

DUNE AI/ML Kick-Off Workshop 2025

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Anomaly Detection & Smart TPC

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U.S. DEPARTMENT
of **ENERGY**

Fermi National Accelerator Laboratory is managed by
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When DUNE reaches Stat. = Syst. Uncertainty?

in CPV measurement

In which exposure?

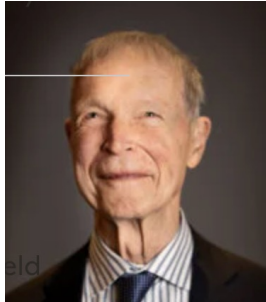
- AI/ML could reduce **resources** to reach the entrance to the syst. era.
- AI/NL could be also used to improve systematic uncertainty.

→ AI/ML will lead us to earlier discoveries.



Nobel Prizes 2024 with AI/ML

☐ Physics: *“for foundational discoveries and inventions that enable machine learning with artificial neural networks”*



John J. Hopfield



Geoffrey Hinton

☐ Chemistry:

The Nobel Prize in Chemistry 2024 is about **proteins**, life’s ingenious chemical tools. **David Baker** has succeeded with the almost impossible feat of building entirely new kinds of proteins. **Demis Hassabis** and **John Jumper** have **developed an AI model to solve a 50-year-old problem**: predicting proteins’ complex structures. These discoveries hold enormous potential.



Roadmap for DUNE AI/ML (my personal view)

AI/ML Application from start (trigger level) to finish (analysis)

- Anomaly detection (raw data)
- Data volume reduction (raw data, trigger)
- Signal processing
- Pattern recognition (reco, analysis)



01

Anomaly Detection



Searching for Anomalies

We'd like to use “**unbiased data**” to detect anomalies.

Anomalies could be due to:

- **New physics** (very rare processes) → the best scenario
 - Known physics: random & rare (SNB) → one of our missions
 - Detector malfunction
 - Statistical fluctuation
 - Systematic effect
- **Detector Monitoring**

Using AI/ML, we would like to detect anomalies at real/near-time.
The AI/ML model can reduce data volume as well.



Anomaly Detection in CMS

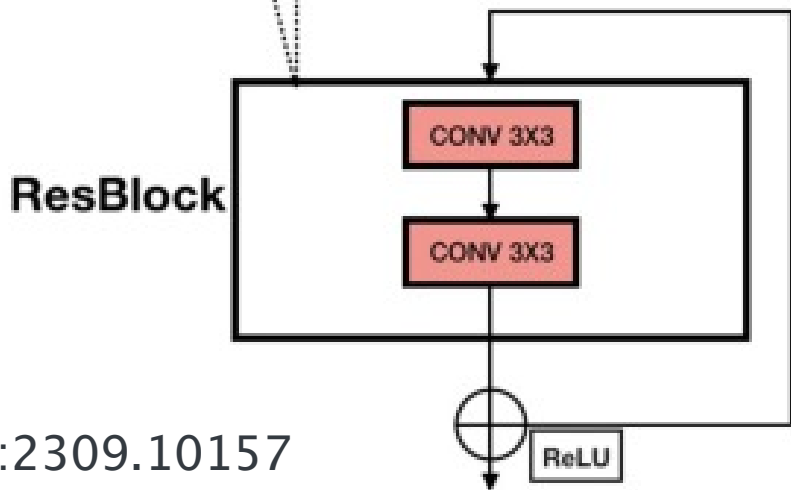
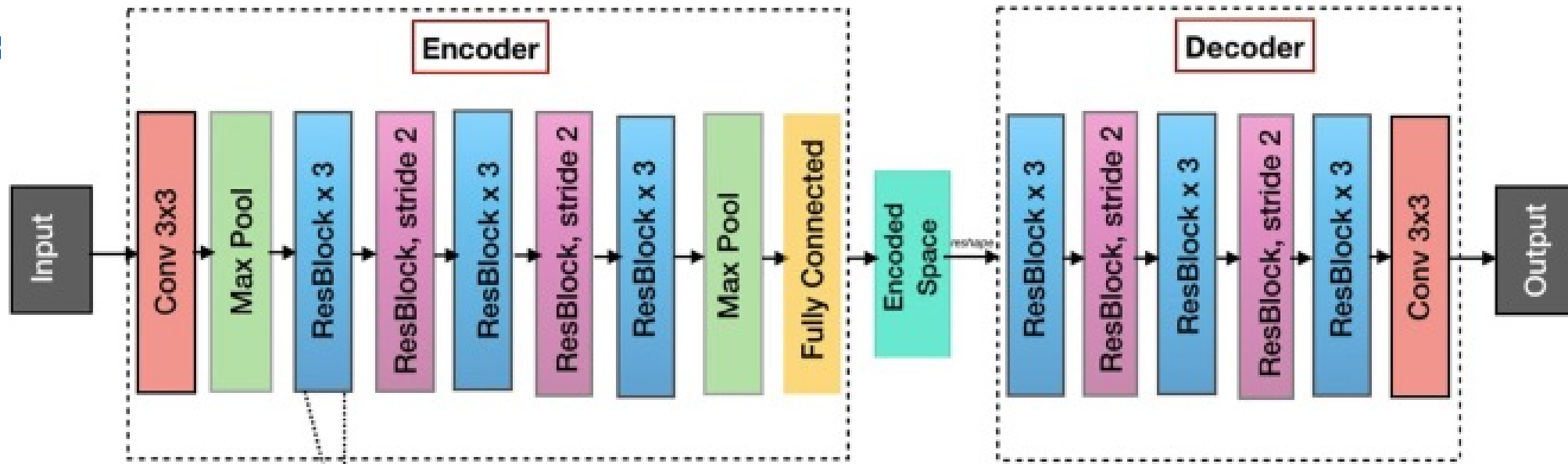
arXiv:2309.10157

□ CMS EM Calorimeter:

-- **Autoencoder**-based anomaly detection system
using **semi-supervised** ML techniques

- The network is trained exclusively on the certified good physics data set.
- Identify anomalies without needing prior examples of anomalous data

• The autoencoder takes care of spatial variations in detector response and the time-dependent nature of anomalies, improving overall detection performance.



Loss function *input* *output*

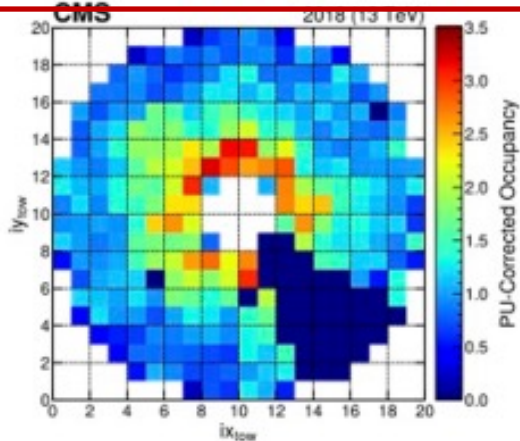
$$\mathcal{L}(x, x') = ||(x - x')||^2$$

Autoencoder Architecture
@CMS Anomaly Detection

arXiv:2309.10157

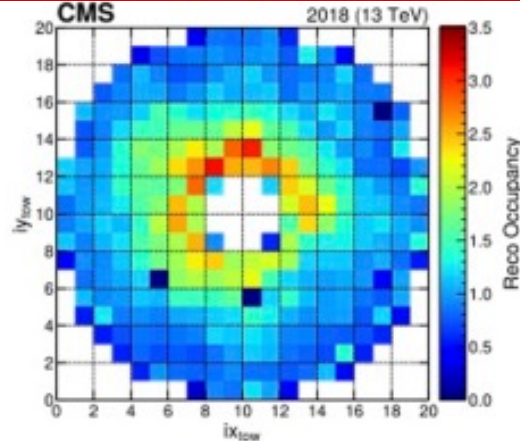


Input



Input occupancy histogram with anomaly:
missing sector

AE
Endcap

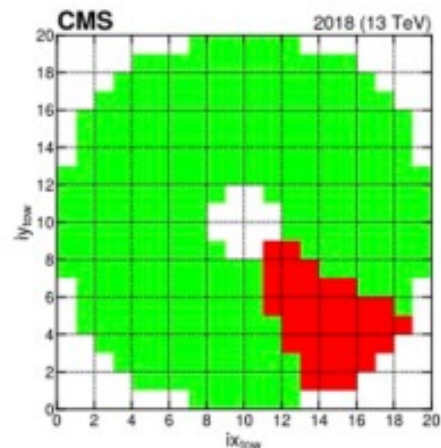


AE-reconstructed image:
anomaly not reconstructed

Reco-
output

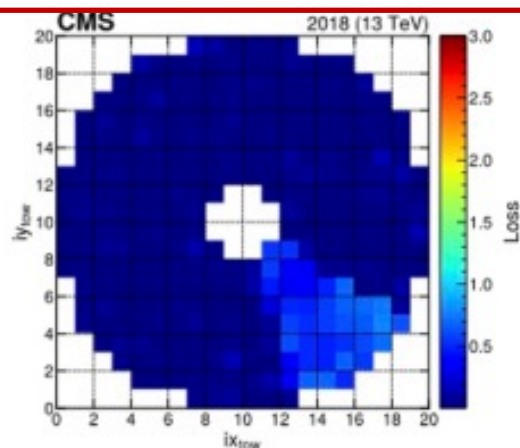
Spatial & time
correction

Flag
Anomaly



Final quality output:
anomalous towers: **red**
good towers: **green**

Set threshold
for flagging anomaly



Loss map:
anomalous showing high loss

Loss
Map



CMS ECAL Barrel Fake Anomaly Scenarios

arXiv:2309.10157

Baseline

	FDR for 99% anomaly detection		
	Missing Supermodule	Zero Occupancy Tower	Hot Tower
Baseline no correction	14%	90%	5.2%
Baseline after time correction	5.9%	80%	< 0.01%
AE no correction	3.6%	51%	2.8%
AE after spatial correction	3.1%	49%	2.9%
AE after spatial and time corrections	0.13%	4.1%	< 0.01%

Autoencoder

Benefits of Autoencoder-based Anomaly Detection System

- Real-time monitoring → immediate feedback
 - Enhanced detection capabilities
 - Low false discovery rate
 - Automation of anomaly detection
-
- We can adopt the same/similar method in DUNE TPC & PDS for anomaly detection.
 - SuperNova Burst can be detected in “real-time” as an anomaly.



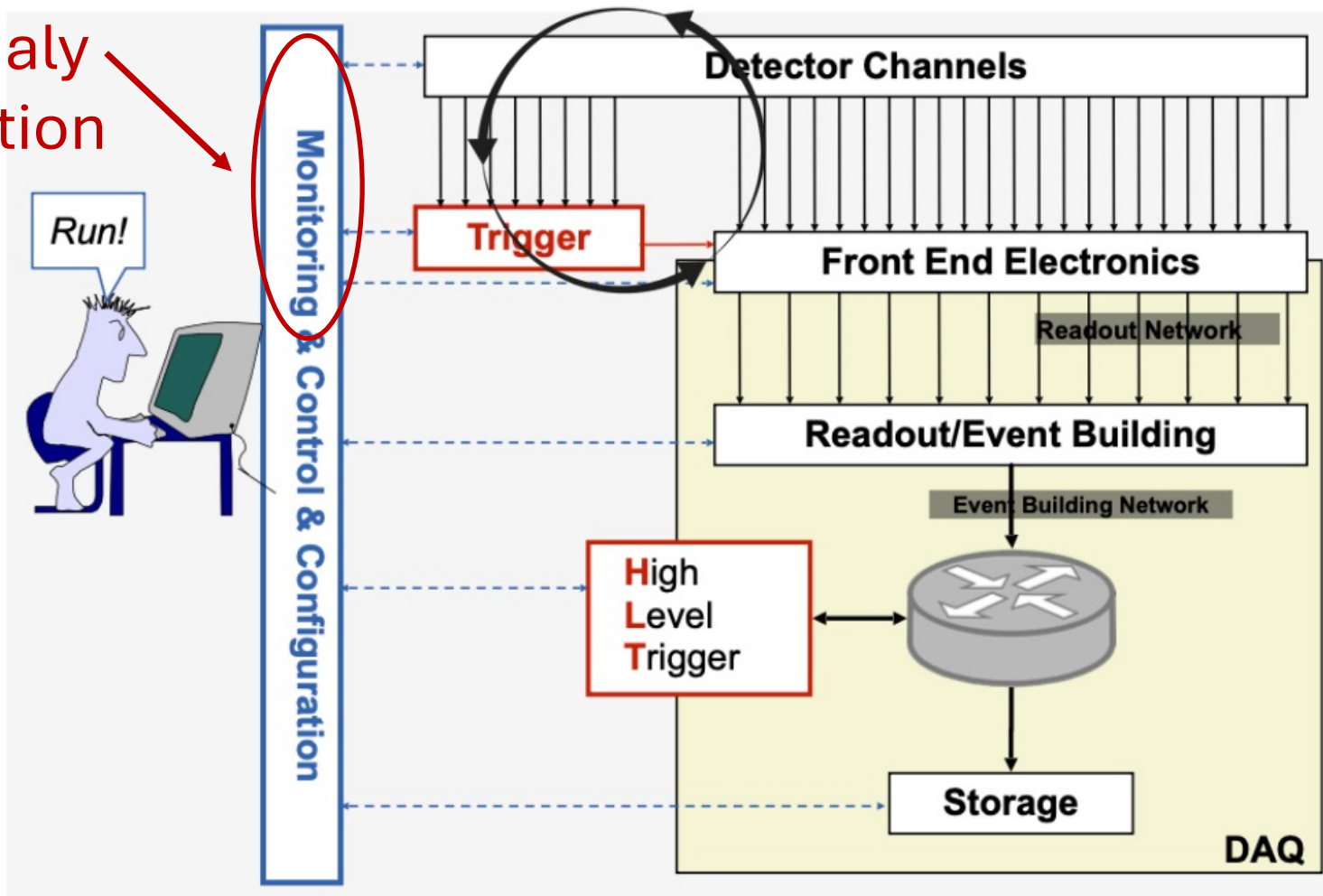
02

Smart TPC



DAQ Trigger & Monitoring

Anomaly detection

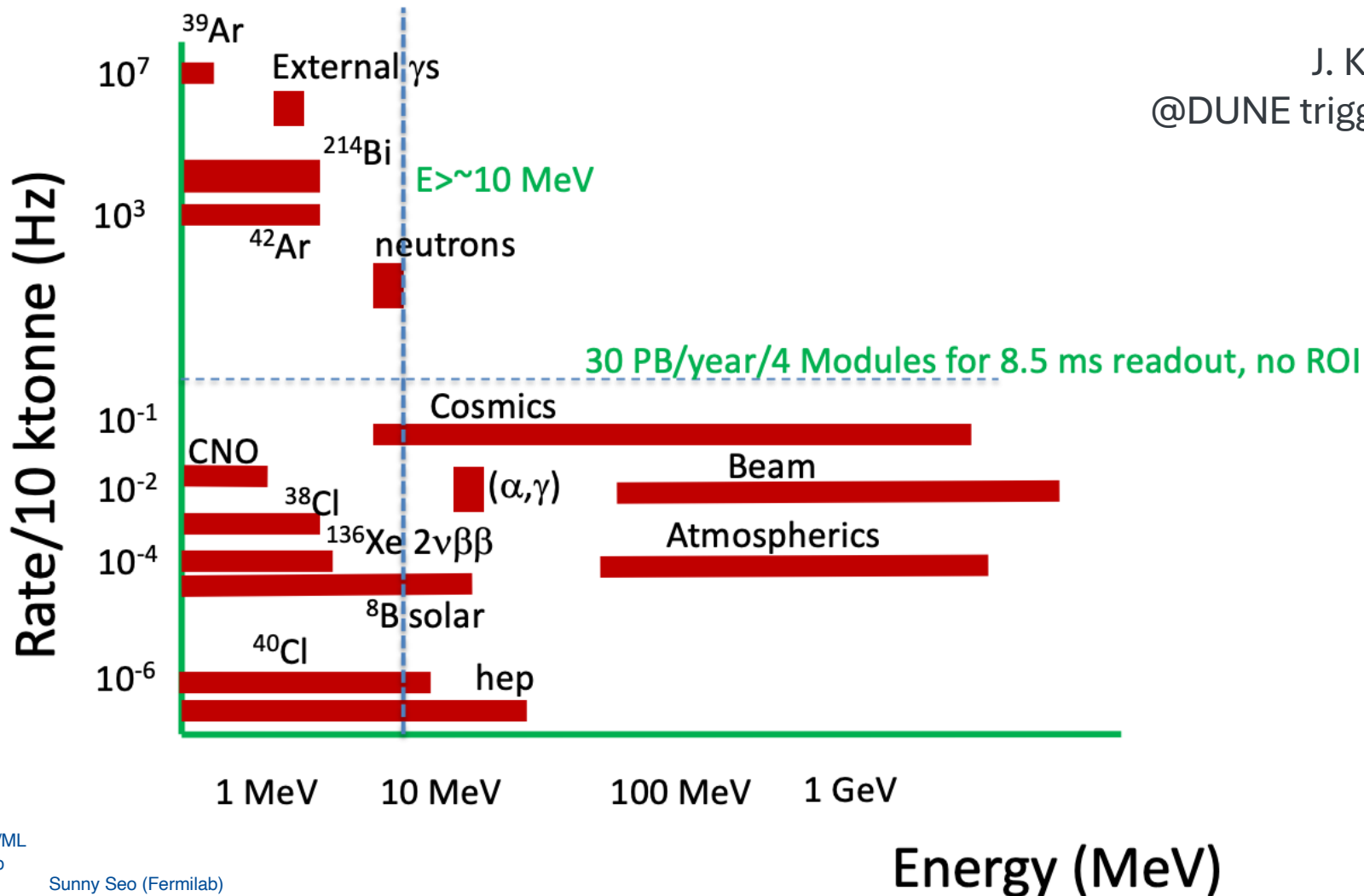




Trigger Design Constraints

Rates and Energy Threshold

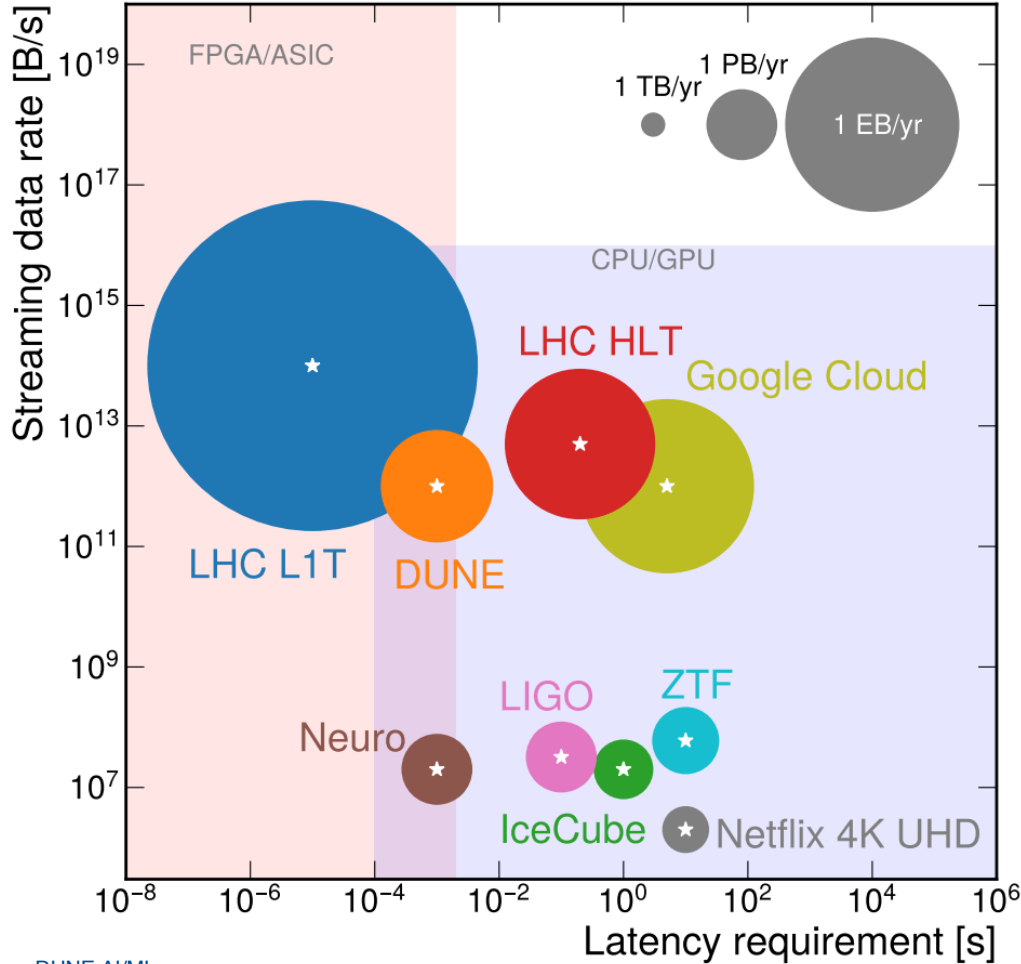
J. Klein's talk
@DUNE trigger workshop, 2025





Motivation for Data Volume Reduction

A3D3 Institute



→ We expect high raw data volumes for (HL-)LHC and DUNE.

□ DUNE: [arXiv:2203.16255](https://arxiv.org/abs/2203.16255)

- ~ TB/sec → **~32 EB/year**
- 100 % livetime (for Supernova)
- > ~ 20 years of operation

□ DUNE's cap for computing:
~ 30 PB/year

→ **3 orders of magnitude reduction is needed.**

Data Volume Summary Table

J. Klein's talk

@DUNE Trigger Workshop, 2025

Under the assumption we read out 2x drift time * all channels with no zero suppression, no ROI imposition, and no compression:

Source	Annual Data Volume/ 10 kt	Assumptions
Beam interactions	10 TB	700 vs+700 dirt μ s; everything read out for 8.5 ms (no ZS); 10 MeV threshold in coincidence with beam time; include cosmics
Cosmics (+atmospherics)	10.5 PB	All channels in 8.5 ms window around HE event; 4000/day/10 kt
Radiologicals	1 PB	E > 10 MeV so rate < 10% cosmics; no ROI imposition
Supernova Bursts		Fake rate of 1/month; 100 s storage/burst
Front-End cals	200 TB	Worst case of measuring every single ADC bin with 100 measurements/point; four times/year
Radioactive source cals	100 TB	Source rate < 5 Hz (or pre-scaled to that); only one APA/CRP readout; PDS is negligible; full readout window per tag; no ZS
Laser cals	200 TB	1x10 ⁶ total laser pulses; tight ZS for both induction and collection; 1/2 of all wires in TPC illuminated
Random Triggers	100 TB	Same as cosmics scheme; rate is 40/day
Trigger Primitives	38 PB	All planes; 26 B/primitive; noise rate = ³⁹Ar rate;

**~50 PB
/year/module**

**Still,
we should
reduce
data volume!
(~one order
of magnitude)**



Proposed Solution

□ AI/ML “*in-situ*” → Reducing computing resources

- Reducing raw data volume by applying AI/ML “*in-situ*”
- Use **all subdetector info “*in-situ*”** to increase S/B

→ **Unique & Challenging**

□ RF network → Reducing use of materials

- Essential for subdetector communication
- **Enabling cable-free detector**

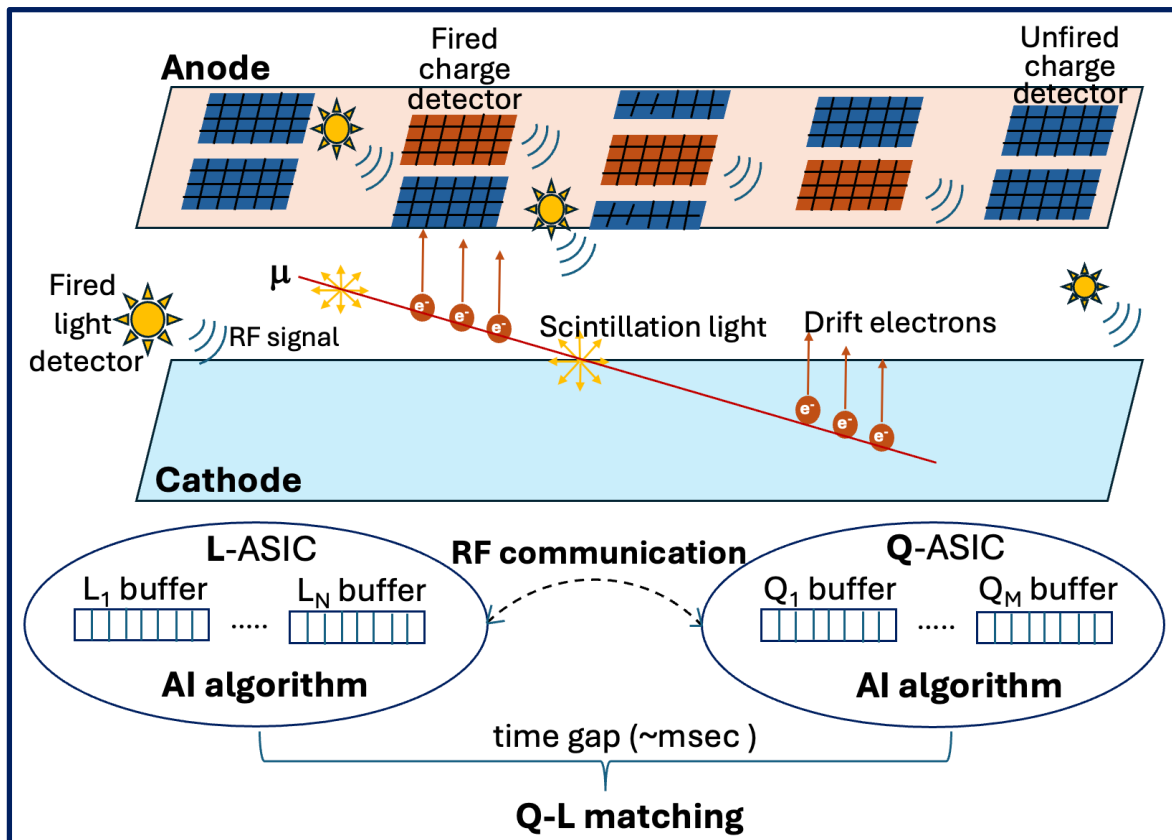
□ Cryo dSiPM → Saving project budget

- ~10% that of commercial SiPM



AI/ML “*in-situ*” in LArTPC

Smart TPC: Charge (Q) + Light (L) matching “*in-situ*”



❑ Q-L matching “*in-situ*”

❑ Pattern recognition “*in-situ*”

- Time
- Space
- Deposited charge & light

→ RF network among all subdetector components are essential.



Test of RF Device(s) at LAr

❑ RF communication between Q & L detectors is essential for raw data reduction.

- We will start with a commercial RF device(s) to test it at LArTPC.
ex) LoRa
low power, cheap
- Through tests in LAr,
the device could be optimized to work properly in Cryo temperature.

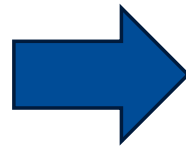


RF Communication

❑ Not only RF communication between sub-detectors, we can consider **sending out raw data over RF network.**

→ This will allow us to build a **cable-free detector.**

We plan to test this during our R&D.



Here, imagine DUNE detector w/ & w/o cables.



Alternative Light Pixel Detector

SPAD: Single Photon Avalanche Diode

□ [Cryo dSiPM](#)

→ Currently under-development
by Fermilab, EPFL, and Global Foundry

- [Pros:](#)
 - Cheaper (~10% of commercial SiPMs)
- [Cons:](#)
 - High dark count rate (→ need to measure it in LAr)
 - Need VUV wavelength shifter



Key Technologies in this R&D

□ AI/ML on Chip (ASICs)

→ Reduce raw data volume “*in-situ*”

□ RF Network

-- Communication between Q & L detector

→ essential for Q-L matching “*in-situ*”

-- Raw Data transfer

→ cable-free detector

□ Digital CryoSPAD

-- Alternative to commercial SiPMs

-- not required for this R&D (but helps reduce budget)

Application to
any other
experiments



AI/ML Model to Hardware

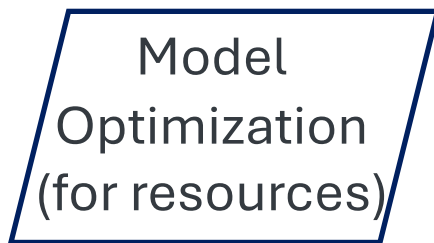
Model Building



+ Simulated data

HW-Aware Test

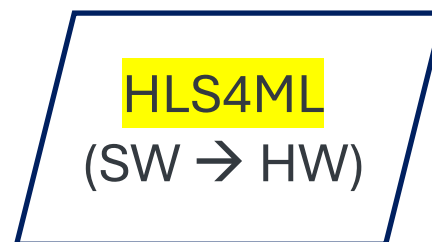
To optimize the model for given HW constraints (memory, speed, power,..)



+ Quantization
+ Pruning

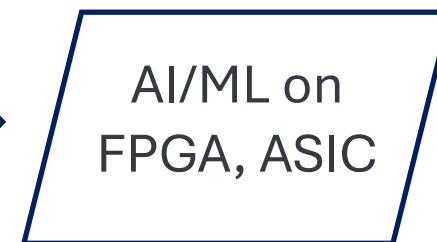
Model Translation

Co-design model (physicist, AI expert, HW engineer)



+ Optimization
+ Profiling
+ Tuning

HW Implementation



HLS = high level synthesis



Timeline of "Smart-Pixel TPC" R&D

Phase-I: Feasibility Study

Build
AI/ML model
using
simulated data

HW-Aware Test,
Model Translation

Implement
& Test AI/ML
on FPGA

Wrapping up

Phase-II: Demonstrator

Implement
& Test AI/ML
on ASIC

Start

~1 yr

~1 yr

~1 yr

~2 yr

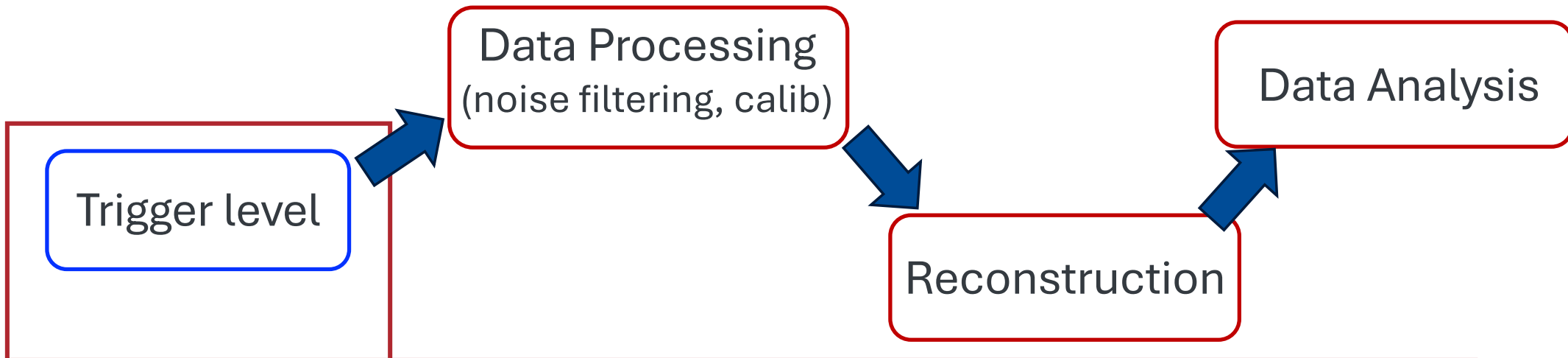
Finish

RF device test,
CryoSPAD test

Cable-free
data transfer test



AI/ML Start-to-Finish



Real-Time Anomaly Detection

- * New physics search
- * Checking data quality
- * Monitoring detector

Q-L Matching “*in-situ*”

- * Increase S/B ratio at the beginning
- * Reduce data volume



Roadmap for DUNE AI/ML (my personal view)

Employ a “**Foundation Model**” for LArTPC experiments

- ❑ A **foundation model**, also known as **large X model (LxM)**, is a [machine learning](#) or [deep learning](#) model that is [trained on vast datasets](#) so it can be applied across a wide range of use cases.
- ❑ Foundation model is itself [incomplete](#) but it serves as the [common basis](#) from which many task-specific models are built via adaptation.
- ❑ The term ‘**foundation**’ to connote the significance of architectural [stability](#), [safety and security](#): poorly constructed foundations are a recipe for disaster and well-executed foundations are a reliable bedrock for future applications.”

Common Triggers → Triggers/Physics
→ Data Processing → Reco → Analysis



Summary & Conclusion

❑ AI/ML has become an essential tool for modern science, as proven by Nobel 2024.

❑ DUNE, as an imaging detector, is the best place to apply AI/ML.

❑ DUNE has been applying AI/ML mostly to reconstruction, but it needs to extend it to the entire process of data taking.

❑ Applying AI/ML to raw data and the trigger level would enhance DUNE's potential for its discoveries.

→ If you are interested in this, let's work together. Let me know!