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Optical Dromions for Spatiotemporal Fractional Nonlinear System in Quantum Mechanics

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Abstract: In physics, mathematics, and other disciplines, new integrable equations have been found using the *P*-test. Novel insights and discoveries in several domains have resulted from this. Whether a solution is oscillatory, decaying, or expanding exponentially can be observed by using the AEM approach. In this work, we examined the integrability of the triple nonlinear fractional Schrödinger equation (TNFSE) via the Painlevé test (*P*-test) and a number of optical solitary wave solutions such as bright dromions (solitons), hyperbolic, singular, periodic, domain wall, doubly periodic, trigonometric, dark singular, plane-wave solution, combined optical solitons, rational solutions, etc., via the auxiliary equation mapping (AEM) technique. In mathematical physics and in engineering sciences, this equation plays a very important role. Moreover, the graphical representation (3D, 2D, and contour) of the obtained optical solitary-wave solutions will facilitate the understanding of the physical phenomenon of this system. The computational work and conclusions indicate that the suggested approaches are efficient and productive.

Keywords: triple nonlinear fractional Schrödinger equation; quantum mechanics; Riemann–Liouville derivatives



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1. Introduction

Currently, researchers are paying close attention to fractional calculus and its implications [1–5]. Fractional differential equations have been used to analyse a wide range of fractal systems [6–8]. Nonlinear fractional partial derivative equations (FPDEs) have many uses in the nonlinear sciences, including for electromagnetic radiation, electrolytic polarisation, visco-elasticity, optical fibres, control theory, data processing, quantum mechanics, astrophysics, switches, as well as biogenetics [9–12]. It has been noticed that FPDEs play an important role in dealing with and modelling nonlinear equations with applications in complex analysis [13]. Due to their importance as complex mathematical tools for the analysis and modelling of many biological and physical phenomena, fractional operators of various types have been used in the natural and scientific fields. FPDEs are a generalization of integer-order time–space partial differential equations that provide a concise representation of nonlinear systems. The Caputo–Riemann terminology [14], Fabrizio–Caputo description [15], Atangana–Baleanu–Caputo concept [16], and Grunwald–Letnikov interpretation [17] are by far the most extensively used fractional operator definitions. The major applications of these soliton solutions are in optics and photonics, including in the production of ultrafast laser pulses and the development of optical instruments for particle manipulation.

Many researchers in various scientific and technical fields pay more attention to dynamic systems described by FPDE today [18]. To study soliton solutions of FPDEs, various effective and productive methodologies have been explored in the literature and,

as a result, sophisticated mathematical methods based on computer software are used to control these problems. Various authors systematically studied numerous experimental and analytical methods to achieve accurate travelling waves, quantitative and approximate solutions of all these models, such as the homotopy perturbation approach, the variational iteration method, the variable separation algorithm, and many more [19–21].

Due to the widespread use of FPDEs in engineering and science, the analysis of exact solutions of the nonlinear fractional Schrödinger equation (NFSE) has grown to the point where it is becoming a major source of concern around the world. Nonrelativistic quantum mechanical behaviour is explained by NFSEs, which are fundamental quantum physics models [22]. In 1965, Feynman et al. [23] observed path integrals over Brownian trajectories to construct the standard NFSE. Following that, new path integrals of Levy trajectories were substituted for Brownian trajectories, resulting in the NFSE [24]. Later, Laskin [25] formulated the space–time NFSE by using the quantum Riesz fractional approach. Since then, the NFSE has attracted the attention of a number of authors; for instance, Naber [26] considered the temporal NFSE under the Caputo fractional derivative. Muslih et al. [27] examined the time-NFSE as well as its solution employed in the Caputo sense. Eid et al. proposed an innovative NFSE model that included a nonsingular kernel, the fractional Caputo–Fabrizio concept, and the newer fractional Mittag–Leffler function operator. Smady et al. [22] explained the periodic and approximate solitary solutions of the NFSE employing the method of conformable residual series [28]. Guo et al. [29] used a class of energy procedures to test for the occurrence and uniqueness of the temporal NFSE solution. Naber [26] solved the NFSE for the first time in 2004. Furthermore, Jumarie [30] modified the fractional definition of the Riemann–Liouville derivative (RLD) by specifying a limit on the fractional difference to avoid the difficulties associated with deriving the constant fractionally. Many phenomena, as well as the non-Markovian evolution of a free molecule in elementary particle physics, fractional dynamics in quantum systems, the fractional Planck quantum energy ratio, etc., are described using the NFSE [31–33]. The TNFSE equation is rich and complex, and it can be utilized for mathematical analysis. Its solutions can display a variety of behaviours, including as soliton propagation, wave packet spreading, and chaotic dynamics. The study of the equation can lead to new ideas and developments in mathematics and physics.

Let us consider the following triple NFSE [34]:

$$\begin{aligned} D_t^\alpha D_x^\beta p &= D_x^\beta D_t^\alpha p + \frac{2}{1-\gamma^2} |p|^2 p + p(q-r), \\ D_t^\alpha q &= -\frac{D_t^\alpha |p|^2}{1+\gamma} + (1+\gamma) D_x^\beta q, \\ D_t^\alpha r &= -\frac{D_t^\alpha |p|^2}{1-\gamma} + (1-\gamma) D_x^\beta r, \end{aligned} \quad (1)$$

where r and q are the real function of temporal t and spatial x variables, and where β is a real constant with $|\beta| \neq 1$, and p is a complex one. D_x^β and D_t^α are, respectively, the modified RLD of functional orders “ β ” and “ α ” in term of “ x ” and “ t ”. Despite their significance, figuring accurate and consistent solutions to these nonlinear fractional models is incredibly difficult. It is a fundamental model of quantum mechanics that is used to model many exciting complex and nonlinear physical mechanisms, including photonics, harmonic oscillator, quantum condensates, fluid mechanics, shallow water waves, etc. The NFSE is used to characterize the Heisenberg dynamical model, which was created to evaluate what is consistent with quantum mechanics, as well as the Lagrange system, which is further consistent with classical physics. The aim of this study was to investigate optical solitons, bright, dark, coupled, trigonometric, rational, and hyperbolic solutions by using an AEM approach, as well as the integrability via the P -test approach. The P -test has been significant in the advancement of mathematical physics. It has been used for a wide

range of physics topics, including the study of solitons, nonlinear waves, and quantum field theory. Moreover, the AEM approach is fundamental in the realm of differential equations and has played an important role in the advancement of modern mathematics and science.

This manuscript is organised as follows: We examine the P -test method in Section 2. The P -test approach is implemented in detail in Section 3 to examine the integrability of the governing system. The AEM scheme is explained in Section 4. In Section 5, the AEM technique is used to achieve an optical soliton solution. The results are presented in Section 6, and Section 7 covers the conclusion.

Definition

The crucial definition and parameters of Jumarie's modification of the RLD are presented here, which are highly useful for presenting this work in a systematic manner. let $g : R \rightarrow R$ be a continuous function. The modified RLD of order δ is then provided as follows:

$$D_t^\alpha g(t) = \begin{cases} \frac{1}{\Gamma(-\delta)} \frac{d}{dt} \int_0^t (t-\zeta)^{-\delta-1} (g(\zeta) - g(0)) d\zeta & \delta < 0, \\ \frac{1}{\Gamma(1-\delta)} \frac{d}{dt} \int_0^t (t-\zeta)^{-\delta} (g(\zeta) - g(0)) d\zeta & 0 < -\delta < 1, \\ [g^{(\delta-m)}(t)]^{(m)}, & m \leq \delta < m+1, \quad m \geq 1. \end{cases} \quad (2)$$

Now, let $g : R \rightarrow R$ be D_t^δ differentiable function at a point $t > 0$ and $f : R \rightarrow R$ be D_t^δ differentiable and defined in the range of " g ". Then,

1. If $g(t) = t^\beta$, then $D_t^\delta t^\beta = \frac{\Gamma(\beta+1)}{\Gamma(\beta+1-\delta)} t^{\beta-\delta}$ for $\beta > 0$.
2. $D_t^\delta(g(t)f(t)) = f(t)D_t^\delta g(t) + g(t)D_t^\delta f(t)$.
3. $D_t^\delta g(f(t)) = \frac{d}{df} g(f(t)) D_t^\delta f(t) = D_g^\delta g(f(t)) \left(\frac{d}{dt} f(t)\right)^\delta$.

In the following, if $g(t)$ has a modified RLD of order δ , then it is called D_t^δ differentiable.

2. Painlevé Test (P-Test)

Generally, the P -test is employed to predict the integrability of NLSEs [35,36]. Ablowitz et al. [37] proposed the P -test for examining the singularities structure for ODE. Later, Weiss et al. [38] extended this test to PDEs, providing a strong framework for examining the integrability of various NLSEs. The ability to pass the P -test is a strong indicator that the model under study can be solved using the inverse scattering transform (IST). NLSEs are completely integrable or partially integrable, and their behaviour is observable [39]. There are also several approaches to solving completely integrable NLSEs, such as using the IST or converting the equations to linear equations. However, since there is no other way to determine whether a given NLSE is IST-decidable, the existence of the P -test property is a reliable indicator of the NLSE's integrability [40]. The P -test [40] has following steps:

First, we calculate the dominant behaviour by letting

$$\psi_i(z) = \pi_i g^{(\beta_i)}(z), \quad i = 1, 2, \dots, N, \quad (3)$$

where π_i denote the constants. We substitute Equation (2) into the following equation

$$H(\pi(z), \pi'(z), \pi''(z), \dots, \pi^{(m)}(z)) = 0. \quad (4)$$

where H is a polynomial for determining the leading exponents $\beta_i \in \mathbb{Z}$, while H has components H_1, H_2, \dots, H_N , and variable $\psi(z)$ has components $\psi_1(z), \psi_2(z), \dots, \psi_N(z)$. Similarly, $\psi^{(m_i)}(z)$ depicts the m_i th order derivative of $\psi(z)$ such that $m = \sum_{i=1}^N m_i$, while the components of the independent variable z are z_1, z_2, \dots, z_N . If there are arbitrary coefficients in the system, we assume them to be nonzero. Now, by inserting the above substitution in Equation (3), in each equation, we equalize the lowest available exponents of $g(z)$ to construct a linear system in β_i , the solution of which yields values for the coefficients β_i .

We allocate integer values to the free β_i if some of the β_i 's are yet undetermined. We adopt the following substitution after evaluating β_i :

$$\psi_i(z) = \psi_{i,0}(z)g^{\beta_i}(z), \quad i = 1, 2, \dots, N, \quad (5)$$

invoking it into Equation (3). Then, using the balance of the leading terms, we examine the values of $\psi_{i,0}(z)$, focusing only on those terms that have the smallest power of $g(z)$.

Then, we determine the resonances. For each β_i and $\psi_{i,0}(z)$, integers $p_1 \leq p_2 \leq \dots \leq p_m$ are calculated such that $\psi_{i,p_j}(z)$ becomes

$$\psi_i(z) = g^{\beta_i}(z) \sum_{k=0}^{\infty} \psi_{i,k}(z)g^k(z),$$

where $i = 1, 2, \dots, N$. We achieve this by placing

$$\psi_i(z) = \psi_{i,0}(z)g^{\beta_i}(z) + \psi_{i,s}(z)g^{\gamma_i+p}(z), \quad (6)$$

into Equation (3). Then, we choose the terms with the smallest powers $g(z)$. The coefficients at $\psi_{i,s}(z)$ are assumed to be equal to zero. This is resolved by commuting the values of p for $\det(Q_p) = 0$,

$$Q_p \psi_p = 0, \quad \psi_p = (\psi_{1,p} \psi_{2,p} \dots \psi_{N,p})^Y.$$

When there is at least one integer resonance, the solutions to Equation (4) have algebraic branch points.

Next, the compatibility conditions are computed, and the integration constants are evaluated. A system retains the property of Painlevé if $\psi_{i,p}(z)$ is arbitrary to the highest-level resonance. This is accomplished by inserting

$$\psi_i(z) = g^{\beta_i}(z) \sum_{k=0}^{p_m} \psi_{i,k}(z)g^k(z), \quad (7)$$

into Equation (4), where p_m represents the integral with the greatest positive resonance. Because of the vanishing coefficient of $h^{p+\min pow}g$, $\psi_{i,p}(z)$ should be arbitrary. We must determine whether or not this compatibility criterion is fulfilled. In the system, the negative power in g of the most singular terms is described by $\min pow g$.

If all of the preceding procedures are performed and when all resonances satisfy the compatibility constraints, then the system is said to be integrable and passes the P -test.

3. Implementation of Painlevé Test (P-Test)

We assume the following transformations:

$$\begin{aligned} p(x, t) &= P(\xi)e^{i\eta}, \\ q(x, t) &= Q(\xi), \\ r(x, t) &= R(\xi). \end{aligned} \quad (8)$$

where $\xi = \frac{kx^\alpha}{\Gamma(\alpha+1)} + \frac{st^\beta}{\Gamma(\beta+1)}$, $\eta = \frac{mx^\alpha}{\Gamma(\alpha+1)} + \frac{nt^\beta}{\Gamma(\beta+1)}$.

Where k, s, m , and n , are nonzero arbitrary constants, after substituting above transformation, (1) becomes:

$$(ks - k^2)P'' + (m^2 - mn)P - \frac{2}{1 - \gamma^2}P^3 - P(Q - R) = 0, \quad (9)$$

where

$$Q = \frac{-s}{(1+\gamma)(s-(1+\gamma))k} P^2, \quad (10)$$

and

$$R = \frac{s}{(1-\gamma)(s-(1-\gamma))k} P^2, \quad (11)$$

Putting Equations (10) and (11) into Equation (9), we obtain:

$$P'' + \frac{m(m-n)}{k(s-k)} P + \frac{2}{(s-k)^2 - k^2\gamma^2} P^3 = 0. \quad (12)$$

The Painlevé test consists of three phases.

3.1. Dominant Behaviour Calculation

Assume the following:

$$P(x, t) = \zeta h^q(x, t), \quad (13)$$

where q indicates the dominant behaviour and ζ indicates a constant. Now, invoking Equation (13) into Equation (12) yields $q = -1$. Consider the following assumption,

$$P(x, t) = P_0(x, t) h^q(x, t). \quad (14)$$

Placing this value of q into Equation (14) yields

$$P(x, t) = P_0(x, t) h^{-1}(x, t). \quad (15)$$

Placing Equation (15) into Equation (12) gives

$$P_0(x, t) = -k\sqrt{k-s}\gamma, \quad (16)$$

where P_0 represents the first integration constant.

3.2. Calculation for Resonances

Take

$$P(x, t) = P_0(x, t) h^q(x, t) + P_r(x, t) h^{q+r}(x, t), \quad (17)$$

where r denotes the resonance associated with the dominant behaviour q . Now, placing Equation (16) and $q = -1$ into Equation (17) gives

$$P(x, t) = -k\sqrt{k-s}\gamma h^{-1}(x, t) + P_r(x, t) h^{r-1}(x, t). \quad (18)$$

By invoking Equation (18) in Equation (12) and equating the sum of the coefficients of $P_r(x, t)$ to zero of the terms involving the smallest exponent of $g(x, t)$, the resonances have the following equation:

$$k^2(-4+r)(1+r)(k-s)\gamma^2 = 0, \quad (19)$$

Equation (19) yields

$$r = 4, \quad r = -1. \quad (20)$$

3.3. Computation of Integration Constants and Compatibility Condition

Equation (12) satisfies the P -test if $P_r(x, t)$ is arbitrary for the highest resonance level. For verification, assume the following:

$$P(x, t) = h^0(x, t) \sum_{q=0}^{r_m} P_q(x, t) h^q(x, t), \quad (21)$$

where r_m is the greatest resonance, and in our instance, $r_m = 4$. Equation (20) gives the following results:

$$P(x, t) = h^{-1}(x, t) \sum_{q=0}^4 P_q(x, t) h^q(x, t). \quad (22)$$

By putting Equation (21) into Equation (11), by collecting the same powers $g(x, t)$, and by equating them to zero at different levels q , we calculate $P_q(x, t)$, $q = 1, 2, \dots, 4$.

Thus, for $q = 1$, this ensures

$$P_1(x, t) = 0, \quad (23)$$

at $q = 2$,

$$P_2(x, t) = -\frac{m(m-n)}{6\sqrt{k-s}}, \quad (24)$$

at $q = 3$,

$$P_3(x, t) = 0, \quad (25)$$

at $q = 4$,

$$P_4(x, t) = P_4(x, t). \quad (26)$$

where $P_4(x, t)$ is an arbitrary constant. As a result of the analysis, the defining model satisfies the criteria of the P -test, since there are no compatibility conditions and both resonance conditions are satisfied.

4. Auxiliary Equation Mapping (AEM) Technique

Consider the TNFSEs in one dimension to understand the basic scheme of AEM, which can be written as follows:

$$T(\nu, D_t^\alpha \nu, D_x^\beta \nu, D^\alpha D^\beta \nu, \dots) = 0, \quad (27)$$

where ν is an analytic function and D^α , D^β , $D^\alpha D^\beta$ are the fractional operator in terms of the modified RLD with respect to " x " and " t ". While T is a polynomial function that has higher-order linear and nonlinear derivative terms.

For transforming independent variables into a single variable, assume the following wave transformation:

$$\nu(x, t) = \nu(\Omega) e^{i\zeta}, \quad (28)$$

where $\Omega = \frac{kx^\alpha}{\Gamma(\alpha+1)} + \frac{st^\beta}{\Gamma(\beta+1)}$, $\zeta = \frac{mx^\alpha}{\Gamma(\alpha+1)} + \frac{nt^\beta}{\Gamma(\beta+1)}$.

Utilizing Equation (28) reduces Equation (27) into the following ODE:

$$T(\nu, \nu', \nu'', \nu''', \dots) = 0. \quad (29)$$

Now, assume Equation (29) has a general solution as follows [41,42]:

$$v(\theta) = \sum_{p=0}^m a_p q^p(\theta) + \sum_{p=-1}^{-m} b_{-p} q^p(\theta) + \sum_{p=2}^m c_p q^{p-2}(\theta) q'(\theta) + \sum_{p=1}^m d_p \left(\frac{q'(\theta)}{q(\theta)} \right)^p, \quad (30)$$

where the a_p , b_p , c_p , and d_p are arbitrary constants and $q(\phi)$ meets the following auxiliary solution:

$$q'(\theta)^2 = \left(\frac{dq}{d\theta} \right)^2 = \mu_1 q^2(\theta) + \mu_2 q^3(\theta) + \mu_3 q^4(\theta), \quad (31)$$

$$q''(\theta) = \mu_1 q(\theta) + \frac{3}{2} \mu_2 q^2(\theta) + 2\mu_3 q^3(\theta), \quad (32)$$

$$q'''(\theta) = \mu_1 + 3\mu_2 q(\theta) + 6\mu_3 q^2(\theta) q'(\theta), \quad (33)$$

$$q''''(\theta) = \frac{1}{2} q(\theta) (2\mu_1^2 + 15\mu_1 \mu_2 q(\theta) + 5(3\mu_2^2 + 8\mu_1 \mu_3 q^2(\theta)) + 60\mu_2 \mu_3 q^3(\theta) + 48\mu_3^2 q^4(\theta)), \quad (34)$$

where μ_1 , μ_2 , and μ_3 are constants. By placing Equation (31) together with Equation (30) into Equation (29), we obtain a set of equations, which can be solved by using Mathematica software; then, the parameter values can be obtained.

5. Implementation of Auxiliary Equation Mapping (AEM)

From Equation (12),

$$P'' + \frac{m(m-n)}{k(s-k)} P + \frac{2}{(s-k)^2 - k^2 \gamma^2} P^3 = 0. \quad (35)$$

Now, utilizing the homogeneous balance principle, Equation (35) yields $n = 1$. Therefore, it yields the general solution of the form

$$P(\xi) = a_0 + a_1 q(\xi) + \frac{b_1}{q(\xi)} + d_1 \left(\frac{q'(\xi)}{q(\xi)} \right). \quad (36)$$

Placing Equation (36) along its derivative into Equation (35), then collecting all the coefficients of the same powers $q^m(\xi)$ $q^n(\xi)$ ($m = 0, 1, 2, \dots, n$), ($n = 0, 1$), we obtain a system of algebraic equations that provides solutions from which, using Mathematica, we can obtain different and newly generalized solitary wave solutions with constants a_0 , a_1 , b_1 , d_1 , and by using Equation (8), we obtain the following solutions:

Case 1:

$$\begin{aligned} a_0 &= 0, \quad a_1 = 0, \\ b_1 &= \frac{2a_0(-m^2s^2 + 2m^2sk - m^2k^2 + m^2\gamma^2k^2 + mns^2 - 2mnsk + mnk^2 - mn\gamma^2k^2 - 2a_0^2ks + 2a_0^2k^2)}{\mu_2k(-s+k)(-s+k+\gamma k)(s-k+\gamma k)}, \\ \mu_1 &= \frac{-m^2s^2 + 2m^2sk - m^2k^2 + m^2\gamma^2k^2 + mns^2 - 2mnsk + mnk^2 - mn\gamma^2k^2 - 6a_0^2ks + 6a_0^2k^2}{k(-s+k)(-s+k+\gamma k)(s-k+\gamma k)}, \\ \mu_2 &= \mu_2, \quad \mu_3 = \mu_3. \end{aligned}$$

By inserting all values into Equation (36) and by employing Equation (8), the following solutions of Equation (1) are achieved [41,42]:

$$p_{1,1}(x, t) = \left[-\frac{b_1(b^2 - ac(1 + \tanh(\frac{\sqrt{a}\xi}{2}))^2}{ab \sec h^2(\frac{\sqrt{a}\xi}{2})} \right] e^{i\left(\frac{mx^\alpha}{\Gamma(\alpha+1)} + \frac{nt^\beta}{\Gamma(\beta+1)}\right)}, \quad (37)$$

$$q_{1,1}(x, t) = \frac{-s}{(1+\gamma)(s-(1+\gamma))k} \left[-\frac{b_1(b^2 - ac(1 + \tanh(\frac{\sqrt{a}\xi}{2}))^2}{ab \sec h^2(\frac{\sqrt{a}\xi}{2})} \right]^2, \quad (38)$$

$$r_{1,1}(x, t) = \frac{s}{(1-\gamma)(s-(1-\gamma))k} \left[-\frac{b_1(b^2 - ac(1 + \tanh(\frac{\sqrt{a}\xi}{2}))^2}{ab \sec h^2(\frac{\sqrt{a}\xi}{2})} \right]^2, \quad (39)$$

$$p_{1,2}(x, t) = \left[\frac{b_1(\sqrt{\delta} - b \csc(\sqrt{-a}\xi))}{2a \csc(\sqrt{-a}\xi)} \right] e^{i\left(\frac{mx^\alpha}{\Gamma(\alpha+1)} + \frac{nt^\beta}{\Gamma(\beta+1)}\right)}, \quad (40)$$

$$q_{1,2}(x, t) = \frac{-s}{(1+\gamma)(s-(1+\gamma))k} \left[\frac{b_1(\sqrt{\delta} - b \csc(\sqrt{-a}\xi))}{2a \csc(\sqrt{-a}\xi)} \right]^2, \quad (41)$$

$$r_{1,2}(x, t) = \frac{s}{(1-\gamma)(s-(1-\gamma))k} \left[\frac{b_1(\sqrt{\delta} - b \csc(\sqrt{-a}\xi))}{2a \csc(\sqrt{-a}\xi)} \right]^2, \quad (42)$$

$$p_{1,3}(x, t) = \left[\frac{b_1 b}{a(1 + \tanh(\frac{\sqrt{a}\xi}{2}))} \right] e^{i\left(\frac{mx^\alpha}{\Gamma(\alpha+1)} + \frac{nt^\beta}{\Gamma(\beta+1)}\right)}, \quad (43)$$

$$q_{1,3}(x, t) = \frac{-s}{(1+\gamma)(s-(1+\gamma))k} \left[\frac{b_1 b}{a(1 + \tanh(\frac{\sqrt{a}\xi}{2}))} \right]^2, \quad (44)$$

$$r_{1,3}(x, t) = \frac{s}{(1-\gamma)(s-(1-\gamma))k} \left[\frac{b_1 b}{a(1 + \tanh(\frac{\sqrt{a}\xi}{2}))} \right]^2, \quad (45)$$

$$p_{1,4}(x, t) = \left[\frac{-b_1(b^2 \xi^2 - ac)}{ab} \right] e^{i\left(\frac{mx^\alpha}{\Gamma(\alpha+1)} + \frac{nt^\beta}{\Gamma(\beta+1)}\right)}, \quad (46)$$

$$q_{1,4}(x, t) = \frac{-s}{(1+\gamma)(s-(1+\gamma))k} \left[\frac{-b_1(b^2 \xi^2 - ac)}{ab} \right]^2, \quad (47)$$

$$r_{1,4}(x, t) = \frac{s}{(1-\gamma)(s-(1-\gamma))k} \left[\frac{-b_1(b^2 \xi^2 - ac)}{ab} \right]^2, \quad (48)$$

$$p_{1,5}(x, t) = \left[\frac{b_1 b}{a(1 + \coth(\frac{\sqrt{a}\xi}{2}))} \right] e^{i\left(\frac{mx^\alpha}{\Gamma(\alpha+1)} + \frac{nt^\beta}{\Gamma(\beta+1)}\right)}, \quad (49)$$

$$q_{1,5}(x, t) = \frac{-s}{(1+\gamma)(s-(1+\gamma))k} \left[\frac{b_1 b}{a(1 + \coth(\frac{\sqrt{a}\xi}{2}))} \right]^2, \quad (50)$$

$$r_{1,5}(x, t) = \frac{s}{(1 - \gamma)(s - (1 - \gamma))k} \left[\frac{b_1 b}{a \left(1 + \coth\left(\frac{\sqrt{a}\xi}{2}\right) \right)} \right]^2. \quad (51)$$

Case 2:

$$\begin{aligned} a_1 &= a_1, & a_0 &= 0, & b_1 &= b_1, \\ d_1 &= 0, & \mu_1 &= \frac{m(m-n)}{k(-s+k)}, \\ \mu_2 &= 0, & \mu_3 &= \mu_3. \end{aligned}$$

By inserting all values into Equation (36) and by employing Equation (8), the following solutions of Equation (1) are achieved [41,42]:

$$p_{2,1}(x, t) = \left[\frac{a_1 a \left(1 + \coth\left(\frac{\sqrt{a}\xi}{2}\right) \right)}{b} + \frac{b_1 b}{a \left(1 + \coth\left(\frac{\sqrt{a}\xi}{2}\right) \right)} \right] e^{i \left(\frac{mx^\alpha}{\Gamma(\alpha+1)} + \frac{nt^\beta}{\Gamma(\beta+1)} \right)}, \quad (52)$$

$$q_{2,1}(x, t) = \frac{-s}{(1 + \gamma)(s - (1 + \gamma))k} \left[\frac{a_1 a \left(1 + \coth\left(\frac{\sqrt{a}\xi}{2}\right) \right)}{b} + \frac{b_1 b}{a \left(1 + \coth\left(\frac{\sqrt{a}\xi}{2}\right) \right)} \right]^2, \quad (53)$$

$$r_{2,1}(x, t) = \frac{s}{(1 - \gamma)(s - (1 - \gamma))k} \left[\frac{a_1 a \left(1 + \coth\left(\frac{\sqrt{a}\xi}{2}\right) \right)}{b} + \frac{b_1 b}{a \left(1 + \coth\left(\frac{\sqrt{a}\xi}{2}\right) \right)} \right]^2, \quad (54)$$

$$p_{2,2}(x, t) = \left[\frac{4aa_1 e^{\sqrt{a}\xi}}{(e^{\sqrt{a}\xi} - b)^2 - 4ac} + \frac{b_1(e^{\sqrt{a}\xi} - b)^2 - 4ac}{4ae^{\sqrt{a}\xi}} \right] e^{i \left(\frac{mx^\alpha}{\Gamma(\alpha+1)} + \frac{nt^\beta}{\Gamma(\beta+1)} \right)}, \quad (55)$$

$$q_{2,2}(x, t) = \frac{-s}{(1 + \gamma)(s - (1 + \gamma))k} \left[\frac{4aa_1 e^{\sqrt{a}\xi}}{(e^{\sqrt{a}\xi} - b)^2 - 4ac} + \frac{b_1(e^{\sqrt{a}\xi} - b)^2 - 4ac}{4ae^{\sqrt{a}\xi}} \right]^2, \quad (56)$$

$$r_{2,2}(x, t) = \frac{s}{(1 - \gamma)(s - (1 - \gamma))k} \left[\frac{4aa_1 e^{\sqrt{a}\xi}}{(e^{\sqrt{a}\xi} - b)^2 - 4ac} + \frac{b_1(e^{\sqrt{a}\xi} - b)^2 - 4ac}{4ae^{\sqrt{a}\xi}} \right]^2, \quad (57)$$

$$p_{2,3}(x, t) = \left[\frac{-aa_1 \sec^2\left(\frac{\sqrt{a}\xi}{2}\right)}{b + 2\sqrt{ac} \tanh\left(\frac{\sqrt{a}\xi}{2}\right)} - \frac{b_1(b + 2\sqrt{ac} \tanh\left(\frac{\sqrt{a}\xi}{2}\right))}{a \sec^2\left(\frac{\sqrt{a}\xi}{2}\right)} \right] e^{i \left(\frac{mx^\alpha}{\Gamma(\alpha+1)} + \frac{nt^\beta}{\Gamma(\beta+1)} \right)}, \quad (58)$$

$$q_{2,3}(x, t) = \frac{-s}{(1 + \gamma)(s - (1 + \gamma))k} \left[\frac{-aa_1 \sec^2\left(\frac{\sqrt{a}\xi}{2}\right)}{b + 2\sqrt{ac} \tanh\left(\frac{\sqrt{a}\xi}{2}\right)} - \frac{b_1(b + 2\sqrt{ac} \tanh\left(\frac{\sqrt{a}\xi}{2}\right))}{a \sec^2\left(\frac{\sqrt{a}\xi}{2}\right)} \right]^2, \quad (59)$$

$$r_{2,3}(x, t) = \frac{s}{(1 - \gamma)(s - (1 - \gamma))k} \left[\frac{-aa_1 \sec^2\left(\frac{\sqrt{a}\xi}{2}\right)}{b + 2\sqrt{ac} \tanh\left(\frac{\sqrt{a}\xi}{2}\right)} - \frac{b_1(b + 2\sqrt{ac} \tanh\left(\frac{\sqrt{a}\xi}{2}\right))}{a \sec^2\left(\frac{\sqrt{a}\xi}{2}\right)} \right]^2, \quad (60)$$

$$p_{2,4}(x, t) = \left[\frac{-aca_1 \csc^2\left(\frac{\sqrt{-a}\xi}{2}\right)}{b + 2\sqrt{-ac} \cot\left(\frac{\sqrt{-a}\xi}{2}\right)} - \frac{b_1(b + 2\sqrt{-ac} \cot\left(\frac{\sqrt{-a}\xi}{2}\right))}{ac \csc^2\left(\frac{\sqrt{-a}\xi}{2}\right)} \right] e^{i \left(\frac{mx^\alpha}{\Gamma(\alpha+1)} + \frac{nt^\beta}{\Gamma(\beta+1)} \right)}, \quad (61)$$

$$q_{2,4}(x, t) = \frac{-s}{(1+\gamma)(s-(1+\gamma))k} \left[\frac{-aca_1 \csc^2(\frac{\sqrt{-a}\xi}{2})}{b+2\sqrt{-ac} \cot(\frac{\sqrt{-a}\xi}{2})} - \frac{b_1(b+2\sqrt{-ac} \cot(\frac{\sqrt{-a}\xi}{2}))}{a \csc^2(\frac{\sqrt{-a}\xi}{2})} \right]^2, \quad (62)$$

$$r_{2,4}(x, t) = \frac{s}{(1-\gamma)(s-(1-\gamma))k} \left[\frac{-aca_1 \csc^2(\frac{\sqrt{-a}\xi}{2})}{b+2\sqrt{-ac} \cot(\frac{\sqrt{-a}\xi}{2})} - \frac{b_1(b+2\sqrt{-ac} \cot(\frac{\sqrt{-a}\xi}{2}))}{a \csc^2(\frac{\sqrt{-a}\xi}{2})} \right]^2, \quad (63)$$

$$p_{2,5}(x, t) = \left[\frac{4aa_1 e^{\sqrt{a}\xi}}{1-4ace^{\sqrt{a}\xi}} + \frac{b_1(1-4ace^{\sqrt{a}\xi})}{4ae^{\sqrt{a}\xi}} \right] e^{i\left(\frac{mx^\alpha}{\Gamma(\alpha+1)} + \frac{nt^\beta}{\Gamma(\beta+1)}\right)}, \quad (64)$$

$$q_{2,5}(x, t) = \frac{-s}{(1+\gamma)(s-(1+\gamma))k} \left[\frac{4aa_1 e^{\sqrt{a}\xi}}{1-4ace^{\sqrt{a}\xi}} + \frac{b_1(1-4ace^{\sqrt{a}\xi})}{4ae^{\sqrt{a}\xi}} \right]^2, \quad (65)$$

$$r_{2,5}(x, t) = \frac{s}{(1-\gamma)(s-(1-\gamma))k} \left[\frac{4aa_1 e^{\sqrt{a}\xi}}{1-4ace^{\sqrt{a}\xi}} + \frac{b_1(1-4ace^{\sqrt{a}\xi})}{4ae^{\sqrt{a}\xi}} \right]^2. \quad (66)$$

Case 3:

$$a_1 = 0,$$

$$a_0 = \sqrt{\frac{m^2 k^2 + m^2 \gamma^2 k^2 - m^2 s^2 + 2m^2 sk + mnk^2 - mn\gamma^2 k^2 + mns^2 - 2mnsk}{-2sk + 2k^2}},$$

$$b_1 = b_1, \quad d_1 = 0, \mu_1 = \frac{-2m(m-n)}{k(-s+k)}, \quad \mu_2 = 0, \quad \mu_3 = \mu_3.$$

By inserting all values into Equation (36) and by employing Equation (8), the following solutions of Equation (1) are achieved [41,42]:

$$p_{3,1}(x, t) = \left[a_0 + \frac{b_1(e^{\sqrt{a}\xi} - b)^2 - 4ac}{4ae^{\sqrt{a}\xi}} \right] e^{i\left(\frac{mx^\alpha}{\Gamma(\alpha+1)} + \frac{nt^\beta}{\Gamma(\beta+1)}\right)}, \quad (67)$$

$$q_{3,1}(x, t) = \frac{-s}{(1+\gamma)(s-(1+\gamma))k} \left[a_0 + \frac{b_1(e^{\sqrt{a}\xi} - b)^2 - 4ac}{4ae^{\sqrt{a}\xi}} \right]^2, \quad (68)$$

$$r_{3,1}(x, t) = \frac{s}{(1-\gamma)(s-(1-\gamma))k} \left[a_0 + \frac{b_1(e^{\sqrt{a}\xi} - b)^2 - 4ac}{4ae^{\sqrt{a}\xi}} \right]^2, \quad (69)$$

$$p_{3,2}(x, t) = \left[a_0 + b_1 c \sqrt{\xi} \right] e^{i\left(\frac{mx^\alpha}{\Gamma(\alpha+1)} + \frac{nt^\beta}{\Gamma(\beta+1)}\right)}, \quad (70)$$

$$q_{3,2}(x, t) = \frac{-s}{(1+\gamma)(s-(1+\gamma))k} \left[a_0 + b_1 c \sqrt{\xi} \right]^2, \quad (71)$$

$$r_{3,2}(x, t) = \frac{s}{(1-\gamma)(s-(1-\gamma))k} \left[a_0 + b_1 c \sqrt{\xi} \right]^2, \quad (72)$$

$$p_{3,3}(x, t) = \left[a_0 + \frac{b_1(b+2\sqrt{-ac}) \tan(\frac{\sqrt{-a}\xi}{2})}{a \sec^2(\frac{\sqrt{-a}\xi}{2})} \right] e^{i\left(\frac{mx^\alpha}{\Gamma(\alpha+1)} + \frac{nt^\beta}{\Gamma(\beta+1)}\right)}, \quad (73)$$

$$q_{3,3}(x, t) = \frac{-s}{(1+\gamma)(s-(1+\gamma))k} \left[a_0 + \frac{b_1(b+2\sqrt{-ac}) \tan(\frac{\sqrt{-a}\xi}{2})}{a \sec^2(\frac{\sqrt{-a}\xi}{2})} \right]^2, \quad (74)$$

$$r_{3,3}(x, t) = \frac{s}{(1-\gamma)(s-(1-\gamma))k} \left[a_0 + \frac{b_1(b+2\sqrt{-ac}) \tan(\frac{\sqrt{-a}\xi}{2})}{a \sec^2(\frac{\sqrt{-a}\xi}{2})} \right]^2, \quad (75)$$

$$p_{3,4}(x, t) = \left[a_0 + \frac{b_1(b^2 - ac(1 + \coth(\frac{\sqrt{a}\xi}{2})))^2}{ab \csc h^2(\frac{\sqrt{a}\xi}{2})} \right] e^{i\left(\frac{mx^\alpha}{\Gamma(\alpha+1)} + \frac{nt^\beta}{\Gamma(\beta+1)}\right)}, \quad (76)$$

$$q_{3,4}(x, t) = \frac{-s}{(1+\gamma)(s-(1+\gamma))k} \left[a_0 + \frac{b_1 b^2 - ac(1 + \coth(\frac{\sqrt{a}\xi}{2}))^2}{ab \csc h^2(\frac{\sqrt{a}\xi}{2})} \right]^2, \quad (77)$$

$$r_{3,4}(x, t) = \frac{s}{(1-\gamma)(s-(1-\gamma))k} \left[a_0 + \frac{b_1 b^2 - ac(1 + \coth(\frac{\sqrt{a}\xi}{2}))^2}{ab \csc h^2(\frac{\sqrt{a}\xi}{2})} \right]^2, \quad (78)$$

$$p_{3,5}(x, t) = \left[a_0 + \frac{b_1 \sqrt{\delta} - b \csc \sqrt{-a}\xi}{2a \csc \sqrt{-a}\xi} \right] e^{i\left(\frac{mx^\alpha}{\Gamma(\alpha+1)} + \frac{nt^\beta}{\Gamma(\beta+1)}\right)}, \quad (79)$$

$$q_{3,5}(x, t) = \frac{-s}{(1+\gamma)(s-(1+\gamma))k} \left[a_0 + \frac{b_1 \sqrt{\delta} - b \csc \sqrt{-a}\xi}{2a \csc \sqrt{-a}\xi} \right]^2, \quad (80)$$

$$r_{3,5}(x, t) = \frac{s}{(1-\gamma)(s-(1-\gamma))k} \left[a_0 + \frac{b_1 \sqrt{\delta} - b \csc \sqrt{-a}\xi}{2a \csc \sqrt{-a}\xi} \right]^2. \quad (81)$$

Case 4:

$$\begin{aligned} a_0 &= a_0, \quad a_1 = 0, \quad b_1 = -a_0, \quad d_1 = \frac{1}{2} \sqrt{\gamma^2 k^2 - s^2 + 2sk - k^2}, \\ \mu_1 &= \frac{-2(-m^2 s^2 + 2m^2 sk - m^2 k^2 + m^2 \gamma^2 k^2 + mns^2 - 2mnsk + mnk^2 - mn\gamma^2 k^2 - 6a_0^2 ks + 6a_0^2 k^2)}{k(-s+k)(-s^2+2sk-k^2+\gamma^2 k^2)}, \\ \mu_2 &= \frac{-2(-m^2 s^2 + 2m^2 sk - m^2 k^2 + m^2 \gamma^2 k^2 + mns^2 - 2mnsk + mnk^2 - mn\gamma^2 k^2 - 2a_0^2 ks + 2a_0^2 k^2)}{k(-s+k)(-s+k+\gamma k)(s-k+\gamma k)}, \\ \mu_3 &= 0. \end{aligned}$$

By inserting all values into Equation (36) and by employing Equation (8), the following solutions of Equation (1) are achieved [41,42]:

$$p_{4,1}(x, t) = \left[a_0 + \frac{b_1 \sqrt{\delta} - b \sec(\sqrt{-a}\xi)}{2a \sec(\sqrt{-a}\xi)} - \frac{d_1 \sqrt{-a} \sqrt{\delta} \sin(\sqrt{-a}\xi)}{b + \sqrt{\delta} \cos(\sqrt{-a}\xi)} \right] e^{i\left(\frac{mx^\alpha}{\Gamma(\alpha+1)} + \frac{nt^\beta}{\Gamma(\beta+1)}\right)}, \quad (82)$$

$$q_{4,1}(x, t) = \frac{-s}{(1+\gamma)(s-(1+\gamma))k} \left[a_0 + \frac{b_1 \sqrt{\delta} - b \sec(\sqrt{-a}\xi)}{2a \sec(\sqrt{-a}\xi)} - \frac{d_1 \sqrt{-a} \sqrt{\delta} \sin(\sqrt{-a}\xi)}{b + \sqrt{\delta} \cos(\sqrt{-a}\xi)} \right]^2, \quad (83)$$

$$r_{4,1}(x, t) = \frac{s}{(1-\gamma)(s-(1-\gamma))k} \left[a_0 + \frac{b_1 \sqrt{\delta} - b \sec(\sqrt{-a}\xi)}{2a \sec(\sqrt{-a}\xi)} - \frac{d_1 \sqrt{-a} \sqrt{\delta} \sin(\sqrt{-a}\xi)}{b + \sqrt{\delta} \cos(\sqrt{-a}\xi)} \right]^2, \quad (84)$$

$$p_{4,2}(x, t) = \left[a_0 + \frac{b_1(b\zeta^2 - ac)}{ab} - \frac{2d_1ab^2\zeta}{ac - b^2\zeta^2} \right] e^{i\left(\frac{mx^\alpha}{\Gamma(\alpha+1)} + \frac{nt^\beta}{\Gamma(\beta+1)}\right)}, \quad (85)$$

$$q_{4,2}(x, t) = \frac{-s}{(1+\gamma)(s-(1+\gamma))k} \left[a_0 + \frac{b_1(b\zeta^2 - ac)}{ab} - \frac{2d_1ab^2\zeta}{ac - b^2\zeta^2} \right]^2, \quad (86)$$

$$r_{4,2}(x, t) = \frac{s}{(1-\gamma)(s-(1-\gamma))k} \left[a_0 + \frac{b_1(b\zeta^2 - ac)}{ab} - \frac{2d_1ab^2\zeta}{ac - b^2\zeta^2} \right]^2, \quad (87)$$

$$p_{4,3}(x, t) = \left[a_0 - \frac{b_1(b + 2\sqrt{-ac} \tan(\frac{\sqrt{-a}\zeta}{2}))}{a \sec^2(\frac{\sqrt{-a}\zeta}{2})} - d_1 \left(\frac{\sqrt{a} \sec^2(\frac{\sqrt{-a}\zeta}{2}) 2\sqrt{-ac} \cos(\sqrt{a}\zeta) - b \sin(\sqrt{a}\zeta)}{2(b + 2\sqrt{-ac} \tan(\frac{\sqrt{-a}\zeta}{2}))} \right) \right] e^{i\left(\frac{mx^\alpha}{\Gamma(\alpha+1)} + \frac{nt^\beta}{\Gamma(\beta+1)}\right)}, \quad (88)$$

$$q_{4,3}(x, t) = \frac{-s}{(1+\gamma)(s-(1+\gamma))k} \left[a_0 - \frac{b_1(b + 2\sqrt{-ac} \tan(\frac{\sqrt{-a}\zeta}{2}))}{a \sec^2(\frac{\sqrt{-a}\zeta}{2})} - d_1 \left(\frac{\sqrt{a} \sec^2(\frac{\sqrt{-a}\zeta}{2}) 2\sqrt{-ac} \cos(\sqrt{a}\zeta) - b \sin(\sqrt{a}\zeta)}{2(b + 2\sqrt{-ac} \tan(\frac{\sqrt{-a}\zeta}{2}))} \right) \right]^2, \quad (89)$$

$$r_{4,3}(x, t) = \frac{s}{(1-\gamma)(s-(1-\gamma))k} \left[a_0 - \frac{b_1(b + 2\sqrt{-ac} \tan(\frac{\sqrt{-a}\zeta}{2}))}{a \sec^2(\frac{\sqrt{-a}\zeta}{2})} - d_1 \left(\frac{\sqrt{a} \sec^2(\frac{\sqrt{-a}\zeta}{2}) 2\sqrt{-ac} \cos(\sqrt{a}\zeta) - b \sin(\sqrt{a}\zeta)}{2(b + 2\sqrt{-ac} \tan(\frac{\sqrt{-a}\zeta}{2}))} \right) \right]^2. \quad (90)$$

6. Results and Discussion

In this section, we analyse our findings and correlate our gained solutions to previous results of this system. Some optical soliton solutions of space–time–fractional NLSE via three different strategies were obtained by Gang et al. [43]. A conformable NLSE with a second-order temporal and group velocity dispersion was observed by Rezazadeh et al. [44]. A locally extrapolated exponential splitting scheme for the fractional spatial NLSE was investigated by Liang et al. [45]. By employing the Riccati expansion approach, some periodic and kink soliton solutions for nonlinear time-fractional differential equations were obtained by Emad et al. [46]. Linearized compact ADI schemes for the space-fractional NLSE were explored by Chen et al. [22]. A fast linearized conservative finite element method for the fully coupled NLSE was investigated by Meng et al. [47]. Travelling wave solutions for TNFSEs were investigated by Alabedalhadi [34]. Guo [48] obtained standing waves for a fractional NLSE by employing the method of commutator estimates and concentration compactness.

In this manuscript, the P -test was employed to check the integrability of TNFSEs. For the integrability, the first constant of the integration was calculated in Equation (15). The resonance was calculated in Equation (19). The other remaining constants of integrations were computed in Equations (22)–(25). There was no compatibility condition and both resonance conditions were verified. Therefore, the governing systems fully satisfied the P -test criteria. The AEM approach was implemented to obtain optical solitary wave solutions. Figure 1 show a smooth soliton solution. Figure 2 show a bright soliton solution. Figures 3 and 4 also show a smooth soliton solution. Figures 5–9 shows kink soliton solution. There is a singularity in its wave form. Figures 10–12 shows smooth kink soliton solution. And Figure 13 shows bell kink soliton solution. Some of the solutions disclosed in this research study have not yet been published in the literature. These two

approaches are simpler and more productive than other methods, they can also yield multiple soliton solutions at the same time, and they can also be applied to other FPDEs. More sophisticated and time-consuming algebraic computations can be performed with the help of mathematical packages (Mathematica). It is anticipated that the solutions presented here will be useful in further numerical analysis and will help in explaining some physical phenomena. This study is only an initial work, further applications to some other nonlinear physical systems can be explored and require considerable attention in many areas of physics and engineering, such as optics, fluid dynamics, plasma physics, and biological systems, where these obtained solitary wave solutions can be used. Optical communications, ocean wave modelling, plasma physics, and biological signal transmission are also some additional examples of their applications.

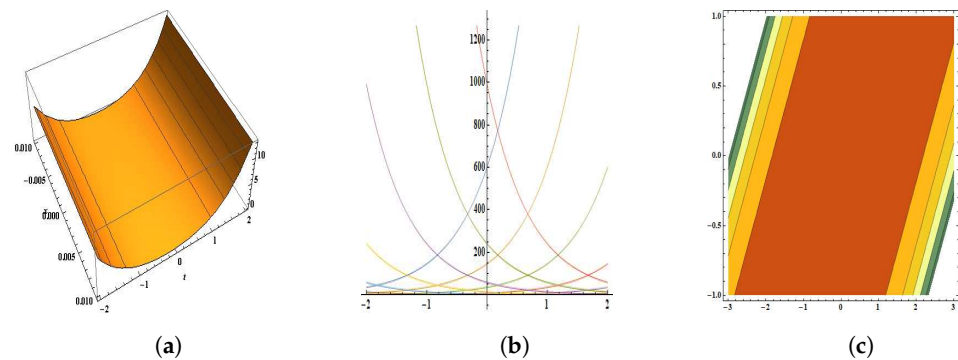


Figure 1. The parameters are $a = 2$, $b = 1.5$, $c = 1$, $k = 2$, $s = 2$, $m = 1$, $n = 1$, $\alpha = 1$, $\beta = 1$, and $\Gamma = 1$. The figure provides a pictorial illustration of $p_{1,1}(x, t)$: (a) displays the 3D plot in $[-0.01, 0.01]$ and $[-2, 2]$, (b) displays the 2D plot in $[-2, 2]$ and $[-5, 5]$, (c) displays the contour plot.

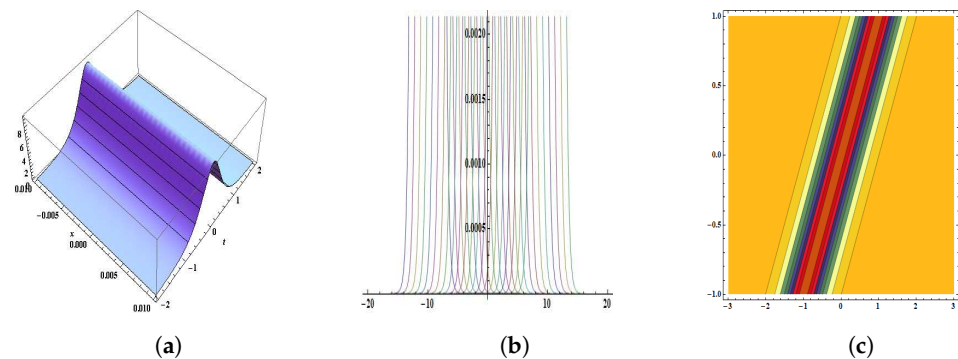


Figure 2. The parameters are $a = 2$, $k = 2$, $s = 2$, $m = 1$, $n = 1$, $b = 1.5$, $c = 1$, $\gamma = 2$, $\alpha = 1$, $\beta = 1$, $\Gamma = 1$, and $\delta = 5$. The figure provides the pictorial illustration of $q_{1,2}(x, t)$: (a) displays the 3D plot in $[-0.01, 0.01]$ and $[-2, 2]$, (b) displays the 2D plot in $[-20, 20]$ and $[-10, 10]$, (c) displays the contour plot.

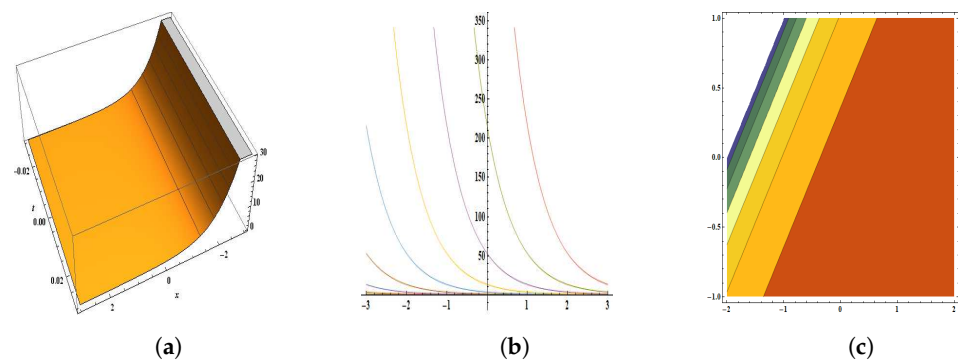


Figure 3. The parameters are $a = 2, k = 2, s = 2, m = 1, b = 1.5, c = 1, n = 1, \gamma = 2, \alpha = 1, \beta = 1$, and $\Gamma = 1$. The figure provides the pictorial illustration of $r_{1,3}(x, t)$: (a) displays the 3D plot in $[-3, 3]$ and $[-0.03, 0.03]$, (b) displays the 2D plot in $[-3, 3]$ and $[-5, 5]$, (c) displays the contour plot.

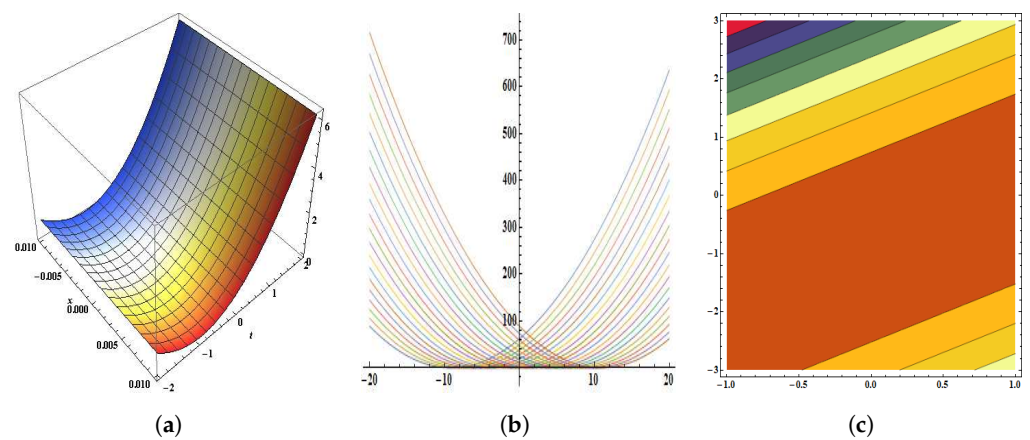


Figure 4. The parameters are $a = 2, k = 2, s = 2, m = 1, n = 1, b = 1.5, c = 1, \gamma = 2, \alpha = 1, \beta = 1$, and $\Gamma = 1$. The figure provides the pictorial illustration of $q_{1,4}(x, t)$: (a) displays the 3D plot in $[-1, 1]$ and $[-0.01, 0.01]$, (b) displays the 2D plot in $[-10, 10]$ and $[-20, 20]$, (c) displays the contour plot.

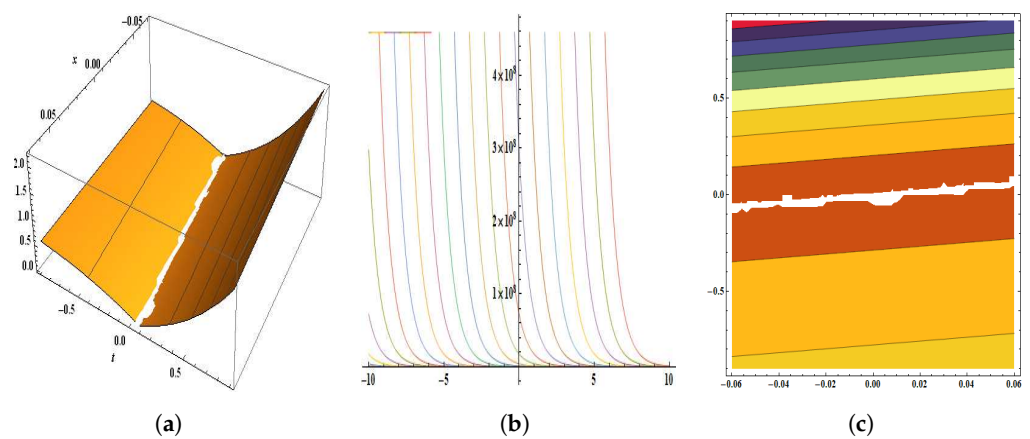


Figure 5. The parameters are $a = 2, s = 2, m = 1, n = 1, \gamma = 2, \alpha = 1, b = 1.5, c = 1, k = 2, \beta = 1$, and $\Gamma = 1$. The figure provides the pictorial illustration of $p_{1,5}(x, t)$: (a) displays the 3D plot in $[-0.07, 0.07]$ and $[-0.9, 0.9]$, (b) displays the 2D plot in $[-10, 10]$ and $[-20, 20]$, (c) displays the contour plot.

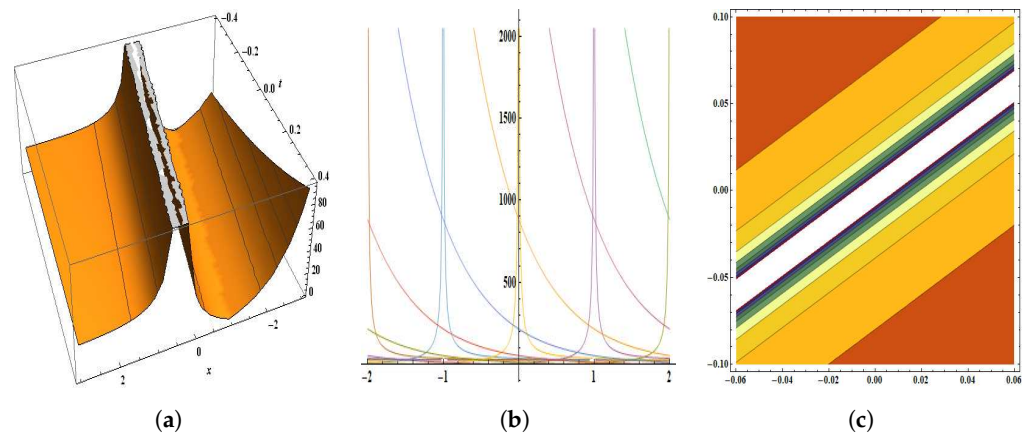


Figure 6. The parameters are $a = 2, k = 2, s = 2, m = 1, n = 1, \gamma = 2, \alpha = 1, b = 1.5, c = 1, \beta = 1$, and $\Gamma = 1$. The figure provides the pictorial illustration of $p_{2,1}(x, t)$: (a) displays the 3D plot in $[-3, 3]$ and $[-0.4, 0.4]$, (b) displays the 2D plot in $[-7, 7]$ and $[-2, 2]$, (c) displays the contour plot.

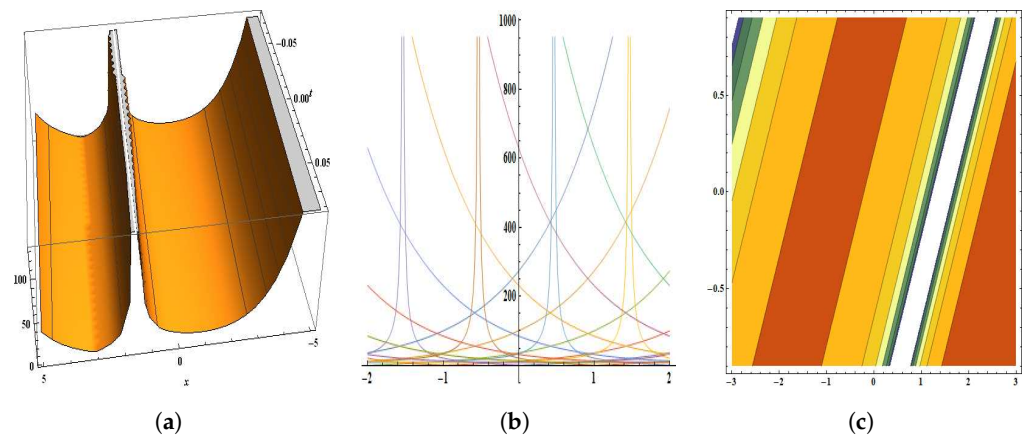


Figure 7. The parameters are $a = 2, k = 2, s = 2, m = 1, n = 1, b = 1.5, c = 1, \gamma = 2, \alpha = 1, \beta = 1$, and $\Gamma = 1$. The figure provides the pictorial illustration of $p_{2,2}(x, t)$: (a) displays the 3D plot in $[-3, 3]$ and $[-0.4, 0.4]$, (b) displays the 2D plot in $[-7, 7]$ and $[-2, 2]$, (c) displays the contour plot.

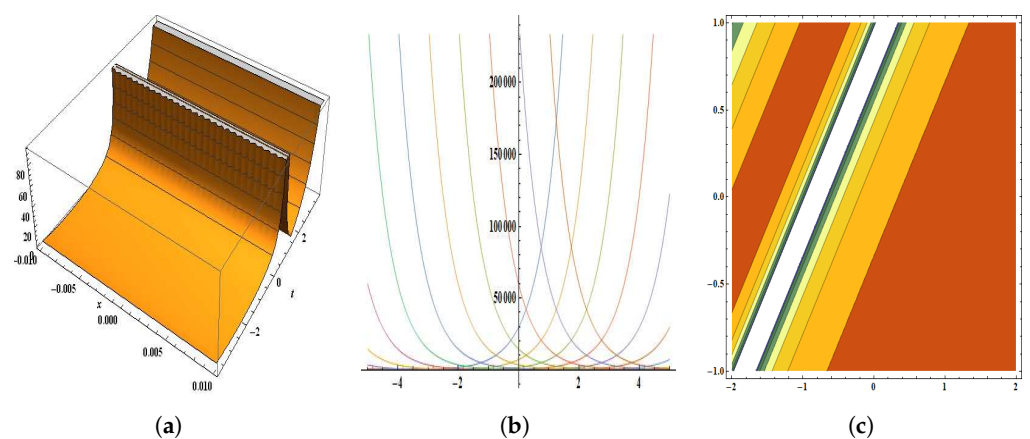


Figure 8. The parameters are $a = 2, k = 2, s = 2, m = 1, n = 1, b = 1.5, c = 1, \alpha = 1, \beta = 1$, and $\Gamma = 1$. Pictorial illustration of $p_{2,3}(x, t)$: (a) displays the 3D plot in $[-0.01, 0.01]$ and $[-3.75, 3.75]$, (b) displays the 2D plot in $[-5, 5]$ and $[-10, 10]$, (c) displays the contour plot.

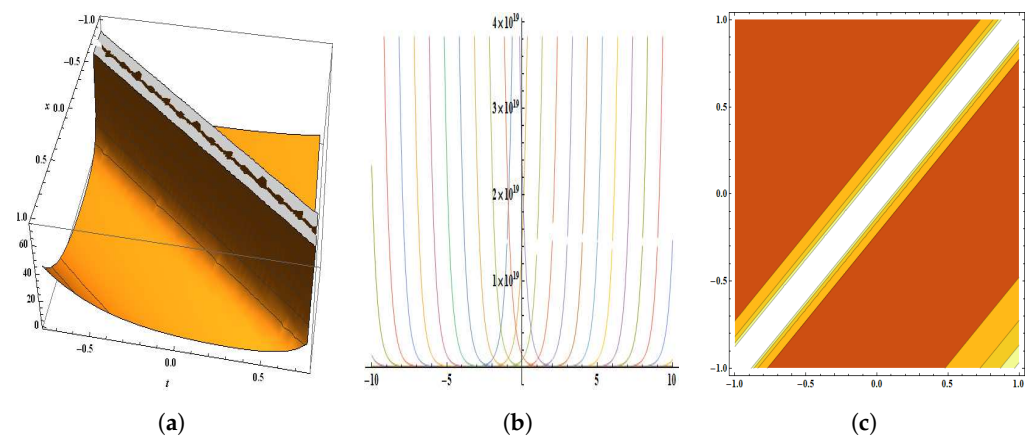


Figure 9. The parameters are $a = 2, k = 2, s = 2, m = 1, n = 1, b = 1.5, c = 1, \alpha = 1, \beta = 1$, and $\Gamma = 1$. Pictorial illustration of $q_{2,4}(x, t)$: (a) displays the 3D plot in $[-1, 1]$ and $[-0.75, 0.75]$, (b) displays the 2D plot in $[-10, 10]$ and $[-17, 17]$, (c) displays the contour plot.

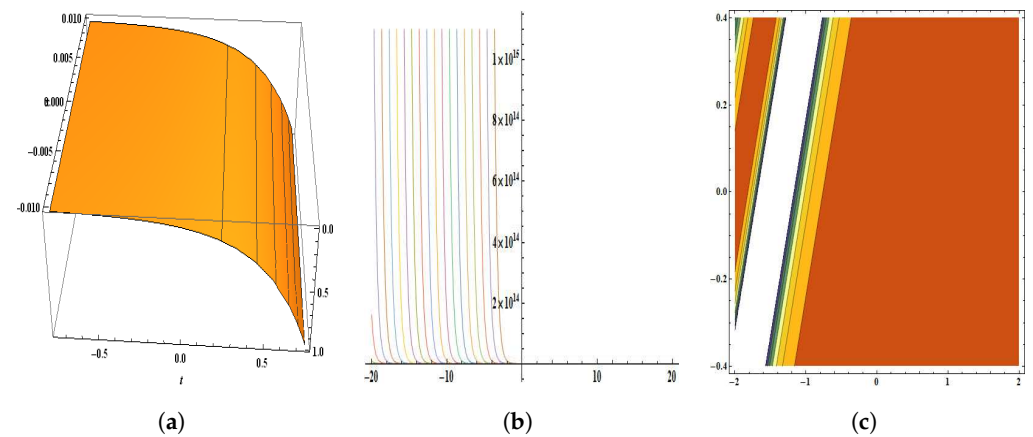


Figure 10. The parameters are $a = 2, k = 2, s = 2, m = 1, n = 1, b = 1.5, c = 1, \gamma = 2, \alpha = 1, \beta = 1$, and $\Gamma = 1$. The figure provides the pictorial illustration of $r_{2,5}(x, t)$: (a) displays the 3D plot in $[-0.01, 0.01]$ and $[-0.75, 0.75]$, (b) displays the 2D plot in $[-20, 20]$ and $[-10, 10]$, (c) displays the contour plot.

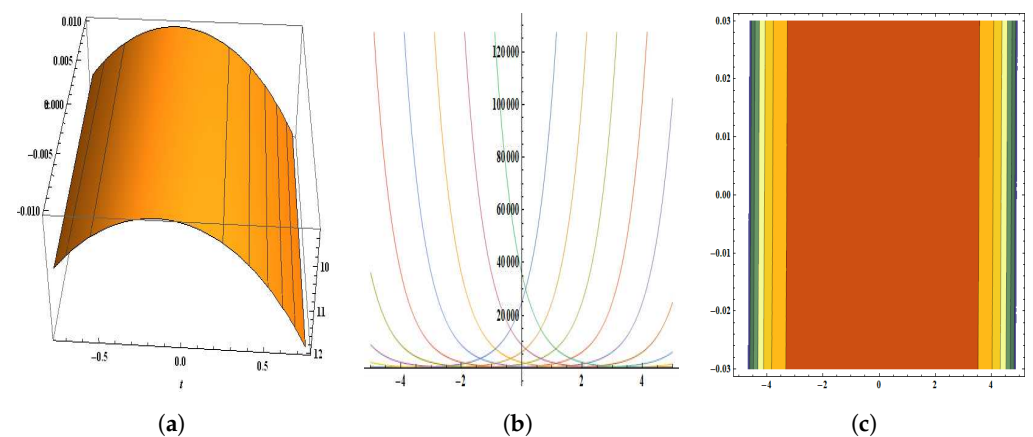


Figure 11. The parameters are $a = 2, k = 2, s = 2, m = 1, n = 1, b = 1.5, c = 1, \gamma = 2, \alpha = 1, \beta = 1$, and $\Gamma = 1$. The figure provides the pictorial illustration of $r_{3,1}(x, t)$: (a) displays the 3D plot in $[-0.01, 0.01]$ and $[-0.75, 0.75]$, (b) displays the 2D plot in $[-5, 5]$ and $[-7, 7]$, (c) displays the contour plot.

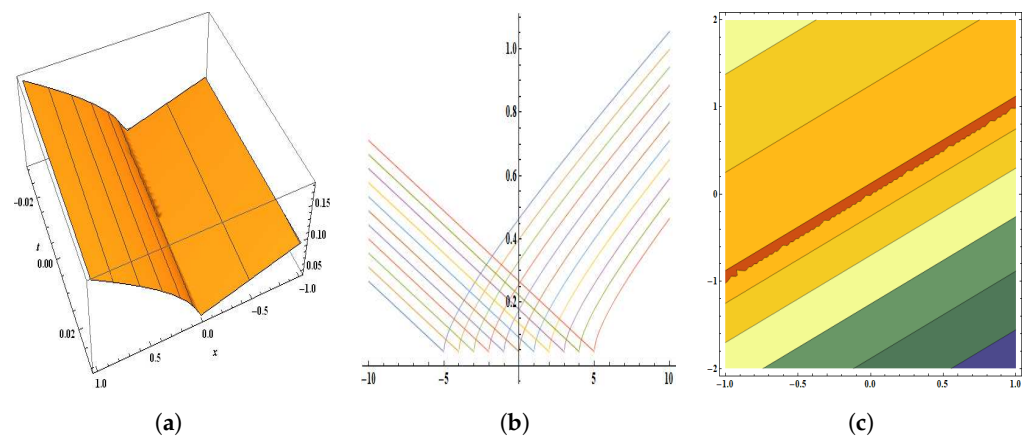


Figure 12. The parameters are $a = 2, k = 2, s = 2, m = 1, b = 1.5, c = 1, n = 1, \gamma = 2, \alpha = 1, \beta = 1$, and $\Gamma = 1$. The figure provides the pictorial illustration of $q_{3,2}(x, t)$: (a) displays the 3D plot in $[-1, 1]$ and $[-0.03, 0.03]$, (b) displays the 2D plot in $[-5, 5]$ and $[-10, 10]$, (c) displays the contour plot.

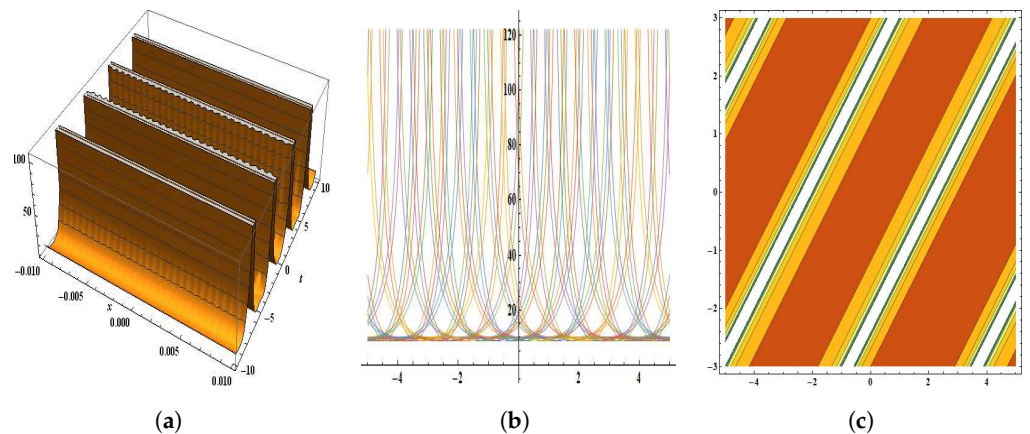


Figure 13. The parameters are $a = 2, k = 2, s = 2, m = 1, n = 1, b = 1.5, c = 1, \alpha = 1, \beta = 1$, and $\Gamma = 1$. The figure provides the pictorial illustration of $p_{3,3}(x, t)$: (a) displays the 3D plot in $[-0.01, 0.01]$ and $[-10, 10]$, (b) displays the 2D plot in $[-5, 5]$ and $[-10, 10]$, (c) displays the contour plot.

7. Conclusions

Using the mathematical computing software tool Mathematica, the P -test and the AEM technique were used to determine the integrability and some new optical solitary wave solutions of the TNFSE with modified RLD derivatives. These obtained solitons solutions are widely used in optics and photonics including the production of ultrafast laser pulses and the development of optical instruments for particle manipulation, while these soliton solutions are not directly used in most everyday applications, they do have significant indirect uses in domains such as communication, materials processing, and oceanography. There have been numerous graphical presentations of solitary periodic, kink-shaped, and singular solutions. These algorithms are efficient for finding a single exact solution and working with the nonlinear fractional governing equations existing in physics.

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