers with more extreme mass ratio (Abedi and Afshordi 2020).

The LIGO/Virgo Collaboration also searched for echoes in signals of gravitational-wave events in GWTC-2 (Abbott et al. 2021b) and GWTC-3 (Abbott et al. 2021c). For GWTC-2, the collaboration used a template-based search (Lo et al. 2019), using the model described in Abedi et al. (2017). The waveform model takes and repeats the modified ringdown portion of the IMRPhenomPv2 waveform with 5 additional parameters: the relative amplitude of the echoes, the damping factor between each echo, the start time of ringdown, the time of the first echo with respect to the merger, and the time delay between each echo. The collaboration computed the Bayes factor comparing the hypotheses with and without echoes and found no statistically significant evidence of echoes. For GWTC-3, they carried out a morphology-independent approach (Tsang et al. 2018, 2020) via BayesWave

(Cornish and Littenberg 2015; Littenberg and Cornish 2015) that uses sine Gaussians as basis functions for modeling gravitational waves. Once again, the features of echoes are captured by introducing 5 extra parameters. The Collaboration estimated the *p*-value for the log Bayes factors between hypotheses for signal versus noise and found that the measurement is consistent with no echoes within 90% credibility.

5 Results of gravitational-wave tests with pulsar-timing data

Due to the nature of pulsar timing experiments, PTAs offer advantages over interferometers for detecting new polarizations or constraining the polarization content of GWs. For instance, each line of sight to a pulsar can be used to construct an independent projection of the various GW polarizations, and since PTAs typically observe tens of pulsars, linear combinations of the data can be formed to measure or constrain each of the six polarization modes many times over. A number of analyses of pulsar timing data have been performed searching for evidence of additional polarization modes which arise in modified theories of gravity. Additionally, PTAs have an enhanced response to the longitudinal polarization modes (Chamberlin and Siemens 2012; Cornish et al. 2018; O’Beirne et al. 2019). Indeed, the constraint on the energy density of longitudinal modes inferred from recent NANOGrav data is about three orders of magnitude better than the constraint for the transverse modes (Cornish et al. 2018). Robust searches for evidence of modified gravity via non-Einsteinian modes are complex and, to illustrate this, it is worth summarizing some of the work here.

To date the most comprehensive searches for non-Einsteinian polarization modes in pulsar timing data have been performed by the NANOGrav collaboration on their 12.5-year data set (Arzoumanian et al. 2021) as well as using PPTA DR2 data (Wu et al. 2022). We summarize the NANOGrav results here. In Arzoumanian et al. (2021), the data were analyzed with a suite of Bayesian and frequentist techniques assuming that the observed stochastic common red noise process found in Arzoumanian et al. (2020) is due to various combinations of the possible modes that can exist in metric theories of gravity. Interestingly, NANOGrav found a monopolar correlation signature which was the origin of some claims of detection of the scalar-transverse (ST) modes in the NANOGrav 12.5-year data set (Chen et al. 2021), favored with a Bayesian odds ratio of about 100 to 1 (these authors also analyzed the IPTA Second Data release finding a Bayesian odds ratio in favor of scalar transverse modes of about 30:1, see Chen et al. 2022). On theoretical grounds, we expect the presence of ST correlations to be accompanied by the standard quadrupolar +- and \times -modes of General Relativity: metric theories of gravity have at least the +- and \times -modes and possibly additional modes.

A detailed analysis of the NANOGrav 12.5-year data set revealed that the significance of non-quadrupolar correlations is reduced significantly (the Bayes factor drops to about 20) when one of the pulsars, J0030+0451, is excluded from the analyses. This pulsar has a history of being problematic in detection searches (Hazboun et al. 2020), and the results point to the possibility of noise modeling

issues involving this MSP. The apparent albeit weak presence of non-Einsteinian modes of gravity is likely unphysical. Having found no statistically significant evidence in favor of any correlations, NANOGrav placed upper limits on the amplitudes of all possible subsets of polarization modes of gravity predicted by metric spacetime theories.

More recently (Agazie et al. 2024), the NANOGrav 15-yr data were searched for evidence of a gravitational-wave background with quadrupolar (HD) and ST correlations, finding that HD correlations are the best fit to the data and no significant evidence in favor of ST correlations. We discuss the details of this work below.

5.1 Details of the analyses of the NANOGrav 12.5-yr dataset

Here we discuss some of the detailed results of the NANOGrav 12.5-yr dataset search for additional polarization modes (Arzoumanian et al. 2021). We begin by summarizing the naming convention used for the various models in their analyses.

The two general types of Bayesian models used in this paper are referred to as *M2A* and *M3A* which were also used in Arzoumanian et al. (2020). The M2A model includes various white noise terms for each pulsar, an intrinsic red noise term for each pulsar, and an uncorrelated so-called common red noise process, which has the same spectral index and amplitude across all pulsars. The M2A model does not include correlations between pulsars so its full PTA covariance matrix is block-diagonal. The M3A models include identical noise processes as M2A, with the common red noise process correlated across pulsars. Therefore, for the M3A models the full PTA covariance matrix has non-vanishing off-diagonal components. If the spectral index of the common process is fixed, it is given in square brackets after either M2A or M3A; and for M3A models, the type of correlations are given in square brackets before M3A. For example, [HD]M3A[13/3] refers to a model where the common process has Hellings–Downs (quadrupolar correlations) with a spectral index of 13/3. When more than one type of common correlated red noise process is included, it is indicated by more than one type of correlation in the square bracket preceding the term “M3A” and additional spectral indices. For instance, [HD,ST]M3A[13/3,5] means that the M3A contains two different correlated common signals: a red noise process with spectral index of 13/3 and quadrupolar Hellings–Downs correlations, and second red noise process with spectral index of 5 with scalar-transverse correlations.

NANOGrav calculated the results of several different Bayesian analyses shown in Fig. 8 (Arzoumanian et al. 2021). The model with the highest odds is a GWB with GW-like monopolar correlations (where the correlations between pulsars are not angular separation dependent and fixed to 1/2, to be compared with a clock-error monopole where the correlations between pulsars are unity). The odds of [GW-like Monopole]M3A[5] are greater than 100 compared with a model with no correlations and the same spectral index M2A[5]. NANOGrav was also able to reproduce the results of Chen et al. (2021), where [ST]M3A[5] was compared to a model without correlations and a spectral index of 13/3, M2A[13/3] finding odds of around 94:1 in favor of [ST]M3A[5], which is consistent with the results in Chen et al. (2021). This

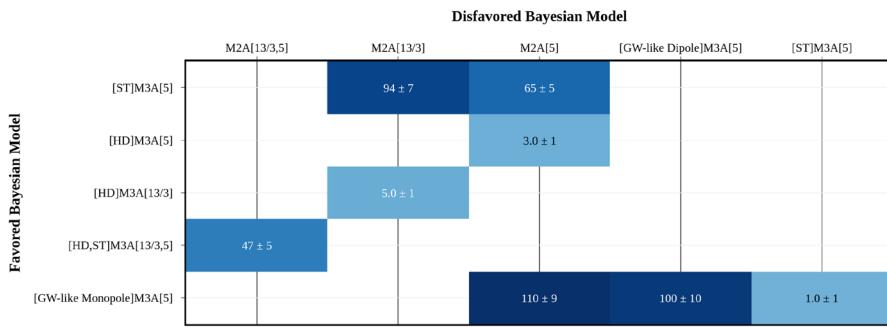


Fig. 8 The table shows the odds ratios for comparisons of various models. Darker shades of blue correspond to higher odds ratios. The model with the highest odds is the GW-like monopole, where the correlations between pulsars are not angular separation dependent and fixed to 1/2 (to be compared with a clock-error monopole where the correlations between pulsars are unity). Image reproduced with permission from Arzoumanian et al. (2021), copyright by the author(s)

results in part due to the difference in spectral index between the two models (the NANOGrav 12.5-yr dataset prefer a steeper spectral index), and a degeneracy between ST and HD correlations at low S/N. Finally, as we have mentioned, the result is very sensitive to the inclusion of one MSP, J0030+0451, which indicates a problem with noise modeling for that pulsar. NANOGrav also examined the problem using the frequentist optimal statistic and found consistent results.

From a theoretical perspective, some models shown in Fig. 8 are not viable. Metric theories of gravity always contain the two Einsteinian $+$ - and \times -modes so that even when a model with ST-only correlations is found to have high odds, this model does not correspond to a metric theory of gravity. However, models with multiple spatial correlations that include the TT modes, such as [HD,ST]M3A[13/3,5] are theoretically viable.

Having found no compelling evidence for gravitational waves, NANOGrav proceeded to present upper limits on all possible polarization content in metric theories of gravity. The naming convention they introduced for this model classification is the letters MG (an abbreviation for metric theory of gravity), followed by 4 digits which can be unity or zero depending on which polarization modes (TT, ST, VL, SL) are present in any particular theory. For example, MG1000 is a metric theory of gravity with only the TT modes present, i.e. Einstein gravity; MG1100 is a theory with TT and ST modes, e.g., Jordan–Fierz–Brans–Dicke gravity, etc. In this classification there are only 8 families of metric theories of gravity, since the TT mode is present in all metric theories of gravity.

The results for the upper limits are shown in Fig. 9. It is worth noting the higher sensitivity of pulsar timing arrays to the longitudinal polarizations, VL and SL. This results in upper limits that are about an order of magnitude smaller for VL modes and about two orders of magnitude smaller for the SL mode compared with the TT mode. These upper limits are theory agnostic, and can be used to constrain the parameters of metric theories of gravity that couple to these modes.

	TT	ST	VL	SL
MG1111	$(1.1 \pm 0.06) \times 10^{-15}$	$(1.2 \pm 0.07) \times 10^{-15}$	$(2.2 \pm 0.1) \times 10^{-16}$	$(2.5 \pm 0.1) \times 10^{-17}$
MG1011	$(1.2 \pm 0.05) \times 10^{-15}$		$(2.6 \pm 0.09) \times 10^{-16}$	$(2.5 \pm 0.2) \times 10^{-17}$
MG1101	$(1.2 \pm 0.04) \times 10^{-15}$	$(1.1 \pm 0.05) \times 10^{-15}$		$(2.6 \pm 0.2) \times 10^{-17}$
MG1110	$(1.1 \pm 0.06) \times 10^{-15}$	$(1.1 \pm 0.05) \times 10^{-15}$	$(2.7 \pm 0.1) \times 10^{-16}$	
MG1001	$(1.3 \pm 0.05) \times 10^{-15}$			$(2.9 \pm 0.2) \times 10^{-17}$
MG1010	$(1.2 \pm 0.09) \times 10^{-15}$		$(2.7 \pm 0.1) \times 10^{-16}$	
MG1100	$(1.2 \pm 0.06) \times 10^{-15}$	$(1.2 \pm 0.07) \times 10^{-15}$		
MG1000	$(1.4 \pm 0.04) \times 10^{-15}$			

Fig. 9 95% upper limits on the amplitude of GWs for the eight families of metric theories of gravity. For simplicity, the spectral index for gravitational waves was fixed at $\gamma = 5$, which corresponds to a flat spectrum in Ω_{GW} , the ratio of the energy density in GWs to the critical density. Image reproduced with permission from Arzoumanian et al. (2021), copyright by the author(s)

5.2 Details of the searches in the NANOGrav 15-yr dataset

NANOGrav also recently searched their 15-year data set for evidence of a gravitational wave background with all possible transverse modes: HD and ST correlations (Agazie et al. 2024) (see left panel of Fig. 10). This analysis was restricted to the transverse modes because their overlap reduction functions have no frequency dependence and are more simple to model. Analyses that include the remaining 3 modes (SL and VL), with frequency dependent overlap reduction functions, are underway.

The right panel of Fig. 10 shows the odds ratios for a series of Bayesian runs on NANOGrav's 15-yr dataset. The base model is a stochastic common uncorrelated red noise process (CURN), i.e., a stochastic process that has the same amplitude and spectral index for all pulsars but no correlations among the different pulsars. The HD model, which is the prediction of General Relativity, has odds of $\sim 200:1$

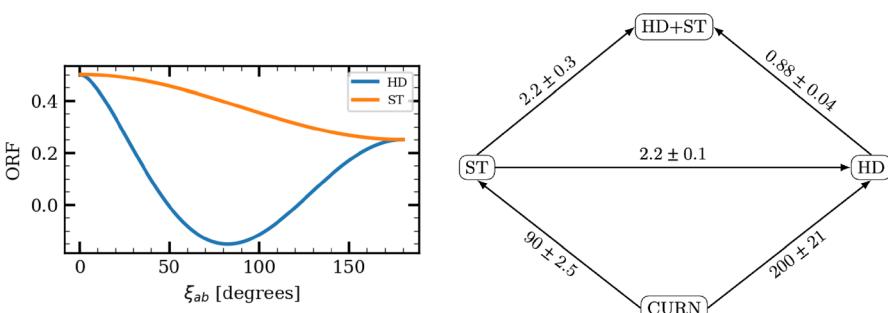


Fig. 10 *Left panel:* Plot of the correlation signatures for the transverse modes as a function of angular separation. The blue curve shows the Hellings and Downs curve, and the orange curve shows the correlations produced by ST gravitational waves. These two types of correlations were searched for in NANOGrav's analysis of the 15-yr dataset in separate and combined analyses with Bayesian and frequentist techniques. *Right panel:* Odds ratios for HD and ST models and HD+ST models compared to one another along with a common uncorrelated red noise model (CURN). See the main text for details. Images reproduced with permission from Agazie et al. (2024), copyright by the author(s)

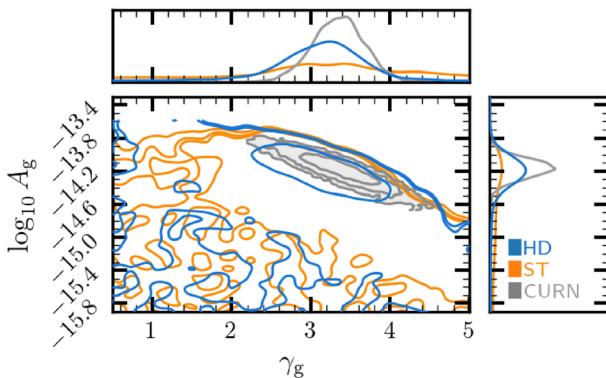


Fig. 11 Plot of the posteriors for the amplitudes (A_g) and spectral indices (γ_g) for HD (blue) and ST (orange) from the combined HD+ST model and the CURN model (grey) (the models at the top and bottom of the right panel of Fig. 10). Image reproduced with permission from Agazie et al. (2024), copyright by the author(s)

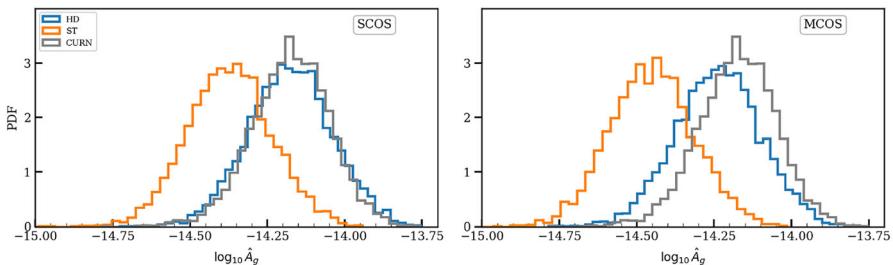


Fig. 12 The left panel shows the recovered amplitudes from single-component noise marginalized optimal statistic (SCOS), where the HD (blue) and ST (orange) correlations are searched for separately, and the right panel shows the recovered amplitudes for the multi-component noise marginalized optimal statistic (MCOS) (right) where the HD and ST correlations are fit for simultaneously. The CURN (gray) is also shown to determine the consistency of the amplitude recovery of HD and ST with the common red noise process. Images reproduced with permission from Agazie et al. (2024), copyright by the author(s)

relative to the CURN model, and the ST model odds are $\sim 90:1$. Interestingly, the odds ratios of standard Bayesian analyses of the data did not show a strong preference for either correlation signature, with odds ratios ~ 2 in favor of HD versus ST correlations, and ~ 1 for HD plus ST correlations versus HD correlations alone, and further analyses were required to establish that HD correlations are indeed the best fit to the data, with no significant evidence in favor of ST correlations.

Looking at the posteriors for the amplitudes and spectral indices of the HD and ST modes when searched for simultaneously, NANOGrav found that the posteriors for the amplitude and spectral index of ST correlations are uninformative, with the HD stochastic process accounting for the majority of the correlated signal. This is shown in Fig. 11 where we plot the posteriors for the amplitudes and spectral

indices for the HD and ST stochastic processes as recovered from a combined HD+ST model as well as the CURN model. These two models correspond to the top and bottom of the right panel of Fig. 10. The amplitude and spectral index recovery for ST is poor when modeled alongside HD. The posterior distribution for ST is uninformative and HD adequately describes the total signal as recovered by CURN.

In addition, using the optimal statistic, a frequentist detection technique that uses only the correlation information (Anholm et al. 2009; Chamberlin et al. 2015; Vigeland et al. 2018; Sardesai et al. 2023), NANOGrav found results consistent with the Bayesian analyses, i.e., similar signal-to-noise-ratios for each of the correlation, but inconsistent parameter estimation recovery for ST. Figure 12 shows the optimal statistic amplitude recovery for the HD and ST amplitudes when searched for separately (right panel) and jointly (left panel), compared with the CURN model, and in both cases the HD amplitude is significantly more consistent with the CURN process than ST.

6 Musings about the future

Gravitational waves hold the key to testing Einstein's theory of general relativity (GR) to new exciting levels in the previously unexplored extreme gravity regime. Depending on the type of wave that is detected, e.g., compact binary inspirals, mergers, ringdowns, continuous sources, supernovae, etc, different tests will be possible. Irrespective of the type of wave detected, two research trends seem currently to be arising: direct tests and generic tests. These trends aim at answering different questions. With direct tests, one wishes to determine whether a certain modified theory is consistent with the data. Generic tests, on the other hand, ask whether the data is statistically consistent with our canonical beliefs, or put another way, whether there are any statistically-significant deviations present in the data. The approaches, however, are interconnected because once a generic test has established that no statistically significant deviations from GR are present in the data, then this information can be recast to draw inferences from the data on constraints on specific GR deviations.

Gravitational waves have now been detected with ground-based detectors, opening up an entire new area in experimental relativity. Many concrete efforts are currently underway to develop and extend formalisms and implementation pipelines to test Einstein's theory in extreme gravity. Currently, the research groups separate into two classes: theory and implementation. The theory part of the research load is being carried out at a variety of institutions without a given focal point. The implementation part is being done mostly within the LIGO Scientific Collaboration, the Virgo Scientific collaboration, the KAGRA Scientific Collaboration, and the pulsar timing consortia. Cross-communication between the theory and implementation groups has been flourishing in recent years and one expects the interdisciplinary work to continue and expand in the future.

So many accomplishments have been made in the past 50 years that it is almost impossible to list them all here. From the implementation side, perhaps one of the

most important is the actual construction and operation of the initial and advanced ground-based instruments that have given us the first gravitational wave observations. This is a tremendously important engineering and physics accomplishment. Similarly, the construction of impressive pulsar timing arrays, and the timing of these pulses to nanosecond precision is an instrumental and data analysis feat to be admired. Without these observatories, there would be no gravitational wave physics, and of course, no tests of Einstein's theory in extreme gravity. On the theory side, perhaps the most important accomplishment has been the understanding of the inspiral phase to extremely high post-Newtonian order and the merger phase with numerical simulations. The latter, in particular, had been an unsolved problem for over 50 years. It is these accomplishments that then allow us to postulate modified inspiral template families and study mergers in modified gravity, since we understand what the GR model is. This is particularly true if one is considering small deformations away from Einstein's theory, as it would be impossible to perturb about an unknown solution.

The main questions that are currently at the forefront are the following. On the theory side of things, one would wish to understand the inspiral, merger and ringdown in extreme gravity modifications to GR. We have here discussed only a few of them, such as dynamical Chern–Simons gravity, Einstein–dilaton–Gauss–Bonnet theory and theories with preferred frames, such as Einstein–Aether theory or Hořava–Lifshitz gravity. The first step in this direction is to develop higher post-Newtonian order models for the inspiral phase. Such a task, of course, is very difficult, given that the complexity of the calculation in GR alone is already daunting. Simultaneously, the second step is to numerically simulate the merger in modified gravity theories. This task is also very difficult because the characteristic structure of the evolution equations in modified gravity is likely different from that in GR, sometimes requires a reformulation of the standard evolution methods. Once these two steps are complete, one then needs to construct an inspiral–merger–ringdown model that smoothly connects these two phases of coalescence. This, in turn, requires many numerical simulations of modified gravity mergers to properly sample the parameter space, a task that is still not complete today in GR.

On the implementation side of things, there is also much work that remains to be done. Currently, efforts are ongoing on the implementation and improvement of Bayesian frameworks for hypothesis testing, one of the most promising approaches to testing Einstein's theory with gravitational waves. Present studies on future prospects concentrate mostly on single-detectors, but by the beginning of the next decade we expect four or five detectors to be online, and thus, one will have to extend these implementations. The use of multiple detectors also opens the door to the extraction of new information, such as multiple polarization modes, a precise location of the source in the sky, etc. Moreover, the evidence for a given model increases dramatically if the event is observed in several detectors. One therefore expects that the strongest tests of GR will come from leveraging the data from all detectors in a multiply-coincident event, perhaps also including information from electromagnetic counterparts.

Research is moving toward the construction of robust techniques to test Einstein's theory, and in particular, testing the general principles that serve as

foundations of GR. This allows one to answer general questions, such as: Does the graviton have a mass? Are compact objects represented by the Kerr metric and the no-hair theorems satisfied? Does the propagating metric perturbation possess only two transverse-traceless polarization modes? What is the rate of change of a binary's binding energy? Do naked singularities exist in nature and are orbits chaotic? Is Lorentz-violation present in the propagation of gravitons? The more questions of this type that are generated and the more robust the methods to answer them are, the more stringent the test of Einstein's theories and the more information we will obtain about the gravitational interaction in a previously unexplored regime.

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