

Axially symmetric McMillan map & Round beams

The most general map can be reduced to the form

$$r' = \sqrt{p_r^2 + \frac{p_\theta^2}{r^2}}, \quad \theta' = \theta + \arctan \frac{p_\theta}{p_r r},$$

$$p_r' = -p_r \frac{r}{r'} + \frac{a r'}{1 + \text{sgn}[\Gamma] r'^2}, \quad p_\theta' = p_\theta,$$

with two independent invariants

$$\mathcal{K}_r[p_r, r] = \underbrace{p_r^2 - a p_r r + r^2}_{\propto \text{Courant-Snyder}} + \underbrace{\text{sgn}(\Gamma) p_r^2 r^2}_{\text{nonlinearity}} + \underbrace{\frac{p_\theta^2}{r^2}}_{\text{rotation}}, \quad \mathcal{K}_\theta[p_\theta, \theta] = p_\theta,$$

and one intrinsic parameter equal to unperturbed betatron tune

$$\nu_0 = \frac{\Phi}{2\pi} = \frac{1}{2\pi} \arccos \frac{a}{2}.$$

Considering general axially symmetric lattice with thin nonlinear kick $\delta\hat{R}$, we can rewrite the map as

$$r' = \sqrt{p_r^2 + \frac{p_\theta^2}{r^2}}, \quad \theta' = \theta + \arctan \frac{p_\theta}{r p_r},$$

$$p_r' = -p_r \frac{r}{r'} + \delta\hat{r}(r'), \quad p_\theta' = p_\theta,$$

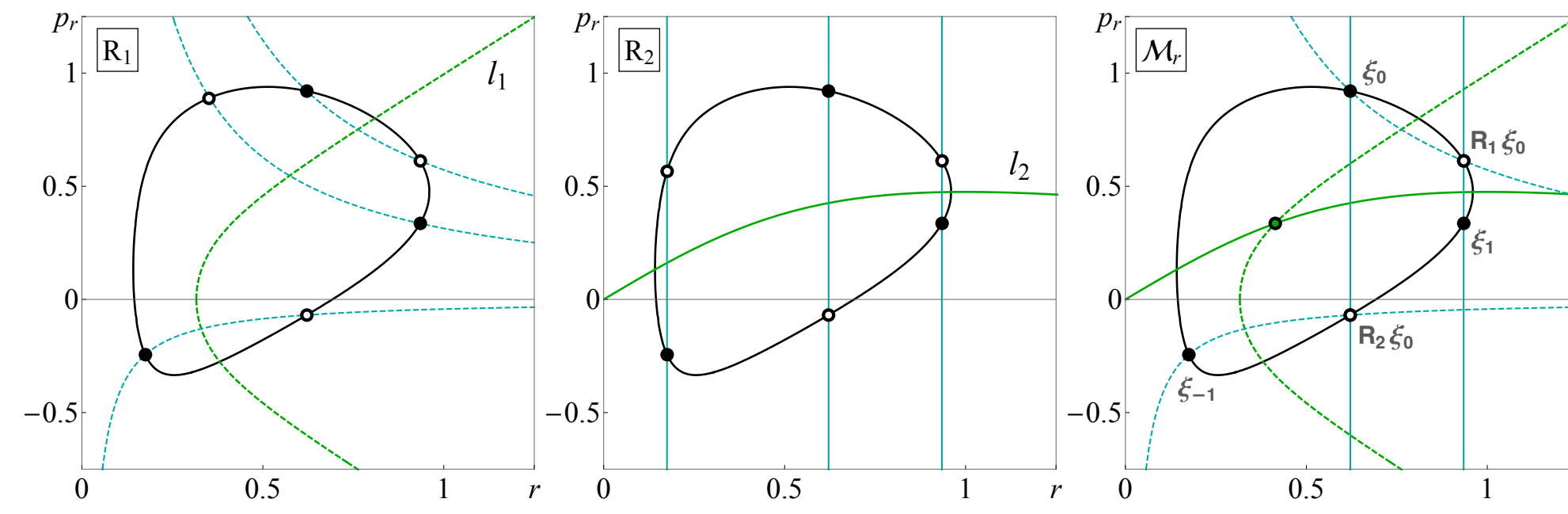
where $\delta\hat{r}(r) = 2r \cos \Phi + \beta \delta\hat{R}(r) \sin \Phi$. It has one exact, $\mathcal{K}_\theta = p_\theta$, and one approximated invariant in McMillan form

$$\mathcal{K}_r[p_r, r] \approx \text{C.S.}_r - \frac{c}{3!} \frac{p_r^2 r^2}{a} + \frac{p_\theta^2}{r^2},$$

where the parameters a and c are defined as

$$a = 2 \cos \Phi + \beta \sin \Phi \partial_r \delta\hat{R}(0) \quad \text{and} \quad c = \beta \sin \Phi \partial_{rrr} \delta\hat{R}(0).$$

Symmetry lines



The map and its inverse can be broken down into a composition of two nonlinear reflections, denoted by $R_{1,2}$

$$\mathcal{M}_r^\pm = R_2 \circ R_1, \quad (\mathcal{M}_r^\pm)^{-1} = R_1 \circ R_2,$$

where

$$R_1 : r' = \sqrt{p_r^2 + \frac{p_\theta^2}{r^2}}, \quad \text{and} \quad R_2 : r' = r,$$

$$p_r' = -p_r \frac{r}{r'}, \quad p_r' = -p_r + f(r).$$

Both transformations are anti-area preserving involutions

$$R_{1,2} = R_{1,2}^{-1}, \quad R_{1,2}^2 = I_2, \quad \det \mathbf{J}_{R_{1,2}} = -1,$$

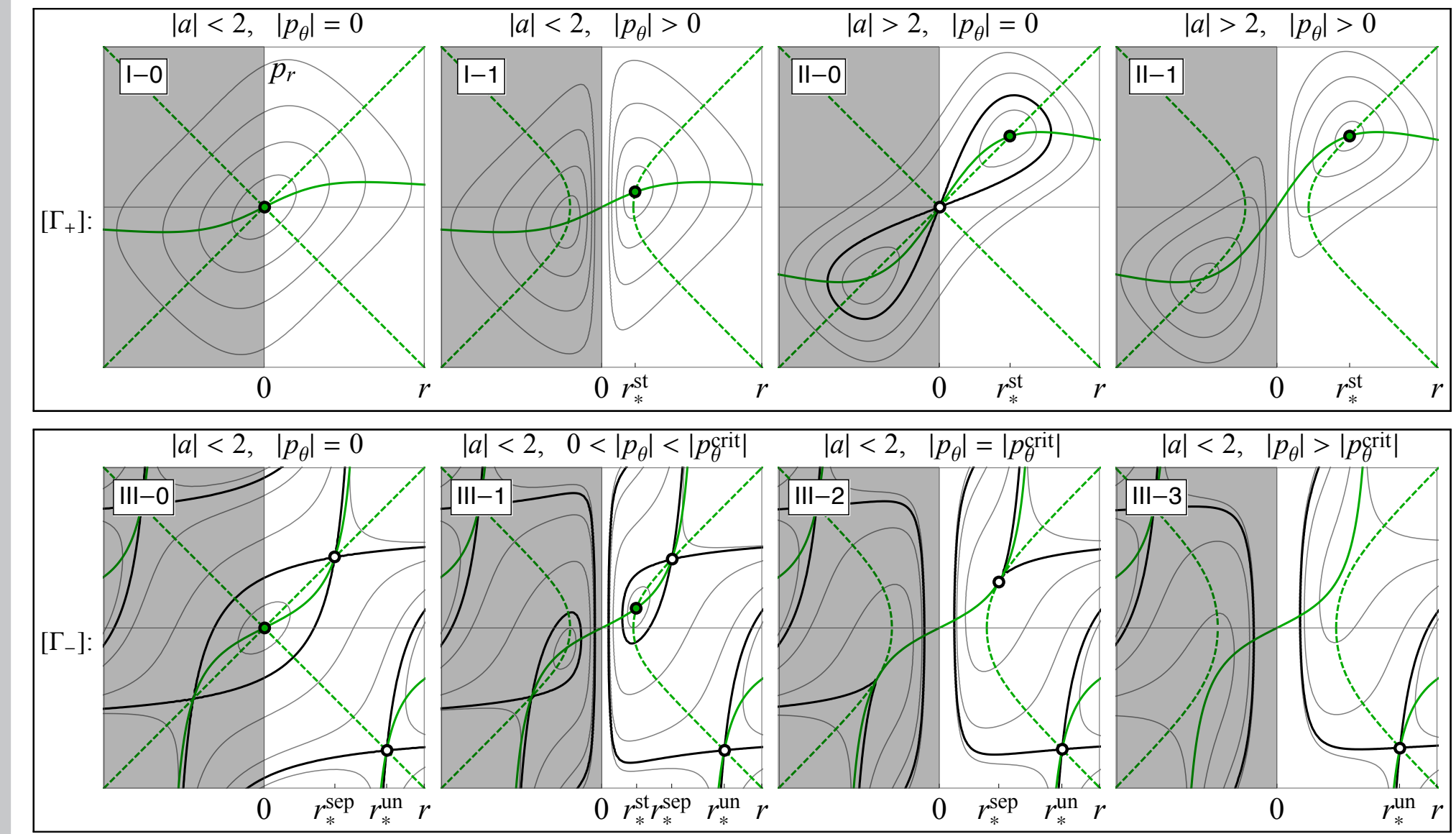
each (and in composition) preserving the radial invariant:

$$\mathcal{K}_r[p_r, r] - \mathcal{K}_r[R_{1,2}(p_r, r)] = 0.$$

Fixed points of $R_{1,2}$ form continuous lines of equilibrium solutions, the *first* and *second symmetry lines*, respectively:

$$l_1 : p_r^2 = r^2 - \frac{p_\theta^2}{r^2} \quad l_2 : p_r = \frac{f(r)}{2}.$$

Fixed points & Regimes of motion



- In the case $[\Gamma_+]$, map has only one positive root and motion is stable for any value of a and almost all values of angular momentum (except $p_\theta = 0$). Based on the absolute value of a we distinguish two different regimes: $|a| < 2$ [I] and $|a| > 2$ [II].
- In the case $[\Gamma_-]$, the motion is stable only for $|a| < 2$ and $|p_\theta| < p_\theta^{\text{crit}}$ [III]

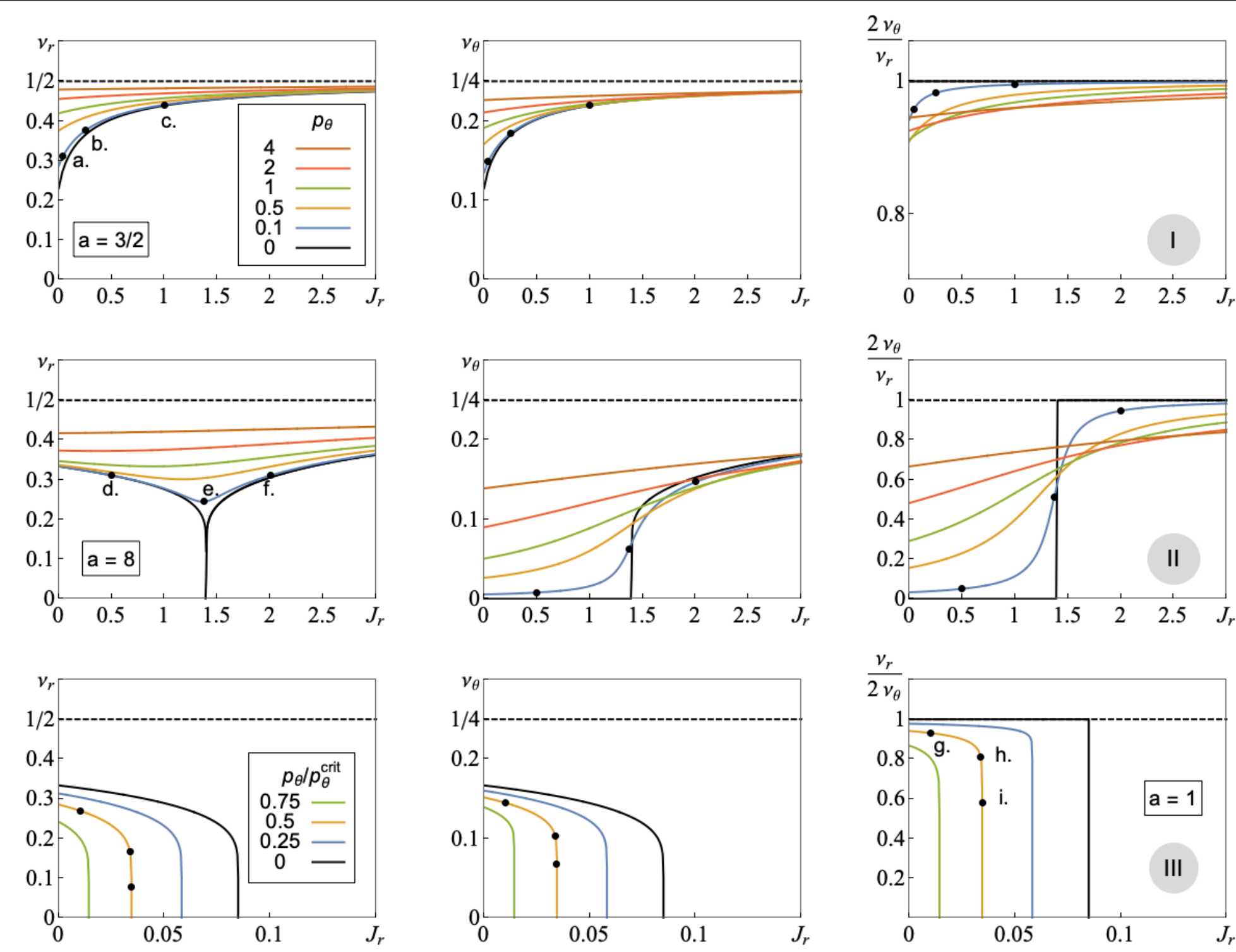
$$p_\theta^{\text{crit}} = \left[1 - (|a|/2)^{2/3}\right]^{3/2} < 1.$$

In this scenario the map has three stationary solutions:

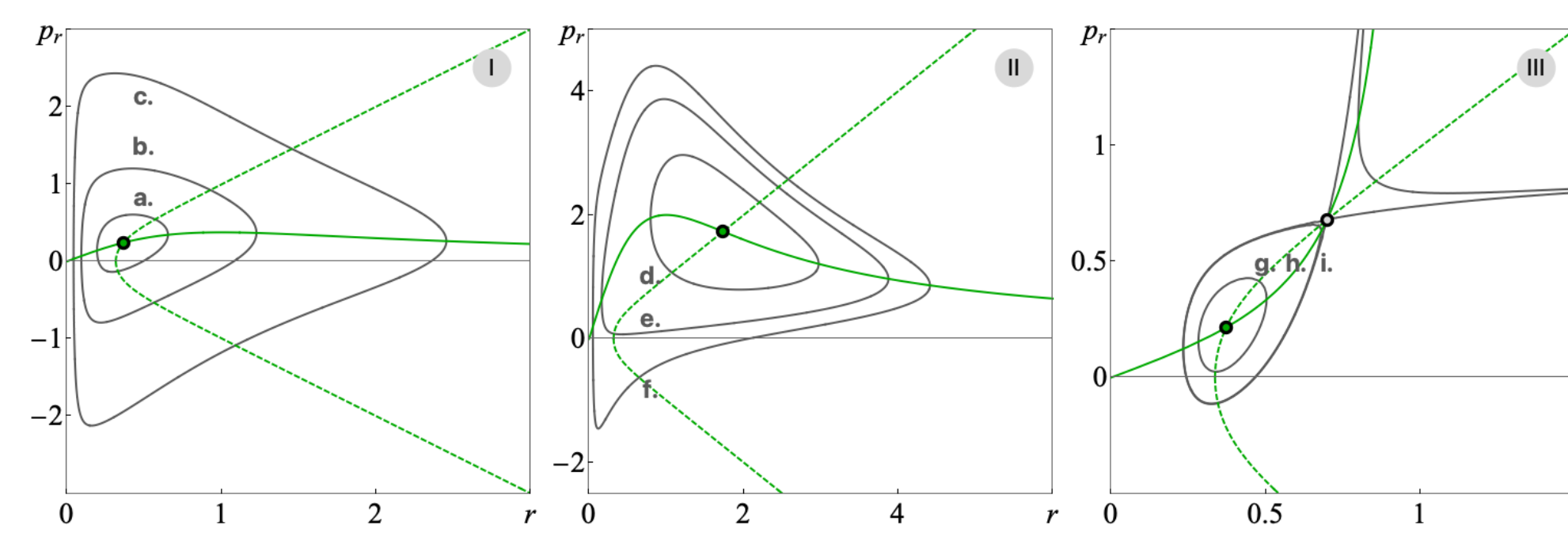
$$0 < r_*^{\text{st}} < r_*^{\text{sep}} < 1 < r_*^{\text{un}},$$

where r_*^{sep} is unstable fixed point with a separatrix isolating stable trajectories and r_*^{un} is the second unstable fixed point.

Action-angle variables



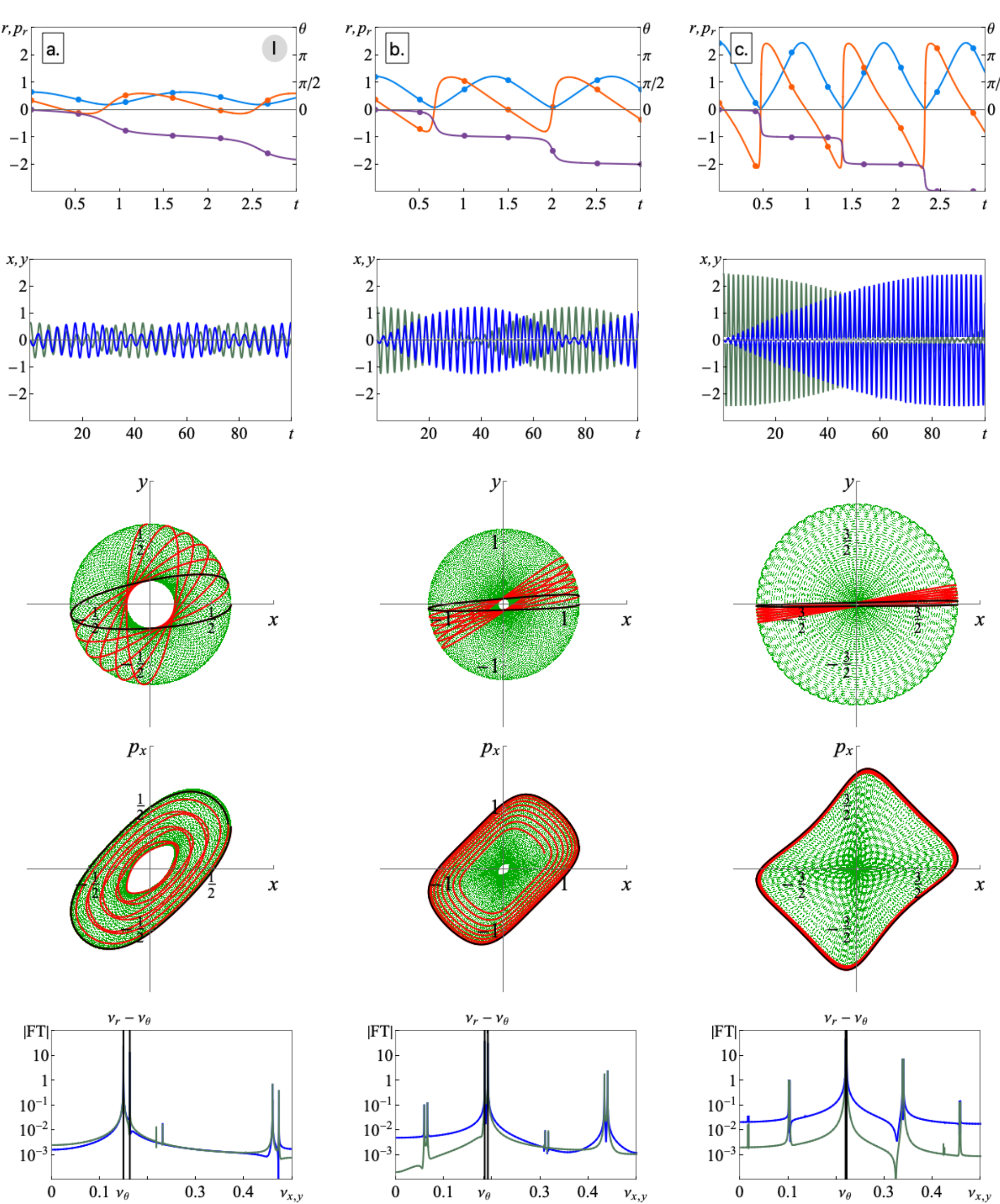
Case studies



Motion invariants \mathcal{K}_r and p_θ , action variables $J_{t,\theta}$ and rotation numbers $\nu_{r,\theta}$ for each case study:

	I $[\Gamma_+]$			II			III $[\Gamma_-]$		
	$a = 3/2, p_\theta = -0.1$			$a = 8, p_\theta = 0.1$			$a = 1, p_\theta = 0.5 p_\theta^{\text{crit}} = 0.1125$		
	(a.)	(b.)	(c.)	(d.)	(e.)	(f.)	(g.)	(h.)	(i.)
J_r	0.04	0.25	1	0.5	1.3695	2	0.01	0.033692	0.0344042
\mathcal{K}_r	0.28228	1.17187	5.54626	-5.54758	0	4.2368	0.217948	0.2746	0.275683
ν_r	0.310521	0.375294	0.440763	0.310913	0.244355	0.310346	0.269487	0.166497	0.0785715
ν_θ	0.148603	0.184318	0.219254	0.007675	0.062641	0.146941	0.144787	0.102572	0.0680104

Case I

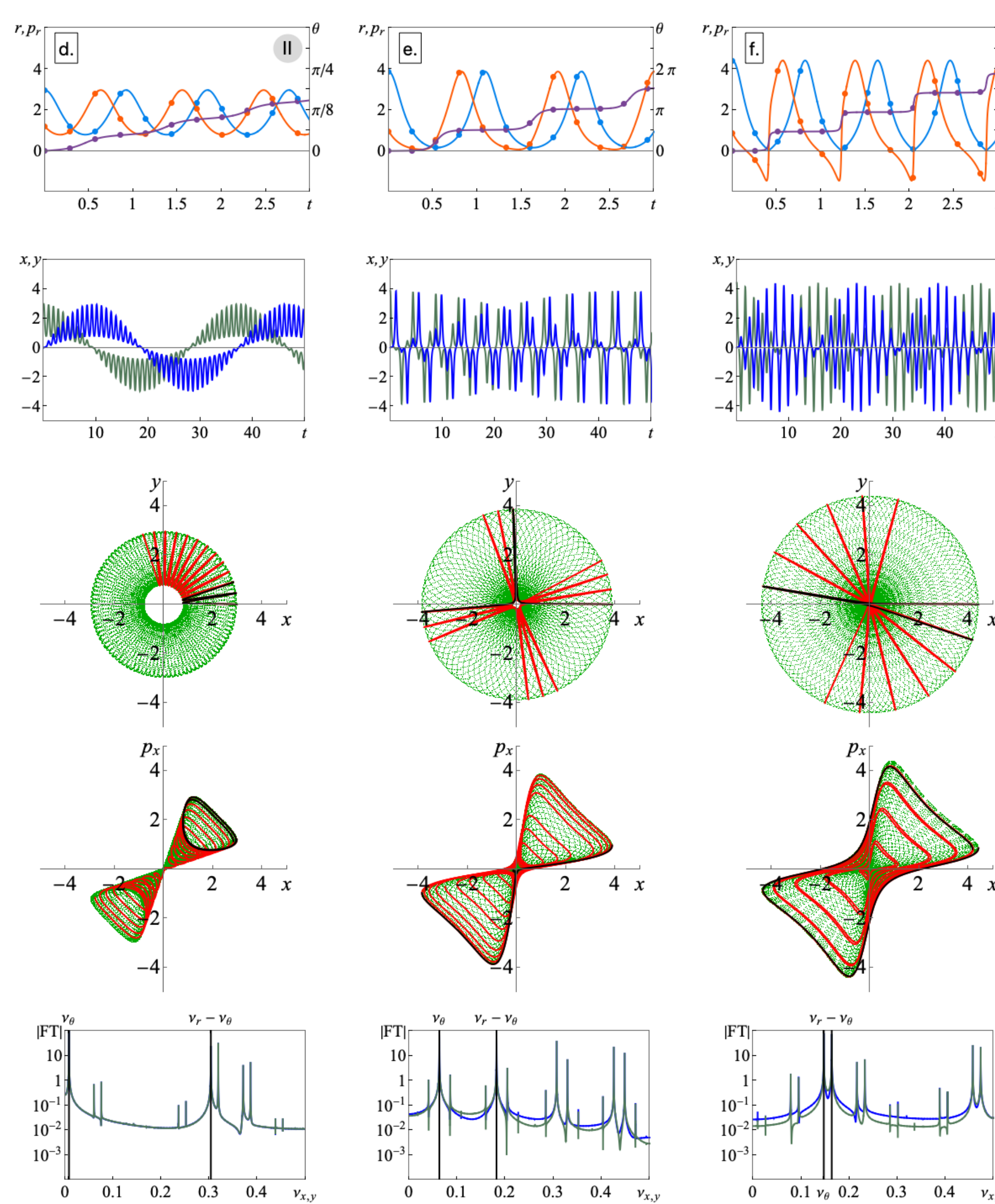


The presence of beats indicates that the sum and difference modes have nearly the same frequencies:

$$\nu_\Sigma \approx \nu_\Delta \quad (\text{or } \nu_r \approx 2\nu_\theta)$$

$$\nu_1 \approx \nu_{\Sigma,\Delta} \quad \text{and} \quad \nu_2 \approx 0$$

Case II

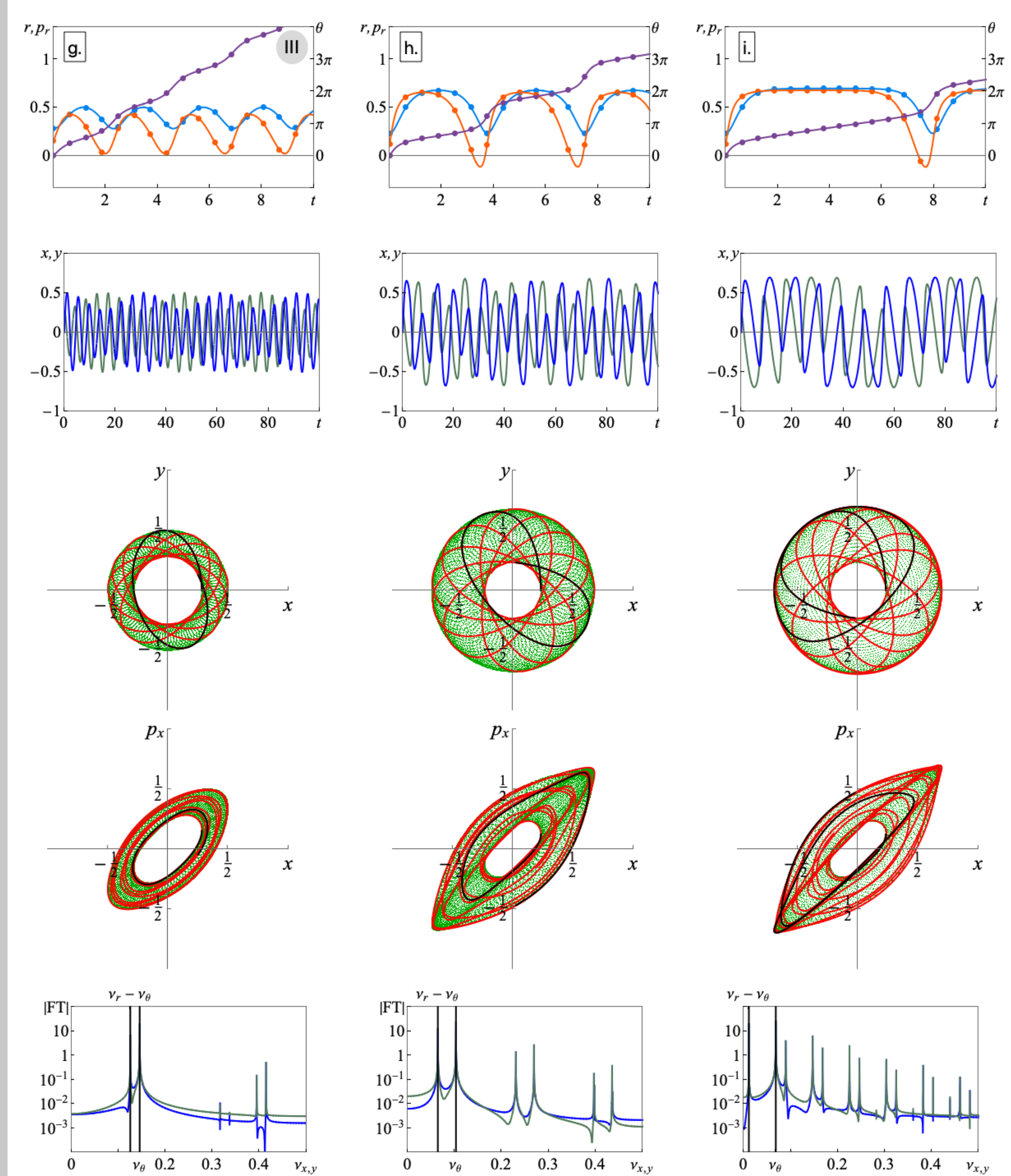


$$(d.) \quad \nu_\theta, \frac{\nu_\theta}{\nu_r} \approx 0 \quad \nu_\Sigma \gg \nu_\Delta \approx 0 \quad \nu_1 \approx \nu_2 \approx \nu_\Sigma/2$$

$$(e.) \quad 0 < \frac{\nu_\theta}{\nu_r} < \frac{1}{2} \quad \nu_\Sigma > \nu_\Delta \quad \nu_1 > \nu_2 \approx 0$$

$$(f.) \quad \frac{\nu_\theta}{\nu_r} \approx \frac{1}{2} \quad \nu_\Sigma \approx \nu_\Delta \quad (\nu_1 \approx \nu_{\Sigma,\Delta}) \gg (\nu_2 \approx 0)$$

Case III



$$(g.) \quad \frac{\nu_\theta}{\nu_r} \approx \frac{1}{2} \quad \nu_\Sigma \approx \nu_\Delta \quad (\nu_1 \approx \nu_{\Sigma,\Delta}) \gg (\nu_2 \approx 0)$$

$$(h.) \quad \frac{1}{2} < \frac{\nu_\theta}{\nu_r} < 1 \quad \nu_\Sigma > \nu_\Delta \quad \nu_1 > \nu_2 \approx 0$$

$$(i.) \quad \frac{\nu_\theta}{\nu_r} \approx 1 \quad \nu_\Sigma \gg \nu_\Delta \approx 0 \quad \nu_1 \approx \nu_2 \approx 0$$